

Modular polynomials for abelian surfaces and related algorithms

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KULB seminar, Leuven, May 17, 2024

Classical modular polynomials

Fix $\ell \geq 1$ prime. The **classical modular polynomial** of level ℓ

$$\Phi_\ell \in \mathbb{Z}[X, Y]$$

satisfies: if k is a field of char. $\neq \ell$, and E, E' are elliptic curves over k , then

$$\Phi_\ell(j(E), j(E')) = 0 \iff E \text{ and } E' \text{ are } \ell\text{-isogenous over } \bar{k}.$$

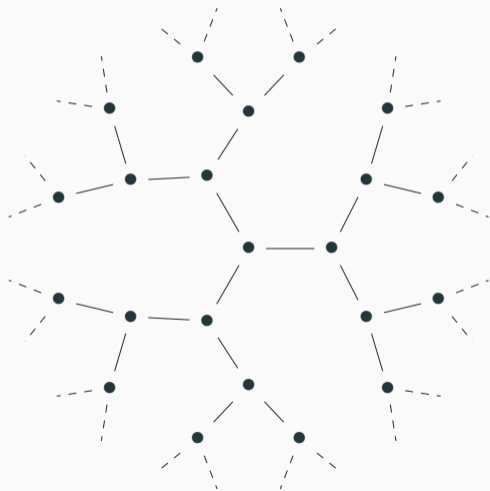
Example

$$\begin{aligned} \Phi_2(X, Y) = & X^3 + Y^3 - X^2Y^2 + 1488X^2Y + 1488XY^2 - 162000X^2 - 162000Y^2 \\ & + 40773375XY + 8748000000X + 8748000000Y - 15746400000000. \end{aligned}$$

Used to navigate isogeny graphs and compute isogenies.

Navigating isogeny graphs

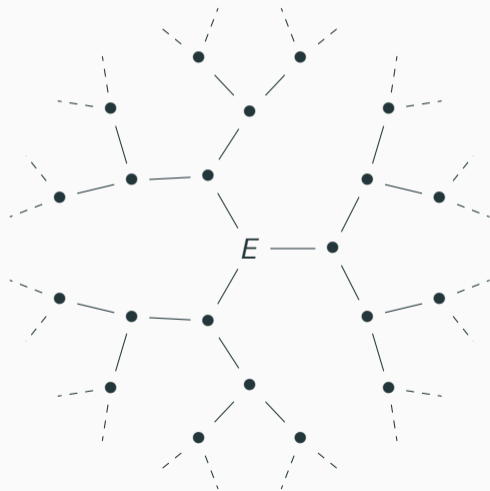
2-isogeny graph of supersingular elliptic curves over \mathbb{F}_{p^2} :



Navigating isogeny graphs

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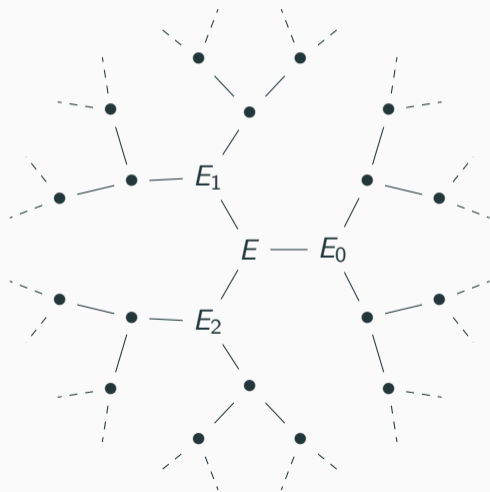
- Starting point: E



Navigating isogeny graphs

2-isogeny graph of supersingular elliptic curves over \mathbb{F}_{p^2} :

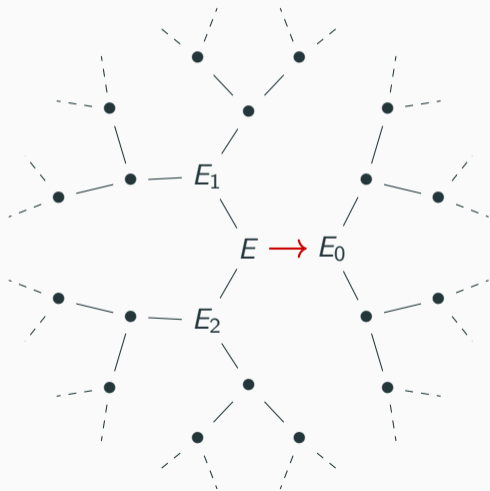
- Starting point: E
- Solve $\Phi_2(j(E), Y) = 0$ in \mathbb{F}_{p^2} :
find 3 roots



Navigating isogeny graphs

2-isogeny graph of supersingular elliptic curves over \mathbb{F}_{p^2} :

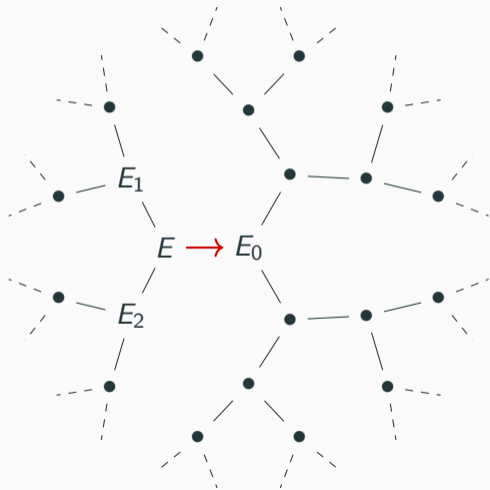
- Starting point: E
- Solve $\Phi_2(j(E), Y) = 0$ in \mathbb{F}_{p^2} :
find 3 roots
- Pick path to E_0 , say



Navigating isogeny graphs

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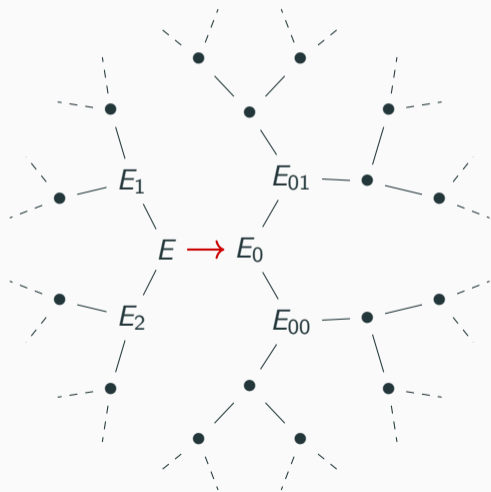
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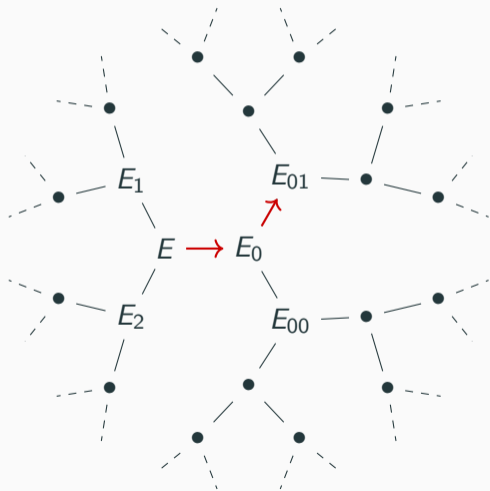
- Starting point: E
- Solve $\Phi_2(j(E), Y) = 0$ in \mathbb{F}_{p^2} :
find 3 roots
- Pick path to E_0 , say
- Solve $\Phi_2(j(E_0), Y)/(Y - j(E)) = 0$:
find 2 roots $j(E_{00}), j(E_{01})$



Navigating isogeny graphs

2-isogeny graph of supersingular elliptic curves over \mathbb{F}_{p^2} :

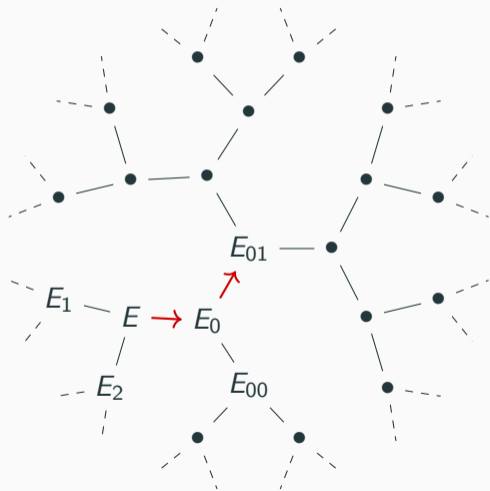
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Navigating isogeny graphs

2-isogeny graph of supersingular elliptic curves over \mathbb{F}_{p^2} :

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- Solve $\Phi_2(j(E), Y) = 0$ in \mathbb{F}_{p^2} :
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- Pick path to E_0 , say
- Solve $\Phi_2(j(E_0), Y)/(Y - j(E)) = 0$:
find 2 roots $j(E_{00}), j(E_{01})$
- Pick path to E_{01} , say
- Continue!



Theorem (Elkies '95, Bostan–Morain–Salvy–Schost '08)

- ℓ prime, k a field of char. 0 or $> 4\ell + 1$.
- E, E' elliptic curves over k that are ℓ -isogenous.
- Assume $\partial_X \Phi_\ell(j(E), j(E')) \neq 0$, i.e. $j(E')$ is a simple root of $\Phi_\ell(j(E), Y)$.
This is true generically.

Then, given E, E' and $\partial_X \Phi_\ell(j(E), j(E'))$, one can compute **polynomial formulas** for the ℓ -isogeny

$$\varphi : E \rightarrow E',$$

in particular an equation of $\ker \varphi$, in $\tilde{O}(\ell)$ operations in k (quasi-linear time.)

Complexity bounds

The **height** of $F \in \mathbb{Q}(X_1, \dots, X_n)$ is

$$h(F) = \log(\max |c|), \quad \text{where } c \text{ runs through the coefficients of } F.$$

Complexity bounds for Φ_ℓ

- Φ_ℓ has degree $\ell + 1$ in both variables X and Y .
- $h(\Phi_\ell) \sim 6\ell \log \ell$ [Cohen '84]. Storing Φ_ℓ costs $O(\ell^3 \log \ell)$ space.
- Φ_ℓ can be computed in quasi-linear time $\tilde{O}(\ell^3)$ [Enge '09, Bröker–Lauter–Sutherland '12, Sutherland '13].

In summary:

- Φ_ℓ allow us to manipulate isogenies **without torsion input**.
- **Cheaper** than computing (subgroups of) $E[\ell]$ from scratch: e.g. the **SEA algorithm** (Schoof–Elkies–Atkin '90s) computes $\#E(\mathbb{F}_q)$ in time $\tilde{O}(\log^4 q)$.

State of the art

	dim 1	dim 2	dim g
Definition of Φ_ℓ	✓		
Complexity bounds	✓		
Evaluating $\Phi_\ell(j(E), Y)$	✓		
Isogenies without torsion input	✓		
Point counting	✓		
More compact variants of Φ_ℓ	✓	Atkin, ...	

Higher dimensions

State of the art

	dim 1	dim 2	dim g
Definition of Φ_ℓ	✓	✓ Bröker–Lauter '09, ...	
Complexity bounds	✓		
Evaluating $\Phi_\ell(j(E), Y)$	✓		
Isogenies without torsion input	✓		
Point counting	✓		
More compact variants of Φ_ℓ	✓	Atkin, ...	

State of the art

	dim 1	dim 2	dim g
Definition of Φ_ℓ	✓	✓ Bröker–Lauter '09, ...	✓ K. '22
Complexity bounds	✓	✓ K. '22	✓ K. '22
Evaluating $\Phi_\ell(j(E), Y)$	✓	✓ K. '2?	? partial
Isogenies without torsion input	✓	✓ K., Page, Robert '2?	? dim 3?
Point counting	✓	✓ K. '2?	? RM?
More compact variants of Φ_ℓ	✓ Atkin, ...	? Theta functions?	??

Goals of this talk

- Generalize Φ_ℓ using the geometry of **moduli spaces**.
- Briefly talk about complexity bounds and computing isogenies.
- Present the **evaluation algorithm**, its performance and applications.

Geometric interpretation of Φ_ℓ (1)

It is easier to work over \mathbb{C} .

- \mathcal{H}_1 is the upper half plane $\{\text{Im}(\tau) > 0\}$. Action of $\text{SL}_2(\mathbb{Z})$ on \mathcal{H}_1 :

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \tau = \frac{a\tau + b}{c\tau + d}.$$

$\mathcal{A}_1 = \text{SL}_2(\mathbb{Z}) \backslash \mathcal{H}_1$ is the **moduli space of elliptic curves**. It is an algebraic variety defined over \mathbb{Q} . We view the j -invariant as a **coordinate** on \mathcal{A}_1 .

- Let $\Gamma^0(\ell) \subset \text{SL}_2(\mathbb{Z})$ be the subgroup of matrices such that $b = 0 \pmod{\ell}$. It has index $\ell + 1$ in $\text{SL}_2(\mathbb{Z})$.

The quotient $\mathcal{A}_1(\ell) = \Gamma^0(\ell) \backslash \mathcal{H}_1$ is the **moduli space of pairs (E, K)** where $K \subset E$ is the kernel of an ℓ -isogeny. It is a more complicated curve than \mathcal{A}_1 .

Geometric interpretation of Φ_ℓ (2)

We have **two maps** $\mathcal{A}_1(\ell) \rightarrow \mathcal{A}_1$, both $(\ell + 1)$ -to-one:

	$\mathcal{A}_1(\ell) \rightarrow \mathcal{A}_1$	$\Gamma^0(\ell) \backslash \mathcal{H}_1 \rightarrow \mathrm{SL}_2(\mathbb{Z}) \backslash \mathcal{H}_1$
“Domain” map	$(E, K) \mapsto E$	$\tau \mapsto \tau$
“Codomain” map	$(E, K) \mapsto E/K$	$\tau \mapsto \tau/\ell$.

Geometric interpretation

Φ_ℓ is an equation for the image in $\mathcal{A}_1 \times \mathcal{A}_1$ of the joint map

$$\begin{aligned}\mathcal{A}_1(\ell) &\rightarrow \mathcal{A}_1 \times \mathcal{A}_1 \\ (E, K) &\mapsto (E, E/K),\end{aligned}$$

using the j -invariant as a coordinate on \mathcal{A}_1 .

For every $\tau \in \mathcal{H}_1$,

$$\Phi_\ell(j(\tau), Y) = \prod_{\gamma \in \Gamma^0(\ell) \backslash \Gamma(1)} \left(Y - j\left(\frac{1}{\ell}\gamma\tau\right) \right).$$

Modular polynomials for abelian surfaces (1)

- \mathcal{A}_2 is the moduli space of **principally polarized abelian surfaces**.
 \mathcal{A}_2 is an algebraic variety defined over \mathbb{Q} of dimension 3, consisting of **Jacobians** of genus 2 curves (dense open) and **products** $E_1 \times E_2$ (dimension 2 subvariety).
- The **Igusa invariants** j_1, j_2, j_3 are convenient coordinates on \mathcal{A}_2 .
- $\mathcal{A}_2(\ell)$ is the moduli space of pairs (A, K) where K is the kernel of an (ℓ, ℓ) -isogeny, i.e. $K \subset A[\ell]$ is isomorphic to $(\mathbb{Z}/\ell\mathbb{Z})^2$ and isotropic for the Weil pairing.

Modular polynomials for abelian surfaces

The **Siegel modular polynomials** $\Psi_{\ell,1}, \Psi_{\ell,2}, \Psi_{\ell,3}$ are equations for the image of

$$\begin{aligned} \mathcal{A}_2(\ell) &\rightarrow \mathcal{A}_2 \times \mathcal{A}_2 \\ (A, K) &\mapsto (A, A/K) \end{aligned}$$

using the Igusa invariants as coordinates on \mathcal{A}_2 .

Modular polynomials for abelian surfaces (2)

The image of $\mathcal{A}_2(\ell)$ is a dimension 3 subvariety in a dimension 6 ambient space, so has several possible sets of equations.

Choose the polynomials $\Psi_{\ell,k}$ such that $\Psi_{\ell,k} \in \mathbb{Q}(X_1, X_2, X_3)[Y]$ and

$$\Psi_{\ell,1}(j_1(A), j_2(A), j_3(A), j_1(A/K)) = 0,$$

$$j_2(A/K) = \frac{\Psi_{\ell,2}}{\partial_Y \Psi_{\ell,1}}(j_1(A), j_2(A), j_3(A), j_1(A/K)), \quad \text{and same for } j_3.$$

Note

- Computing the isogenous abelian surfaces is easy (no Gröbner bases!)
- Convenient **analytic formulas** as in the case of Φ_ℓ .
- Can play the same game with any moduli space of abelian varieties: any dimension g , real multiplication, level structures, etc. **PEL Shimura varieties**.

State of the talk

	dim 1	dim 2	dim g
Definition of Φ_ℓ	✓	✓ Bröker–Lauter '09, ...	✓ K. '22
Complexity bounds	✓		
Evaluating $\Phi_\ell(j(E), Y)$	✓		
Isogenies without torsion input	✓		
Point counting	✓		
More compact variants of Φ_ℓ	✓ Atkin, ...	? Theta functions?	??

Complexity bounds

Recall: $\Psi_{\ell,k} \in \mathbb{Q}(X_1, X_2, X_3)[Y]$ for $1 \leq k \leq 3$.

Theorem (K. '22)

- The degree of $\Psi_{\ell,k}$ in each variable is $O(\ell^3)$. Tight explicit bounds.
- $h(\Psi_{\ell,k}) = O(\ell^3 \log \ell)$. Explicit bounds (huge, not tight).

A general theorem applies to modular polynomials on any PEL Shimura variety.

Corollary

- The size of $\Psi_{\ell,k}$ as a 4-variable fraction is $O(\ell^{15} \log \ell)$. [Note: 410 MB for $\ell = 3$]
- If $j_1, j_2, j_3 \in \mathbb{Q}$, the size of $\Psi_{\ell,k}(j_1, j_2, j_3, Y) \in \mathbb{Q}[Y]$ is $O(\ell^6(H + \log \ell))$ where $H = \max\{h(j_1), h(j_2), h(j_3)\}$.

We need an algorithm to **evaluate the modular polynomials** at (j_1, j_2, j_3) directly!

Theorem (K., Page, Robert)

- ℓ prime, k a field of char. 0 or $> 8\ell + 7$.
- A, A' Jacobians of genus 2 curves over k that are (ℓ, ℓ) -isogenous.
- Assume that the 3×3 matrix $(\partial_{X_i} \Psi_{\ell, k})_{i, k}$ evaluated at the Igusa invariants of A, A' is invertible. This is true generically.

Then, given A, A' and the above matrix, one can compute **polynomial formulas** for the (ℓ, ℓ) -isogeny

$$\varphi : A \rightarrow A'$$

in $\tilde{O}(\ell)$ operations in k (quasi-linear time).

One can then compute $\ker(\varphi)$ using polynomial arithmetic (resultants...)

The evaluation algorithm should also evaluate the derivatives of $\Psi_{\ell, k}$.

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Isogenies without torsion input	✓	✓ K., Page, Robert '2?	? dim 3?
Point counting	✓		
More compact variants of Φ_ℓ	✓ Atkin, ...	? Theta functions?	??

The evaluation algorithm

Analytic formula

Recall: for $\tau \in \mathcal{H}_1$,

$$\Phi_\ell(j(\tau), Y) = \prod_{\gamma \in \Gamma^0(\ell) \backslash \mathrm{SL}_2(\mathbb{Z})} \left(Y - j\left(\frac{1}{\ell}\gamma\tau\right) \right).$$

Similar formula in dimension 2:

- $\mathcal{H}_2 = \{\tau \in \mathrm{Mat}_{2 \times 2}(\mathbb{C}) : \tau \text{ symmetric, } \mathrm{Im} \tau \text{ pos. def.}\}$: Siegel upper half space.
- The symplectic group $\mathrm{Sp}_4(\mathbb{Z})$ acts on \mathcal{H}_2 : in block notation,

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \tau = (a\tau + b)(c\tau + d)^{-1}.$$

- Subgroup $\Gamma^0(\ell) \subset \mathrm{Sp}_4(\mathbb{Z})$ defined by $b = 0 \pmod{\ell}$, with index $\ell^3 + \ell^2 + \ell + 1$.

For instance: for $\tau \in \mathcal{H}_2$,

$$\Psi_{\ell,1}(j_1(\tau), j_2(\tau), j_3(\tau), Y) = \prod_{\gamma \in \Gamma^0(\ell) \backslash \mathrm{Sp}_4(\mathbb{Z})} \left(Y - j_1\left(\frac{1}{\ell}\gamma\tau\right) \right).$$

The evaluation algorithm

Let $j_1, j_2, j_3 \in \mathbb{Q}$ of height H be given.

1. Find $\tau \in \mathcal{H}_2$ with these Igusa invariants (a **period matrix**) at **high precision**.
 2. Enumerate the matrices $\frac{1}{\ell}\gamma\tau$ and compute their Igusa invariants.
 3. Compute the modular polynomials in $\mathbb{C}[Y]$ using the analytic formula.
 4. Recognize each coefficient as a **rational number**.
- This algorithm has been implemented in C using the libraries FLINT/Arb.
 - We use **interval arithmetic** throughout to ensure correctness. In step 4, we can actually get **integers** instead of rational numbers.
 - In step 1, we use the AGM method (Dupont '06) with some improvements.
 - Step 2 dominates the algorithm and relies on **theta functions**: stay tuned.

Theorem (K.)

We can evaluate the Siegel modular polynomials of level ℓ and their derivatives at

- 1. a generic point $(j_1, j_2, j_3) \in \mathbb{Q}^3$ of height at most H in time $\tilde{O}(\ell^3 H^2 + \ell^6 H)$,*
- 2. a generic point $(j_1, j_2, j_3) \in \mathbb{F}_p^3$ for p prime in time $\tilde{O}(\ell^3 \log^2 p + \ell^6 \log p)$.*

This is **almost quasi-linear time**.

“Generic” means that the algorithm will fail on a closed dimension 2 subvariety of \mathcal{A}_2 (e.g. Igusa invariants not defined...)

Proof of 2.: lift to \mathbb{Q} and apply 1.! To handle \mathbb{F}_q , we extend 1. to number fields.

Practical timings

Time to evaluate $\Psi_{\ell,k}(j_1, j_2, j_3, Y)$ at $(j_1, j_2, j_3) =$ random 3-digit rational numbers:

ℓ	2	3	5	7	11	13	17
Time (s)	1.3	5.1	97	1200	40000	$1.6 \cdot 10^5$	$1.1 \cdot 10^6$
$0.002 \ell^6 \log^3(\ell) \log \log(\ell)$	-	-	62	1200	43000	$1.5 \cdot 10^5$	$1.1 \cdot 10^6$

Using related methods, we computed a Jacobians of genus 2 curves over \mathbb{Q} linked by isogenies of large degree, e.g. $(19^2, 19, 19)$ or $(31, 31)$, in roughly 1h (van Bommel, Costa, Chidambaram, K. '24).

Consequences on point counting

Results

- If A is a p.p. abelian surface over \mathbb{F}_p with **small Igusa invariants**, then we compute $\#A(\mathbb{F}_p)$ in heuristic time $\tilde{O}(\log^7 p)$. Improves on Schoof's method in $\tilde{O}(\log^8 p)$ (Gaudry–Schost '12)
- If A/\mathbb{Q} is fixed, then we can compute $\#A(\mathbb{F}_p)$ for several primes p (in fact $\Omega(H \log p)$ of them) in **average time** $\tilde{O}(\log^6 p)$.
- If A/\mathbb{F}_p has **real multiplication** by $\mathbb{Q}(\sqrt{5})$ or another small real quadratic field, then we compute $\#A(\mathbb{F}_p)$ in time $\tilde{O}(\log^4 p)$ as in the dimension 1 case.

I still need an **implementation** to (hopefully) establish a new point-counting record.

Theta functions

Theta functions

Recall: in the evaluation algorithm, we get matrices $\tau_1, \dots, \tau_n \in \mathcal{H}_2$. We need to **evaluate their Igusa invariants** in \mathbb{C} at high precision N , i.e. up to an error of $\leq 2^{-N}$.

We do this in **quasi-linear time** $O(\mathcal{M}(N) \log N)$ using theta functions.

Definition

Fix theta characteristics $a, b \in \{0, 1\}^g$. Then

$$\theta_{a,b}(\tau) = \sum_{n \in \mathbb{Z}^g + \frac{a}{2}} \exp(i\pi(n^T \tau n + n^T b)).$$

- They are 2^{2g} analytic functions on \mathcal{H}_g (16 for $g = 2$.)
- Coordinates on \mathcal{A}_g , e.g. the Igusa invariants, can be expressed as rational fractions in terms of theta functions.

Main theorem on theta functions

Theorem (Elkies, K., in preparation)

Given $g \geq 1$, $N \geq 0$, and given $\tau \in \mathcal{H}_g$ and $z \in \mathbb{C}^g$ that are suitably reduced, one can evaluate $\theta_{a,b}(z, \tau)$ for all characteristics (a, b) to precision N in **quasi-linear time** $O(2^{O(g \log g)} \mathcal{M}(N) \log N)$, **uniformly** in τ and z .

- Implemented in FLINT 3.1: https://flintlib.org/doc/acb_theta.html
- The “naive” algorithm (sum the exponential series) is **not** quasi-linear.
- Earlier works (Dupont '06, Labrande–Thomé '14) are specific to small g and tricky to run in interval arithmetic. This new algorithm is $\sim 10\times$ faster for $g = 2$. The timings above were with Dupont’s algorithm.
- When evaluating modular polynomials, we add a (negligible) reduction step.
- For general g , how do we compute τ in the first place?

Thank you for listening!
Any questions?

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