

Safe Navigation in Urban Environments

Esther Galbrun, Konstantinos Pelechrinis and Evimaria Terzi



Example

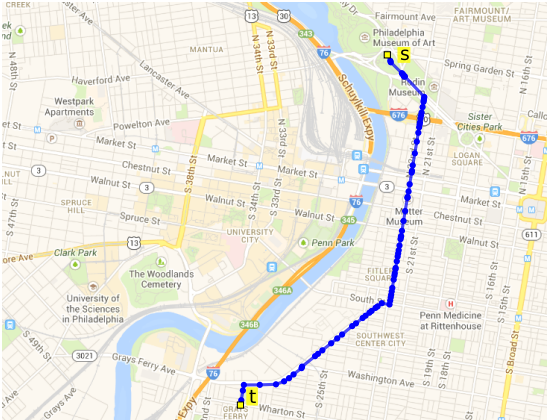
After a visit to the
Philadelphia Museum of Art



Rocky wants to walk home,
on Warthon street.

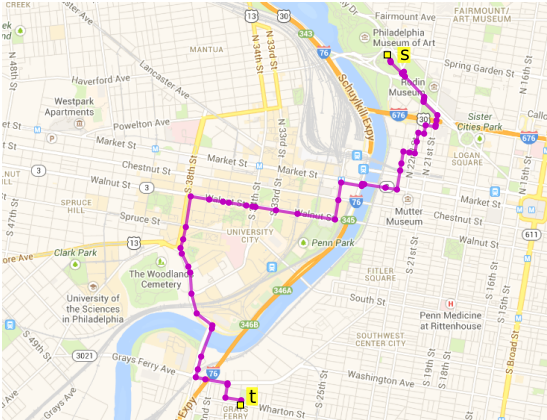
Example

the shortest path



Example

the safest path



Example

trade-offs

Path	Length ℓ (m)	Risk r (10^{-3})
1	3955	2.32
2	4027	2.02
3	4060	2.01
4	4922	1.71
5	5988	1.70



Road network

Exported from OpenStreetMap

Nodes Intersections

Edges Street segments

Weight $\ell(e)$ Physical length

Risk model

Built from publicly available civic datasets

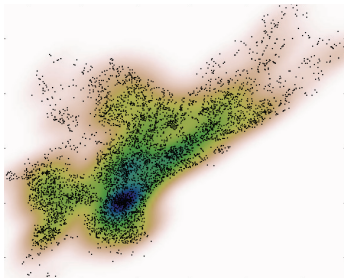
```
DISPATCH_DATE_TIME,TEXT_GENERAL_CODE,POINT_X,POINT_Y
2010-05-05 11:34:00,Robbery No Firearm,-75.17699712,40.0528852
2010-03-31 12:47:00,Thefts,-75.22697891,39.99847574
2007-08-13 07:40:00,Theft from Vehicle,-75.24469105,39.96263542
...
```



Risk model

Built from publicly available civic datasets

1. Obtain a spatial density with Kernel Density Estimation



Risk model

Built from publicly available civic datasets

1. Obtain a spatial density with Kernel Density Estimation
2. Evaluate along street segments and normalize

Weight $r(e)$ relative crime probability

Definitions

Given a graph $G = (V, E)$, a path P from s to t .

Length of P $\ell(P) = \sum_{e \in P} \ell(e)$

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Risk of P $r_t(P) = 1 - \prod_{e \in P} (1 - r(e))$, or *(total risk)*

$r_m(P) = \max_{e \in P} r(e)$. *(max risk)*

Definitions

P dominates P' if

$\ell(P) \leq \ell(P')$ and $r(P) < r(P')$, or
 $\ell(P) < \ell(P')$ and $r(P) \leq r(P')$.

Problem (SafePaths)

*If \mathcal{P} is the set of all possible paths from s to t , our goal is to select a **small** subset of these paths $\mathcal{S} \subseteq \mathcal{P}$ such that for every path $P \in \mathcal{S}$, P is neither dominated by nor equivalent to any other path $P' \in \mathcal{S}$.*

Total-Paths

Solving SafePaths with length and total risk:

$$\ell(P) = \sum_{e \in P} \ell(e)$$

$$r_t(P) = 1 - \prod_{e \in P} (1 - r(e))$$

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sum-sum biobjective minimization problem

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sum-sum biobjective minimization problem

■ Sum-Recursive

Max-Paths

Solving SafePaths with length and max risk:

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■ Max-Exhaustive

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sum-max biobjective minimization problem

- Max-Exhaustive
- Max-Recursive

Speed-ups

- Approximation via early stopping

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- Ellipse pruning

Speed-ups

- Approximation via early stopping (*subset of paths*)
- Ellipse pruning (*same set of paths*)

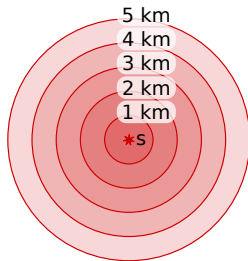
- Sample (s, t) pairs

Setting

- Sample (s, t) pairs
- Focus on short distances

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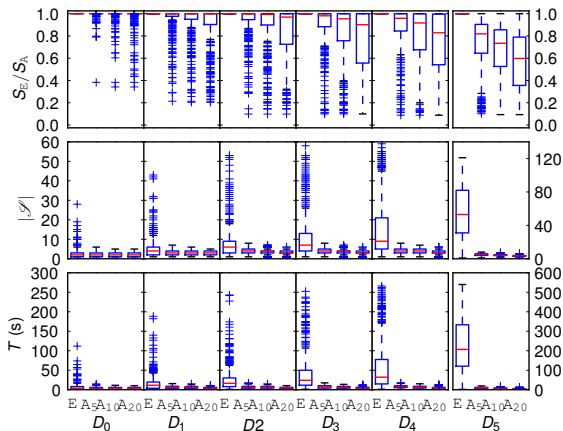
Setting

- Sample (s, t) pairs
- Focus on short distances
- Run algorithms with/without approximation and pruning

Setting

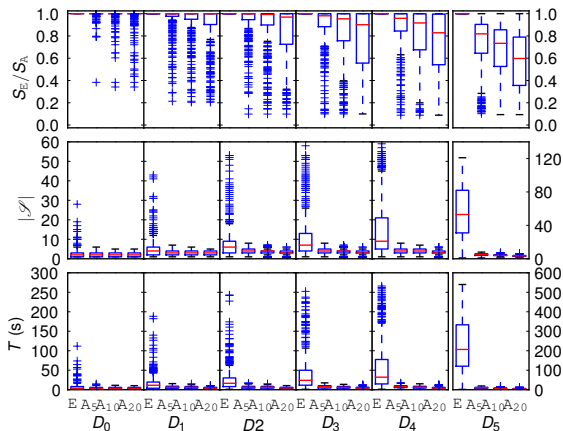
- Sample (s, t) pairs
- Focus on short distances
- Run algorithms with/without approximation and pruning
- Compare solution quality and speed

Results



■ Fairly accurate approximations

Results



- Fairly accurate approximations
- Significant speed-ups

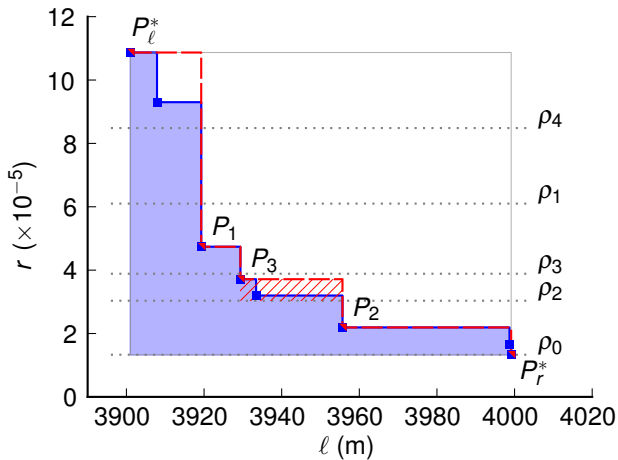
Conclusions

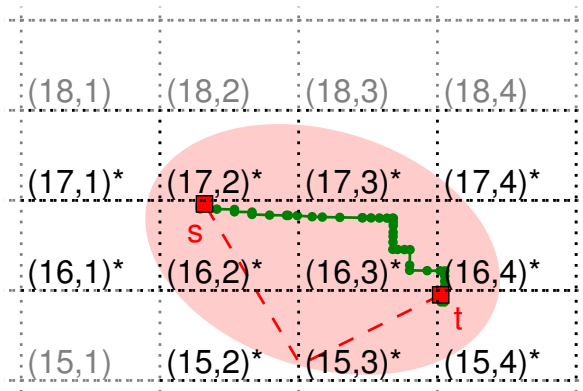
- Built a risk model from civic datasets
- Formalized a problem of safe urban navigation
Two variants: total-risk and max-risk
- Proposed practical algorithmic solutions

Conclusions

- Built a risk model from civic datasets
- Formalized a problem of safe urban navigation
Two variants: total-risk and max-risk
- Proposed practical algorithmic solutions

Thanks!





```
Sum-Recursive( $G, l(), r()$ )  
1:  $P_l^* \leftarrow \text{Dijkstra}(G, l())$   
2:  $P_r^* \leftarrow \text{Dijkstra}(G, r())$   
3:  $\mathcal{S} \leftarrow \{P_l^*, P_r^*\}$   
4:  $\text{sum-rec}(P_l^*, P_r^*, \mathcal{S})$   
5: return  $\mathcal{S}$ 
```

Routine sum-rec(P_u, P_l, \mathcal{S})

- 1: $\lambda \leftarrow (r(P_u) - r(P_l)) / (\ell(P_u) - \ell(P_l))$
- 2: $\forall e \in E : f(e) = r(e) - \lambda \ell(e)$
- 3: $P_i \leftarrow \text{Dijkstra}(G, f())$
- 4: **if** $P_i \neq P_u$ and $P_i \neq P_l$ **then**
- 5: $\mathcal{S} \leftarrow \mathcal{S} \cup \{P_i\}$
- 6: sum-rec(P_u, P_i, \mathcal{S})
- 7: sum-rec(P_i, P_l, \mathcal{S})

Routine $\text{max-rec}(P_u, P_l, \mathcal{S})$

- 1: $\rho \leftarrow (r(P_u) + t(P_l))/2$
- 2: **if** $\exists e \in E, t(P_l) < r(e) < \rho$ **then**
- 3: $P_i \leftarrow \text{Dijkstra}(G_{r(e) < \rho}, \ell())$
- 4: **if** $P_i \neq P_l$ **then**
- 5: $\mathcal{S} \leftarrow \mathcal{S} \cup \{P_i\}$
- 6: $\text{max-rec}(P_i, P_l, \mathcal{S})$
- 7: $\text{max-rec}(P_u, P_i, \mathcal{S})$

	Total-Paths		Max-Paths	
	Chicago	Philadelphia	Chicago	Philadelphia
Total	2400	2400	2400	2400
$ \mathcal{S} = 1$	111	407	263	562
$ \mathcal{S} = 2$	182	148	317	253
Ident. A_5	520	476	398	424
Ident. A_{10}	420	407	340	351
Ident. A_{20}	337	327	14	49