



Towards a better-behaved unification algorithm for Coq

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Unification in Coq

Unification is a **crucial** tool:

- ▶ Type-checking/refinement.

Definition $c : A := t \Rightarrow$ unify the inferred type T of t with A .

- ▶ Tactic applications.

On goal $\Gamma \vdash A$, apply (lemma : forall x .. xn, T) unifies $T[?x_1 \dots ?x_n]$ and A .

Currently two slightly different unification algorithms are used, one for each case.

- ▶ Not documented, not verified, but its results are directly seen by the users.
- ▶ Higher-order (pattern-unification + postponing + heuristics)
- ▶ Dependent on reductions: β , ι and δ
- ▶ Uses a backtracking first-order unification rule for fast success: $f\ u_1 \dots u_n \approx f\ v_1 \dots v_n \rightsquigarrow \overrightarrow{u_i \approx v_i}$
- ▶ Includes canonical structure resolution, an overloading mechanism relying on the precise behavior of the algorithm.
- ▶ “Untyped”: does not rely on the types of terms at hands, which might even not be directly convertible.
- ▶ Unsuitable for automation.

Document and verify a predictable, performant unification algorithm to be used both for type-checking and inside tactics.

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2 CoQ's theory

3 Three difficulties

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The term language of Coq

$$\begin{aligned} t, T \triangleq & \ x \mid c \mid s & x \in \mathcal{V}, c \in \mathcal{C}, s \in \mathcal{S} \\ & \mid i \mid k & i \in \mathcal{I}, k \in \mathcal{K} \\ & \mid \forall x : T. T \mid \lambda x : T. t \mid t \ t \\ & \mid \text{let } x = t : T \text{ in } t \mid ?u[\sigma] & ?u \in \mathcal{M} \\ & \mid \text{case}_T t \text{ of } k_1 \ \bar{x} \Rightarrow t; \dots; k_n \ \bar{x} \Rightarrow t \text{ end} \\ & \mid \text{fix}_j \ \{x/n : T := t; \dots; x/n : T := t\} \end{aligned}$$

$$\begin{aligned} \Gamma, \Psi \triangleq & \ \cdot \mid x : T, \Gamma \mid x := t : T, \Gamma \\ \Sigma \triangleq & \ \cdot \mid ?u : T[\Psi], \Sigma \mid ?u := t : T[\Psi], \Sigma \\ E \triangleq & \ \cdot \mid c : T, E \mid c := t : T, E \mid I, E \end{aligned}$$

Reduction

$$(\lambda x : T.t) \ t' \rightsquigarrow_{\beta} t\{t'/x\}$$

$$\text{let } x = t' : T \text{ in } t \rightsquigarrow_{\zeta} t\{t'/x\}$$

$$h \rightsquigarrow_{\delta} t \quad \text{if } (h := t : T) \in E \text{ or } (h := t : T) \in \Gamma$$

$$?u[\sigma] \rightsquigarrow_{\delta} t\{\sigma/\Psi\} \quad \text{if } (?u := t : T[\Psi]) \in \Sigma$$

$$\text{case}_T (k_j \ \bar{a}) \text{ of } \overline{k \ \bar{x} \Rightarrow t} \text{ end } \rightsquigarrow_{\iota} t_j\{\overline{a/x_j}\}$$

$$\text{fix}_j \{F\} \ \bar{a} \rightsquigarrow_{\iota} t_j\{\overline{\text{fix}_m \{F\}/x_m}\} \ \bar{a} \quad F = \overline{x/n : T := t}$$

Judgment: $\Sigma; \Gamma \vdash t_1 \approx t_2 \triangleright \Sigma'$

Example rule:

$$\frac{\Sigma; \Gamma \vdash \bar{t} \approx \bar{t}' \triangleright \Sigma'}{\Sigma; \Gamma \vdash ?u[\xi] \bar{t} \approx ?u[\xi] \bar{t}' \triangleright \Sigma'} \text{ META-SAME-SAME}$$

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Type dependency and postponement

An example with the existential quantifier:

```
Check (exist :  $\forall (A : \text{Type}) (P : A \rightarrow \text{Prop}) (x : A) (p : P x),$ 
       { $x : A \mid P x\} ).$ 
```

```
Definition f : { $x : \text{nat} \mid x \leq x\} :=$ 
  @exist _ _ 0 (le_n 0).
```

Uses *constraint postponement* to delay the instantiation of $?P$.

Solves $?P 0 = 0 \leq 0 \wedge ?P = \lambda x, x \leq x$.

This has unpredictable behavior:

- ▶ Non-local effect: hard to reason about, error locations hard to guess
- ▶ Source of exponential complexity in presence of backtracking.

We prefer a best-effort local type inference based on bidirectional type-checking, without postponement.

In this example, this would set $?P = \lambda x, x \leq x$ before typechecking the arguments.

$$\frac{\Sigma_0; \Gamma \vdash u \approx u' \triangleright \Sigma_1}{\Sigma_0; \Gamma \vdash t \ u \approx t \ u' \triangleright \Sigma_1} \text{ APP-FO}$$

- ▶ Applies even when t is an unfoldable constant (lose most general unifiers, but fast success in general).
- ▶ Requires backtracking when the argument unification fails \Rightarrow the reduced terms might be unifiable (slow failures if repeatedly applied).

Solutions:

- ▶ Parameterize by a set of constants on which the rule applies without backtracking, e.g. abbreviations only (Pfenning and Schürmann, TYPES'98). Does not play well with reduction.
- ▶ Experiment with caching mechanisms to be less penalized by failures.

Canonical Structure Resolution

Overloading mechanism based on records.

```
Structure monoid :=  
{ carrier : Set;  
  unit : carrier;  
  mult : carrier → carrier → carrier;  
  mult_unit_left : ∀ x, mult unit x = x  
}.
```

```
Canonical Structure nat_monoid :=  
{ carrier := nat;  
  unit := 0;  
  mult := plus;  
  mult_unit_left := fun x => eq_refl }.
```

Check (mult :

$\forall m : \text{monoid}, \text{carrier } m \rightarrow \text{carrier } m \rightarrow \text{carrier } m$).

Lemma on_nat_monoid ($n : \text{nat}$) : mult _ 0 $n = n$.

Proof.

change (mult nat_monoid 0 $n = n$).

apply mult_unit_left.

Qed.

The unification solved the problem carrier ? $m = \text{nat}$ by instantiating ? m with nat_monoid.

- ▶ Relies on unfolding behavior (step-by-step unfolding of constants)
- ▶ Hard to reason about if constraints can be postponed.

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A pencil and paper presentation (3 pages of rules plus pruning) and an implementation.

- ▶ No constraint postponement
- ▶ Clean definition of pruning and higher-order pattern unification.
- ▶ “Sound”
- ▶ **No** other heuristic than first-order unification.

Rules I/III

$$\frac{\Sigma; \Gamma \vdash \text{Prop} \approx \text{Prop} \triangleright \Sigma}{\Sigma; \Gamma \vdash \text{Prop} \approx \text{Prop} \triangleright \Sigma}$$

$$\frac{i = j}{\Sigma; \Gamma \vdash \text{Type}(i) \approx \text{Type}(j) \triangleright \Sigma}$$

$$\frac{i \leq j}{\Sigma; \Gamma \vdash \text{Type}(i) \lesssim \text{Type}(j) \triangleright \Sigma}$$

$$\frac{\Sigma; \Gamma \vdash A_1 \approx A_2 \triangleright \Sigma' \quad \Sigma'; \Gamma, x : A_1 \vdash t_1 \approx t_2 \triangleright \Sigma''}{\Sigma; \Gamma \vdash \lambda x : A_1. t_1 \approx \lambda x : A_2. t_2 \triangleright \Sigma''}$$

$$\frac{\Sigma; \Gamma \vdash A_1 \approx A_2 \triangleright \Sigma' \quad \Sigma'; \Gamma, x : A_1 \vdash B_1 \approx B_2 \triangleright \Sigma''}{\Sigma; \Gamma \vdash \forall x : A_1. B_1 \approx \forall x : A_2. B_2 \triangleright \Sigma''}$$

$$\frac{\Sigma; \Gamma \vdash t_2 \approx t'_2 \triangleright \Sigma' \quad \Sigma'; \Gamma, x := t_2 \vdash t_1 \approx t'_1 \triangleright \Sigma''}{\Sigma; \Gamma \vdash \text{let } x = t_2 : T \text{ in } t_1 \approx \text{let } x = t'_2 : T' \text{ in } t'_1 \triangleright \Sigma''}$$

$$\frac{\Sigma; \Gamma \vdash t_1 \{t_2/x\} \approx t'_1 \{t'_2/x\} \triangleright \Sigma'}{\Sigma; \Gamma \vdash \text{let } x = t_2 : T \text{ in } t_1 \approx \text{let } x = t'_2 : T' \text{ in } t'_1 \triangleright \Sigma'}$$

$$\frac{h \in \mathcal{V} \cup \mathcal{C} \cup \mathcal{I} \cup \mathcal{K}}{\Sigma; \Gamma \vdash h \approx h \triangleright \Sigma}$$

$$\frac{\Sigma_0; \Gamma \vdash T \approx T' \triangleright \Sigma_1 \quad \Sigma_1; \Gamma \vdash t \approx t' \triangleright \Sigma_2 \quad \Sigma_2; \Gamma \vdash \bar{b} \approx \bar{b}' \triangleright \Sigma_3}{\Sigma_0; \Gamma \vdash \text{case}_T t \text{ of } \bar{b} \text{ end} \approx \text{case}_{T'} t' \text{ of } \bar{b}' \text{ end} \triangleright \Sigma_3}$$

$$\frac{\Sigma_0; \Gamma \vdash \bar{T} \approx \bar{T}' \triangleright \Sigma_1 \quad \Sigma_1; \Gamma \vdash \bar{t} \approx \bar{t}' \triangleright \Sigma_2}{\Sigma_0; \Gamma \vdash \text{fix}_j \{x/n : T := t\} \approx \text{fix}_j \{x'/n' : T' := t'\} \triangleright \Sigma_2}$$

$$\frac{?u := t : A[\Gamma] \in \Sigma \quad \Sigma; \Gamma \vdash t' \approx t\{\sigma/\hat{\Gamma}\} \bar{t}_n \triangleright \Sigma'}{\Sigma; \Gamma \vdash t' \approx ?u[\sigma] \bar{t}_n \triangleright \Sigma'}$$

$$\frac{\Sigma; \Gamma \vdash t' \approx t\{t_1/x\} t_2 \dots t_n \triangleright \Sigma'}{\Sigma; \Gamma \vdash t' \approx (\lambda x : A. t) t_1 \dots t_n \triangleright \Sigma'}$$

$$\frac{\Sigma; \Gamma \vdash t' \approx t_1 \{t_2/x\} \bar{t}_n \triangleright \Sigma'}{\Sigma; \Gamma \vdash t' \approx (\text{let } x = t_2 : T \text{ in } t_1) \bar{t}_n \triangleright \Sigma'}$$

$$\frac{(x := t : A) \in \Gamma \quad \Sigma; \Gamma \vdash t' \approx t \bar{t}_n \triangleright \Sigma'}{\Sigma; \Gamma \vdash t' \approx x \bar{t}_n \triangleright \Sigma'}$$

$$\frac{\Sigma; \Gamma \vdash t' \downarrow_{\beta_1\theta}^w t'' \quad t' \neq t'' \quad \Sigma; \Gamma \vdash t \approx t'' \triangleright \Sigma'}{\Sigma; \Gamma \vdash t \approx t' \triangleright \Sigma'}$$

$$\frac{(c := t : A) \in E \quad \text{not } \Sigma; \Gamma \vdash \text{is_stuck } (c \bar{t}_n) \quad \Sigma; \Gamma \vdash t' \approx t \bar{t}_n \triangleright \Sigma'}{\Sigma; \Gamma \vdash t' \approx c \bar{t}_n \triangleright \Sigma'}$$

$$\frac{(c := t : A) \in E \quad \Sigma; \Gamma \vdash \text{is_stuck } t' \quad \Sigma; \Gamma \vdash t \bar{t}_n \approx t' \triangleright \Sigma'}{\Sigma; \Gamma \vdash c \bar{t}_n \approx t' \triangleright \Sigma'}$$

$$\frac{(c := t : A) \in E \quad \Sigma; \Gamma \vdash t' \approx t \bar{t}_n \triangleright \Sigma'}{\Sigma; \Gamma \vdash t' \approx c \bar{t}_n \triangleright \Sigma'}$$

$$\frac{\Sigma_0; \Gamma \vdash t : T}{\Sigma_0, ?v : \text{Type}(i)[\Gamma, y : A]; \Gamma \vdash T \approx \forall y : A. ?v[\text{id}_{\Gamma, y}] \triangleright \Sigma_1}$$

$$\frac{\Sigma_1; \Gamma, x : A \vdash (t x) \approx t_1 \triangleright \Sigma_2}{\Sigma_0; \Gamma \vdash t \approx \lambda x : A. t_1 \triangleright \Sigma_2}$$

Rules II/III

$$\frac{\Sigma; \Gamma \vdash \bar{t} \approx \bar{t}' \triangleright \Sigma'}{\Sigma; \Gamma \vdash ?u[\sigma] \bar{t} \approx ?u[\sigma] \bar{t}' \triangleright \Sigma'}$$

$$\frac{\text{FV}(T) \subseteq \Psi_2 \quad ?u : T[\Psi_1] \in \Sigma \quad \Psi_1 \vdash \sigma \cap \sigma' \triangleright \Psi_2 \quad \Sigma \vdash \Psi_2}{\Sigma; \Gamma \vdash ?u[\sigma] \bar{t} \approx ?u[\sigma'] \bar{t}' \triangleright \Sigma'}$$

$$\frac{\begin{array}{c} ?u : T[\Psi] \in \Sigma_0 \\ \xi_1, \xi_2, \bar{t}'' = \max_{|\xi_2|} (\xi_1, \xi_2, \bar{t}'' \mid t' = h \bar{t}'' \wedge \xi_2 \wedge \xi' = \xi_1 \wedge \xi_2 \wedge \nexists x \in \xi_2. x \in h \bar{t}'' \wedge \xi_1) \\ \Sigma_0 \vdash \text{prune}(\xi, \xi_2; t) \triangleright \Sigma_1 \\ t' = \lambda x : A\{\xi, \xi_1 / \hat{\Psi}, \bar{x}\}^{-1}.t\{\xi, \xi_1 / \hat{\Psi}, \bar{x}\}^{-1} \\ \Sigma_1; \Psi \vdash t' : T' \quad \Sigma_1; \Psi \vdash T' \lesssim T \triangleright \Sigma_2 \quad ?u \not\in t' \\ \Sigma_0; \Gamma \vdash t \approx ?u[\xi] \xi' \triangleright \Sigma_2 \cup \{?u := t'\} \end{array}}{\Sigma_0; \Gamma \vdash t \approx ?u[\xi] \xi' \triangleright \Sigma_2 \cup \{?u := t'\}}$$

$$\frac{\Sigma_0; \Gamma \vdash t_1 \approx t_2 \triangleright \Sigma_1 \quad \Sigma_1; \Gamma \vdash t' \bar{t}_m' \approx ?u[\sigma] \bar{t}_n \triangleright \Sigma_2}{\Sigma_0; \Gamma \vdash t' \bar{t}_m' t_1 \approx ?u[\sigma] \bar{t}_n t_2 \triangleright \Sigma_2}$$

$$\frac{\begin{array}{c} ?u : T[\Psi] \in \Sigma_0 \\ t \rightsquigarrow_\delta \downarrow_{\beta t \theta}^w t' \\ \Sigma_0; \Gamma \vdash t' \approx ?u[\sigma] \bar{t}_n \triangleright \Sigma_1 \end{array}}{\Sigma_0; \Gamma \vdash t \approx ?u[\sigma] \bar{t}_n \triangleright \Sigma_1}$$

$$\frac{\begin{array}{c} (\mathbf{p}_j, h, \mathbf{v}) \in \Delta_{\text{db}} \\ \mathbf{v} := \lambda \overline{x : B}. k \overline{a'} \overline{v} \quad v_j = h \overline{u'} \\ \Sigma_1; \Gamma \vdash \overline{a} \approx \overline{a'} \{ \overline{?y}/\overline{x} \} \triangleright \Sigma_2 \quad \Sigma_2; \Gamma \vdash \overline{u} \approx \overline{u'} \{ \overline{?y}/\overline{x} \} \triangleright \Sigma_3 \\ \Sigma_3; \Gamma \vdash c \approx \mathbf{v} \overline{?y} \triangleright \Sigma_4 \quad \Sigma_4; \Gamma \vdash \overline{t} \approx \overline{t'} \triangleright \Sigma_5 \end{array}}{\Sigma_0; \Gamma \vdash p_j \overline{a} c \overline{t} \approx h \overline{u} \overline{t'} \triangleright \Sigma_5}$$

Problem: $?t + ?u \approx [1; 2] + [3; 4]$.

- ▶ In general, many solutions, no m.g.u.
- ▶ Here we allow first-order unification, so $?t := [1; 2]$, $?u := [3; 4]$ is found.
- ▶ A most natural unifier notion?

- ▶ “Easy” debugging
- ▶ Not fast (yet).
- ▶ No control on reduction/expansion (yet).

Tested on SSREFLECT library (one of the largest in Coq, supporting the 4 color theorem and Feit-Thompson):

- ▶ 40/62 files compile (time blowup after that)
- ▶ 60kLoC, 10M unification problems.
- ▶ < 600 problems solvable by the legacy algorithm only.
- ▶ Bidirectional typechecking would reduce this.

- ▶ Higher-Order Dynamic Pattern Unification (Abel & Pientka): uses postponement.
- ▶ Same for J. Reed, U. Norrel's unifier for Agda and C.S.Coen's unifier for CIC.

Conclusion and Future Work

- ▶ A simpler, documented and predictable unification algorithm for Coq.
- ▶ A prototype implementation.

What's left:

- ▶ Parameterization.
- ▶ Proofs (on paper and in Coq).
- ▶ Debug & integrate the algorithm.

That's all folks!