

Efficiently computing a pairing: Tricks old and new.

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Implementing Pairing-Based Cryptography

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- ▶ The typical structure of a pairing implementation is a Miller loop, followed by a final exponentiation. These can each in turn be subdivided into smaller steps.
- ▶ For example the final exponentiation can be divided into an “easy” part and a “hard” part.
- ▶ In this talk we will focus attention on the Miller loop, and assume either the Tate or Ate pairing.

The Miller Loop

Algorithm 1: Miller loop

Input: $Q \in \mathbb{G}_2$, $P \in \mathbb{G}_1$, curve parameter u

Output: $f \in \mathbb{F}_{p^k}$

```
1  $f \leftarrow 1$ 
2  $T \leftarrow Q$ 
3 for  $i \leftarrow \lfloor \log_2(u) \rfloor - 1$  to 0 do
4      $f \leftarrow f^2 \cdot l_{T,T}(P)$ ,  $T \leftarrow 2T$ 
5     if  $u_i = 1$  then
6          $f \leftarrow f \cdot l_{T,Q}(P)$ ,  $T \leftarrow T + Q$ 
7 return  $f$ 
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- ▶ The line functions are often sparse elements $\in \mathbb{F}_{p^k}$
- ▶ Important to observe that u is a fixed system parameter, and not a variable.
- ▶ As described we are assuming denominator elimination (DE) applies, Barreto et al. [2002],

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- ▶ However for the Ate pairing, rather counter-intuitively, the parameter u actually decreases with increased security.
- ▶ For example for the BLS12-381 $u = d201000000010000$, for the BLS48-581 curve $u = 140000381$.
- ▶ So the Miller loop gets shorter, and in most cases of interest loops less than about 64 times.

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- ▶ It also arises when the group order for the Tate pairing is required to be a composite.
- ▶ (I had rather hoped that David Freeman had saved us from that. Then along came the isogenists...)

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- ▶ In the case of the Tate pairing, u is the group order, so the final value of T will be the point at infinity.
- ▶ So we get a “free” check that Q is of the correct order!
- ▶ Less obviously the free group order check on Q also applies to the Ate pairing. See S. “A note on group membership tests for \mathbb{G}_1 , \mathbb{G}_2 and \mathbb{G}_T on BLS pairing-friendly curves”.

Let's split the Miller loop in two

Algorithm 2: Calculate and store line functions

Input: $Q \in \mathbb{G}_2$, $P \in \mathbb{G}_1$, curve parameter u

Output: An array g of $\lfloor \log_2(u) \rfloor$ line functions $\in \mathbb{F}_{p^k}$

```
1  $T \leftarrow Q$ 
2 for  $i \leftarrow \lfloor \log_2(u) \rfloor - 1$  to 0 do
3    $g[i] \leftarrow l_{T,T}(P)$ ,  $T \leftarrow 2T$ 
4   if  $u_i = 1$  then
5      $g[i] \leftarrow g[i].l_{T,Q}(P)$ ,  $T \leftarrow T + Q$ 
6 return  $g$ 
```

Algorithm 3: Intrinsic Miller loop

Input: An array g of $\lfloor \log_2(u) \rfloor$ line functions $\in \mathbb{F}_{p^k}$

Output: $f \in \mathbb{F}_{p^k}$

```
1  $f \leftarrow 1$ 
2 for  $i \leftarrow \lfloor \log_2(u) \rfloor - 1$  to 0 do
3    $f \leftarrow f^2 \cdot g[i]$ 
4 return  $f$ 
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- ▶ So algorithm 2 will be executed for each of the pairings in a multi-pairing. Since they all share the same u these executions all take place in “lock-step”.
- ▶ Algorithm 3 is only run once, independent of the number of pairings. Which also applies to the final exponentiation.

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- ▶ Looked at in this way, it can be seen that the cost of the Miller loop cannot be reduced below the requirement of algorithm 3.
- ▶ Algorithm 2 on the other hand is rich in optimization possibilities....

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- ▶ For example if it were a constant, its multiples can be precomputed and stored in affine coordinates
- ▶ And using affine coordinates results in increased sparsity of the line functions.
- ▶ So algorithm 2 can be carefully tuned to the particular context of each individual pairing in a multi-pairing.

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- ▶ But whereas the application to the multiplication of Q by u is standard, the impact on the line functions is not entirely obvious.
- ▶ The first implementation was I believe by myself, as mentioned in the pre-print S. [2005] "Scaling security in pairing-based protocols"

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- ▶ We can exploit the fact that negation of elliptic curve points cost nothing. Similarly inversion of line functions cost little, as inversion can be replaced by conjugation (DE).
- ▶ Hence a windowing strategy based on a NAF (Non-Adjacent Form) is appropriate. Since u is a public parameter constant-time considerations are not an issue, hence a sliding-windows algorithm can be used.

Line functions

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- ▶ For use in a double-and-add left-to-right context we will consider this identity in two particular cases

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- ▶ Observe that the “squaring” step is more expensive than the “multiply” step.
- ▶ Which is bad news, as windowing (which reduces the number of multiplies) works best when squaring is cheaper.

Working out the details

- ▶ Consider the case where two set bits of u are being processed... Instead of calculating

$$\begin{aligned}f_{2m} &= f_m^2 \cdot l_{mQ, mQ} \\f_{2m+1} &= f_{2m} \cdot l_{2mQ, Q} \\f_{4m+2} &= f_{2m+1}^2 \cdot l_{2mQ+Q, 2mQ+Q} \\f_{4m+3} &= f_{4m+2} \cdot l_{4mQ+2Q, Q}\end{aligned}\tag{1}$$

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- ▶ which will require the precomputation of $3Q$ and f_3

Getting ready for a NAF

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- ▶ Extending the idea, a sliding window of size w bits will require the precomputation of a table E of size M , containing the precomputed points $Q, 3Q, \dots, (2M-1)Q$ and a table F containing $f_1, f_3, \dots, f_{2M-1}$, where $F_0 = f_1 = 1$.

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- ▶ To facilitate the sliding window, assume a function `naf_window`, which given $s = 3u \oplus u$ (the bit-by-bit exclusive or) and a pointer i to the current bit position scans bits from left-to-right returning the tuple $\{n, b, z\}$ where n is the odd signed window value, b is the number of bits processed and z is the number of subsequent zero bits.

Windowed Miller Loop

Algorithm 4: Windowed Miller Loop for Tate pairing

Input: $P \in \mathbb{G}_1$, $Q \in \mathbb{G}_2$, curve parameter u

Output: $f \in \mathbb{F}_{p^k}$

```
1  $f \leftarrow 1$ 
2  $T \leftarrow P$ 
3  $s \leftarrow 3u \oplus u$ 
4  $i \leftarrow \lfloor \log_2(u) \rfloor$ 
5 while  $i > 0$  do
6      $n, b, z \leftarrow \text{naf\_window}(s, i)$ 
7     for  $j \leftarrow 0$  to  $b$  do
8          $f \leftarrow f^2.l_{T,T}$ ,  $T \leftarrow 2T$ 
9     if  $n > 0$  then
10         $f \leftarrow f.l_{T,E[n/2]} \cdot F[n/2]$ ,  $T \leftarrow T + E[n/2]$ 
11    if  $n < 0$  then
12         $f \leftarrow f.l_{T,-E[-n/2]} \cdot \overline{F[-n/2]}$ ,  $T \leftarrow T - E[-n/2]$ 
13    for  $j \leftarrow 0$  to  $z$  do
14         $f \leftarrow f^2.l_{T,T}$ ,  $T \leftarrow 2T$ 
15     $i \leftarrow i - b - z$ 
16 return  $f$ 
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Thoughts

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Bottom line

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- ▶ For the Tate pairing on a 160-bit MNT $k = 6$ curve we find that the the optimal window size is 3. The performance improvement to be expected is about 3%. For the Ate pairing over the same curve again the optimal window size is 3, but improvement is a nearly negligible 1%. Clearly the larger the exponent, the greater the gains to be expected from windowing.

Any Questions?

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- ▶ Thank you for your attention.