CSE291-14: The Number Field Sieve

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CSE291-14: The Number Field Sieve

Part 4a

Polynomial selection in NFS

Introduction

Size of the coefficients: possible and impossible things

Searching for good polynomials with base-*m*

Skewness

Non-monic linear polynomials: Kleinjung's 2005 algorithm

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Our goal: review the different methods for polynomial selection.

- Why is it important?
- What kind of game is it?
- What are the different methods?
- How do we measure the quality of the output?

The polynomial selection phase is when we choose the pair of polynomials that define both sides of the NFS diagram.

- The algebraic polynomial *f* defines the number field.
- The rational polynomial (thus far, x m) completes the picture.

In practice, this is more general

In fact, not even x - m is monic. Several methods do relax this condition (but not the first ones). In some cases, both polynomials are of degree > 1.

Importance of polynomial selection

Polynomial selection is important because it determines the size of the "norms" (actually, of the integers being checked for smoothness).

- Asymptotic analysis crudely reduced polynomial selection to the choice of the pair (D, δ) .
- We eventually found out that δ was controlling the compromise between the size of $\text{Res}(\phi, x m)$ and of $\text{Res}(\phi, f)$.

This general role is also true in practice

A good polynomial selection makes these "norms" small as $\phi(x) = a - bx$ ranges over the values we explore.

- Certainly, some things can be achieved, and some can't.
- Can we force these values to be smooth more often than on average?

Starting point: a method that can yield good polynomial pairs.

- Arrange so that the method has many degrees of freedom.
- Explore a huge search space to find exceptional situations.
- Find reasonable assessment criteria that make it possible to identify which are the "exceptionally good" polynomial pairs.

What if we replace x - m by $m_1 x - m_0$?

•
$$\operatorname{Res}(a - bx, x - m) = a - bm$$
 becomes
 $\operatorname{Res}(a - bx, m_1x - m_0) = am_1 - bm_0$, which looks nicer.

- If we write $m = m_0/m_1 \in \mathbb{Q}$ and that $f(m) \equiv 0 \mod N$, everything works as before.
- The condition to meet is the existence of a common root:

$$\operatorname{Res}(f(x), m_1 x - m_0) \equiv 0 \mod N.$$

This extra degree of freedom has been part of all polynomial selection algorithms since the early 2000s.

An extension: higher degree polynomials

If a polynomial selection can find a pair of nonlinear polynomials:

- whose resultant is divisible by N with multiplicity 1
- ullet and with a known common root in $\mathbb{Z}/N\mathbb{Z}$

Then we can work exactly along the lines of NFS.

Caveat: no such thing is known in general, EXCEPT for DLP.

- NFS for DLP (discrete logs in $\mathbb{Z}/p\mathbb{Z}^{\times}$): *p* replaces *N*.
- The existence of root finding mod *p* is the key.
- In some cases (but not always), this wins.

Traditionally, notations are as follows:

f is the algebraic polynomial.
 The coefficients are named f₀,..., f_d, or a₀,..., a_d.

• g is the linear polynomial.

Often, to highlight the symmetric roles played by the two sides:

- f_0 is "the polynomial on side 0" (typically deg $f_0 = 1$).
- f₁ is "the polynomial on side 1".
- But this messes with the per-coefficient notations.
 Notations a₀,..., a_d are preferred for coefficients of the nonlinear polynomial in this case.

Implementations such as Cado-NFS are mostly agnostic w.r.t side numbering.

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Notations: $(f_0, f_1), \deg f_1 = d, f_1 = \sum a_i x^i$.

Our first approach consists in searching for "small" polynomial pairs.

- Eventually, one of our guides will be the size of the integers we will try to factor.
- Given the power dependency in the degrees of the polynomials, we have only a few possible choices for the degree.
- Given a choice for $d = \deg f_1$, can we obtain polynomials f_0 and f_1 with small coefficients?

A good question to ask

In order to reach all integers in a range [M, 2M], how large do we have to choose the coefficients of f_0 and f_1 ? Let M^{c_0} be a bound on the coefficients of f_0 (likewise M^{c_1} for f_1).

• First constraint: to reach *M* different values with the degrees of freedom that we have:

$$c_0 \cdot (d_0 + 1) + c_1 \cdot (d_1 + 1) \ge 1.$$

• Second constraint: $\operatorname{Res}(f_0, f_1)$ must be at least M. Since $\operatorname{Res}(f_0, f_1) = M^{o(1)} \|f_0\|^{\deg f_1} \|f_1\|^{\deg f_0}$, we must have:

$$c_0 \cdot d_1 + c_1 \cdot d_0 \geq 1.$$

Note that the constraints are of different nature.

•
$$c_0 \cdot (d_0 + 1) + c_1 \cdot (d_1 + 1) \ge 1$$
.
Pairs not meeting this constraint may exist, but such a family cannot reach all integers.

$$\bullet \ c_0 \cdot d_1 + c_1 \cdot d_0 \geq 1.$$

It is outright impossible for pairs to not meet this constraint, and be useful for NFS.



Take what the naive polynomial selection method gives: $d_0 = 1$, $d_1 = d$, $c_0 = c_1 = \frac{1}{d+1}$.

•
$$c_0 \cdot (d_0 + 1) + c_1 \cdot (d_1 + 1) = \frac{2}{d+1} + \frac{d+1}{d+1} \ge 1.$$

•
$$c_0 \cdot d_1 + c_1 \cdot d_0 = \frac{d}{d+1} + \frac{1}{d+1} = 1.$$

Put otherwise, the resultant bound is tight, but there is immense legroom in the choice of f_0 .

What can we obtain with $c_1 = 0$? i.e., a family of algebraic polynomials with coefficients bounded by a constant.

The remaining constraint rewrites simply as

$$c_0d_1=1,$$

which does not say much.

Does this do anything?

If we have access to a fictitious oracle that outputs such a polynomial f_1 , what does it give?

SNFS: polynomial selection with an oracle

If we have access to a fictitious oracle that outputs such a polynomial f_1 , what does it give?

- We can do the entire NFS analysis based on that.
- The algebraic norm can be rewritten as $L_N[1/3, \times + \alpha \delta]$.
- This changes the optimum δ from $\sqrt{2/\alpha}$ to $\sqrt{1/\alpha}$.
- Eventually, we end up with $L_N[1/3, (32/9)^{1/3} + o(1)]$.

This is called SNFS.

- The "special" integers are those that are precisely reached by this "ideal" choice.
- By extension, the SNFS term is also used for anything that is reached by a non-general polynomial selection.

The constraint space

Example for $d_0 = 1$ and $d_1 = 6$.



Note that $c_0 + c_1$ appears in the smoothness probability.

•
$$c_0 + c_1 = \log(||f_0|| \cdot ||f_1||) / \log N.$$

 c₀ + c₁ measures the polynomial-dependent part of the maximum size of the integers which are checked for smoothness.

Thus the intersection point P is "ideal". Alas, moving towards P is expensive.

Where are we?

- Base-*m* polynomial selection is a starting point.
- We have an argument that explains that it is not "optimal".
- SNFS numbers are really special.

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Recall that the simplistic base-*m* method choses $m \approx N^{1/(d+1)}$.

- There is an immense degree of freedom in the choice of *m*.
- Can we do many trials and hope for something nice to happen?
- Opportunities for improvement:
 - It is not a very big deal if $||f_0||$ (max coefficient of the linear polynomial) increases by a tiny bit.
 - Can this be compensated by a larger decrease of $||f_1||$?

Instead of picking m first, and then the coefficients of f:

- Choose a_d first, slightly smaller than $N^{1/(d+1)}$.
- Then choose *m*, and deduce the rest of the coefficients.

Our game: correlation between effort and yield

Ultimately, we want to answer the question:

"If we generate C polynomial pairs, what is the best we can obtain, as a function of C?"

Can also be phrased as: if $a_d \approx N^{1/(d+1)}/c$, how many trials does it take to have all coefficients of f close to a_d ?

Let *c* be an arbitrary number.

• Choose $a_d \approx N^{1/(d+1)}/c$ (many possible choices!)

• Let
$$m = \lfloor (N/a_d)^{1/d} \rceil = (N/a_d)^{1/d} + \mu$$
 with $|\mu| \le 1$.

Lemma: $a_{d-1} \approx a_d$

$$|a_{d-1}| = \frac{\left|N - a_d m^d\right|}{m^{d-1}} = a_d \frac{\left|(m-\mu)^d - m^d\right|}{m^{d-1}}$$
$$\leq a_d m \left|(1-\mu/m)^d - 1\right|$$
$$\leq da_d \times \text{small constant bound.}$$

And d is small as well, so we expect a_{d-1} to have roughly as many bits as a_d .

Other coefficients

The d-1 coefficients a_0 to a_{d-2} are a priori close to m, with: $m \approx (N/a_d)^{1/d} \approx (N^{1-1/(d+1)}c)^{1/d} \approx N^{1/(d+1)}c^{1/d}.$



Heuristic: a_0 to a_{d-2} behave like random integers. With probability $(a_d/m)^{d-1} \approx \left(c^{-(1/d+1)}\right)^{d-1} = c^{-(d^2-1)/d}$, all are $\leq a_d$.

Conclusion

By trying
$$c^{(d^2-1)/d}$$
 values a_d , we expect to:

• change $||f_1||$ to $N^{1/(d+1)}/c$.

• change
$$||f_0||$$
 to $N^{1/(d+1)} \times c^{1/d}$

Rewrite

Conclusion (rewrite)

By trying $c^{(d^2-1)/d}$ values a_d , we expect to:

- change $||f_1||$ to $N^{1/(d+1)}/c$.
- change $||f_0||$ to $N^{1/(d+1)} \times c^{1/d}$.

We can also write: by trying C values a_d , we expect to:

- change $||f_1||$ to $N^{1/(d+1)}/C^{d/(d^2-1)}$.
- change $||f_0||$ to $N^{1/(d+1)} \times C^{1/(d^2-1)}$.

• change $||f_0|| ||f_1||$ to $N^{2/(d+1)}/C^{1/(d+1)}$.



This moves in the right direction!

- More work leads to smaller polynomials.
- This is woefully exponential, of course.

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Skewness

Notations: $(f_0, f_1), \deg f_1 = d, f_1 = \sum a_i x^i, \phi(x) = u - vx$.

Skewness is a way to add more flexibility to the polynomial selection process.

Observation: the polynomial x - m is unbalanced. So is the expression Res(u - vx, x - m) = u - vm.

• Can we work with larger u and smaller v?

Skewed polynomials

 $\operatorname{Res}(u - vx, f_1) = F(u, v) = (u^d a_d + \cdots + u^i v^{d-i} a_i + \cdots + v^d a_0).$

 If coefficients of f₁ have roughly the same size and both coefficients of φ(x) are bounded by A, then all a_iuⁱv^{d-i} have the same size.



Skewed polynomials

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- If coefficients of f₁ have roughly the same size and both coefficients of φ(x) are bounded by A, then all a_iuⁱv^{d-i} have the same size.
- If the a_i are unbalanced, say $\frac{a_i}{a_{i+1}} \approx S > 1$, then with $|u| < A\sqrt{S}$ and $|v| < A/\sqrt{S}$, all $a_i u^i v^{d-i}$ have the same size.



The ratio S is called the skewness; the polynomials are skewed.

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Skewed norm

Definition

Given $P = \sum p_i x^i \in \mathbb{R}[x]$, the S-skewed (infinity) norm of P is:

$$\|P\|_{S} = \|P\|_{\infty,S} = \max_{0 \le i \le \deg P} |p_{i}S^{i-(\deg P)/2}|$$



All polynomials above have the same S-skewed norms (with their respective S). If $||P|| = ||Q||_S$, then

$$\max\{\operatorname{Res}(u - vx, P), (u, v) \in [0, A]^2\} \\ = \max\{\operatorname{Res}(u - vx, Q), (u, v) \in [0, A\sqrt{S}] \times [0, A/\sqrt{S}]\}$$

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How do we find skewed polynomials?

When we revisited base-m, we chose a_d first, and then m. This gave rise to:



This polynomial pair is already somewhat skewed, we may turn it to our advantage.

How do we find skewed polynomials?

When we revisited base-m, we chose a_d first, and then m. This gave rise to:

•
$$a_d \approx a_{d-1} \approx N^{1/(d+1)}/c$$
.
• $m = \sqrt[d]{N/a_d} \ge N^{1/(d+1)} =$ the textbook base-*m*.



This polynomial pair is already somewhat skewed, we may turn it to our advantage.

- Aim at the same skew-norm, starting from a smaller a_d (
 - bits we still have to cancel (=),
 - bits we no longer care about (-),
 - new bits to cancel (■),
 - a moderately larger rational norm because m got larger (■),

Analysis is a bit painful, but the outcome is quite clear:

With the same number of trials, we can expect to find smaller skewed-norms that in the non-skewed base-m. $C^{1/(d+1)}$ is replaced by a mildly larger number

Refinements:

- Do not optimize a_0 .
- Rationale: this makes it possible to form many linear combinations like f₀ + tf₁ and choose the best one.
 We'll get to that with root properties and root sieving.

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In fact, f_0 can be non-monic:

$$f_0=m_1x-m_0.$$

Then, the common root modulo N must be $m = m_0/m_1$ and

$$\mathsf{Res}(f_1, m_1 x - m_0) = a_d m_0^d + a_{d-1} m_1 m_0^{d-1} + \dots + a_0 m_1^d$$

Remark: if the latter is equal to *N*, it implies

 $a_d m_0^d \equiv N \mod m_1.$

First ingredient of Kleinjung's algorithms (2006 and 2008) is called Kleinjung "Lemma 2.1". It computes a reasonably good f_1 from a fixed choice of N, d, m_1 , m_0 and a_d .

Kleinjung "Lemma 2.1"

Input: *N*, *d*, *m*₁, *m*₀, and some fixed coefficients $[a_j, \ldots, a_d]$ **Output**: A polynomial f_1 such that $\text{Res}(f_1, m_1x - m_0) = N$ First, compute

$$r_j = \frac{N - \sum_{i=j+1}^d a_i m_0^i m_1^{d-i}}{m_1^{d-j}}$$

Then, for i = j - 1, j - 2, ..., 0, compute:

•
$$r_i = \frac{r_{i+1} - a_{i+1}m_0^{i+1}}{m_1}$$

• $a_i = \frac{r_i + t_im_1}{m_0^i}$, where t_i is an integer such that
 $-\frac{m_0^i}{2} \le t_i < \frac{m_0^i}{2}$ and $t_i \equiv -\frac{r_i}{m_1} \mod m_0^i$
The output is $f_1 = a_d x^d + a_{d-1} x^{d-1} + \dots + a_1 x + a_0$.

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Kleinjung "Lemma 2.1" – example

Kleinjung's "Lemma 2.1" algorithm applied to RSA-155 with d = 5 and

*a*₅ = 358870426380

- $m_0 = 31392776870911769459515309198$
- $m_1 = 823916492006383$

gives:

- $f_1 = 358870426380x^5$
 - $+ 428308592054328x^4$
 - $-\ 16336877672072510723154851996 x^3$
 - $-\ 12601611387318107328006122118 x^2$
 - $-\ 19621855499511523845845304751 x$
 - $-\ 8369763785495595985304502899$

If we apply Kleinjung "Lemma 2.1" with only the leading coefficient a_d fixed and with m_0 close to $\tilde{m}_0 = \sqrt[d]{\frac{N}{a_d}}$, the algorithm yields:

- a_{d-1} rather small: $|a_{d-1}| < m_1 + da_d \frac{m_0 \tilde{m}_0}{m_1}$.
- Other a_i 's satisfy $|a_i| < m_1 + m_0$.



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Our goal, and how we reach it

Have coefficient sizes which are a good match to some skewness.

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- Other a_i 's satisfy $|a_i| < m_1 + m_0$.



Our goal, and how we reach it

Have coefficient sizes which are a good match to some skewness.

- Find smart way to make a_{d-2} small.
- Rely on (mild) luck to make a_{d-3} small.

Use the equation $a_d m_0^d \equiv N \mod m_1$.

Key idea

Build m_1 as a product of small primes. Use the combination of modular information to fabricate a small a_{d-2} .

- Let \mathcal{P} be a set of small primes $\equiv 1 \mod d \pmod{m_1}$ will be a product of a subset of \mathcal{P}).
- Pick some a_d (e.g. smooth).
- Some primes $r \in Q \subset P$ give d solutions to $a_d x^d \equiv N$ mod r.
- Any choice of exactly one *d*-th root modulo each of those *r*'s gives a value m₀ defined modulo m₁ = ∏ *r* by CRT. We may choose one which is close to m₀ = ^d√N/a_d.

Many choices

Pick ℓ primes for which $a_d x^d \equiv N \mod r$ has d solutions.

- In total, d^{ℓ} possible choices for m_0 .
- *m*₀ is a linear combination of ℓ values among *d* × ℓ.
 This follows from explicit Chinese Remainder Theorem.

Expand the value a_{d-2}/m_0 obtained by "Lemma 2.1" from the *d*-th roots of $m_0 \mod r$ that we have chosen.

- By restricting to 1st order terms, we get a linear combination.
- If a_{d-2}/m_0 ends up being close to an integer λ for some chosen m_0 , then for $f'_1 = f_1 \lambda(m_1x m_0)x^{d-2}$, we have:
 - a'_{d-2}/m_0 close to 0,
 - a'_{d-1} does not change much.

The problem can be reduced to the following:

- ℓ sets S_1, \ldots, S_ℓ , each containing d real numbers in [0, 1).
- d^{ℓ} choices: (s_1, \ldots, s_{ℓ}) with each $s_i \in S_i$, and:

$$a_{d-2}/m_0 \mod \mathbb{Z} \equiv \sum s_i.$$

- Naive complexity: $O(d^{\ell})$.
- Ø Better:

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$$a_{d-2}/m_0 \mod \mathbb{Z} \equiv \sum s_i.$$

- Naive complexity: $O(d^{\ell})$.
- Better: $O(d^{\ell/2})$.

What do small combinations give ?

Algorithm has:

- *a_d* chosen small.
- a_{d-1} small by construction, $\approx m_1$.
- a_{d-2} small thanks to small combinations.





With some extra luck, a_{d-3} may be somewhat smaller than expected.