

# Development of a parallelized open-source python library for synthetic diagnostics and inversions for fusion devices

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## Context: Energy generation



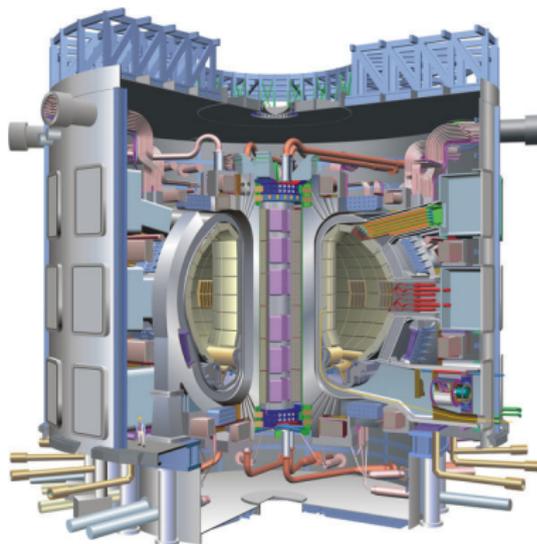
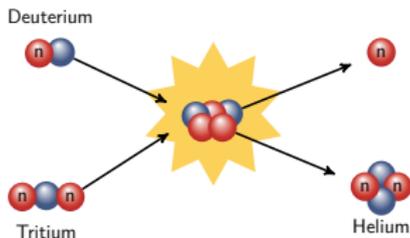
Current solutions present some drawbacks:

- Limited resources
- Production of carbon dioxide
- Radioactive waste
- Not too efficient
- Harmful to surrounding environment

⇒ Fusion reactor: cleaner, more reliable, more powerful energy source ?

# Context: Controlled fusion and magnetic confinement

## D-T Fusion reaction



Temperature  $> 100$  Million $^{\circ}$ K.

⇒ Gas composed of positive ions and negative electrons: plasma

⇒ Plasma responds strongly to electromagnetic fields

⇒ Energy breakeven point still not obtained:  $Q = \frac{E_{\text{output}}}{E_{\text{input}}} = 0.67$

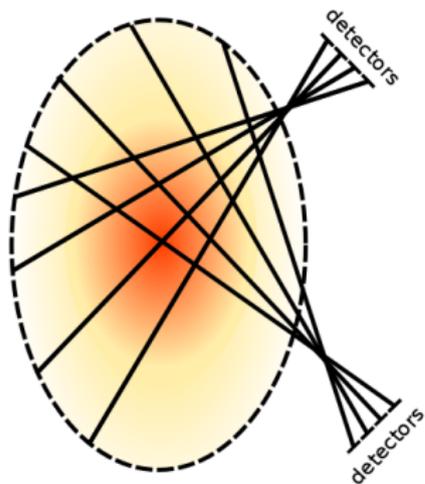
⇒ Current reactors: different shapes, sizes, heating methods, confinement techniques, etc.

# Toakmak diagnostics

- **Diagnostics:** Set of instruments to measure for the understanding, control and optimization of the plasma performance.
- Magnetic diagnostics: currents, plasma stored energy, plasma shape and position;
- Neutron diagnostics (ie. cameras, spectrometers, etc.): fusion power;
- Optical systems (interferometers): temperature and density profiles;
- Bolometric systems (tomography): spatial distribution of radiated power;
- Spectroscopic: X-ray wavelength range, impurity species and density, input particle flux, ion temperature, helium density, fuelling ratio, plasma rotation, and current density.
- Microwave diagnostics probe the main plasma and the plasma in the divertor region in order to measure plasma position.

# Tomography diagnostics

$$M_i(t) = \iiint_{V_i} \overrightarrow{\varepsilon}(x, t) \cdot \vec{n} \Omega_i dV$$



- **Direct problem** (synthetic diagnostic):

Simulated emissivity  $\rightarrow$  integrated measurements

**Spatial integration**

- **Inverse problem** (tomography):

Integrated measurements  $\rightarrow$  Reconstructed emissivity

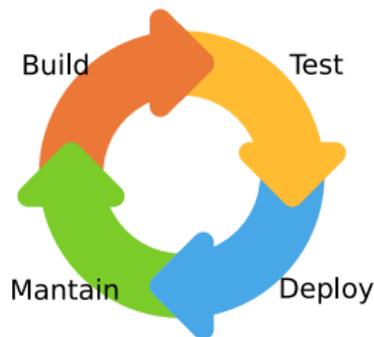
**Mesh and basis functions construction, spatial integration, data filtering, inversion routines, etc.**

Tomography very sensitive to errors, noise and bias  
 $\rightarrow$  **Reputation for low reproducibility / reliability**

# A code for Tomography for Fusion

## Develop a common tool:

- Accessible to everyone (open-source)
- Generic (geometry independent)
- Portable (developped in Python)
- Optimized (reliability and performance)
- Documented online
- Standardization of diagnostics
- Long-term costs saving to the community



**For tomography diagnostics:** The **Tomography for Fusion** code  
(**ToFu<sup>ab</sup>**)

<sup>a</sup>repository: <https://github.com/ToFuProject/tofu>

<sup>b</sup>documentation: <https://tofuproject.github.io/tofu/index.html>



# Geometry reconstruction: ray-tracing techniques

To reconstruct emissivity we need to take account:

- Geometry defined with minimal data  
polygon  $(R, Z)$  extruded along  $\varphi$
- Symmetry of vessel along  $\varphi$
- Upto hundreds of structural elements in vessel
- Scale of the vessel:  $10^4$  bigger than smaller structural detail

