

Regression

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Introduction

Regression:

- ▶ find the relationship between variables,
- ▶ find the best curve to fit data,
- ▶ predict the value for a new data point;

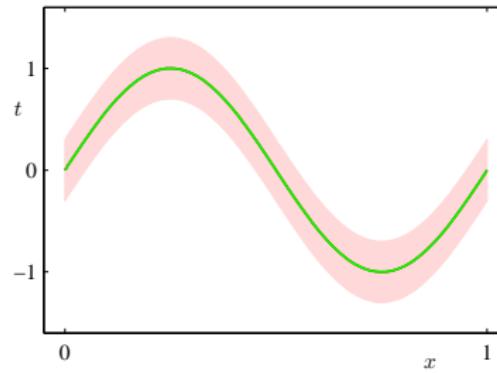
Characteristics:

- ▶ supervised learning,
- ▶ evaluate using goodness of fit,
- ▶ problem of overfitting.

Polynomial curve fitting

Example:

- ▶ synthetic data,
- ▶ generated based on a sine function (green),
- ▶ Gaussian noise (red).

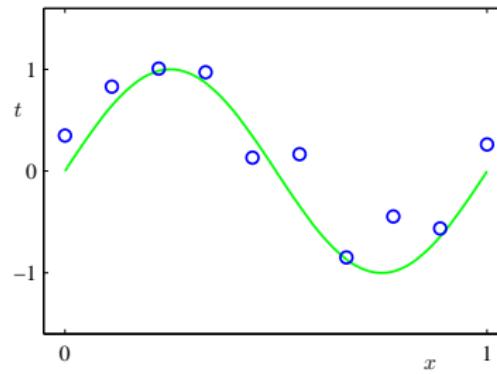


Courtesy C. Bishop, PRML.

Polynomial curve fitting

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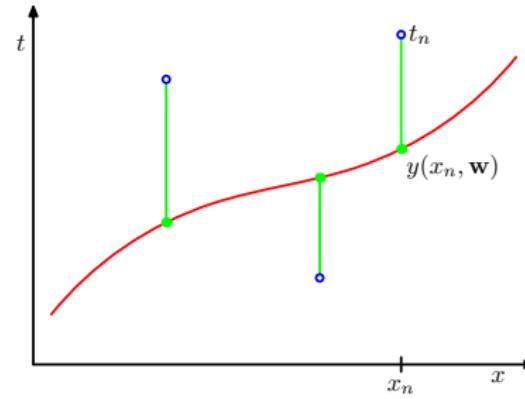


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Problem statement

Aim:

- ▶ from points (x_n, t_n) ,
- ▶ fit model: $y(x, \mathbf{w}) = \sum_{j=0}^M w_j \cdot x^j$,
- ⇒ find weight vector: \mathbf{w} ,
- ▶ minimizing error $E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2$.



Solution

Mathematically:

- ▶ Looking for: $\arg \min_w E(w)$

$$\Rightarrow \text{solve: } \frac{dE}{dw} = \mathbf{0}$$

\Rightarrow solve:

$$\begin{pmatrix} \sum_{n=1}^N x_n^0 (\sum_{j=0}^M w_j x_n^j - t_n) \\ \vdots \\ \sum_{n=1}^N x_n^k (\sum_{j=0}^M w_j x_n^j - t_n) \\ \vdots \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \vdots \end{pmatrix}$$

Solution

Let:

$$\Phi = \begin{pmatrix} x_1^0 & \dots & x_1^j & \dots & x_1^M \\ \vdots & \ddots & \vdots & & \vdots \\ x_n^0 & \dots & x_n^j & \dots & x_n^M \\ \vdots & & \vdots & \ddots & \vdots \\ x_N^0 & \dots & x_N^j & \dots & x_N^M \end{pmatrix}$$

N rows by $M + 1$ columns

$$\Phi = (\phi_{n,j} = x_n^j)$$

Then:

$$\frac{dE}{dw} = w^T \Phi^T \Phi - t^T \Phi = 0$$

Finally:

$$w = (\Phi^T \Phi)^{-1} \Phi^T t$$

Where $(\Phi^T \Phi)^{-1} \Phi^T = \Phi^+$ is the pseudoinverse of Φ

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Then:

$$\frac{dE}{d\mathbf{w}} = \mathbf{w}^T \Phi^T \Phi - \mathbf{t}^T \Phi = 0$$

Finally:

$$\mathbf{w} = (\Phi^T \Phi)^{-1} \Phi^T \mathbf{t}$$

Where $(\Phi^T \Phi)^{-1} \Phi^T = \Phi^+$ is the pseudoinverse of Φ

Polynomial curve fitting

Solve:

- ▶ model: $y(x, \mathbf{w}) = \sum_{j=0}^M w_j \cdot x^j,$
- ▶ minimize SSE: $E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2,$
- ▶ let: $\Phi = (x_n^j)_{n,j},$
- ▶ solution:

$$\mathbf{w} = \Phi^+ \mathbf{t}$$

Summary:

- ▶ model: linear combination of monomials,
- ▶ equation: linear system,
- ▶ solution: linear algebra.

Linear regression

Definition:

- ▶ model: linear combination of basis functions,
- ▶ minimize SSE,
- ▶ equation: linear system,
- ▶ solution: linear algebra.

Basis functions:

- ▶ set of functions $\phi = (\phi_j)_j$,
- ▶ define the model: $y(x, \mathbf{w}) = \sum_{j=0}^M w_j \phi_j(x) = \mathbf{w}^T \phi(x)$.

Solution

Build the $N \times M + 1$ design matrix:

$$\Phi = \begin{pmatrix} \phi_0(x_1) & \cdots & \phi_j(x_1) & \cdots & \phi_M(x_1) \\ \vdots & \ddots & \vdots & & \vdots \\ \phi_0(x_n) & \cdots & \phi_j(x_n) & \cdots & \phi_M(x_n) \\ \vdots & & \vdots & \ddots & \vdots \\ \phi_0(x_N) & \cdots & \phi_j(x_N) & \cdots & \phi_M(x_N) \end{pmatrix}$$

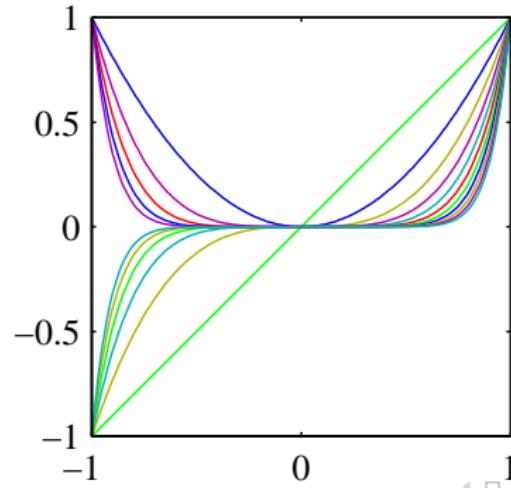
Compute the pseudo-inverse and the weights:

$$\mathbf{w} = \Phi^+ \mathbf{t}$$

Basis functions

Different choices:

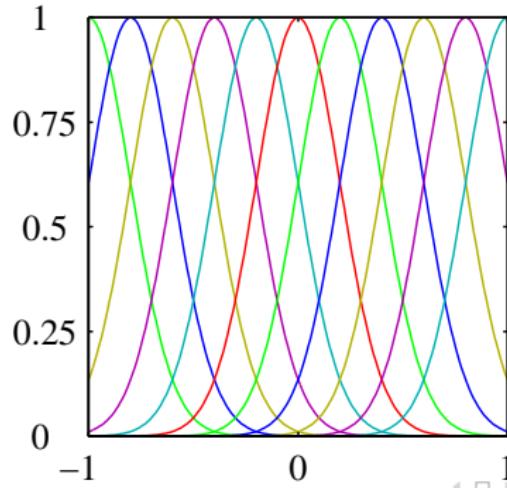
- ▶ monomials (polynomial curve fitting),
- ▶ Gaussian functions,
- ▶ sigmoidal functions
- ▶ ...



Basis functions

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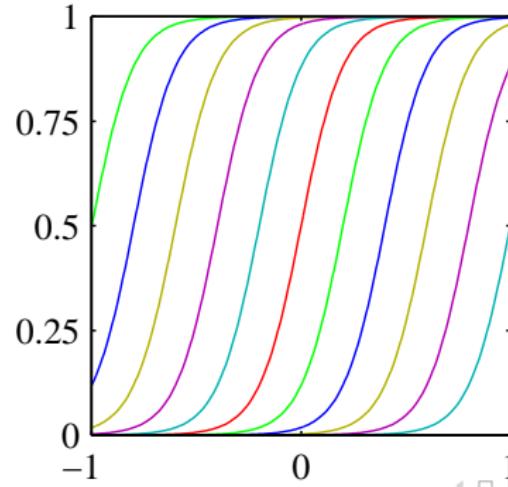


Basis functions

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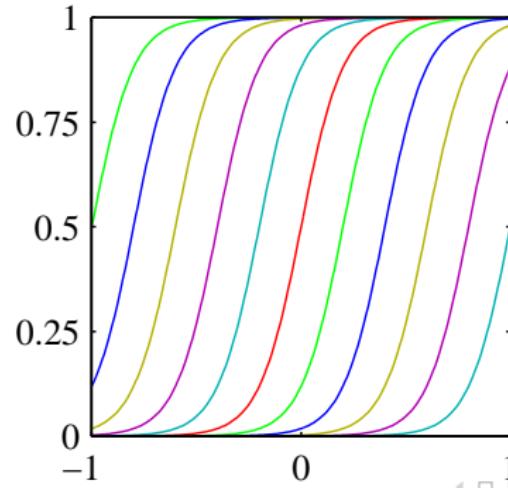
▶ ...



Basis functions

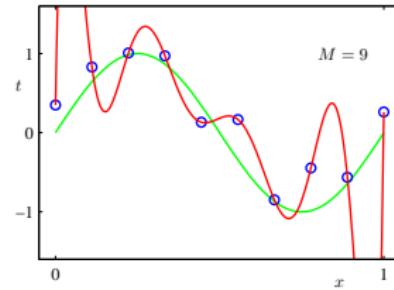
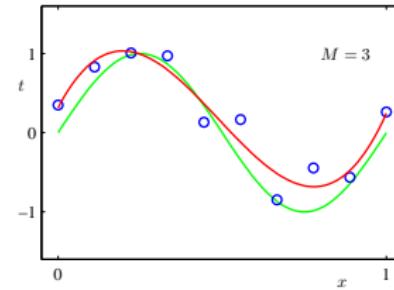
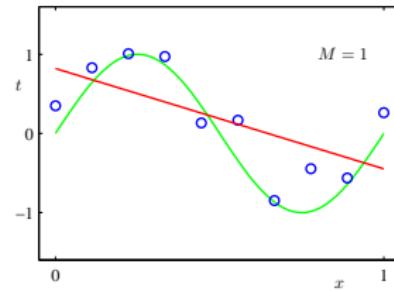
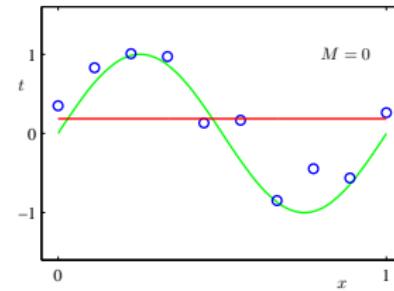
Different choices:

- ▶ monomials (polynomial curve fitting),
- ▶ Gaussian functions,
- ▶ sigmoidal functions
- ▶ ...



Overfitting

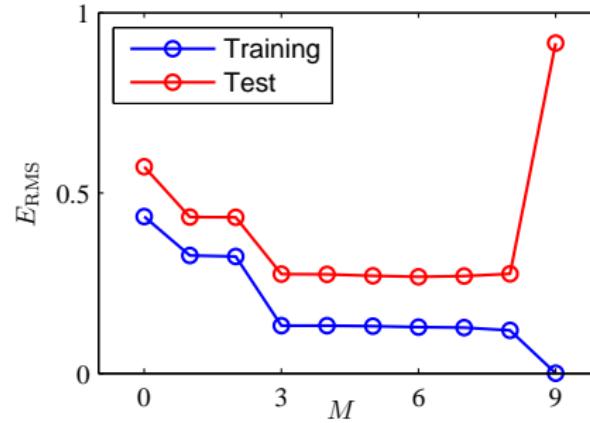
Result depends on the choice and number of basis functions.
With monomials:



Validation

Comparing models:

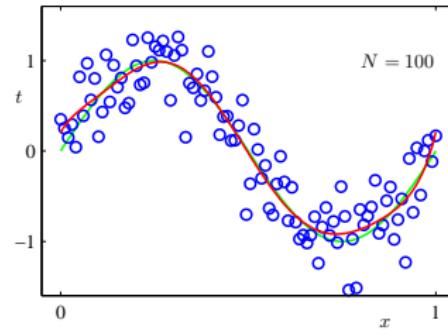
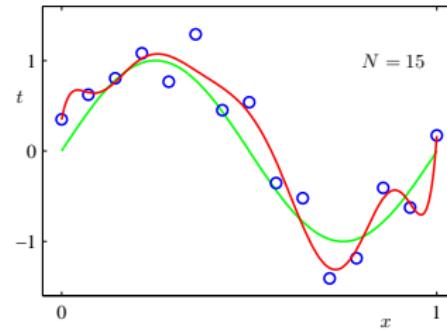
- ▶ training set: involved in fitting each model,
- ▶ test set: to compare the models:



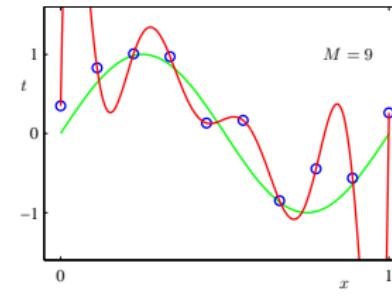
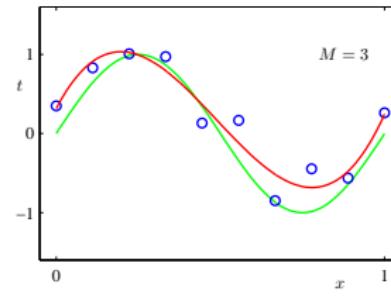
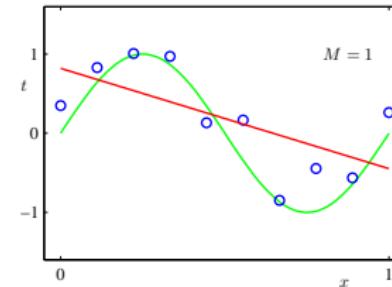
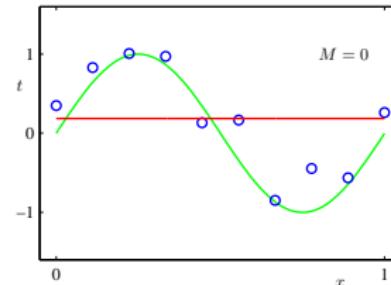
But you need a large enough dataset.

Overfitting

Trade-off between complexity of the model and the data



Regularization



Regularization

Weight vector:

	$M = 0$	$M = 1$	$M = 3$	$M = 9$
w_0	0.19	0.82	0.31	0.35
w_1		-1.27	7.99	232.37
w_2			-25.43	-5321.83
w_3			17.36	48568.31
w_4				-231639.30
w_5				640042.26
w_6				-1061800.52
w_7				1042400.18
w_8				-557682.99
w_9				125201.43

Overfitting → large values!

Regularization

Regularization:

- ▶ penalize high values,
- ▶ change the error function:

$$\tilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2 + \frac{\lambda}{2} \|\mathbf{w}\|^2$$

- ▶ still linear algebra:

$$\mathbf{w} = (\lambda \mathbf{I} + \Phi^T \Phi)^{-1} \Phi^T \mathbf{t}$$

Choice of λ :

- ▶ too large: simple model,
- ▶ too small: overfitting,
- ▶ trade-off between data and model.

Summary

Linear regression:

- ▶ linear combination of basis functions,
- ▶ find weight minimizing error,
- ▶ linear system of equation,
- ▶ overfitting;

Regularization:

- ▶ penalize big weights,
- ▶ change the error,
- ▶ still linear system,
- ▶ choice of regularization parameter.

Reasoning

Regression:

- ▶ estimate parameters,
- ▶ based on data,
- ▶ given a model;

Last week:

- ▶ estimate state,
- ▶ based on data,
- ▶ given a model.

Probabilistic reasoning applied:

- ▶ regression,
- ▶ machine learning.

Probabilistic formulation

We have:

- ▶ x values,
- ▶ predictions y for x given \mathbf{w} ,
- ▶ t values that should be close to y ,

We want:

- ▶ \mathbf{w} .

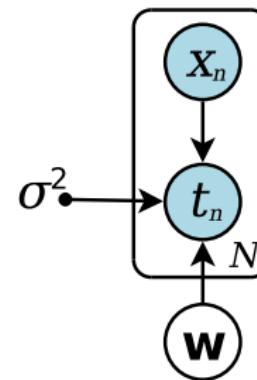
More formally:

- ▶ $t_n = y(x_n, \mathbf{w}) + \epsilon$
- ▶ $P(t_n|x_n, \mathbf{w}) = \mathcal{N}(y(x_n, \mathbf{w}), \sigma^2)$.

Probabilistic formulation

Assumptions:

- ▶ points x_n are all independent,
- ▶ values t_n are independent from everything given x_n and \mathbf{w} ,
- ▶ Gaussian noise with identical variance.



$$P(\mathbf{w}, x_1, t_1, \dots, x_N, t_N) = P(\mathbf{w}) \prod_{n=1}^N P(x_n) P(t_n | x_n, \mathbf{w})$$

Inference

Maximum likelihood estimation (MLE):

$$\arg \max_{\mathbf{w}} P(\mathbf{t}|\mathbf{x}, \mathbf{w})$$

Product \rightarrow taking log:

$$\begin{aligned} & \ln P(\mathbf{t}|\mathbf{x}, \mathbf{w}) \\ &= \sum_{n=1}^N \ln P(t_n|x_n, \mathbf{w}) \\ &= \sum_{n=1}^N \left(-\frac{1}{2} (\ln(2\pi\sigma^2)) - \frac{1}{2\sigma^2} (t_n - y(x_n, \mathbf{w}))^2 \right) \\ &= -\frac{N}{2} \ln(2\pi\sigma^2) - \frac{1}{\sigma^2} \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2 \\ &= \beta - \frac{1}{\sigma^2} E(\mathbf{w}) \end{aligned}$$

Maximum likelihood \Leftrightarrow regression!

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Assuming Gaussian prior over \mathbf{w} :

$$\begin{aligned} & \ln P(\mathbf{w}|\mathbf{x}, \mathbf{t}) \\ &= \alpha + \ln P((\mathbf{t}|\mathbf{x}, \mathbf{w}) + \ln P(\mathbf{w}) \\ &= \alpha + \beta - \frac{1}{\sigma^2} E(\mathbf{w}) + \gamma - \frac{1}{2\sigma_w^2} \mathbf{w}^T \mathbf{w} \\ &= \delta - \frac{1}{\sigma^2} \left(E(\mathbf{w}) + \frac{\sigma^2}{2\sigma_w^2} \|\mathbf{w}\|^2 \right) \end{aligned}$$

Maximum a posteriori \Leftrightarrow regularization!

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Maximum a posteriori \Leftrightarrow regularization!

Example

Fitting a line incrementally:

$$P(t_n|x_n, \mathbf{w}) \quad P(\mathbf{w}|...) \quad \text{data space}$$

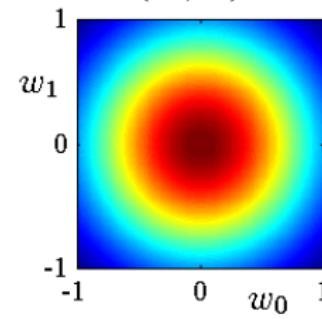
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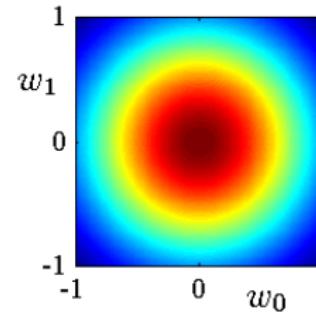


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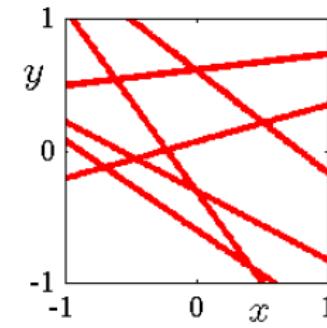
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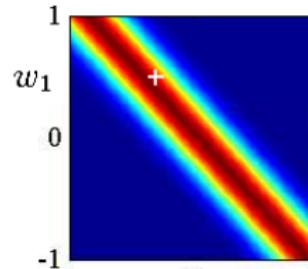
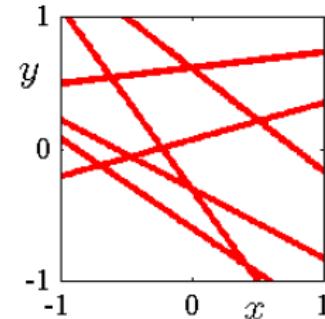
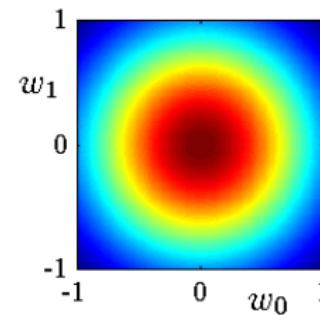
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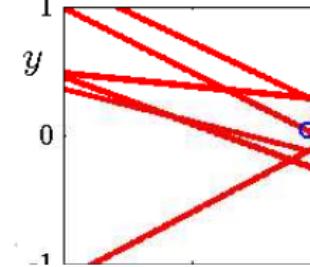
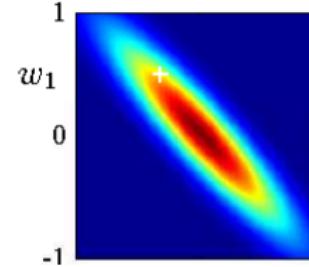
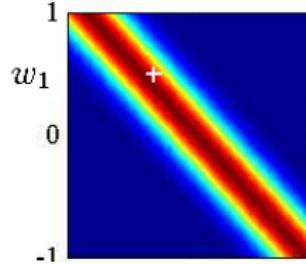
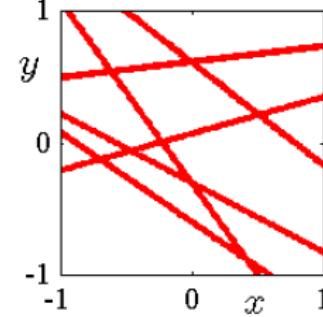
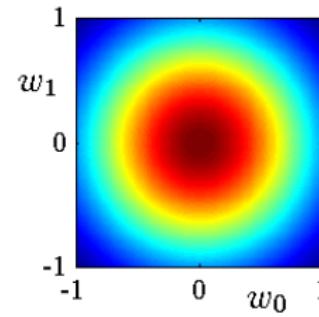
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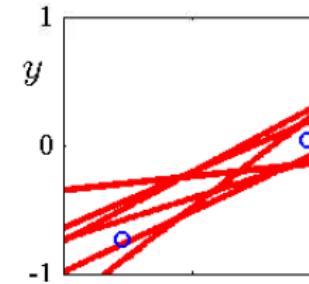
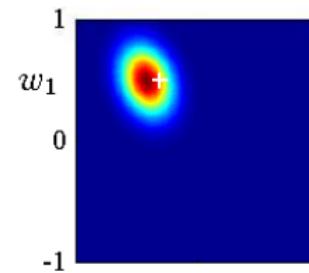
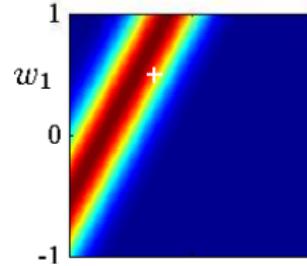
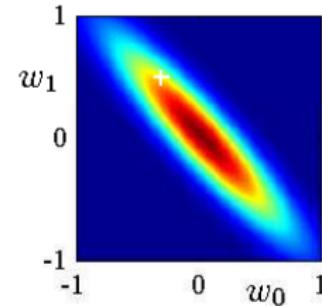
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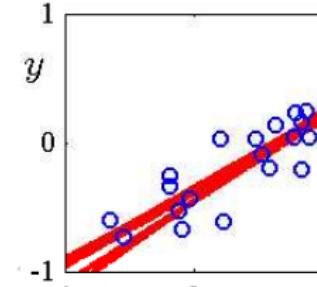
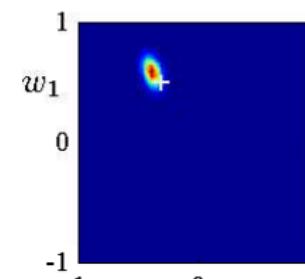
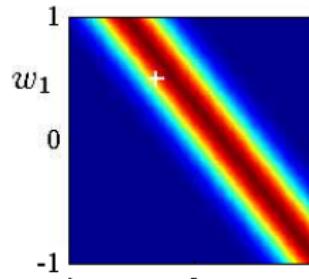
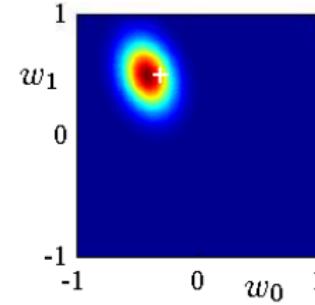
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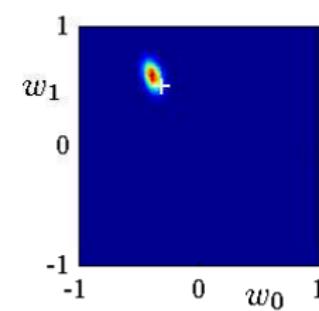


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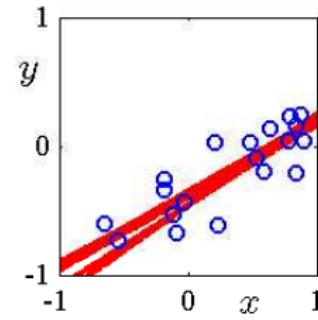
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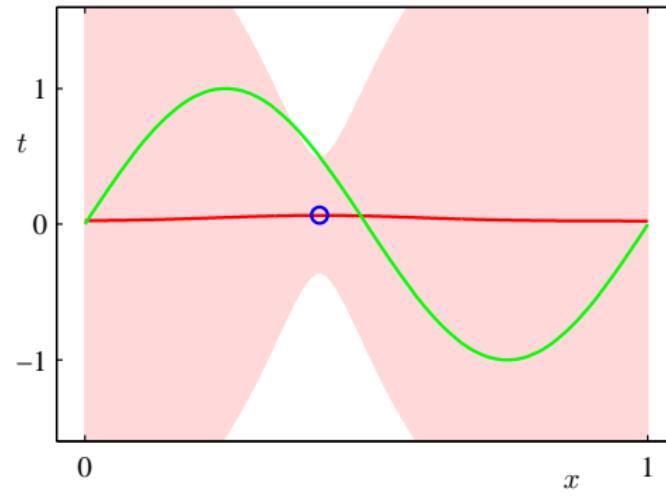
Predict the value for a new point:

$$P(\tilde{t}|\tilde{x}, \mathbf{x}, \mathbf{t}) = \int_{\mathbf{w}} P(\tilde{t}|\tilde{x}, \mathbf{w})P(\mathbf{w}|\mathbf{x}, \mathbf{t})$$

Prediction

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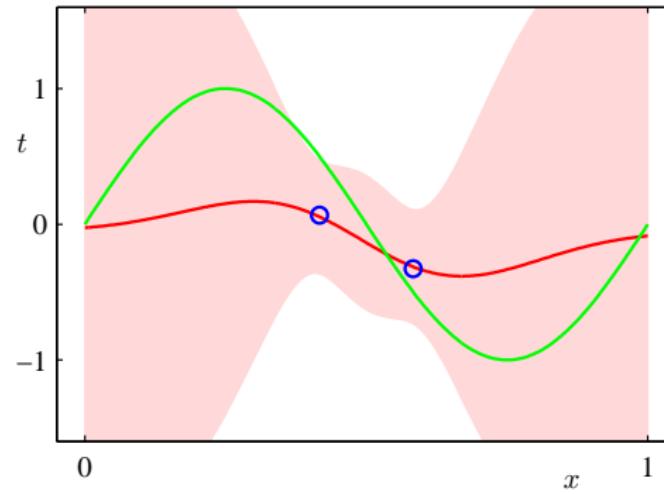
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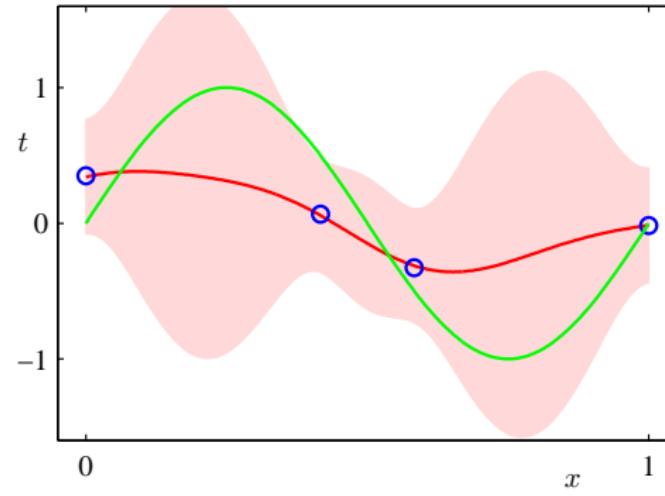
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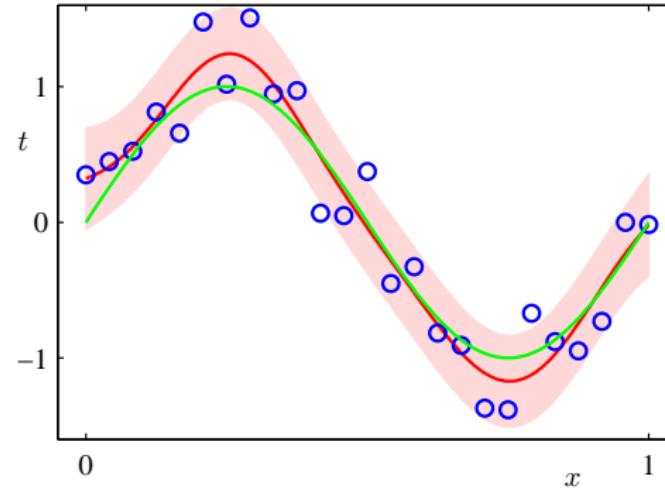
$$P(\tilde{t}|\tilde{x}, \mathbf{x}, \mathbf{t}) = \int_{\mathbf{w}} P(\tilde{t}|\tilde{x}, \mathbf{w})P(\mathbf{w}|\mathbf{x}, \mathbf{t})$$



Prediction

Predict the value for a new point:

$$P(\tilde{t}|\tilde{x}, \mathbf{x}, \mathbf{t}) = \int_{\mathbf{w}} P(\tilde{t}|\tilde{x}, \mathbf{w})P(\mathbf{w}|\mathbf{x}, \mathbf{t})$$



Summary

Linear regression:

- ▶ linear combination of basis functions,
- ▶ linear system of equation,
- ▶ overfitting;

Regularization:

- ▶ penalize big weights,
- ▶ still linear system,
- ▶ choice of regularization parameter;

Probabilistic formulation:

- ▶ Gaussian noise,
- ▶ MLE is regression,
- ▶ Gaussian prior,
- ▶ MAP is regularization.