PROPs and Symbolic dynamics

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Plan

Relation on integral nonnegative matrices:

Definition

M is *Strong Shift Equivalent* to *N*, if $M \sim N$ where \sim is the smallest equivalence relation s.t. $RS \sim SR$ for all nonsquare integral nonnegative matrices *R*, *S*

Main open problem of symbolic dynamics: If SSE decidable ?

To partially solve this problem, one uses invariants:

Definition

An invariant is a quantity $\phi(M)$, easy to compute s.t. If $M \sim N$ then $\phi(M) = \phi(N)$.

This talk: how to get invariants for free.

- I will cheat and obtain invariants for a related notion, called flow equivalence, that I won't define.
- SSE just needs ten more minutes.

Plan

Definition

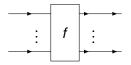
PROPs are symmetric monoidal categories generated by a single object

Wait, what ?

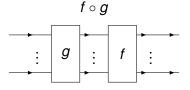
PROPs come from category theory, and correspond to structures with two composition rules: a sequential and a parallel composition rule.

No need to know category theory, but universal algebra might help.

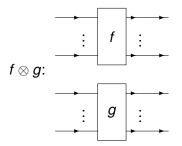
In a prop, we have functions that have *m* inputs and *n* outputs. We write $f : m \rightarrow n$.



We can compose sequentially $g : a \rightarrow b$ and $f : b \rightarrow c$ if $\#outputs_g = \#inputs_f$.



We can compose "in parallel" $g : a \rightarrow b$ and $f : c \rightarrow d$.



We have access to the identity function : $id : 1 \rightarrow 1$:

And to a swap function: $\sigma : 2 \rightarrow 2$.

id :

 σ

Example

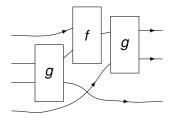
If we have access to $f : 2 \rightarrow 1$ and $g : 2 \rightarrow 2$, we can e.g. write:

$$({m g}\otimes {\it id})\circ ({\it f}\otimes \sigma)\circ ({\it id}\otimes {m g}\otimes {\it id})$$

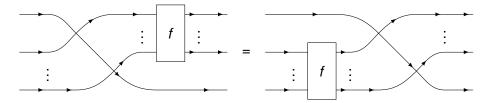
Example

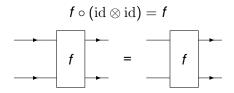
If we have access to $f : 2 \rightarrow 1$ and $g : 2 \rightarrow 2$, we can e.g. write:

$$(g \otimes \mathit{id}) \circ (\mathit{f} \otimes \sigma) \circ (\mathit{id} \otimes g \otimes \mathit{id})$$



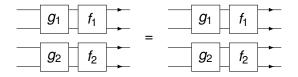
PROPs





$$(f_1 \circ g_1) \otimes (f_2 \circ g_2) = (f_1 \otimes f_2) \circ (g_1 \otimes g_2)$$

$$(f_1 \circ g_1) \otimes (f_2 \circ g_2) = (f_1 \otimes f_2) \circ (g_1 \otimes g_2)$$



(Coherence theorem)

The axioms imply that reasoning with pictures is OK!

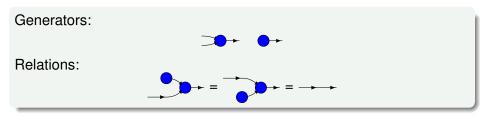
- $f: m \rightarrow n$ are functions from A^m to A^n
- • is the composition of functions
- SWAP: $(x, y) \rightarrow (y, x)$
- $f \otimes g$ is the cartesian product

- $f: m \rightarrow n$ are functions from [1, m] to [1, n].
- • is the composition of functions
- SWAP: $1 \leftrightarrow 2$
- If $f_1 : [1, m_1] \rightarrow [1, n_1]$ and $f_2 : [1, m_2] \rightarrow [1, n_2]$, then

- $f: m \to n$ are matrices from $M_{n,m}(\mathbb{R})$
- $\bullet \ \circ$ is the matrix product
- swap: $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ • $M \otimes N$ is the Kronecker sum: $\begin{pmatrix} M & 0 \\ 0 & N \end{pmatrix}$

Plan

Like with groups and other structures, we can look at props given by generators and relations

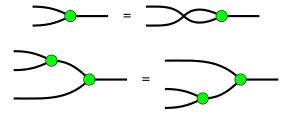


Plan

What are the generators and relations of the props corresponding to functions $\{0,1\}^m \to \{0,1\}^n$?

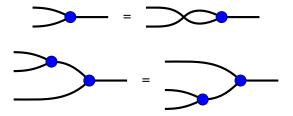
We have a generator: $\textit{AND}: 2 \rightarrow 1$



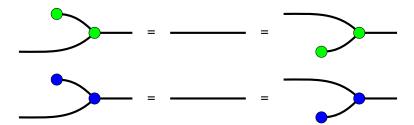


We have a generator: $OR: 2 \rightarrow 1$





We have two generator: $T: 0 \rightarrow 1$ and $F: 0 \rightarrow 1$



We have one generator: $NOT : 1 \rightarrow 1$

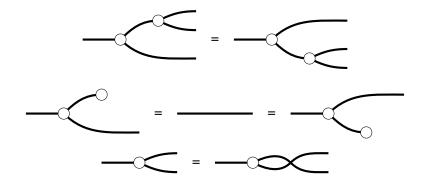




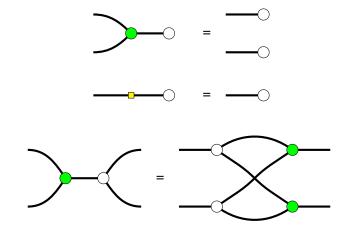
We're missing some equations but do we have all generators ?

We have two generators: $CPY : 1 \rightarrow 2$ and $TRASH : 1 \rightarrow 0$.

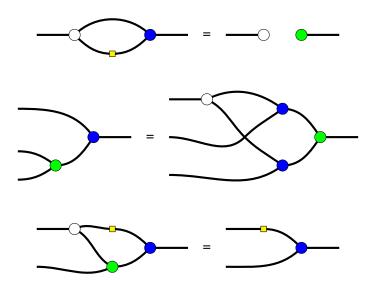




Some of the remaining equations



Some of the remaining equations

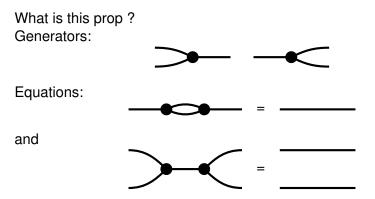


Theorem (Folklore)

The corresponding generators and equations correspond to the PROP of functions from $\{0,1\}^m \rightarrow \{0,1\}^n$.

Plan

Example



(No commutativity or associativity)

What is this prop ?

Theorem

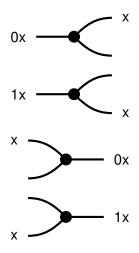
It is the prop of bijective dyadic affine functions from [1, m] to [1, n].

Theorem

It is the prop of bijective "local" functions from $\{1,\ldots,m\}\times\{0,1\}^\omega$ to $\{1,\ldots,n\}\times\{0,1\}^\omega$

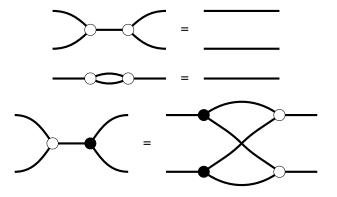
These are called "generalized shifts" in the vocabulary of Moore [1991]. Input (n, x) is to be interpreted as "I have the infinite word x in the *n*-th wire".

Example



Example

Harder example:



Theorem

It is the prop of bijective "local" functions from $\{1,\ldots,m\} \times \{0,1\}^{\omega} \times \{0,1\}^{\omega}$ to $\{1,\ldots,n\} \times \{0,1\}^{\omega} \times \{0,1\}^{\omega}$

Theorem

It is the prop of reversible Turing machines.

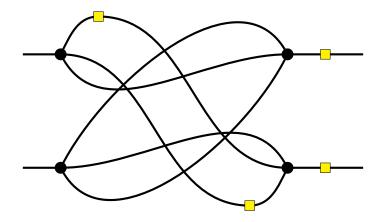
More precisely, maps $m \rightarrow m$ correspond to reversible Turing machines with *m* states.

The following map:



is just the shift!

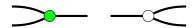
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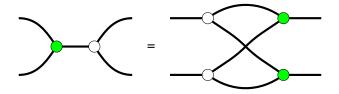
Plan

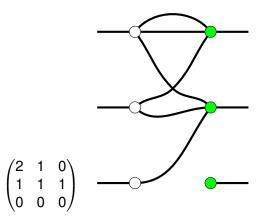
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- • is the matrix product
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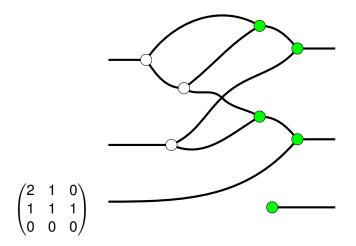
What are the generators and relations ?



Axioms: (co)associativity, (co)commutativity, (co)unit and:







All the previous properties were satisfied by AND and CPY. What does it mean ?

Proposition (Universal Property)

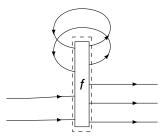
There exists a morphism (technically a functor) from matrices into boolean functions

$$\begin{pmatrix} 1 & 0 & 1 \\ 1 & 2 & 0 \end{pmatrix} \quad (x, y, z) \mapsto (x \text{ AND } z, x \text{ AND } y \text{ AND } y)$$

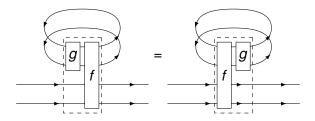
Plan

We are computer scientists, let's add feedback loops!

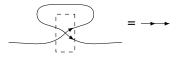
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What becomes the prop of matrices when we add a loop ?

Theorem

Let M and N two matrices, represented as diagrams.

If we completely trace both matrices (we link all outputs to all inputs), then

trM = trN iff M and N are flow equivalent.

Flow equivalence is an equivalence notion on matrices (technically on SFTs) coming from symbolic dynamics.

We have reformulated a notion from symbolic dynamics into a category notion. This is great!

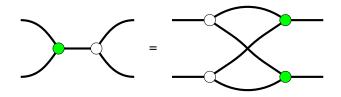
Why is this great ?

- Suppose we know of mathematical objects in some structure C that satisfy all properties I gave
- By the universal property, there is a morphism from (traced) matrices to these objects
- If we start from two matrices that are flow equivalent, then they should correspond to the same thing in C

We have produced an invariant of flow equivalence!



Axioms: (co)associativity, (co)commutativity, (co)unit and:



And there is a trace.

These equations are incredibly common, and appear in many parts of math.

Monoids

Let $\mathcal M$ be a commutative monoid. Inputs and outputs are elements of $\mathcal M$:



For the trace to make sense, we have to go with monoids with multiplicities rather than monoids.

Theorem

The number of solutions in \mathcal{M} of the equation Mx = x is an invariant of flow equivalence. If M and N are flow equivalent, the equations Mx = x and Nx = x have the same number of solutions. Inputs/Outputs are polynomials in n/m variables

- Green node: identify two variables $X_1^k X_2^m \to X^{k+m}$
- White node: divide two variables $X^n \to \sum_k {n \choose k} X_1^k X_2^{n-k}$
- Trace: sum over all *n* of the coefficient of *Xⁿ* of the output if the input is *Xⁿ*

Theorem

det(I - M) is an invariant of flow equivalence.

Cospans

- A box with *m* inputs and *n* outputs is a *commutative group*, with at least *n* + *m* generators
- Composition = identifying generators
- Green node: Group with three generators x, y, z s.t. the output z is the sum of the two inputs.
- White node: Group with three generators x, y, z s.t. the outputs y and z are equal to x

Theorem

The group

$$G = \langle x | x = Mx \rangle$$

is an invariant of flow equivalence

(This is the Bowen-Franks group)

- Many invariants of symbolic dynamics can be recovered by trying to find structures (traced bialgebras) in some unrelated objects.
- This can also be done for conjugacy (strong shift equivalence)
 - We can recover the Zeta function
 - We can recover the dimension group

Now: test other categories, to obtain new invariants!