

# Implicit characterization of the class of Basic Feasible Functionals

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# Motivations

We aim at providing characterizations of complexity classes:

- ▶ **machine-independent**,
- ▶ with **no prior knowledge** on the complexity of analyzed codes.

If the characterization is **tractable** then we obtain an **automated complexity analysis** for a high-level programming language.



State of the art:

- ▶ 30 years of intensive research,
- ▶ hundreds of publications,
- ▶ some tools: Costa, SPEED, TcT, ...

# The Implicit Computational Complexity approach

## Methodology

Consider your favorite programming language  $\mathcal{L}$  and your favorite complexity class  $\mathcal{C}$ .

Find a tractable restriction  $\mathcal{R} \subseteq \mathcal{L}$  such that  $\llbracket \mathcal{R} \rrbracket = \mathcal{C}$ ,

where  $\llbracket X \rrbracket$  is the set of functions computed by programs in  $X$ .

## Examples of (type-1) complexity class $\mathcal{C}$

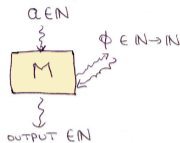
- ▶ P, FP,
- ▶ PSPACE, FPSPACE,
- ▶ NP,
- ▶ PP, BPP, EQP, BQP,
- ▶ ...

## Examples of restriction $\mathcal{R}$

- ▶ type systems:
  - ▶ linear logic, sized types, ...
- ▶ interpretation methods,
- ▶ amortized resource analysis,
- ▶ ...

## What about type-2 complexity classes?

**Type-2** objects are functions in  $\overbrace{(\mathbb{N} \rightarrow \mathbb{N})}^{\phi} \times \overbrace{\mathbb{N}}^a \rightarrow \mathbb{N}$



**Type-2** polynomial time is taken to be the class of Basic Feasible Functionals (BFF)

Goal (Open problem for more than 20 years)

Find a **tractable** technique for certifying **type-2 polynomial time** complexity.

Rephrasing: Find a tractable restriction  $\mathcal{R}$  such that  $\llbracket \mathcal{R} \rrbracket = \text{BFF}$ .

N.B.: The problem was solved for **type-1** polytime FP by Bellantoni and Cook in 1992.

## A reminder on type-2 polynomial time

BFF was introduced by Melhorn in 1976.

Theorem [Cook and Urquhart [1989]]

$$\text{BFF} = \lambda(\text{FP} \cup \{\mathcal{I}\})_2$$

$\mathcal{I}$  is a type-2 bounded iterator:

$$\mathcal{I}^{f,g}(\epsilon, a) = a$$

$$\mathcal{I}^{f,g}(ix, a) = \min(f(ix, \mathcal{I}^{f,g}(x, a)), g(ix))$$

$\lambda(X)_2$ : type-2 restriction of the simply-typed lambda-closure using constants in  $X$ .

Theorem [Kapron and Cook [FOCS1991]]

The set of functionals computable by an Oracle TM (OTM) in time  $P(|\phi|, |a|)$  is exactly BFF.

Type-2 polynomials and size function are defined by:

- ▶  $P(X_1, X_0) ::= c \in \mathbb{N} \mid X_0 \mid P + P \mid P \times P \mid X_1(P)$
- ▶  $|\phi|(n) = \max_{|x| \leq n} |\phi(x)|$

## How to get rid of type-2 polynomials?

→ Type-2 polynomials are not tractable.

Definition [Oracle Polynomial Time (OPT) – Cook [1992]]

Let  $n^{\phi, A}$  be the biggest size of  $a$  and of an oracle's answer in the run of  $M(\phi, a)$ .  
The OTM  $M$  is in OPT if its runtime is bounded by  $P(n^{\phi, a})$ , for a type-1 polynomial  $P$ .

$\text{BFF} \subsetneq \text{OPT}$ , as OPT contains exponential functions.

Theorem [Kapron and Steinberg [LICS2018]]

$$\text{BFF} = \lambda(\llbracket \text{OPT} \cap \text{FLAR} \rrbracket)_2$$

→ FLAR = Finite LookAhead Revision

# Finite LookAhead Revision

## Definition [Finite LookAhead Revision - Kapron and Steinberg [LICS2018]]

An OTM is in FLAR, if, for any input, the number of times a query is posed whose size exceeds the size of all previous queries is bounded by a constant.

### Example

```
while (x>0){
  y =  $\phi(x)$ ;
  x = x-1;
}
```

in FLAR.

The constant bound is 0.

### Example

```
while (x<z && y<8){
  y =  $\phi(x)$ ;
  x = x+1;
}
```

not in FLAR for  $\phi = \lambda x.4$

but is in FLR (I will briefly mention this class in the conclusion)

## How to get rid of (Oracle Turing) machines?

→ Design a typed PL ensuring that computed functions are in  $\text{OPT} \cap \text{FLAR}$ .

### Imperative PL on words with oracles

*Expressions*  $\ni E ::= x \mid \text{true} \mid \text{false} \mid \text{op}(E, \dots, E) \mid \phi(\mathbf{E} \upharpoonright \mathbf{E})$

*Commands*  $\ni C ::= x := E; \mid C \ C \mid \text{if}(E)\{C\}\text{else}\{C\} \mid \text{while}(E)\{C\}$

In an oracle call  $\phi(w \upharpoonright v)$ :

- ▶  $\phi$  computes a type-1 function on words, i.e.  $\phi \in \mathbb{W} \rightarrow \mathbb{W}$ .
- ▶  $w$  is the **oracle input**.
- ▶  $v$  is the **input bound**:  $w \upharpoonright v = w_1 \dots w_{|v|}$ .



## Tier-based type discipline

Tiers  $\mathbf{k}, \mathbf{k}', \dots$  are security levels (in  $\mathbb{N}$ ) assigned to Expressions and Commands.

The type system ensures some non-interference properties.

In a tier  $\mathbf{k}$  command:

- ▶ the program flow cannot be controlled by expressions of a lower tier  $\mathbf{k}^- < \mathbf{k}$ ,
- ▶ data of upper tier  $\mathbf{k}^+ \geq \mathbf{k}$  cannot increase (in size).

Judgments:  $\Gamma, \Delta \vdash C : (\mathbf{k}, \mathbf{k}_{in}, \mathbf{k}_{out})$  with  $(\mathbf{k}, \mathbf{k}_{in}, \mathbf{k}_{out}) \in \mathbb{N}^3$

1. The tier  $\mathbf{k}$  implements the non-interference policy.
2. The *innermost* tier  $\mathbf{k}_{in}$  is used for declassification.
3. The *outermost* tier  $\mathbf{k}_{out}$  is used to ensure FLAR on oracle calls.

# Tier-based type system: an overview

## Typing rules

$$\frac{\vdash x : (\mathbf{k}_1, \mathbf{k}_{in}, \mathbf{k}_{out}) \quad \vdash E : (\mathbf{k}_2, \mathbf{k}_{in}, \mathbf{k}_{out}) \quad \mathbf{k}_1 \leq \mathbf{k}_2}{\vdash x := E : (\mathbf{k}_1, \mathbf{k}_{in}, \mathbf{k}_{out})} \text{ (Asg)}$$

$$\frac{\vdash E : (\mathbf{k}, \mathbf{k}_{in}, \mathbf{k}_{out}) \quad \vdash C : (\mathbf{k}, \mathbf{k}, \mathbf{k}_{out}) \quad \mathbf{1} \leq \mathbf{k} \leq \mathbf{k}_{out}}{\vdash \text{while}(E)\{C\} : (\mathbf{k}, \mathbf{k}_{in}, \mathbf{k}_{out})} \text{ (Wh)}$$

$$\frac{\vdash E : (\mathbf{k}, \mathbf{k}_{in}, \mathbf{k}_{out}) \quad \vdash E' : (\mathbf{k}_{out}, \mathbf{k}_{in}, \mathbf{k}_{out}) \quad \mathbf{k} < \mathbf{k}_{in} \leq \mathbf{k}_{out}}{\vdash \phi(E \uparrow E') : (\mathbf{k}, \mathbf{k}_{in}, \mathbf{k}_{out})} \text{ (Orc)}$$

⋮

## Illustrating example

Program computing the decision problem  $\exists n \leq x, \phi(n) = 0$ .

```
y = x;  
z = false;  
while(x1 >= 0){  
  if( $\phi(y^0 \upharpoonright x^1) == 0$ ){  
    z0 = true;  
  } else {;}  
  x1 = x1 - 1;  
}  
return z
```

- ▶ The program is typable and the while body has tier **(1, 1, 1)**.
- ▶ The computed function is in  $\text{OPT} \cap \text{FLAR}$ .

## A tier-based characterization of BFF

- ▶ Let SAFE be the set of typable programs.
- ▶ Let SN be the set of strongly normalizing programs.
- ▶ Let  $\llbracket X \rrbracket$  be the set of functions computed by programs in X.

Theorem [Hainry-Kapron-Marion-Péchox [LICS2020]]

$$\text{BFF} = \lambda(\llbracket \text{SAFE} \cap \text{SN} \rrbracket)_2$$

Main drawbacks:

- ▶ Lambda closure (for completeness)
- ▶ Termination assumption (for soundness)

## How to get rid of the lambda-closure?

Naïve idea: internalize lambda-abstraction and application into the language.  
 → cannot be done straightforwardly as it breaks soundness.

Extended language ( $e_i$ :  $e$  is a type- $i$  object)

(Expressions)	$E ::= x_0 \mid op(E, \dots, E) \mid x_1(E \uparrow E)$
(Statements)	$C ::= [x_0 := E]; \mid C C \mid \text{if}(E)\{C\}\{C\} \mid \text{while}(E)\{C\}$
(Procedures)	$P ::= P(\overline{x_1}, \overline{x_0})\{C \text{ return } x_0\}$
(Terms)	$t ::= x \mid \lambda x.t \mid t@t \mid \text{call } P(\overline{\{x_0 \rightarrow t_0\}}, \overline{t_0})$
(Programs)	$\text{prog} ::= t_0 \mid \text{declare } P \text{ in prog}$

Solution: type-1 arguments in a procedure call are restricted to closures  $\{x_0 \rightarrow t_0\}$ .

# Type system

The extended type system just consists of two layers:

- ▶ SAFE procedures (using the HKMP[LICS2020] paper),
- ▶ Simply-typed terms on words  $\mathbb{W}$ .

## Definitions

A program is a **type- $i$**  program if all its  $\lambda$ -abstractions are of order  $\leq i$ .

- ▶  $\text{SAFE}_i$  is the set of type- $i$  typable programs.
  - ▶ Remark:  $\text{SAFE}_0$  is the set of typable programs without lambda-abstraction.
- ▶ SN is still the set of strongly normalizing programs.

## Example

```

prog( $\phi, w$ )  $\triangleq$  declare KS(Y, v) {
    u := 10;
    z :=  $\epsilon$ ;
    while ( $v^1 \neq 0$ ) { //  $k_{in} = k_{out} = 1$ 
         $v^1 := v - 1$ ;
         $z^0 := Y(z^0 \upharpoonright u^1)$ 
    }
    return z
}
in call KS( $\{x \rightarrow \phi @ (\phi @ x)\}$ , w)

```

- ▶  $\llbracket \text{prog} \rrbracket \in (\mathbb{W} \rightarrow \mathbb{W}) \rightarrow \mathbb{W} \rightarrow \mathbb{W}$
- ▶  $\llbracket \text{prog} \rrbracket(\phi^{\mathbb{W} \rightarrow \mathbb{W}}, w^{\mathbb{W}}) = F_{|w|}(\phi)$  with  $\begin{cases} F_0(\phi) = \epsilon \\ F_{n+1}(\phi) = (\phi \circ \phi)(F_n(\phi)^{\leq |10|}) \end{cases}$
- ▶  $\text{prog} \in \text{SAFE}_0 \cap \text{SN}$  whereas  $\llbracket \text{prog} \rrbracket \notin \text{OPT} \cap \text{FLAR}$ .

# First characterizations of BFF

Characterizations without external lambda-closure:

Theorem [Hainry-Kapron-Marion-Péchoux [FoSSaCS22]]

$$\forall i \geq 0, \llbracket \text{SAFE}_i \cap \text{SN} \rrbracket = \text{BFF}$$

Surprisingly, the internal lambda-abstraction is not required for completeness.

→ Can we weaken the SN requirement?



## How to get rid of Strong Normalization?

We consider Size Change Termination (SCT).

### General idea

Program:

```
while (x > 0) {
    y = φ(x);
    x = x - 1;
}
```

$\Rightarrow$

Size change graph abstraction:

$$\left( \begin{array}{c} \text{x} \xrightarrow{-1} \text{x} \\ \text{y} \quad \text{y} \end{array} \right)^\omega$$

### Theorem [Lee, Jones, and Ben Amram [POPL2001]]

“If every infinite computation would give rise to an infinitely decreasing value sequence in the size-change graph, then no infinite computation is possible.”

→ SCT is not “tractable”: PSPACE-complete.

## Tractable characterizations of BFF

Completeness is preserved for SCT and for an instance SCP (Ben Amram-Lee [2007]).

### Theorem

$$\forall i \geq 0, \llbracket \text{SAFE}_i \cap \text{SCP}_S \rrbracket = \text{BFF}$$

$\text{SCP}_S$  can be decided in time quadratic in the program size.

### Theorem [Type inference]

- ▶  $\text{prog} \in \cup_i \text{SAFE}_i \cap \text{SCP}_S$  is Ptime-complete (using Mairson[2004]).
- ▶  $\text{prog} \in \text{SAFE}_0 \cap \text{SCP}_S$  is in time cubic in  $|\text{prog}|$  (using HKMP[2022]).

# Conclusion

## Conclusion

We have obtained **sound** and **complete** characterizations of type-2 polynomial time:

- ▶ **machine-independent** (a typed programming language with procedure calls)
- ▶ **implicit** (no prior knowledge on the bound is required),
- ▶ **tractable** (decidable type inference in polytime)  $\Rightarrow$  it can be automated.

## Open issues

- ▶ **expressive power** (capture more false negatives),
- ▶ **extension to Finite Length Revision** (harder, WIP using declassification).

# Thank you for your attention !



**I ❤️ MY  
BFF**