On Anti-unification in Absorption Theories

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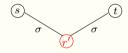


Outline

- 1. Motivation
- 2. Absorption Theory
- 3. Anti-Unification Algorithm for absorption theory
- 4. Conclusions and Future work

Unification

Goal: find a substitution that identifies two expressions (terms).



where $t\sigma \approx r' \approx s\sigma$.

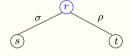
Example 1

Identify the terms h(g(a), y) and h(g(z), f(w)). Using the substitution $\sigma = \{y \mapsto f(w), z \mapsto a\}$ the expressions unify to h(g(a), b).

Anti-unification

Goal: find the commonalities between two expressions (terms).

An expression with such commonalities is called a generalization.



where $r\sigma \approx s$ and $r\rho \approx t$.

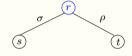
Example 2

Generalize the terms h(g(a), y) and h(g(z), f(w)).

Anti-unification

Goal: find the commonalities between two expressions (terms).

An expression with such commonalities is called a generalization.



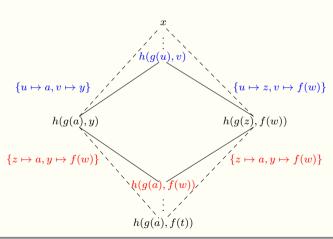
where $r\sigma \approx s$ and $r\rho \approx t$.

Example 2

Generalize the terms h(g(a), y) and h(g(z), f(w)). generalization: h(g(u), v), with substitutions $\sigma = \{u \mapsto a, v \mapsto u\}$ and

$$\rho = \{u \mapsto z, v \mapsto f(w)\}.$$

Unification and Anti-unification



One interesting example of verbatim plagiarism:

- (Original sentence). All around the world, technology is continuing to become a part of everyday life, and its capabilities are progressing rapidly.
- (Possibly sentence with plagiarism). All over the world, technology became a part of our lives, and its capabilities are progressing very quickly.

Then finding the common parts and the differences in the sentences:

- All around the world, technology is continuing to become a part of everyday life, and its capabilities are progressing rapidly.
- All over the world, technology became a part of our lives, and its capabilities are progressing very quickly.

All \square the world, technology \square a part of \square , and its capabilities are progressing \square .

Applications of anti-unification include:

- searching parallel recursion schemes to transform sequential algorithms into parallel algorithms (Barwell et al. [BBH18]);
- preventing bugs and misconfigurations in software (Mehta et al. [MBK⁺20]);
- finding duplicate code and similarities;
- detecting code clones (i.e., plagiarism).

Absorption Theory

Absorption Theory

- ullet The alphabet consists of a countable set of variables ${\mathcal V}$ and set ${\mathcal F}$ of function and with a special constant symbol \star (The wild card).
- Terms over this alphabet, $\mathcal{T}(\mathcal{F}, \mathcal{V})(\mathcal{T})$ and $\mathcal{T}(\mathcal{F} \cup \{\star\}, \mathcal{V})(\mathcal{T}_{\star})$, defined as usually:

$$t := x \mid f(t_1, \dots, t_n)$$

- A finite set E that consists of equations $s \approx t$.
- A preorder \prec_E , which states that $s \prec_E t$ if there exists a substitution σ such that $s\sigma \approx_E t$.

Absorption Theory

Type of anti-unification problems

The type of an anti-unification modulo ${\cal E}$ problem is classified as below.

- Nullary(0): if there are terms s and t such that $mcsg_E(s,t)$ does not exist. Also, called $type\ zero$.
- Unitary(1): if for all s and t, $mcsg_E(s,t)$ has just one generalization.
- Finitary(ω): if for all s and t, $mcsg_E(s,t)$ has more than one generalization.
- Infinitary(∞): there are terms s and t such that $mcsg_E(s,t)$ is infinite.

Type of some Theories

Absorption Theory ○○●○○○○○

Type	Authors and References	Procedure or Term
1	G. Plotkin and [Plo70, Rey70]	Dec, Sol, Rec
	J. Reynolds	
ω	M. Alpuente et al. [AEEM14]	A-left, A-right
ω	M. Alpuente et al. [AEEM14]	С
ω	D. Cerna [CK20a]	Start-C, Sat-C, M
∞	D. Cerna and T. Kutsia [CK20a]	M, Id-left,Id-right
		ld-both (1,2,3)
0	D. Cerna and T. Kutsia [CK20b]	$e_f \triangleq e_g$
	f(g(x,y),x)	
	1 ω ω ω ω	1 G. Plotkin and [Plo70, Rey70] J. Reynolds ω M. Alpuente et al. [AEEM14] ω M. Alpuente et al. [AEEM14] ω D. Cerna [CK20a] ∞ D. Cerna and T. Kutsia [CK20a]

Absorption Theory ○○○●○○○○

Theory	Type	Authors and References	Procedure or Term
AC, ACU	ω	M. Alpuente et al. [AEEM14]	AC-left, AC-right
AU_2 , CU_2 , ACU_2	0	D. Cerna and T. Kutsia [CK20b]	$e_f \triangleq e_g$
			f(g(x,y),x)
$(UI)_2$, $(ACUI)_2$	0	D. Cerna and T. Kutsia [CK20b]	$e_f \triangleq e_g$
			$f(g(f(x,y),e_f),x)$
Semirings (S), SC	0	D. Cerna [Cer20]	$e_f \triangleq e_g$
			$\prod_{i=1}^{n} m_i$
			$\prod_{i=1}^{n} x$

Type of some Theories

Theory	Type	Authors and References	Procedure or Term
$Absorption_{\geq 1} \; (\mathtt{Abs})$?	_	_
$(ACU)_2$, $(ACU)_2Abs$	0	D. Cerna [Cer20]	$e_f \triangleq e_g$
			$\prod_{i=1}^{n} x$
Simply-typed λ -calculus	0	D. Cerna and	$\lambda xy.f(x) \triangleq \lambda xy.f(y)$
		M. Buran[BC22]	
$IAbs_1(UI)_2Abs$	\emptyset,∞ ?	_	_

Absorption Theory

- An anti-unification equation (AUE) between s and t in a normal form is denoted by $s \stackrel{x}{\triangleq}_E t$, where x is called as label.
- A valid set of AUEs is a set of AUEs where all the labels are different.
- An AUE $s \stackrel{\sim}{=} t$ is *solved* if head(s) and head(t) are not related absorption symbols, where $s,t \in \mathcal{T}$.
- An AUE $s \stackrel{\mbox{\tiny \'e}}{=} t$ is *wild* if one of the terms is the wild card and the other belongs to $\mathcal{T}.$

Absorption Theory

Absorption Theory

Absorption is an important algebraic attribute in some magmas: for some function symbol f there is a constant ε_f such that

$$f(x, \varepsilon_f) \approx \varepsilon_f$$
, or/and $f(\varepsilon_f, x) \approx \varepsilon_f$

Equational theories with these equations are called an absorption theories (Abs).

Example 3

Let's find one generalization of the AUE $\varepsilon_f \triangleq_{\mathtt{Abs}} f(f(a,b),c)$.

The idea of the algorithm is to expand the ε_f to get the generalization:

$$\begin{array}{cccc}
\varepsilon_f & \stackrel{x}{\triangleq} f(f(a,b),c) & x \\
f(\varepsilon_f,c) & \stackrel{x}{\triangleq} f(f(a,b),c) & x \\
\varepsilon_f & \stackrel{x}{\triangleq} f(a,b),c & \stackrel{z}{\triangleq} c \\
f(\varepsilon_f,b) & \stackrel{x}{\triangleq} f(a,b) & f(y,z) \\
\varepsilon_f & \stackrel{u}{\triangleq} a,b & \stackrel{v}{\triangleq} b \\
\varepsilon_f & \stackrel{u}{\triangleq} a & f(f(u,v),c) \\
\varepsilon_f & \stackrel{u}{\triangleq} a & f(f(u,b),c)
\end{array}$$

Algorithm for absorption theory

To build the algorithm we consider a quadruple $\langle A;S;T;\theta\rangle$ as a *configuration* in each step of the procedure, where:

- A is the valid set of unsolved AUEs;
- S is the *store*, the valid set of *solved* AUEs;
- T is the abstraction, the valid set of wild AUEs;
- \bullet θ is a *substitution* mapping the labels of the AUEs to the term of the generalization given by the rules.

Inference Rules

Then we define the next rules

(Dec): **Decompose**

$$\langle \{f(s_1, \dots, s_n) \stackrel{x}{\triangleq} f(t_1, \dots, t_n)\} \sqcup A; S; \theta \rangle$$

$$\stackrel{Dec}{\Longrightarrow} \langle \{s_1 \stackrel{y_1}{\triangleq} t_1, \dots, s_n \stackrel{y_n}{\triangleq} t_n\} \cup A; S; \theta \{x \mapsto f(y_1, \dots, y_n)\} \rangle$$

For f any function symbol, n > 0, and y_1, \ldots, y_n are fresh variables.

Inference Rules

(Solve): **Solve**

$$\langle \{s \overset{x}{\triangleq} t\} \sqcup A; S; T; \theta \rangle \overset{Sol}{\Longrightarrow} \langle A; \{s \overset{x}{\triangleq} t\} \cup S; T; \theta \rangle$$

Where $head(s) \neq head(t)$ are not related absorption symbols.

(Mer): Merge

$$\langle \emptyset; \{s \overset{x}{\triangleq} t\} \cup \{s \overset{y}{\triangleq} t\} \cup S; \theta \rangle \overset{Mer}{\Longrightarrow} \langle \emptyset; \{s \overset{y}{\triangleq} t\} \cup S; \theta \{x \mapsto y\} \rangle$$

Inference Rules

(ExpLA1): Expansion for Absorption, Left 1

$$\langle \{ \varepsilon_f \stackrel{x}{\triangleq} f(t_1, t_2) \} \sqcup A; S; T; \theta \rangle$$

$$\stackrel{\text{ExpLA1}}{\Longrightarrow} \langle \{ \varepsilon_f \stackrel{y_1}{\triangleq} t_1 \} \cup A; S; \{ \star \stackrel{y_2}{\triangleq} t_2 \} \cup T; \theta \{ x \mapsto f(y_1, y_2) \} \rangle$$

(ExpLA2): Expansion for Absorption, Left 2

$$\begin{split} & \langle \{\varepsilon_f \overset{x}{\triangleq} f(t_1, t_2)\} \sqcup A; S; T; \theta \rangle \\ & \xrightarrow{\text{ExpLA2}} & \langle \{\varepsilon_f \overset{y_2}{\triangleq} t_2\} \cup A; S; \{\star \overset{y_1}{\triangleq} t_1\} \cup T; \theta \{x \mapsto f(y_1, y_2)\} \rangle \end{split}$$

Inference Rules

(ExpRA1): Expansion for Absorption, Right 1

$$\langle \{f(s_1, s_2) \overset{x}{\triangleq} \varepsilon_f\} \sqcup A; S; T; \theta \rangle$$

$$\overset{\text{ExpRA1}}{\Longrightarrow} \langle \{s_1 \overset{y_1}{\triangleq} \varepsilon_f\} \cup A; S; \{s_2 \overset{y_2}{\triangleq} \star\} \cup T; \theta \{x \mapsto f(y_1, y_2)\} \rangle$$

(ExpRA2): Expansion for Absorption, Right 2

$$\begin{split} & \langle \{f(s_1,s_2) \overset{x}{\triangleq} \varepsilon_f\} \sqcup A; S; T; \theta \rangle \\ & \overset{y_2}{\Longrightarrow} \langle \{s_2 \overset{\Delta}{\triangleq} \varepsilon_f\} \cup A; S; \{s_1 \overset{y_1}{\triangleq} \star\} \cup T; \theta \{x \mapsto f(y_1,y_2)\} \rangle \end{split}$$

Algorithm Ant_Unif

The algorithm ANT_UNIF is an exhaustive application of the inference rules to transform an initial configuration $\langle A; \emptyset; \emptyset; \iota \rangle$ into a set of final configurations with an empty set of unsolved AUEs of the form $\langle \emptyset, S, T, \theta \rangle$ and there are no different AUEs with the same terms s,t and with a different label.

Example 4

Apply Ant_Unif to the anti-unification problem $g(\varepsilon_f, a) \triangleq g(f(h(\varepsilon_f), a), \varepsilon_f)$.

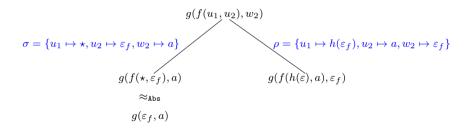
$$\langle \{g(\varepsilon_f, a) \stackrel{\triangle}{\triangleq} g(f(h(\varepsilon_f), a), \varepsilon_f)\}; \emptyset; \emptyset; \iota \rangle \stackrel{Dec}{\Longrightarrow}$$

$$\langle \{\varepsilon_f \stackrel{\omega_1}{\triangleq} f(h(\varepsilon_f), a), a \stackrel{\omega_2}{\triangleq} \varepsilon_f\}; \emptyset; \emptyset; \{x \mapsto g(w_1, w_2)\} \rangle \stackrel{ExplA2}{\Longrightarrow}$$

$$\langle \{\varepsilon_f \stackrel{\Delta}{\triangleq} a, a \stackrel{\Delta}{\triangleq} \varepsilon_f\}; \emptyset; \{\star \stackrel{\Delta}{\triangleq} h(\varepsilon_f)\}; \{x \mapsto g(f(u_1, u_2), w_2)\} \rangle \stackrel{Sol}{\Longrightarrow}$$

$$\langle \{\varepsilon_f \stackrel{\Delta}{\triangleq} a\}; \{a \stackrel{\omega_2}{\triangleq} \varepsilon_f\}; \{\star \stackrel{\Delta}{\triangleq} h(\varepsilon_f)\}; \{x \mapsto g(f(u_1, u_2), w_2)\} \rangle \stackrel{Sol}{\Longrightarrow}$$

$$\langle \emptyset; \{\varepsilon_f \stackrel{\Delta}{\triangleq} a, a \stackrel{\omega_2}{\triangleq} \varepsilon_f\}; \{\star \stackrel{\Delta}{\triangleq} h(\varepsilon_f)\}; \{x \mapsto g(f(u_1, u_2), w_2)\} \rangle$$



Then, $g(f(u_1, u_2), w_2)$ is a generalization with the substitutions σ and ρ .

Abstraction Set

Abstraction Set

Let t be a term in Abs-normal form, and σ be a substitution with images in Abs-normal form. The abstraction of t with respect to σ is the set:

$$\uparrow(t,\sigma):=\{r\mid r\sigma\approx_{\text{\tiny Abs}}t,\, r\text{ is an Abs-normal form, and } \textit{Var}(r)\subseteq\textit{Dom}(\sigma)\}$$

Example 5

Find the abstraction set of $h(\varepsilon_f)$ with respect to $\rho = \{u_2 \mapsto a, w_2 \mapsto \varepsilon_f\}$:

$$\uparrow (h(\varepsilon_f), \rho) = \{h(\varepsilon_f), h(w_2), h(f(w_2, \star)), h(f(\star, w_2)), h(f(u_2, w_2)), \dots \}$$

Where \star could be replaced by a term whose variables are included in $Dom(\rho)$. For example, $h(f(w_2,a))$ and $h(f(w_2,h(g(u_2,w_2))))$ belong to the abstraction set.

Continue with Example 4:

$$(\varepsilon_f, a) \triangleq g(f(h(\varepsilon_f), a), \varepsilon_f)$$

The final branch:

$$\langle \emptyset; \{ \varepsilon_f \stackrel{u_2}{\triangleq} a, a \stackrel{w_2}{\triangleq} \varepsilon_f \}; \{ \star \stackrel{u_1}{\triangleq} h(\varepsilon_f) \}; \{ x \mapsto g(f(u_1, u_2), w_2) \} \rangle$$

To find a less general generalization, it is possible to replace the variable u_1 in the generalization $g(f(u_1, u_2), w_2)$ for one of the elements of the abstraction set $\uparrow (h(\varepsilon_f), \rho)$.

Then, the term $g(f(h(f(w_2, a)), u_2), w_2)$ is a generalization too.

$$g(f(h(f(w_2,a)),u_2),w_2)$$

$$\sigma = \{u_2 \mapsto \varepsilon_f, w_2 \mapsto a\}$$

$$\rho = \{u_2 \mapsto a, w_2 \mapsto \varepsilon_f\}$$

$$g(f(h(f(a,a)),\varepsilon_f),a)$$

$$g(f(h(f(\varepsilon_f,a)),a),\varepsilon_f)$$

$$\approx_{\mathsf{Abs}}$$

$$g(\varepsilon_f,a)$$

$$g(f(h(\varepsilon_f),a),\varepsilon_f)$$

Algorithm for ANT_UNIF

Termination

The procedure Ant_Unif is terminating. Particularly, for any configuration $\langle A; S; T; \theta \rangle$, it outputs a finite set of configurations of the form $\langle \emptyset; S'; T'; \theta' \rangle$.

Algorithm for ANT_UNIF

Soundness

If $\langle A_0; S_0; T_0; \theta_0 \rangle \Longrightarrow^* \langle \emptyset; S_n; T_n; \theta_n \rangle$ is a derivation to a final configuration, then for each $s \triangleq t \in A_0 \cup S_0 \cup T_0$:

- $x\theta_n$ is a generalization of s and t, and $x\theta_n\sigma_{\mathcal{D}}\approx_{\mathsf{Abs}} s$ and
- $x\theta_n\rho_{\mathcal{D}} \approx_{\mathsf{Abs}} t$.

Conclusions and Future work

- We design an algorithm for anti-unification in absorption theories. The algorithm is terminating and sound.
- We conjecture that the algorithm is complete.
 The complete set of least general generalizers can be built from the computed substitutions, the store, and the abstraction set.

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