

# Randomized algorithms for Delaunay triangulations

- Randomized backward analysis of binary trees
- Randomized incremental construction of Delaunay
- Jump and walk
- The Delaunay hierarchy
- Biased randomized incremental order
- Chew algorithm for convex polygon



# Sorting

$-\infty$

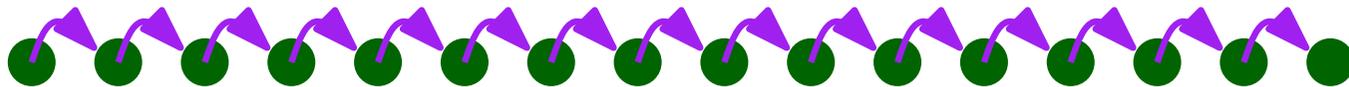


$\infty$

3 - 1

# Sorting

$-\infty$



$\infty$

3 - 2

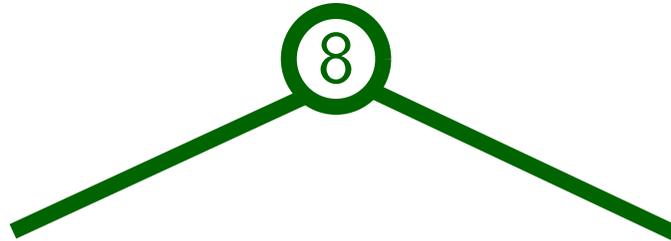
# Sorting

## Binary tree



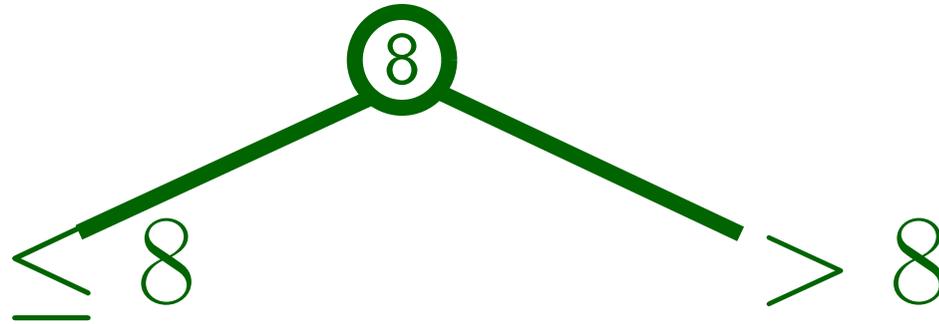
# Sorting

## Binary tree



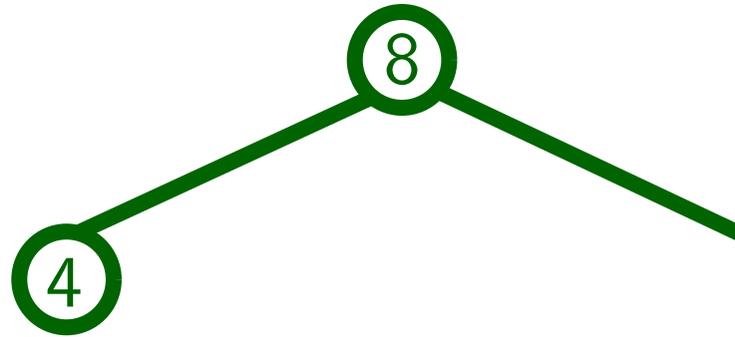
# Sorting

## Binary tree



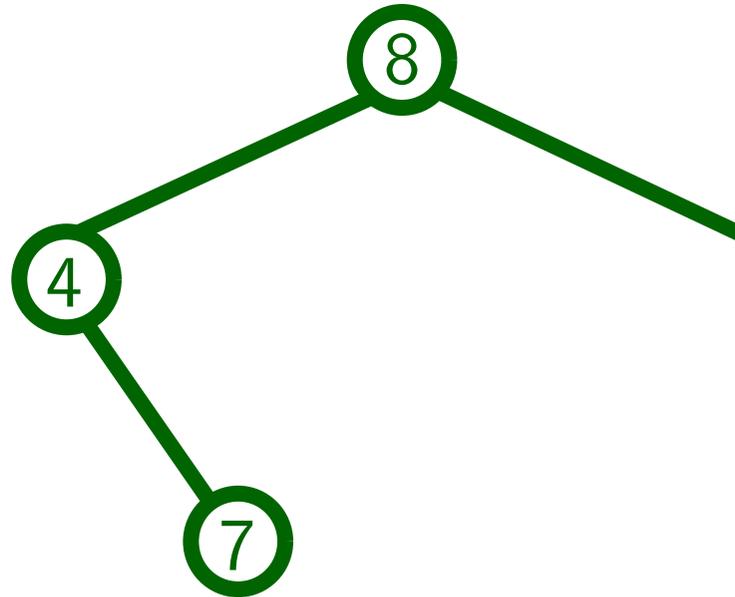
# Sorting

## Binary tree



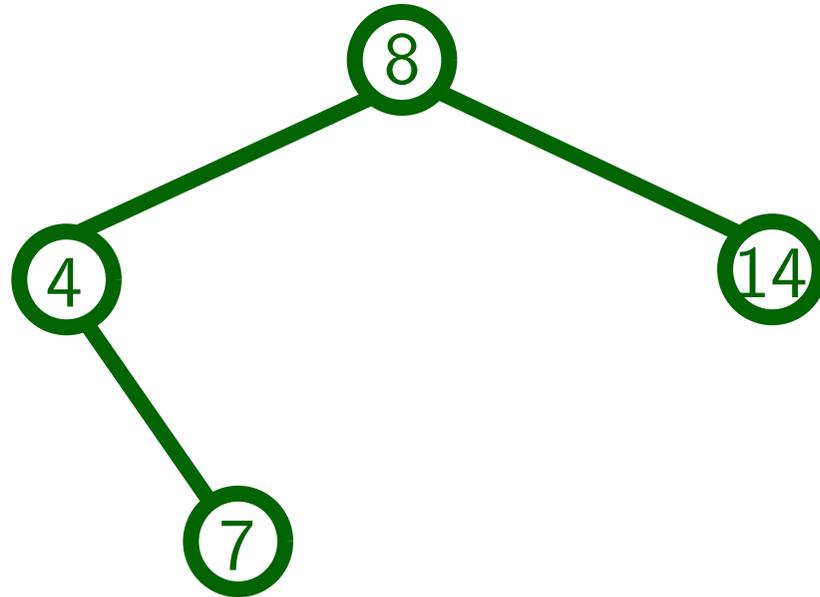
# Sorting

## Binary tree



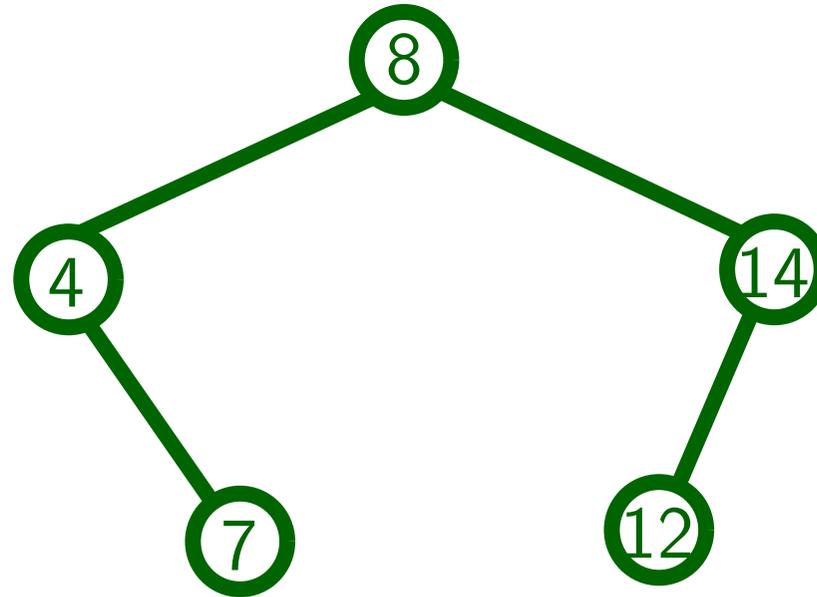
# Sorting

## Binary tree



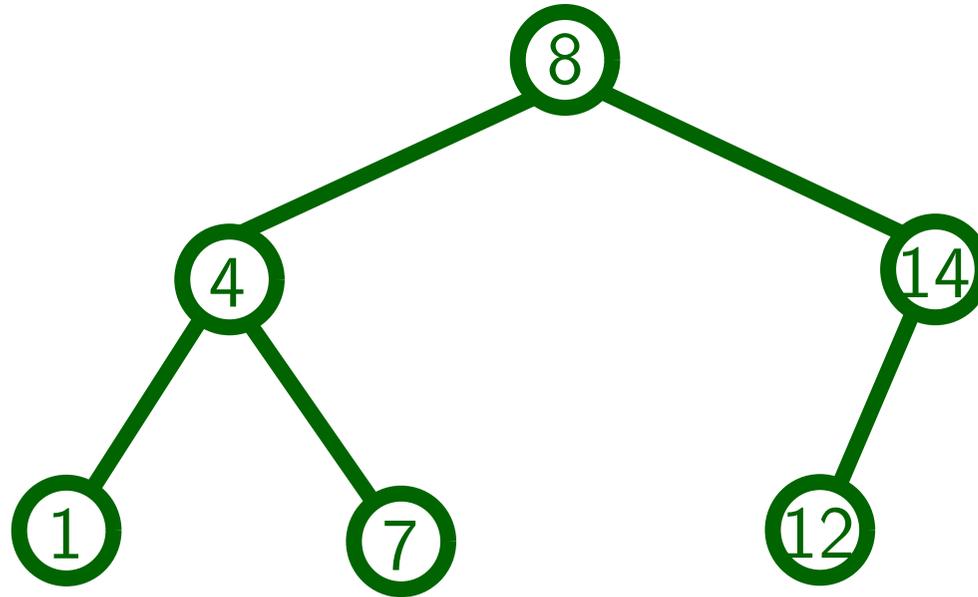
# Sorting

## Binary tree



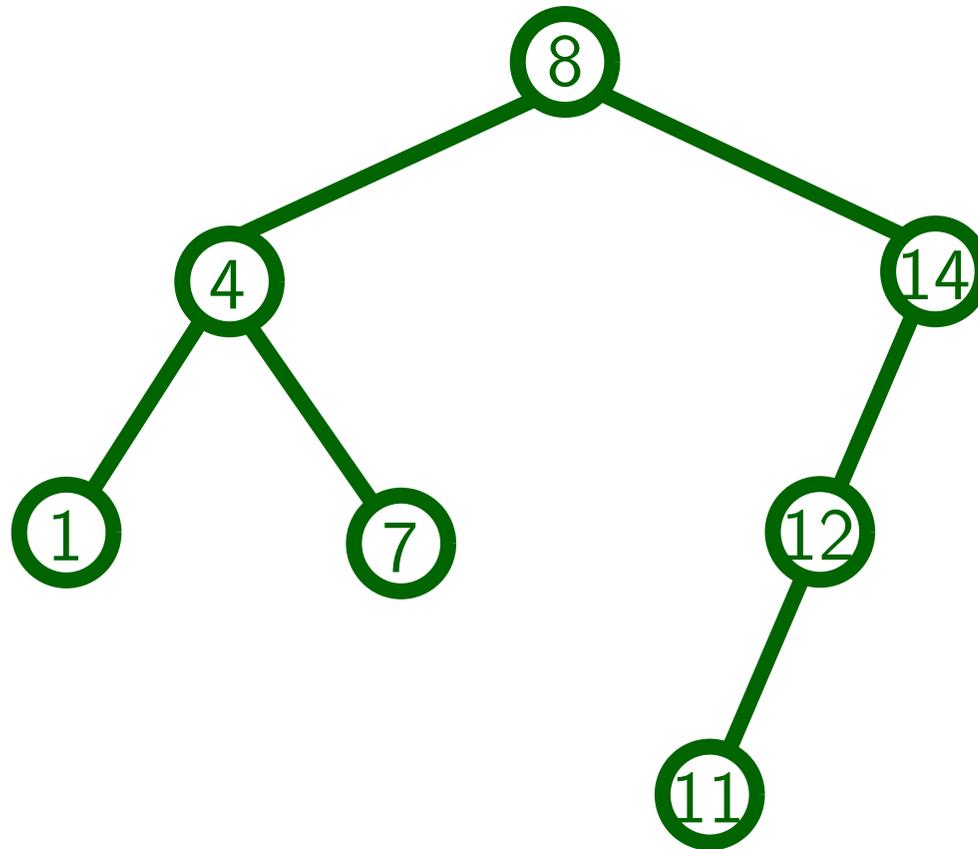
# Sorting

## Binary tree



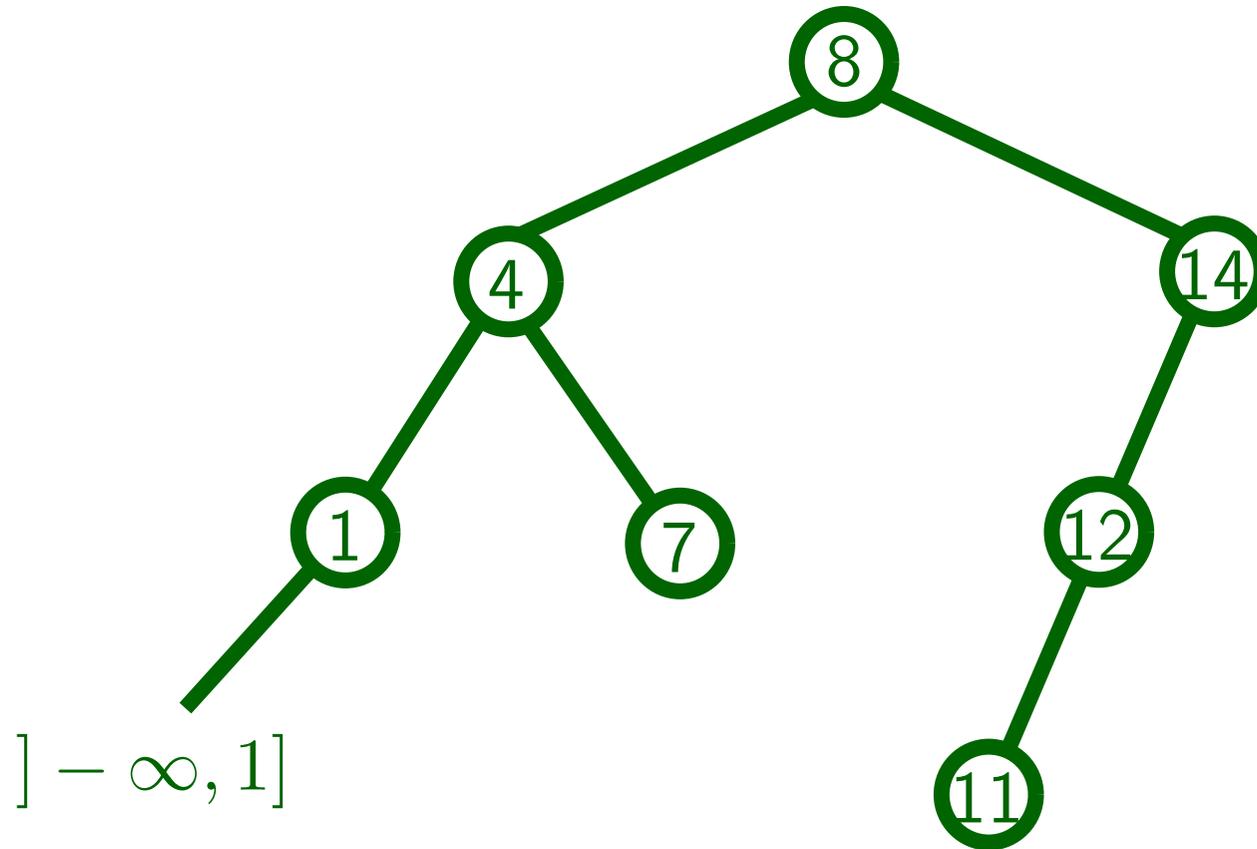
# Sorting

## Binary tree



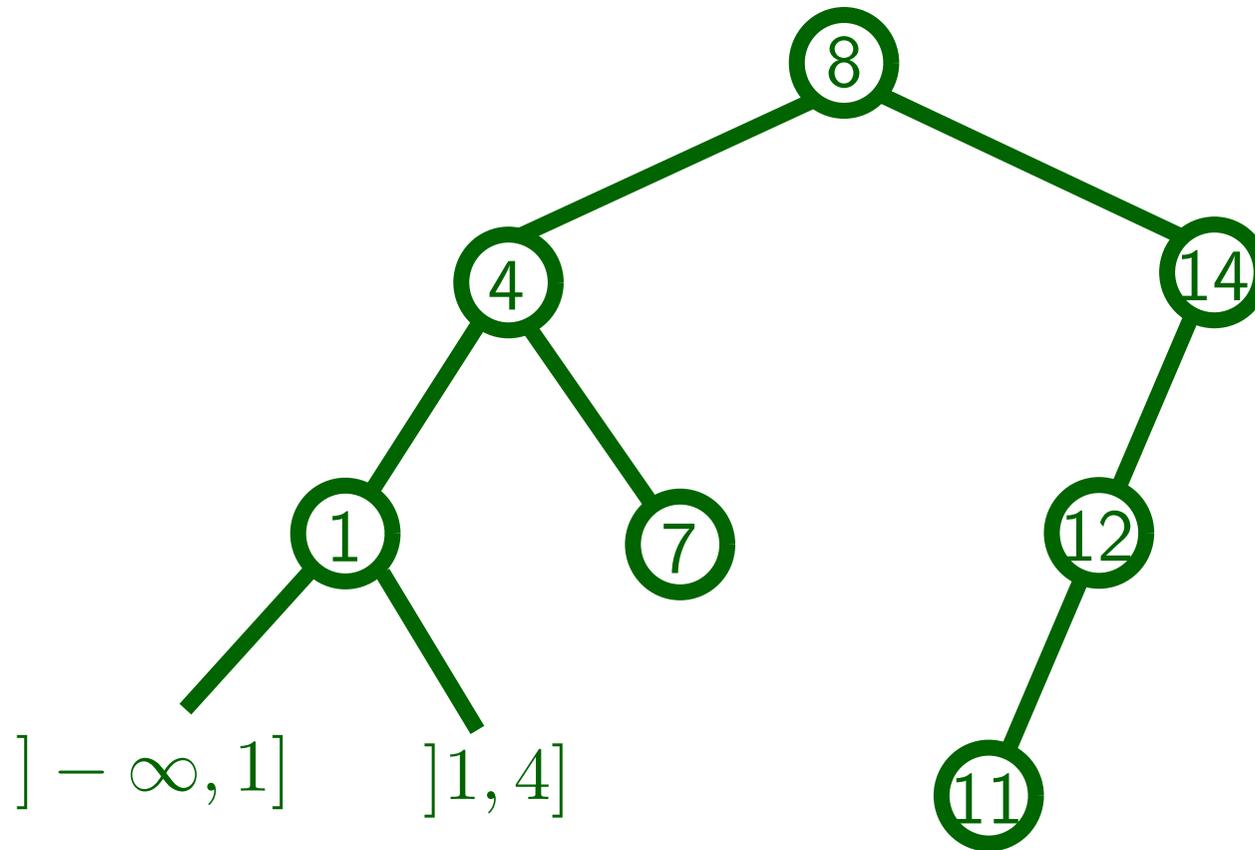
# Sorting

## Binary tree



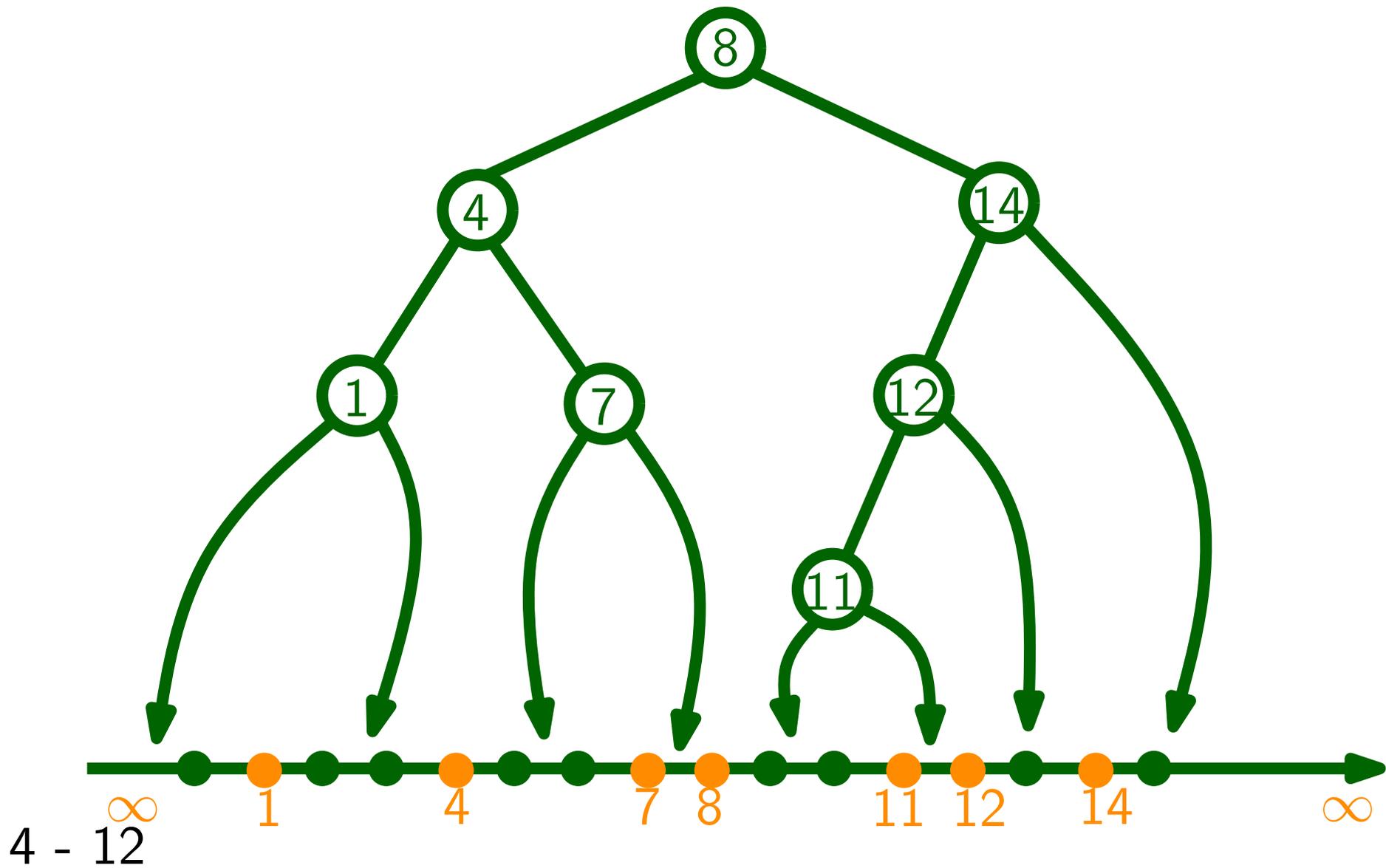
# Sorting

## Binary tree



# Sorting

## Binary tree



# Sorting

1

8

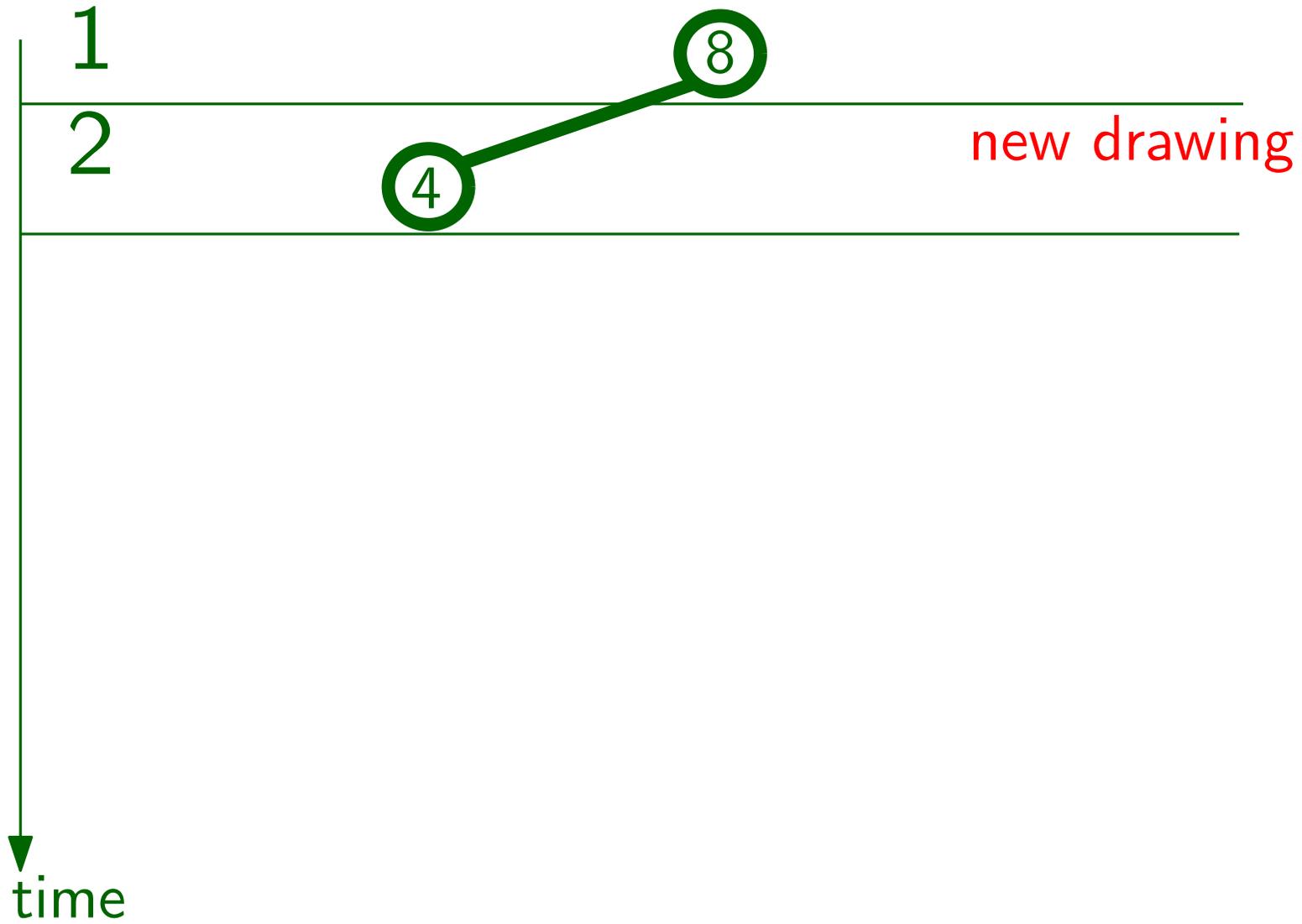
new drawing



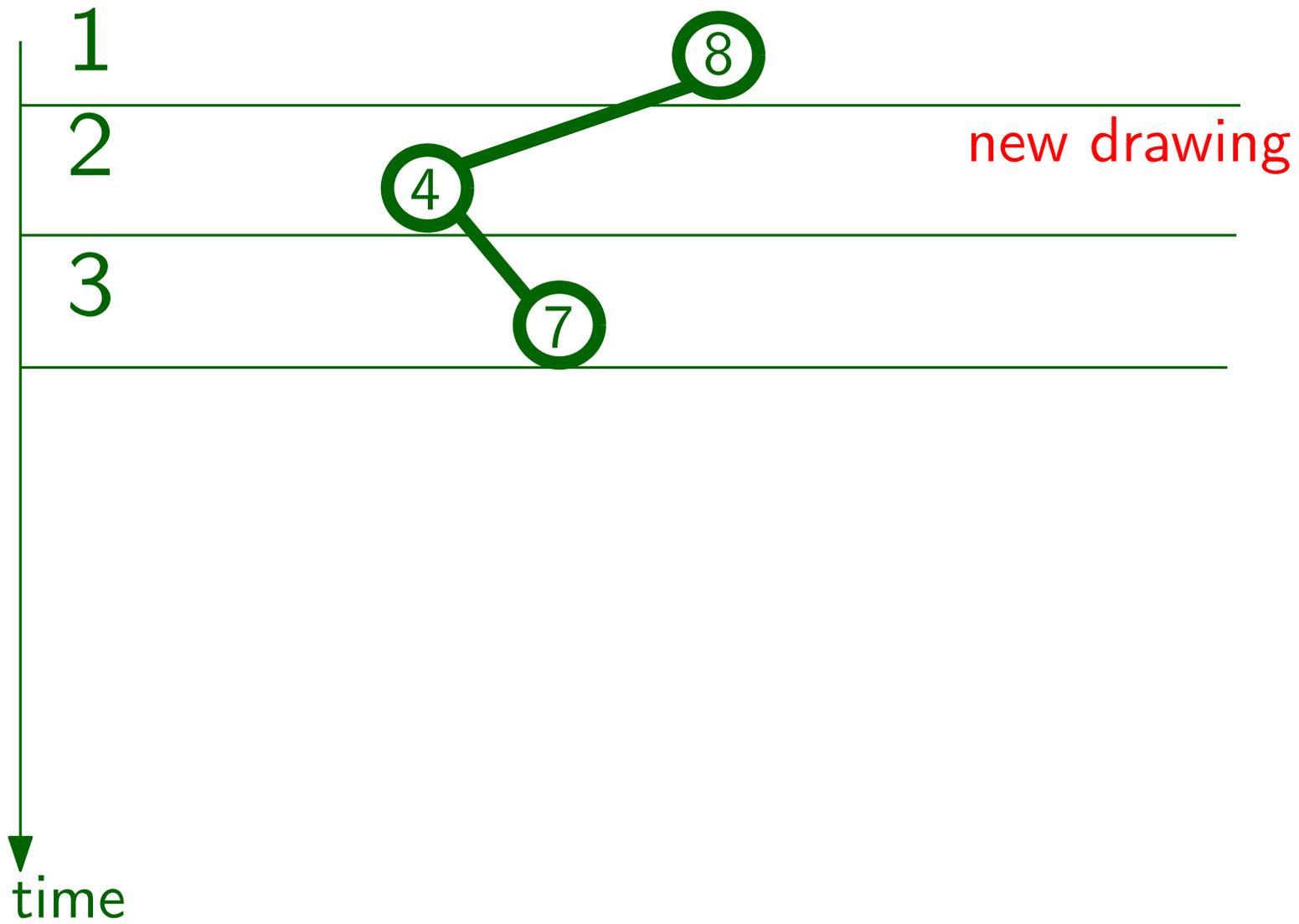
time

5 - 1

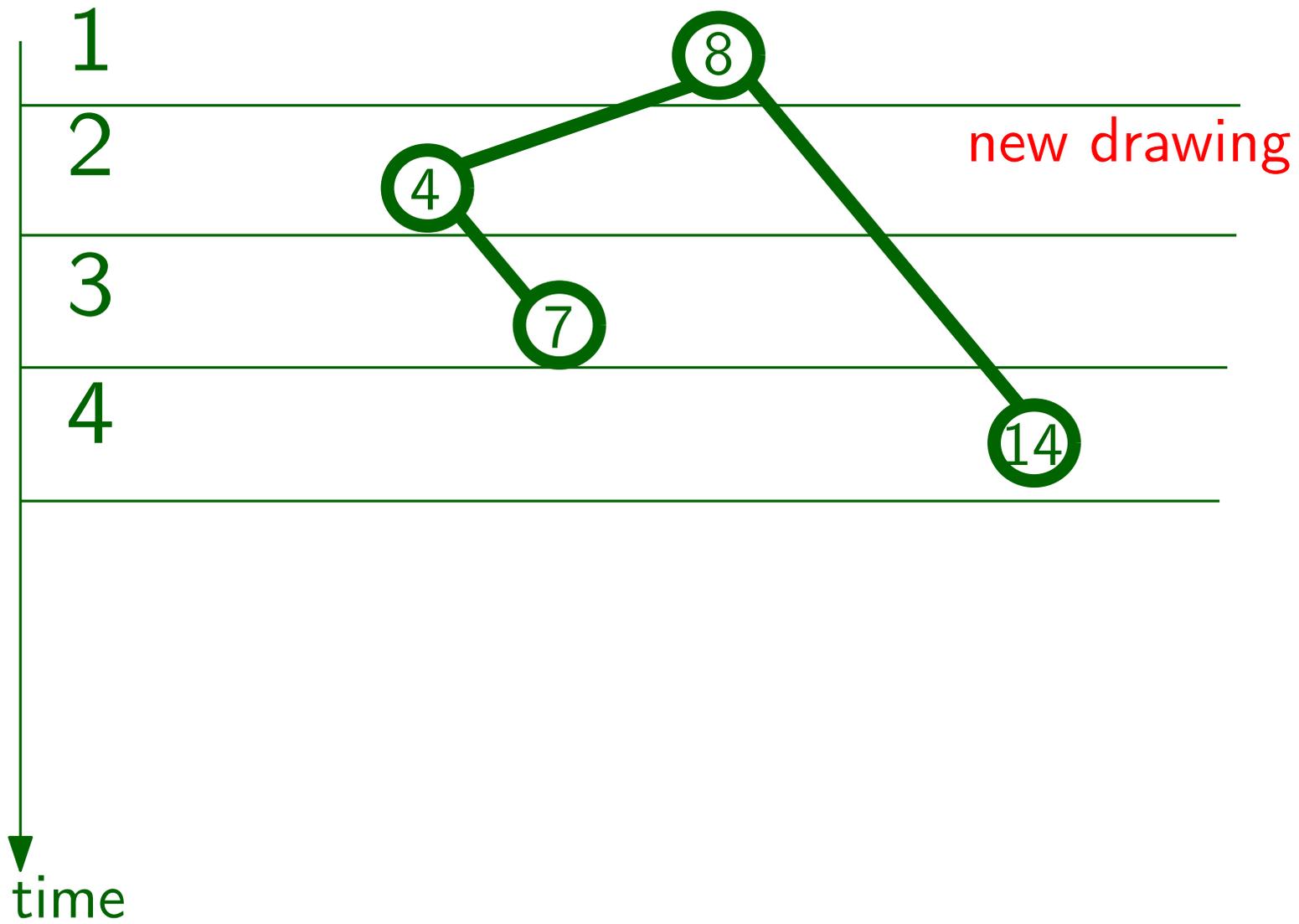
# Sorting



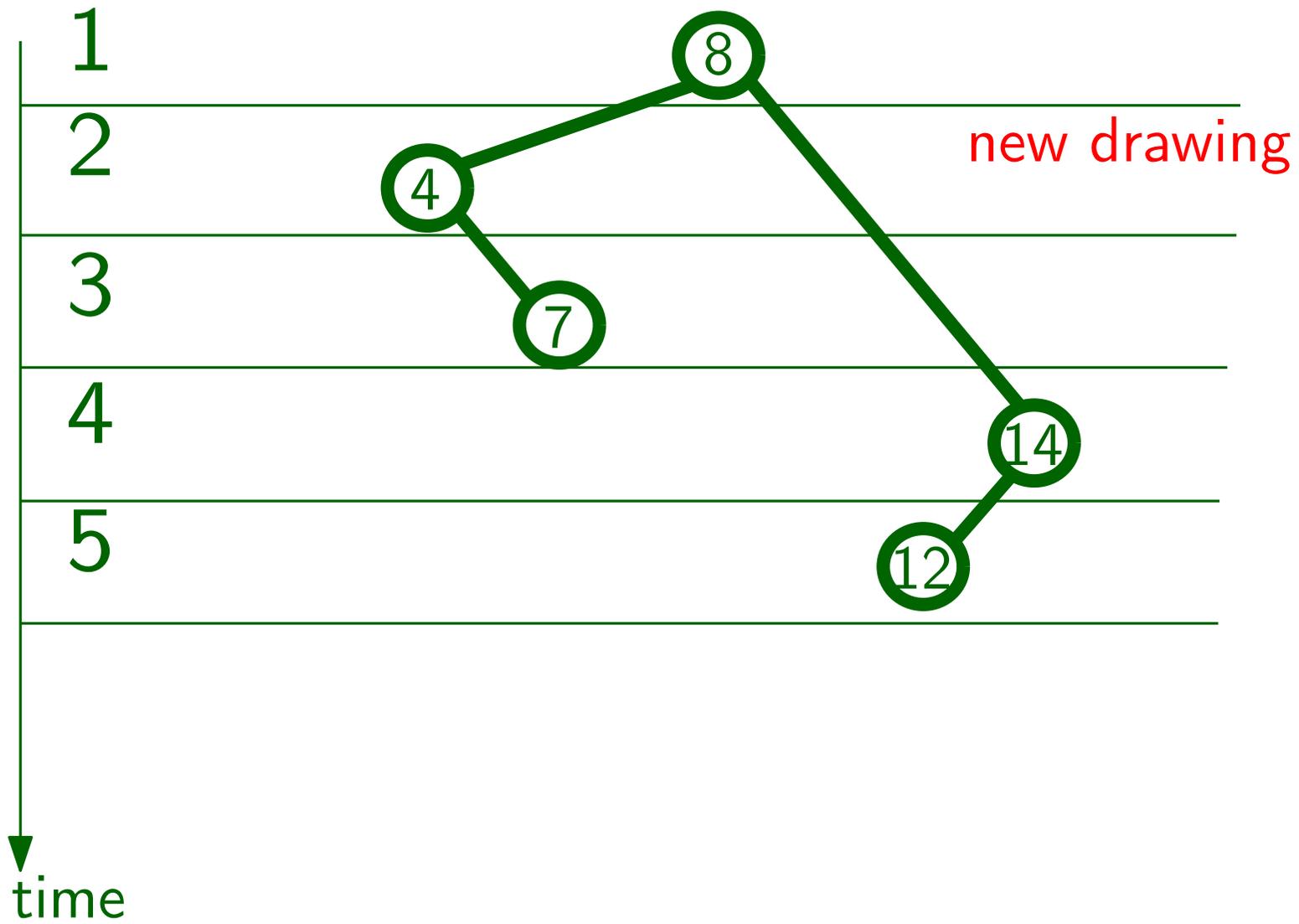
# Sorting



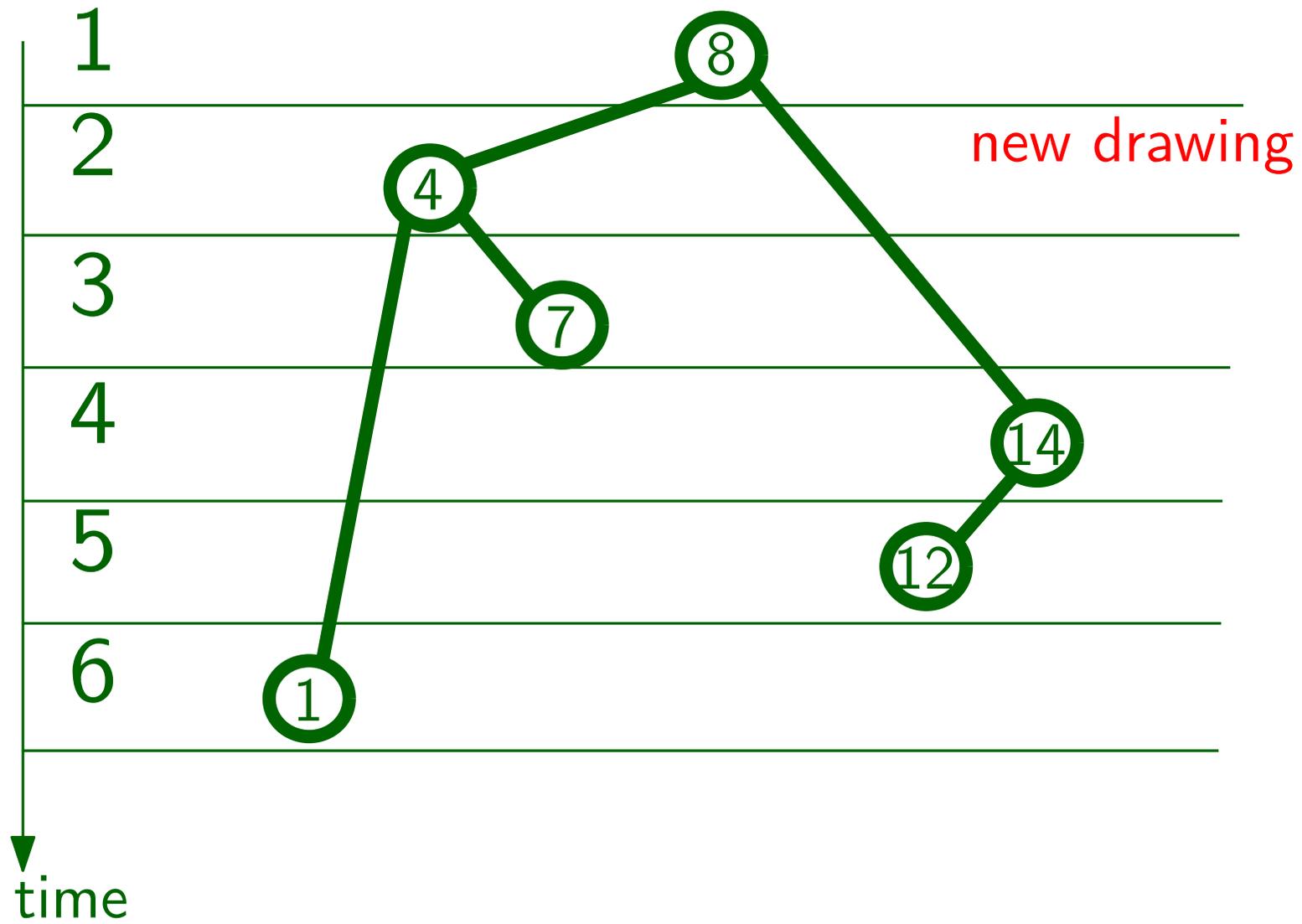
# Sorting



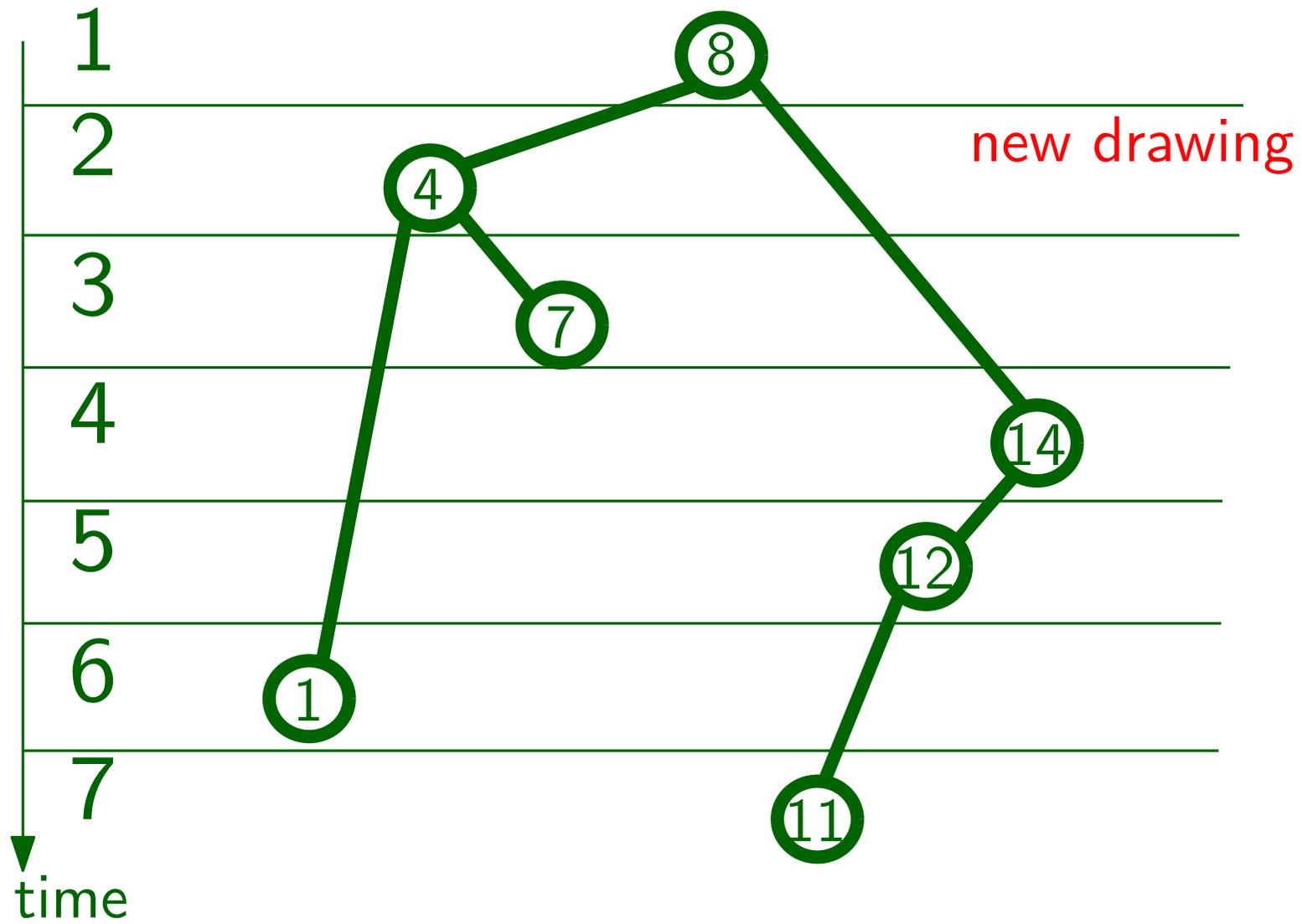
# Sorting



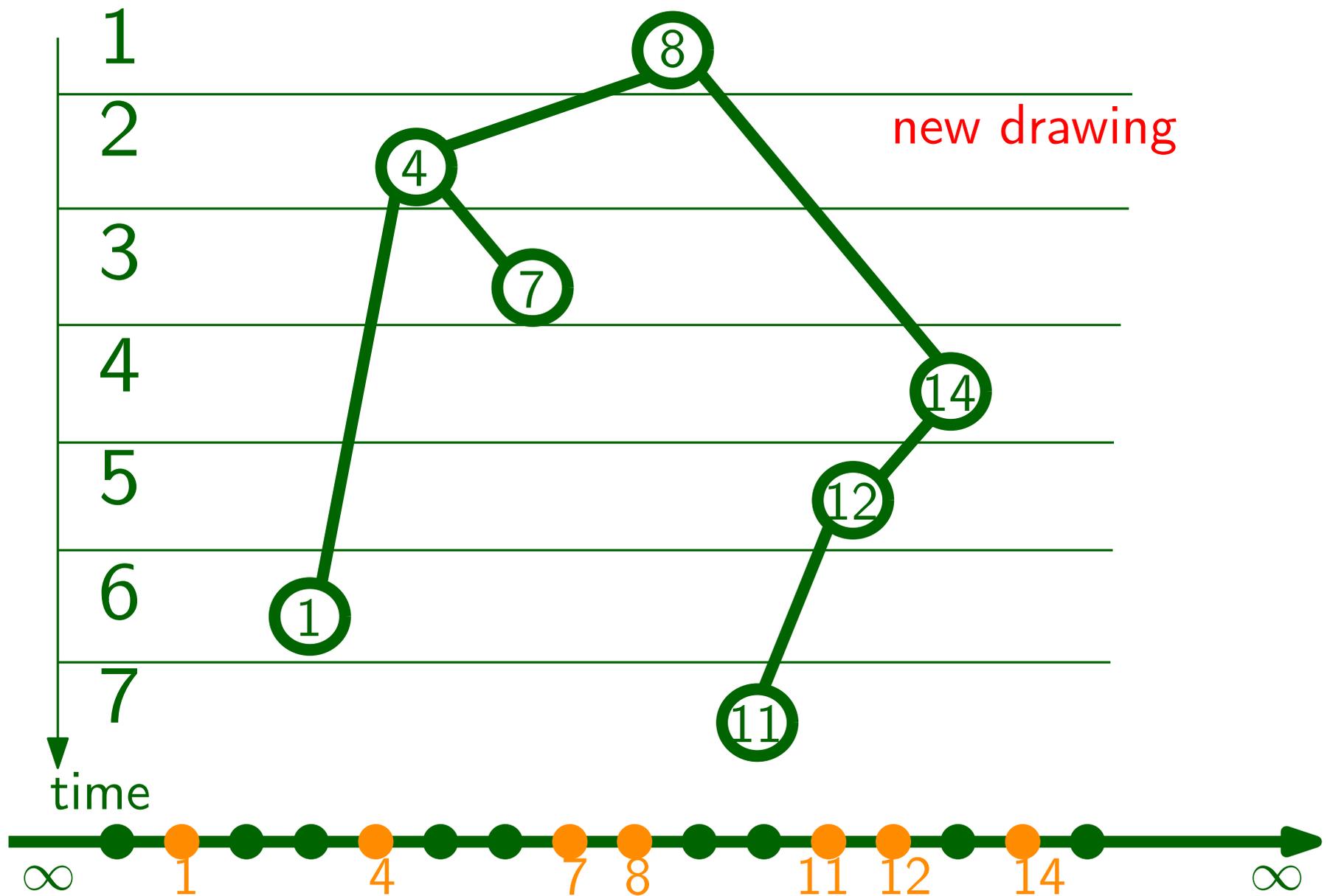
# Sorting



# Sorting

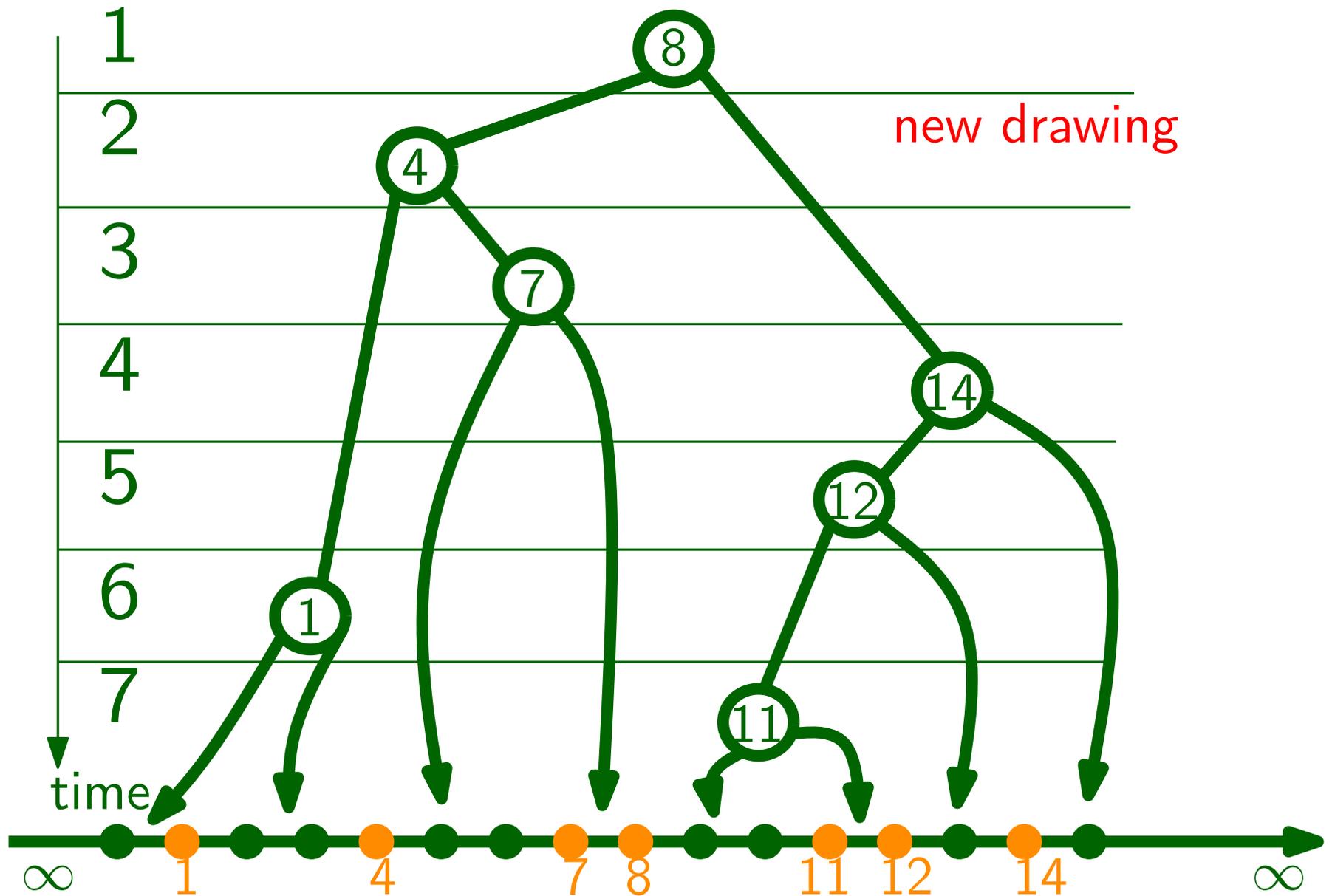


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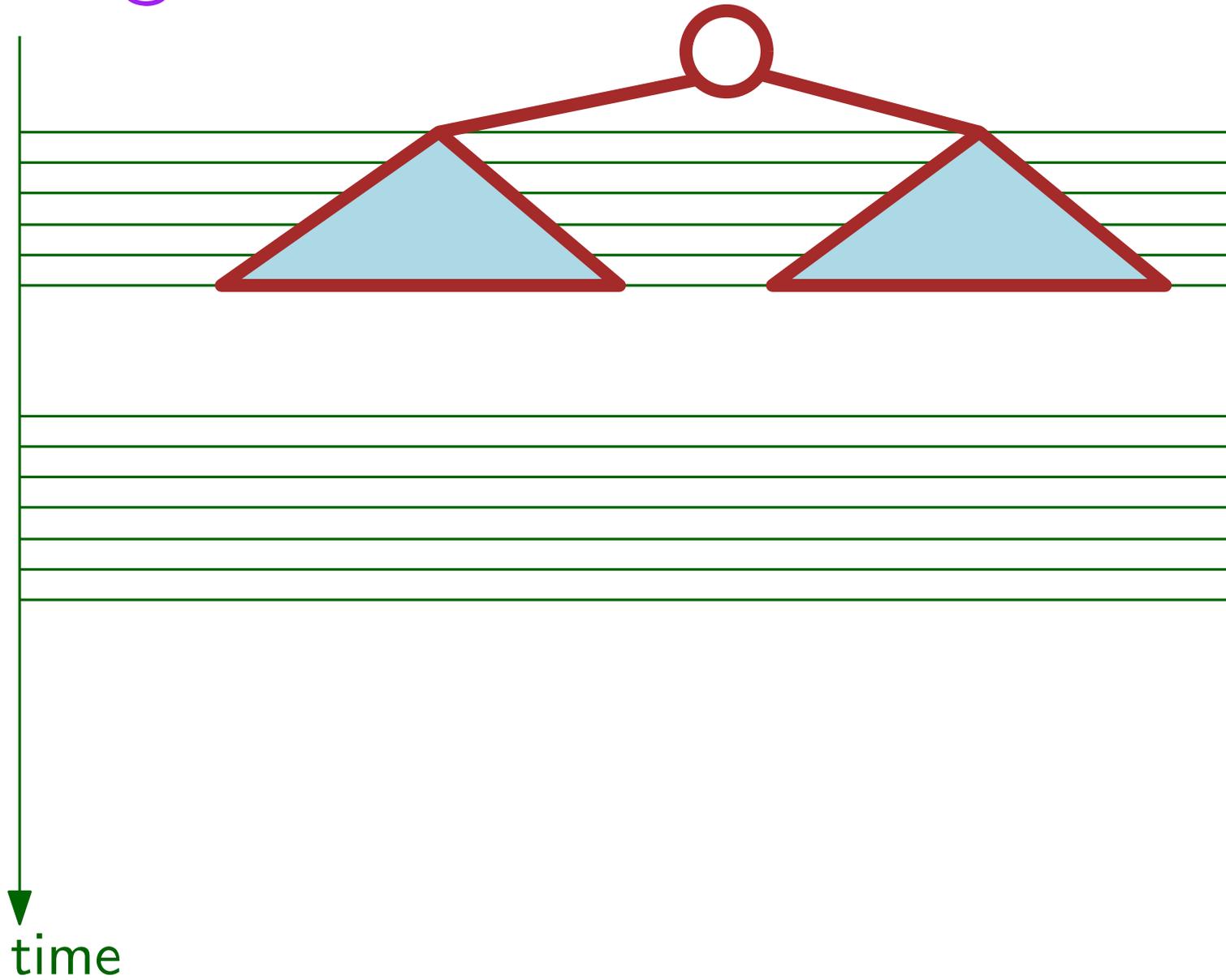


5 - 8

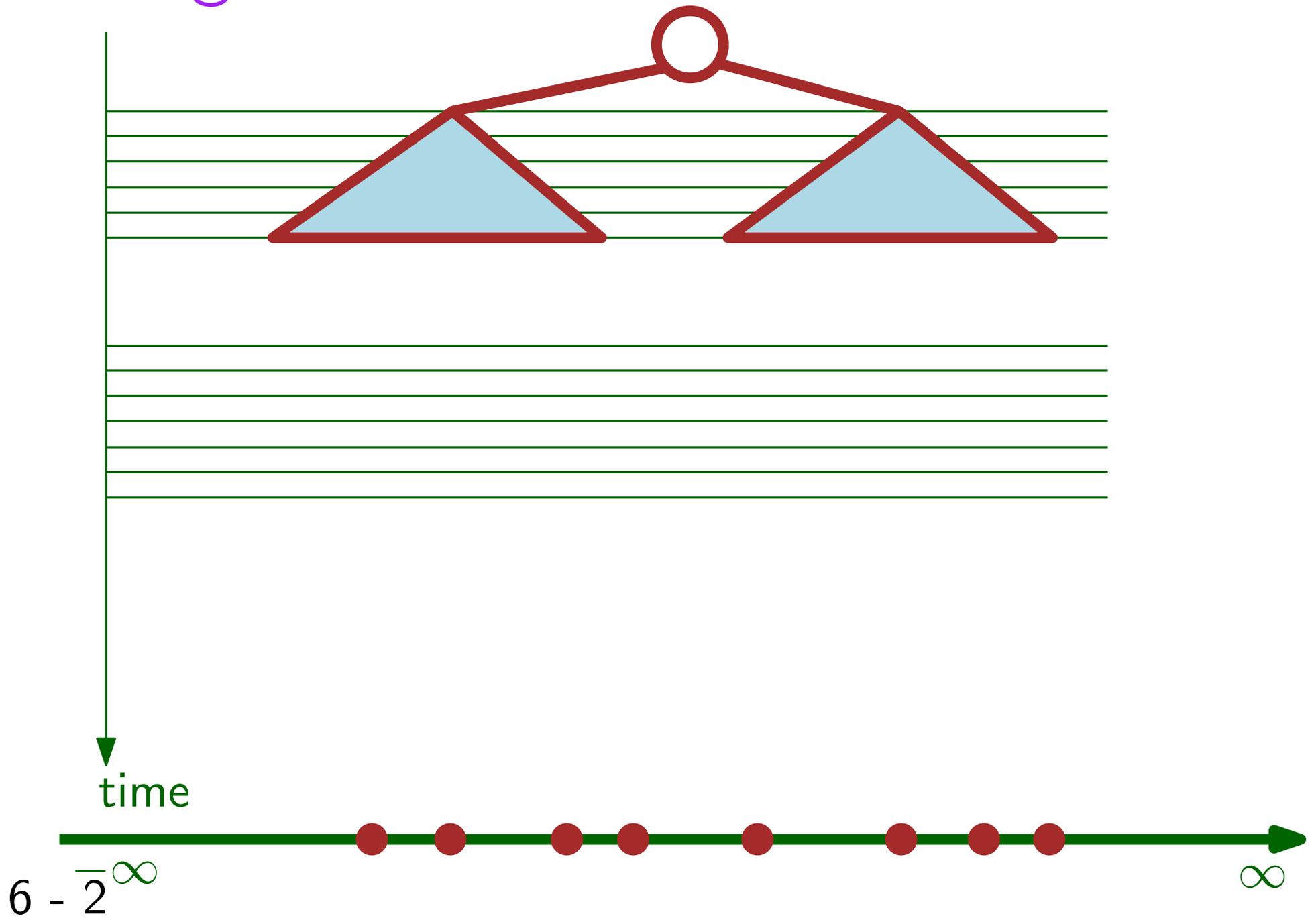
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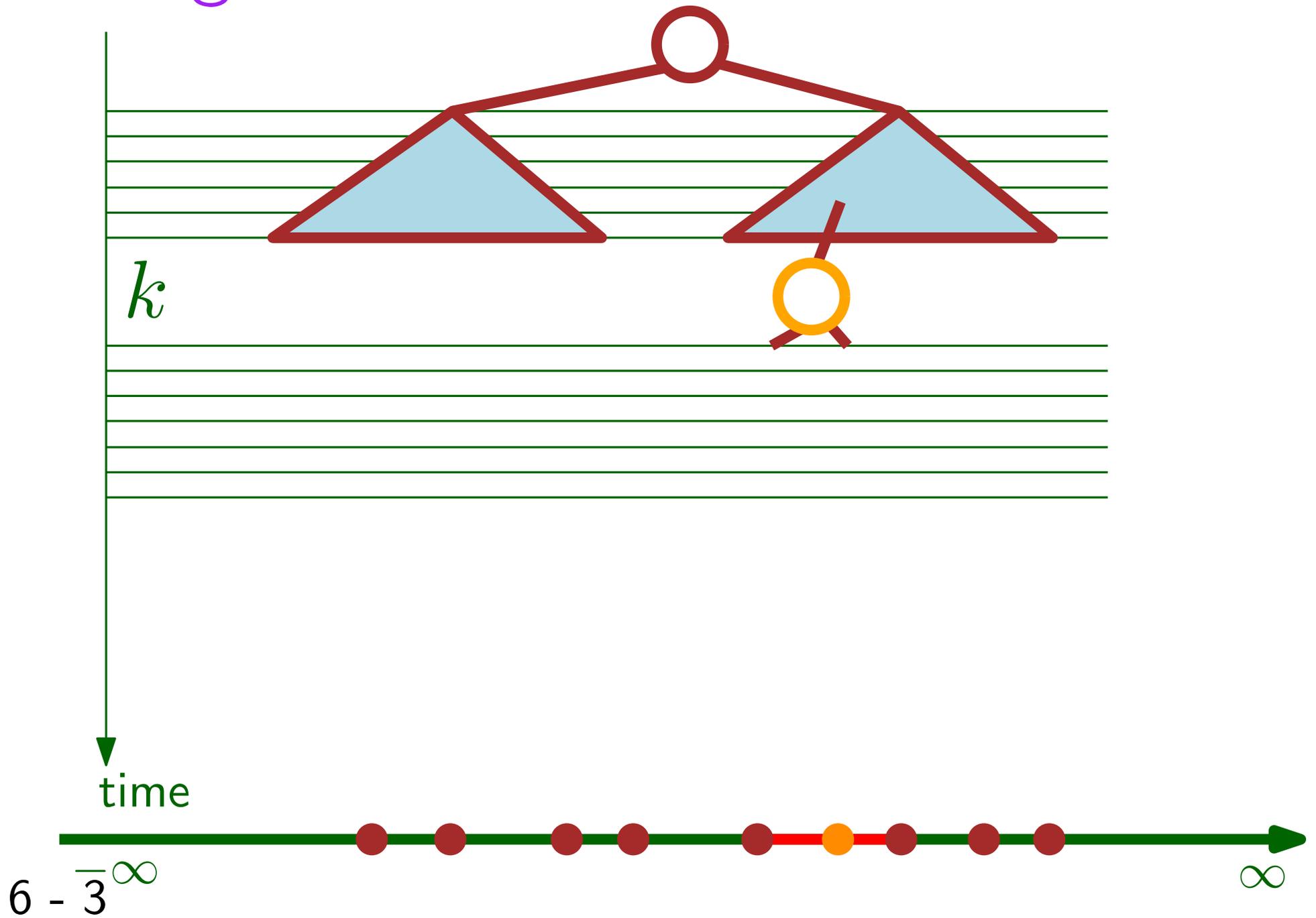
# Sorting



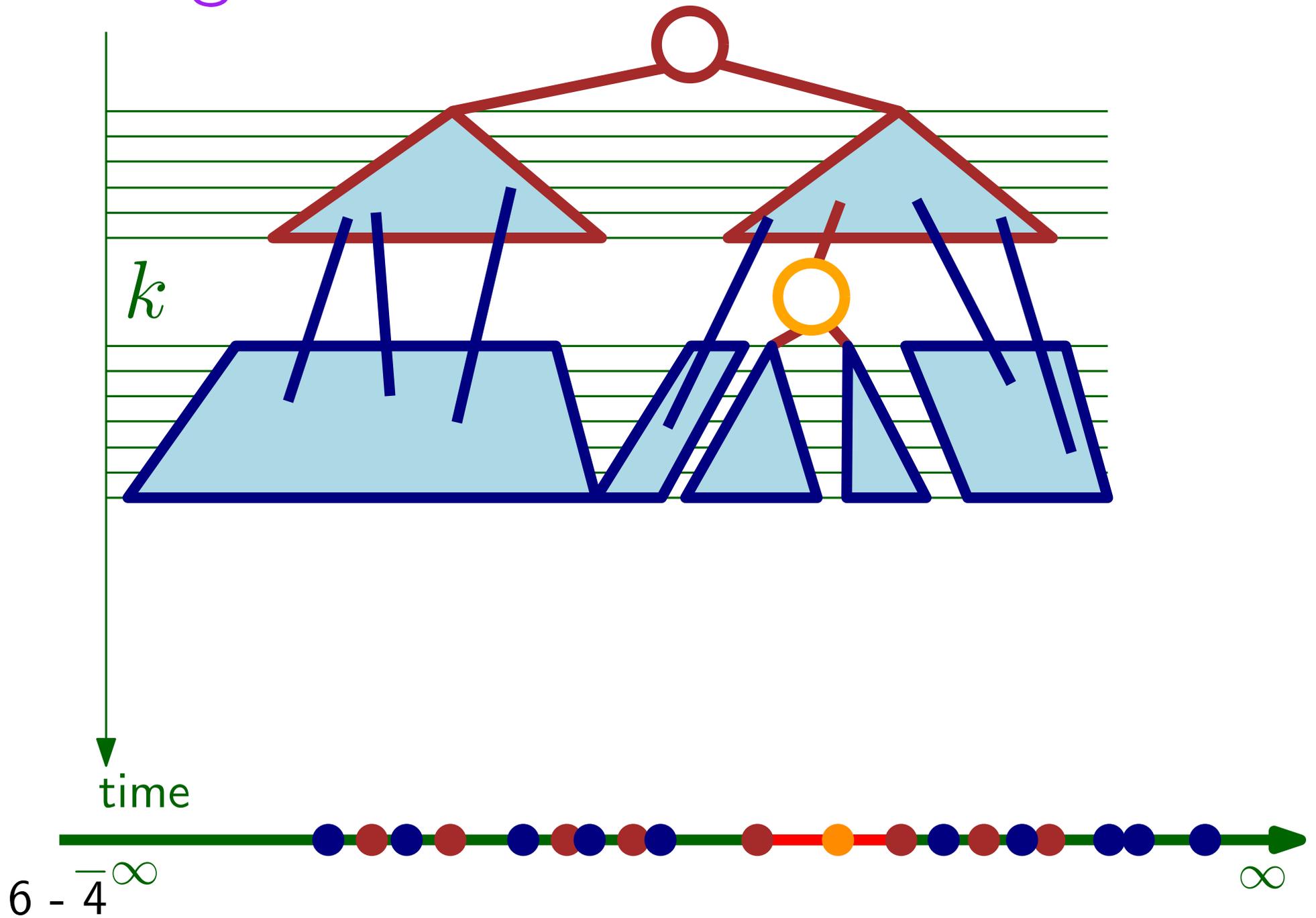
# Sorting



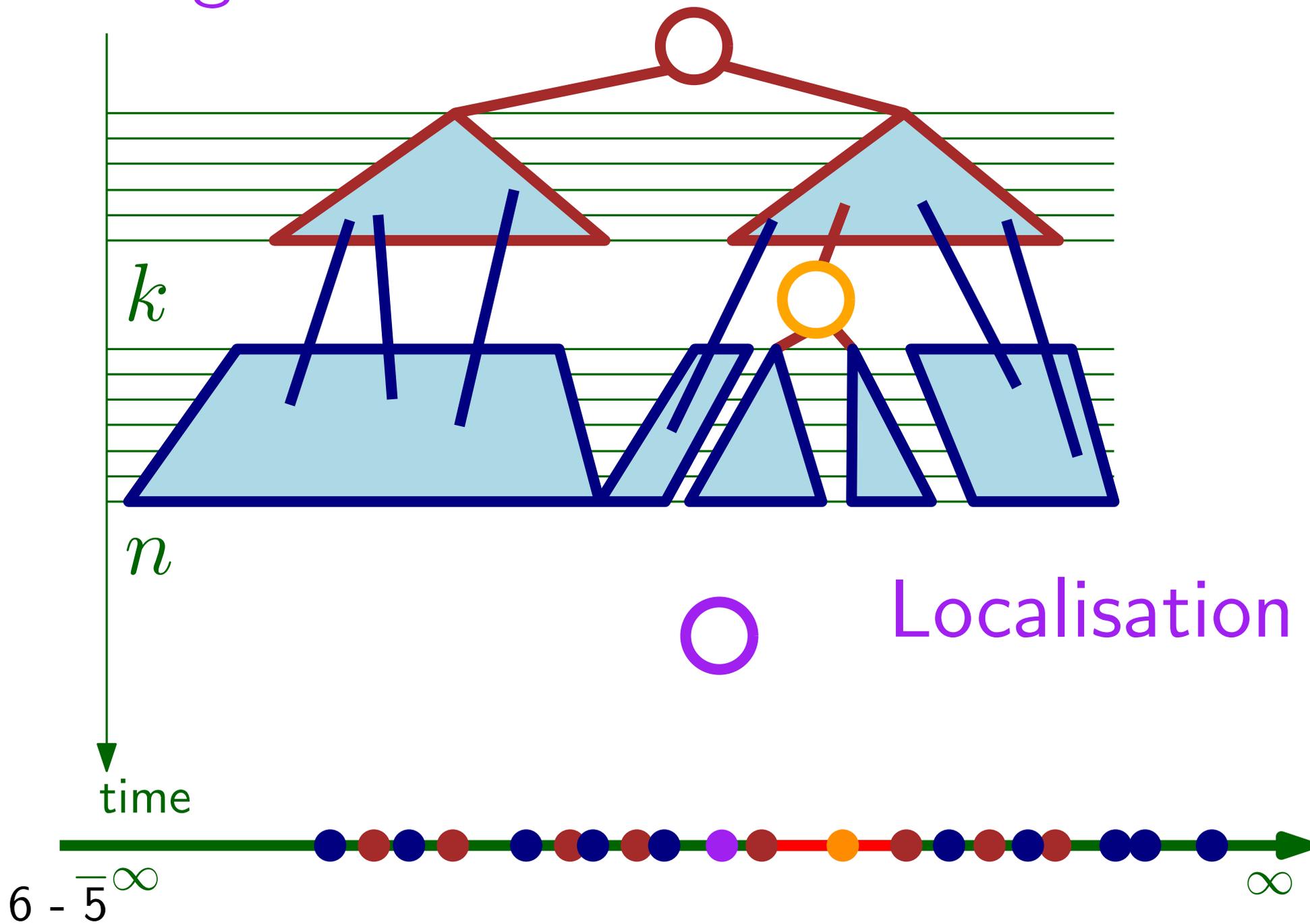
# Sorting



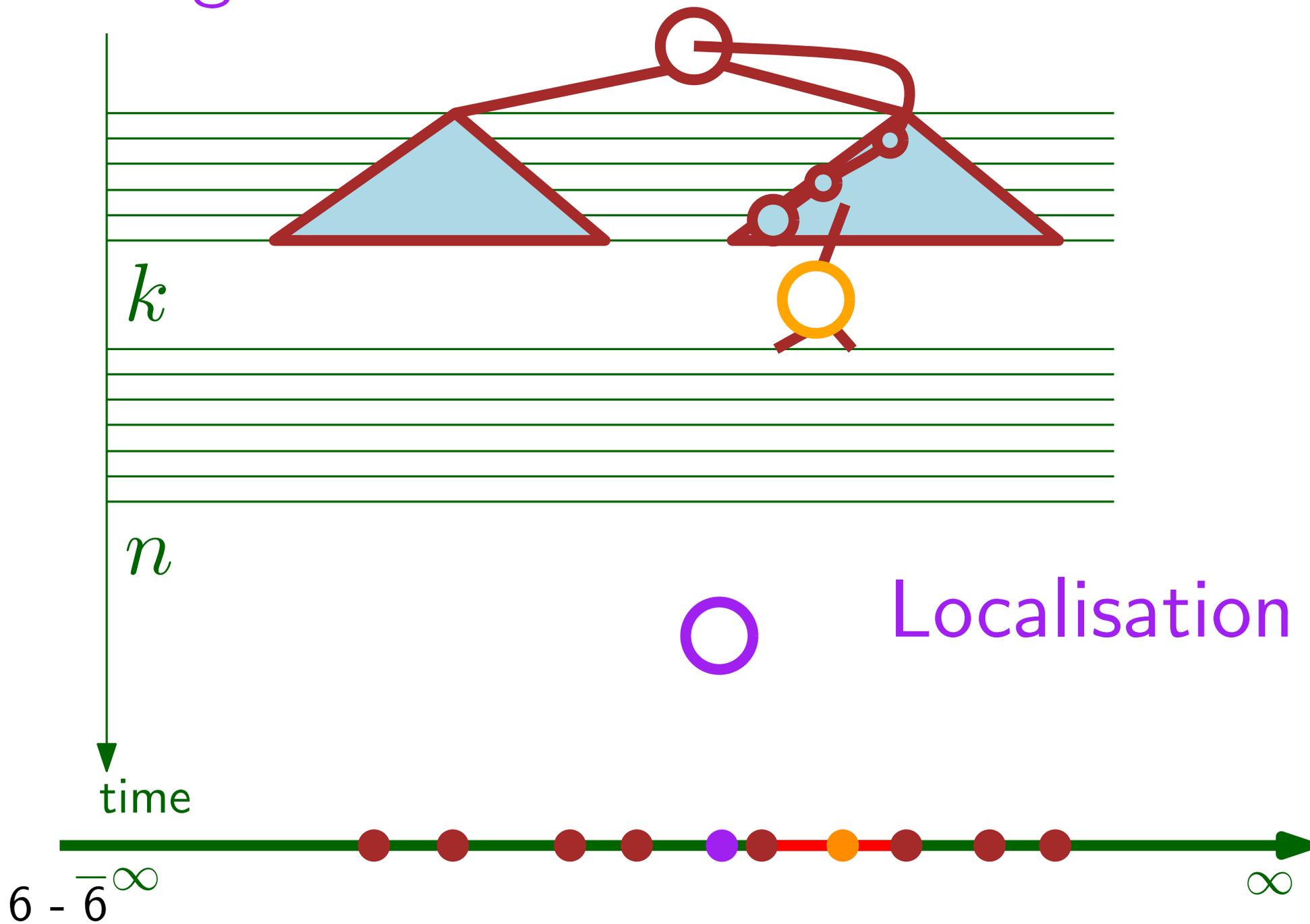
# Sorting



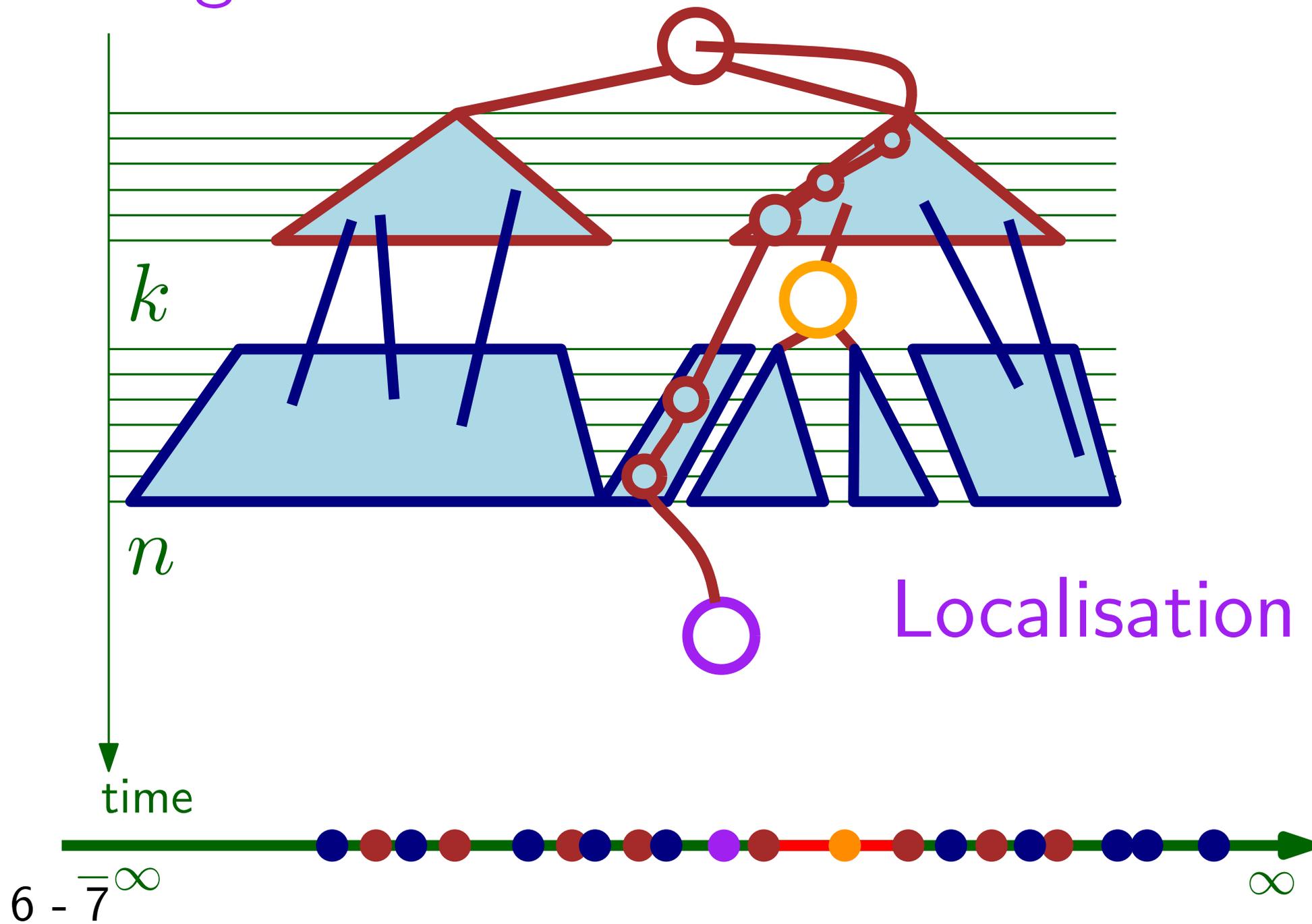
# Sorting



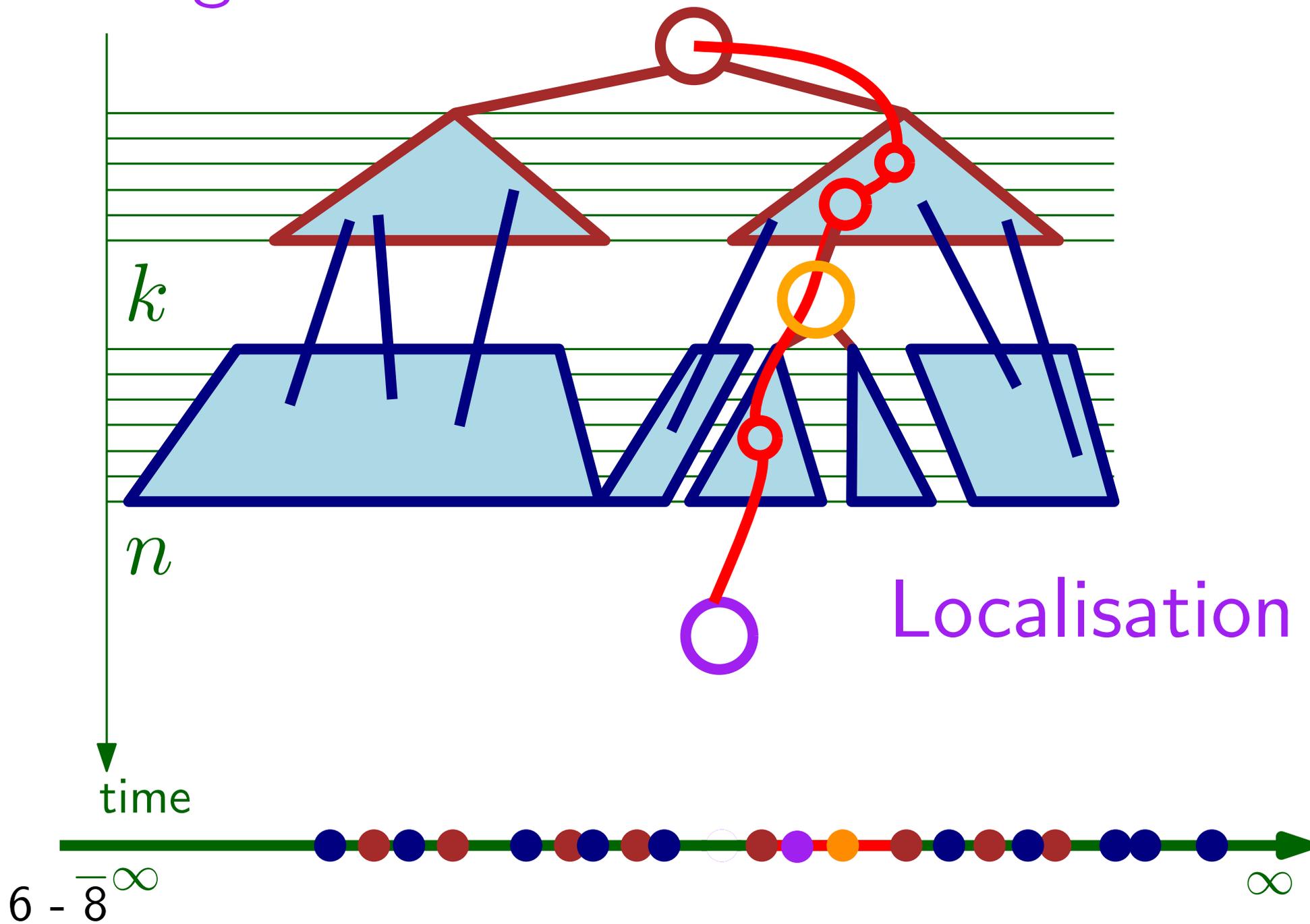
# Sorting



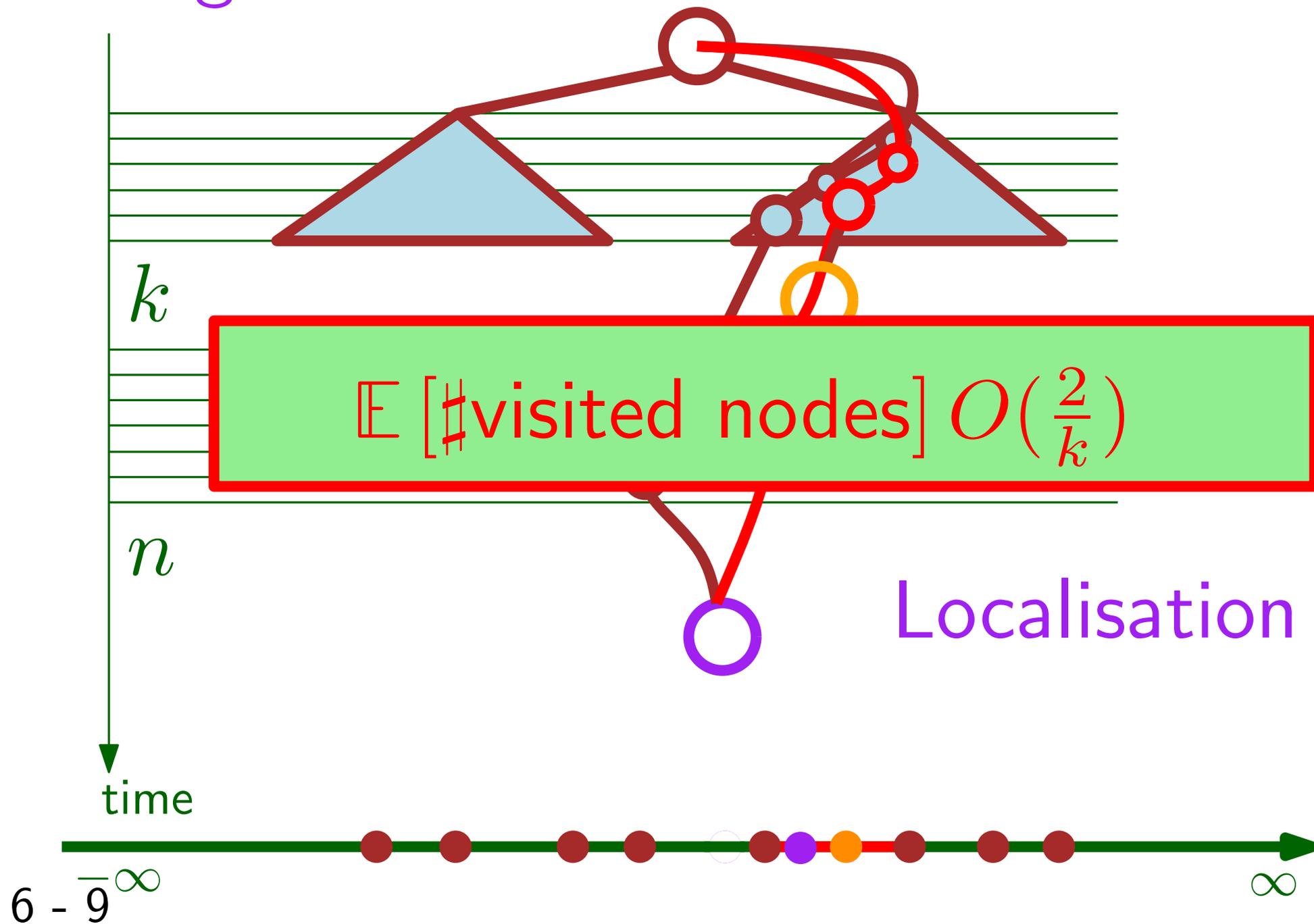
# Sorting



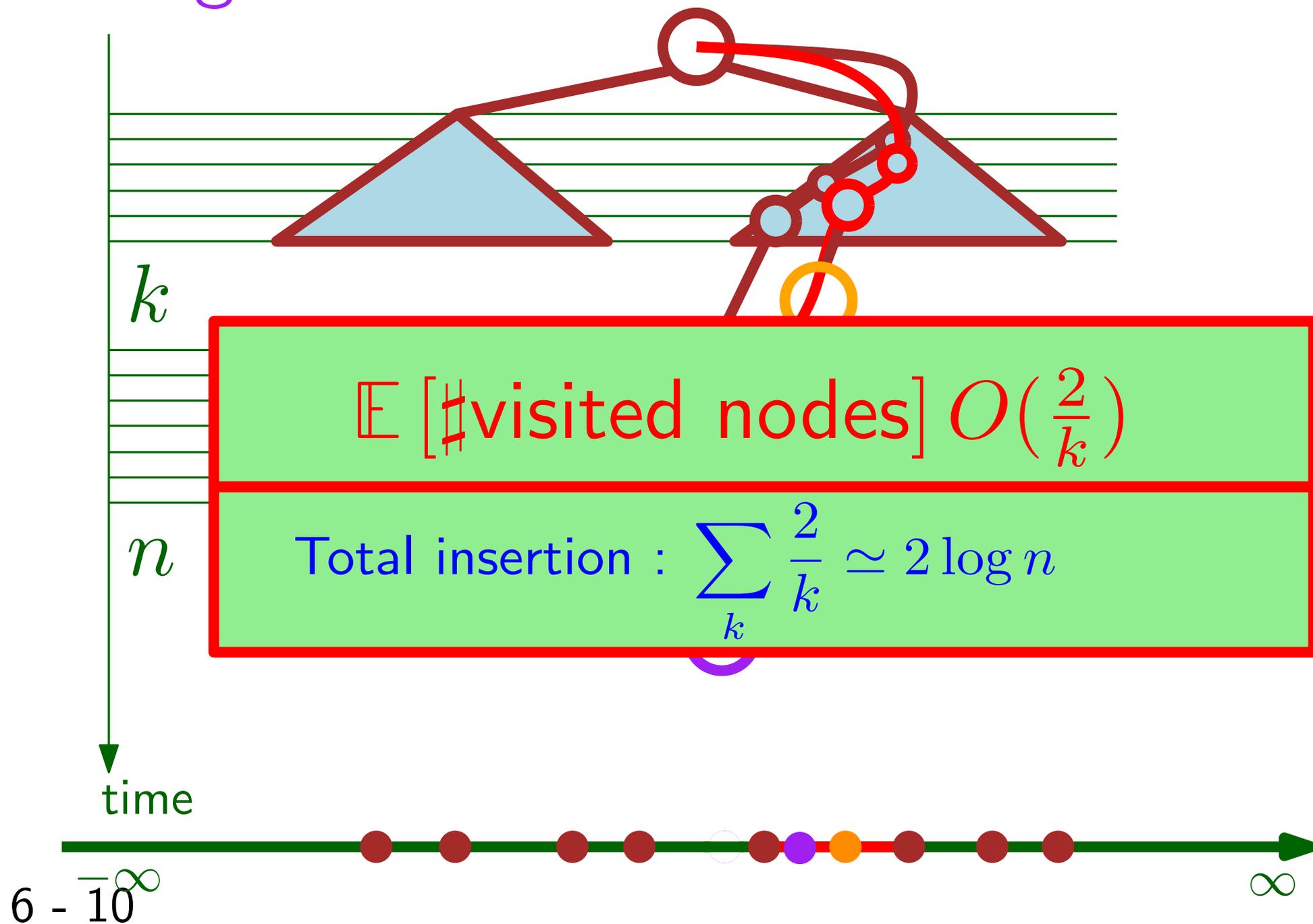
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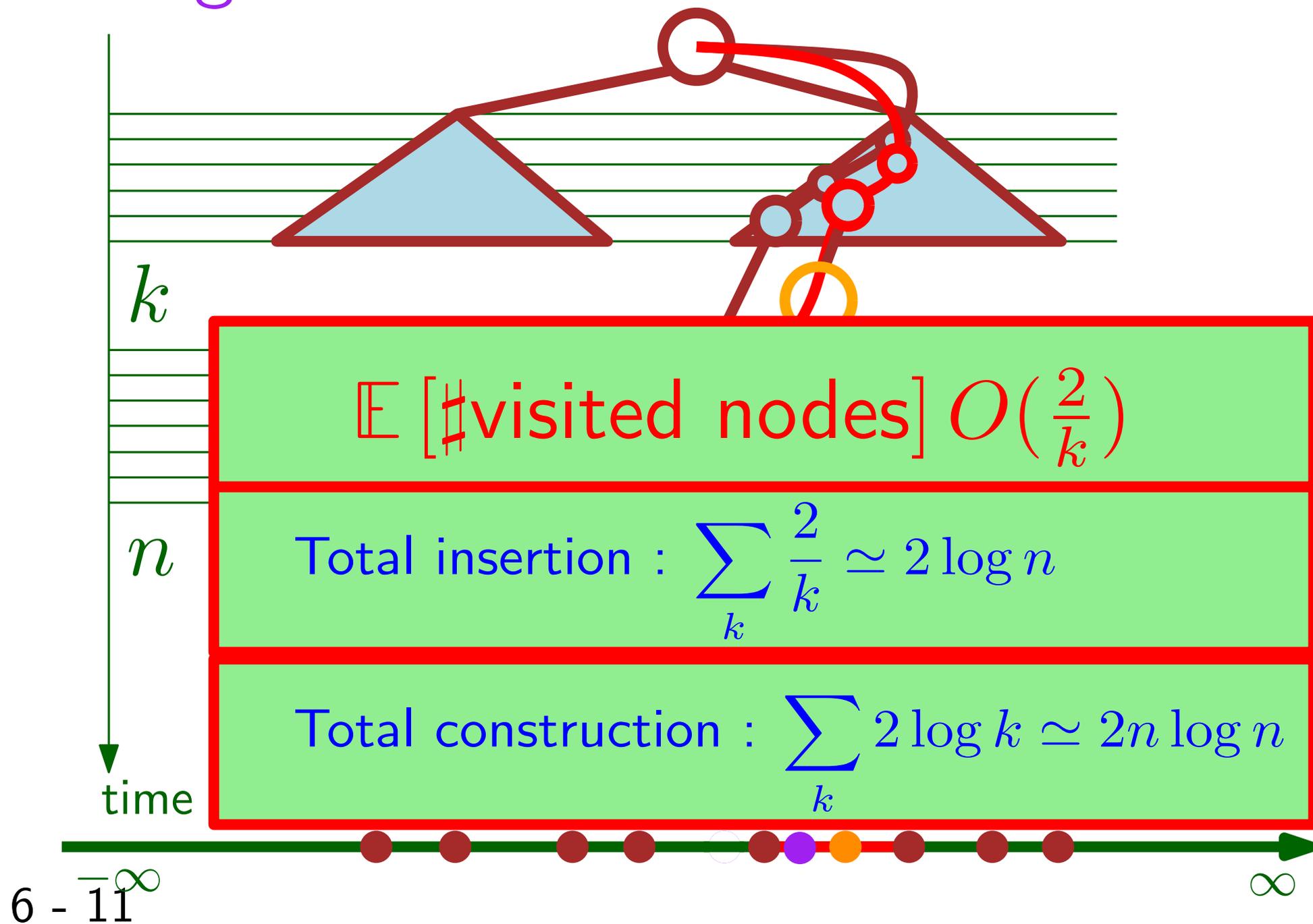
# Sorting



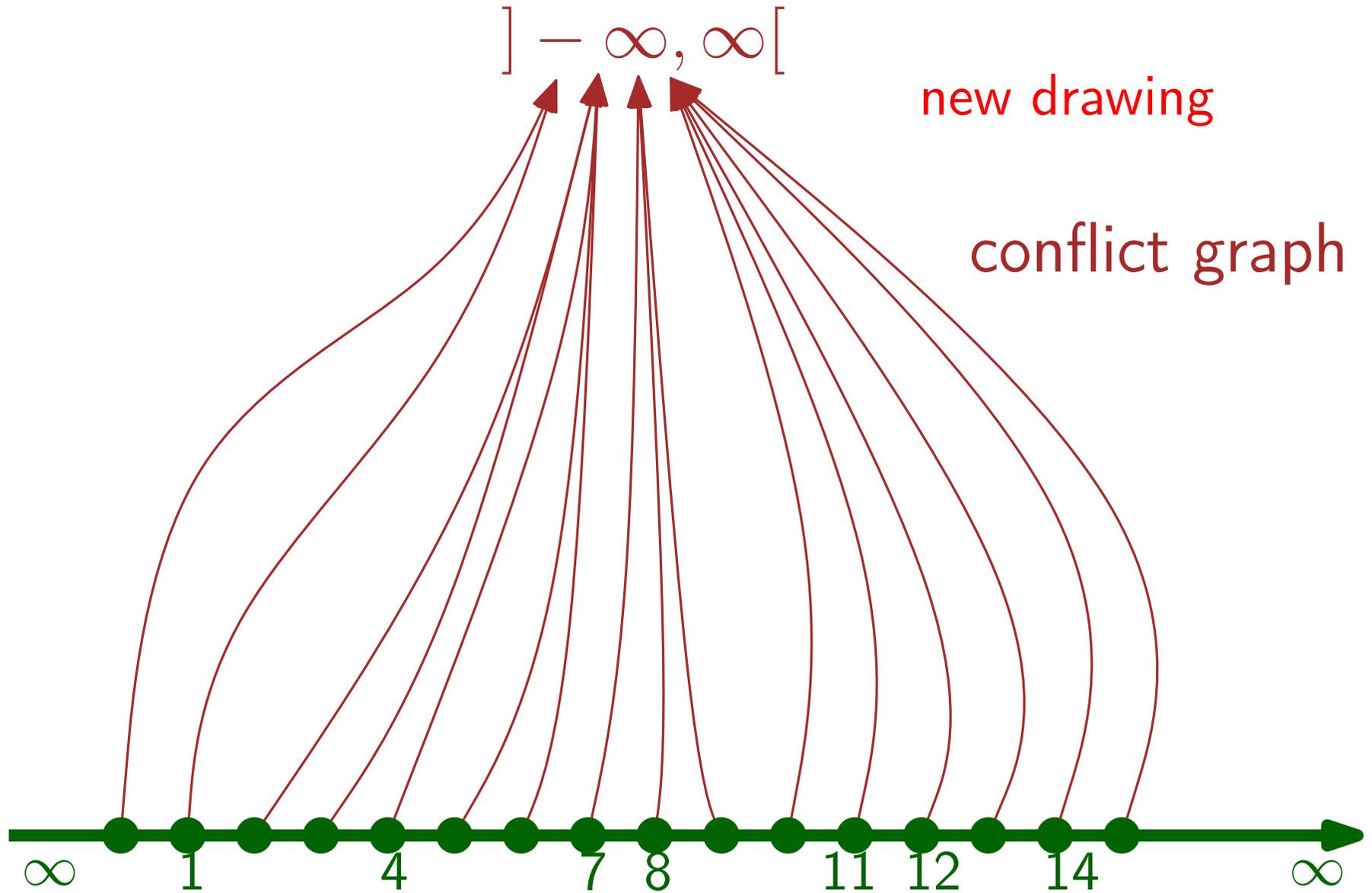
# Sorting



# Sorting



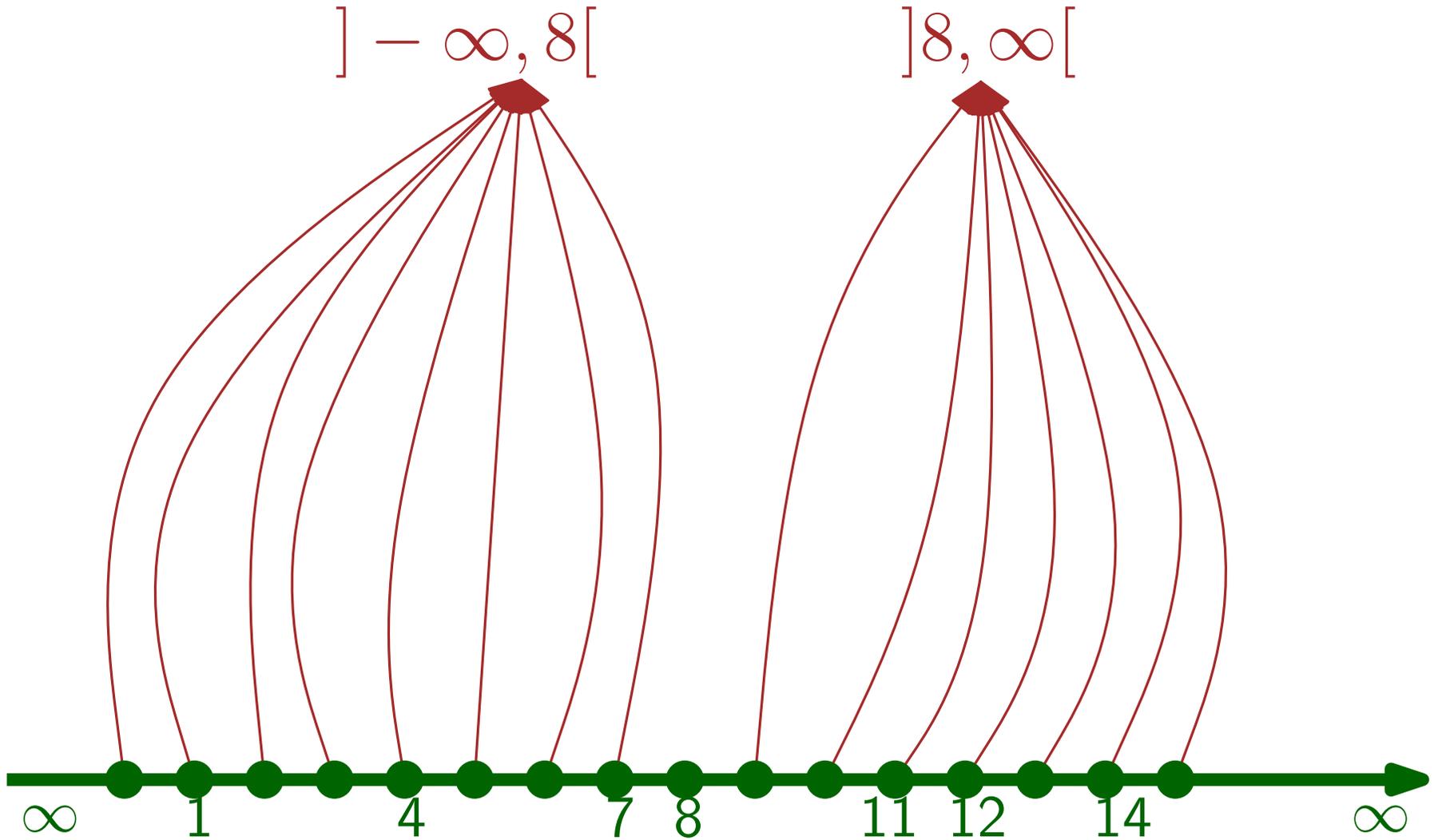
# Sorting



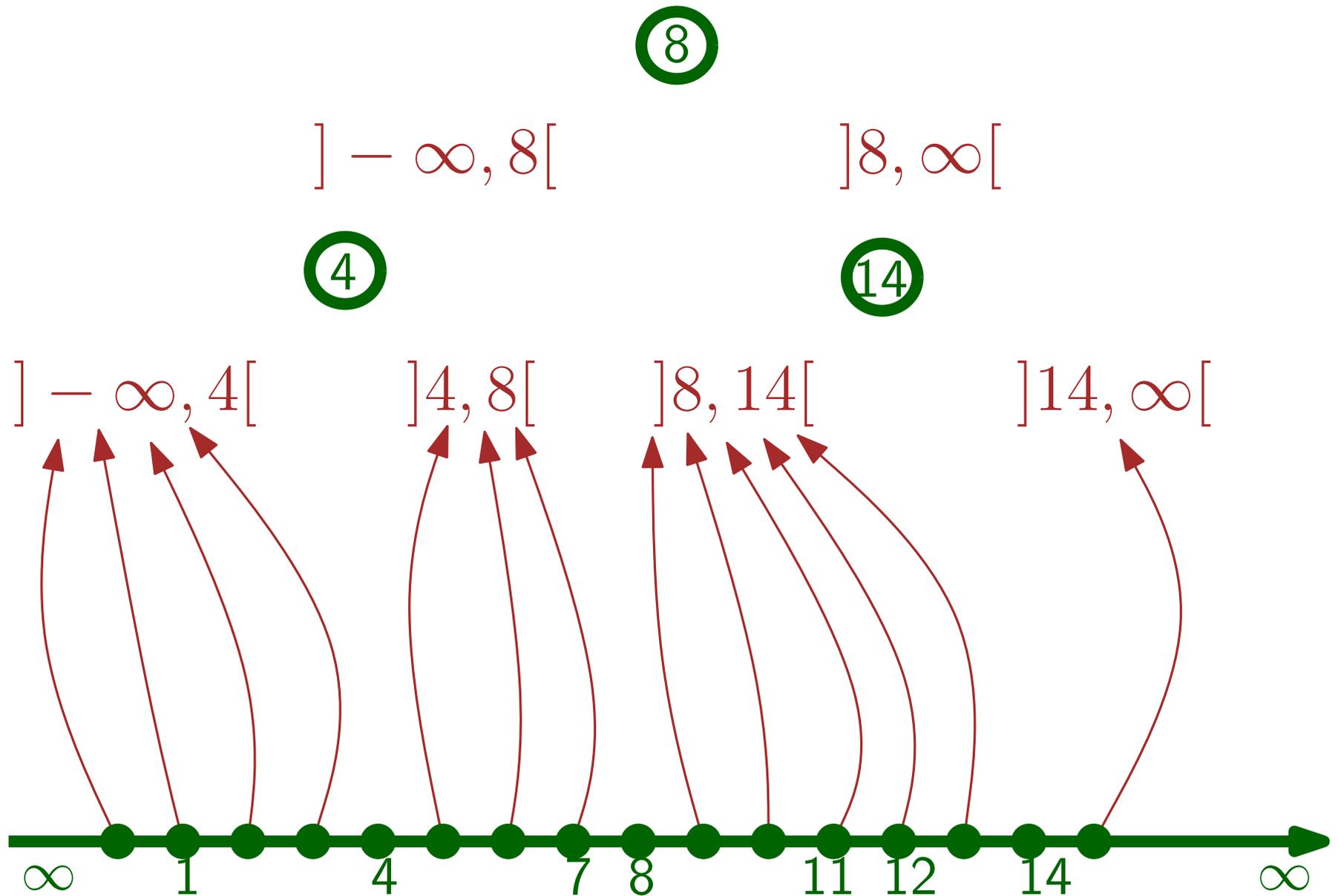
7 - 1

# Sorting

8



# Sorting



# Sorting

Unbalanced binary tree

History graph

Quicksort

Conflict graph

$O(n \log n)$

Same analysis

Backwards analysis

Analyse last insertion and sum

Last object is a random object

# Randomization

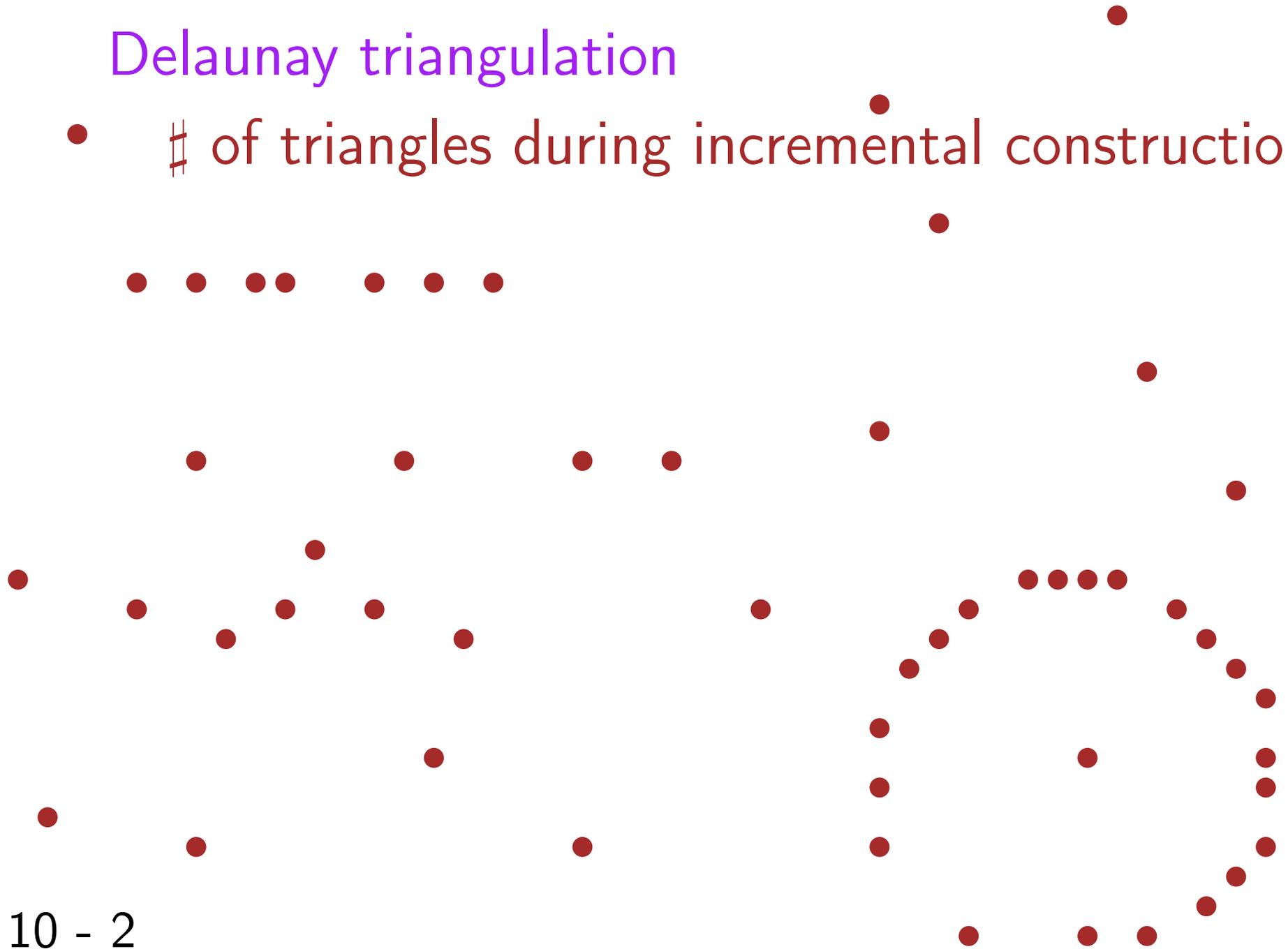
Backwards analysis for Delaunay triangulation

## Delaunay triangulation

# of triangles during incremental construction?

# Delaunay triangulation

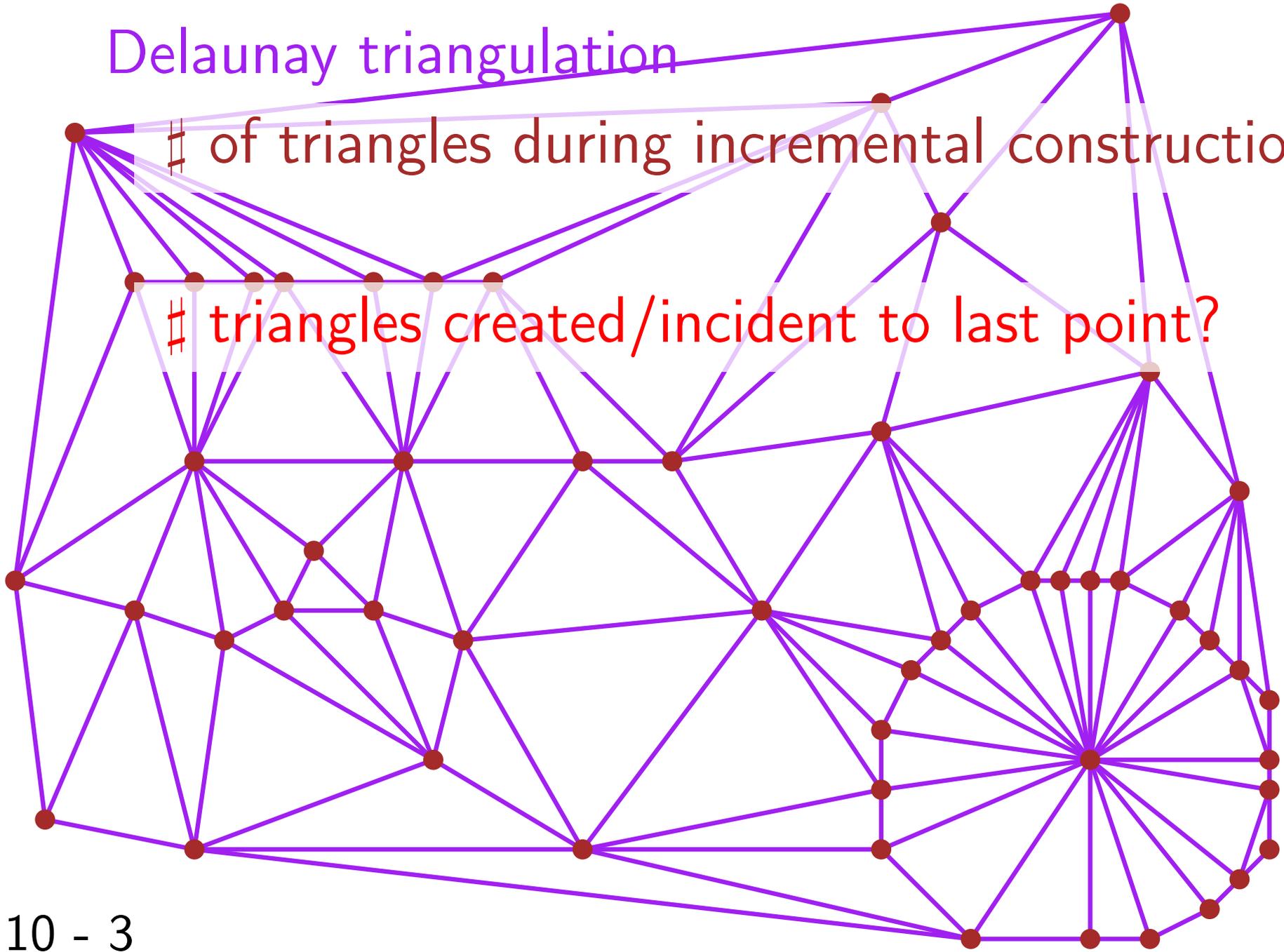
- # of triangles during incremental construction?



# Delaunay triangulation

# of triangles during incremental construction?

# triangles created/incident to last point?



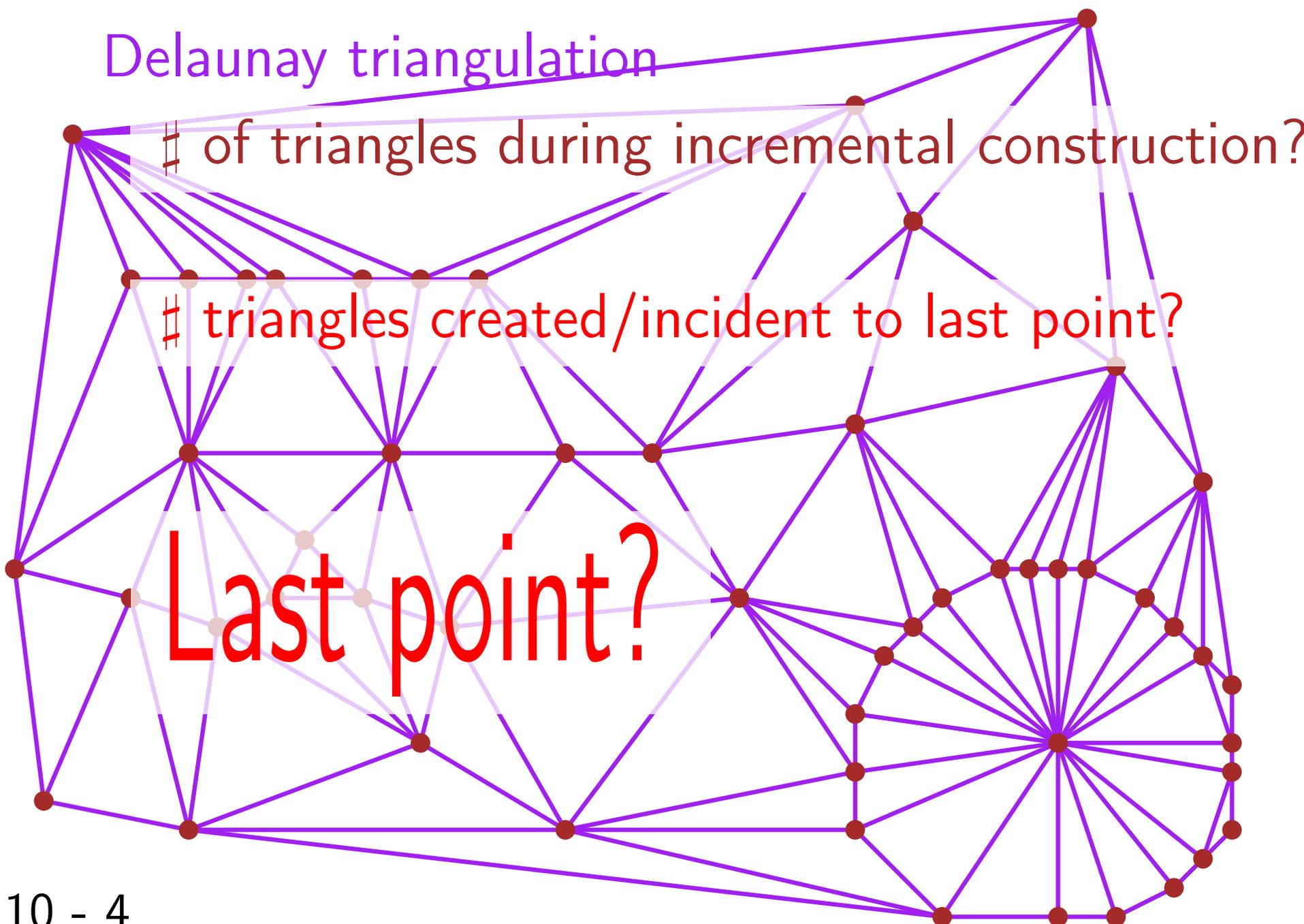
10 - 3

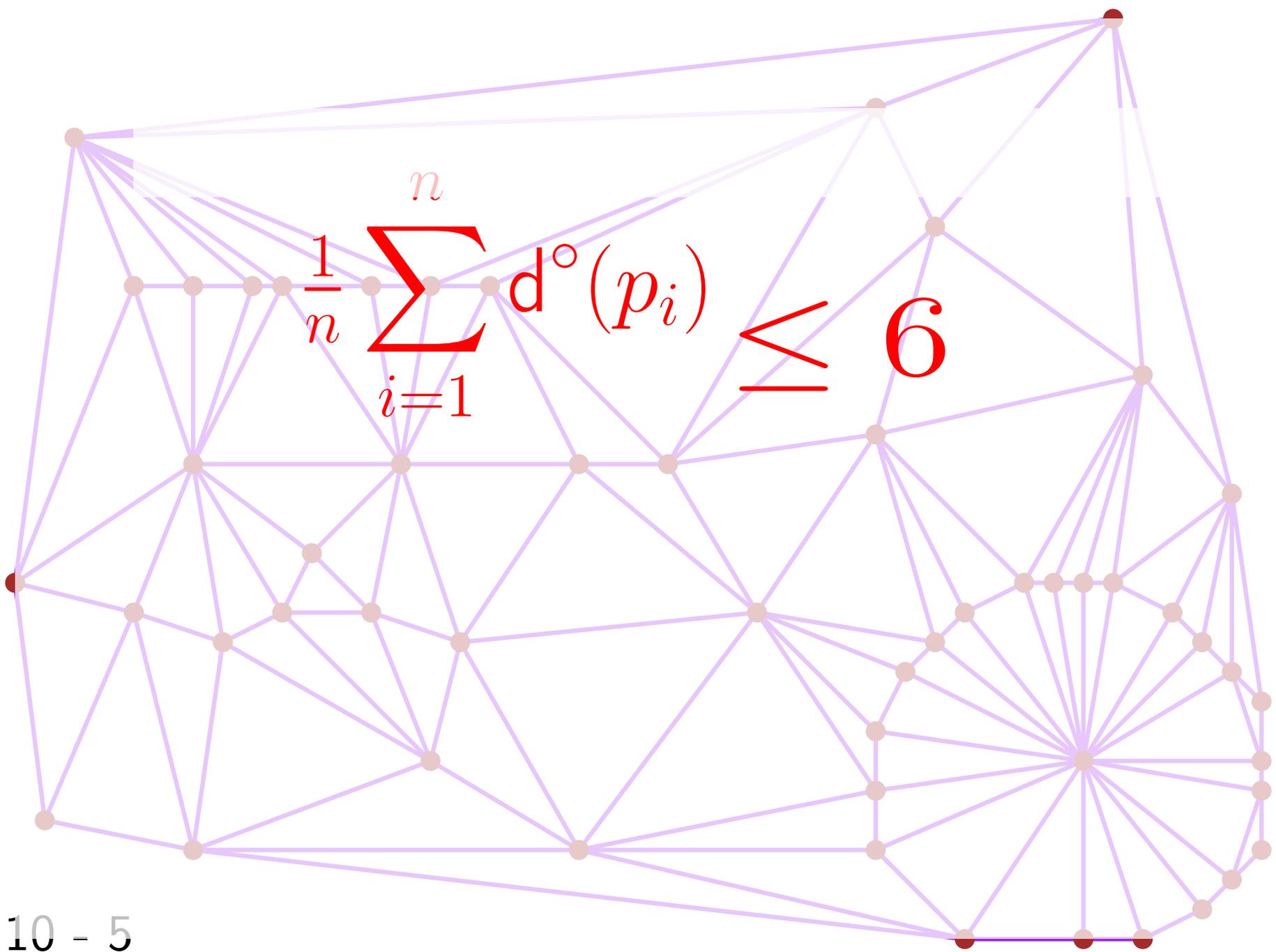
# Delaunay triangulation

# of triangles during incremental construction?

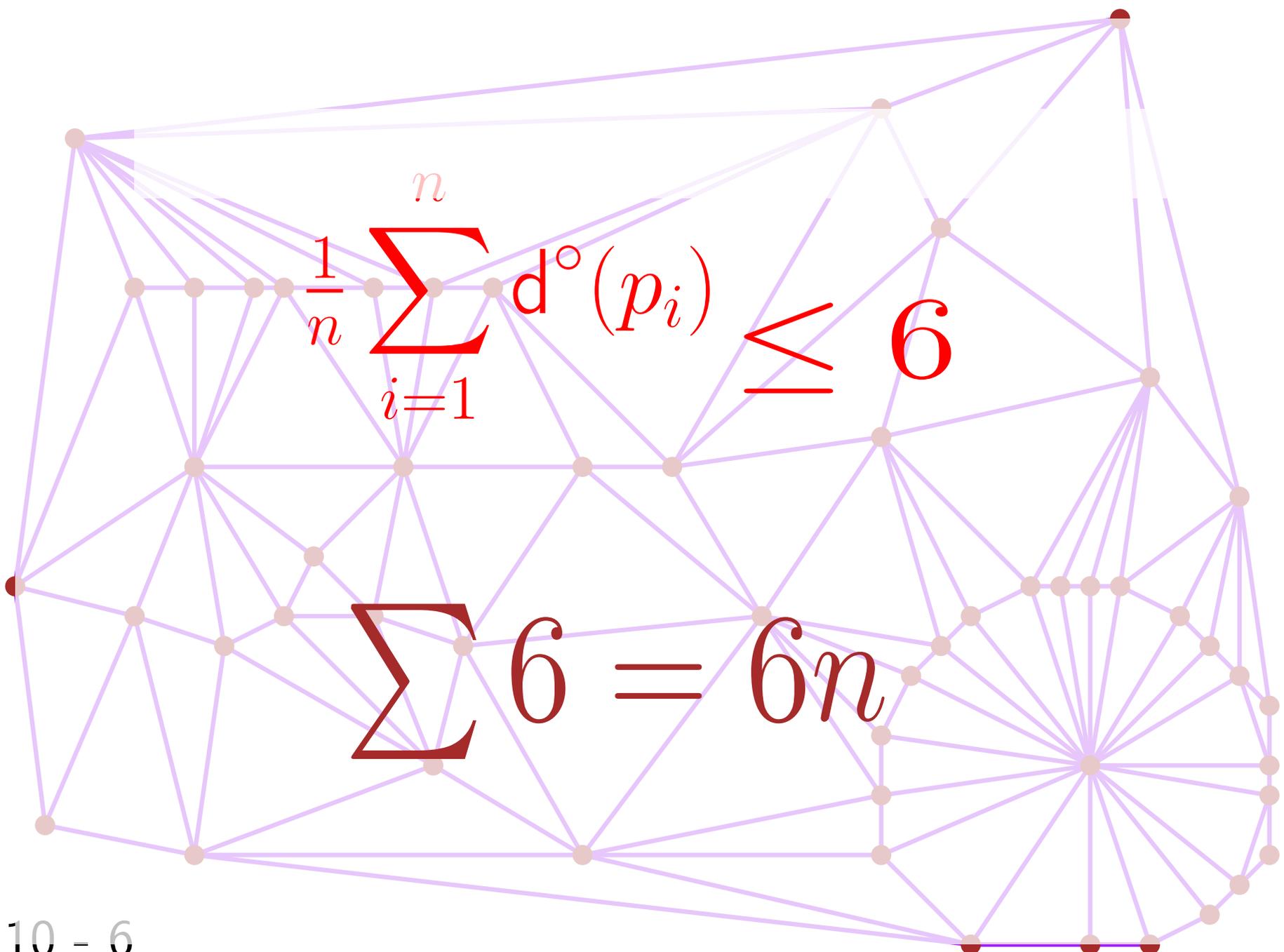
# triangles created/incident to last point?

Last point?





10 - 5

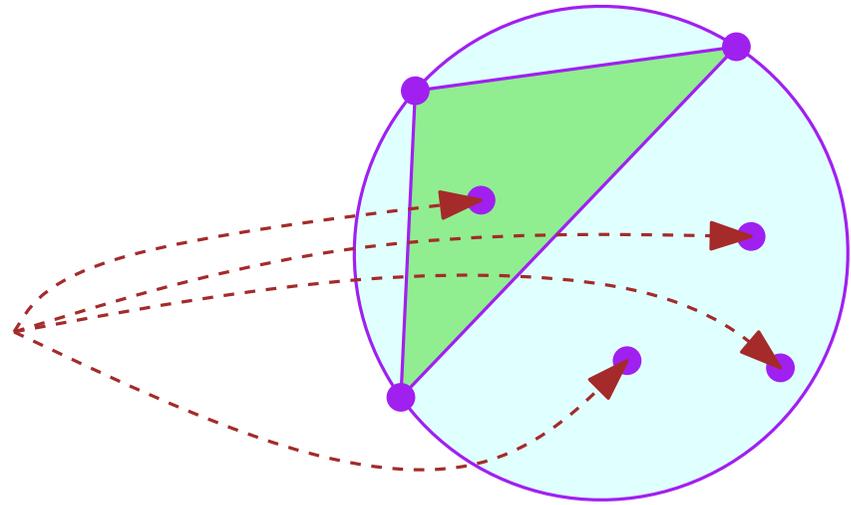


$$\frac{1}{n} \sum_{i=1}^n d^o(p_i) \leq 6$$

$$\sum 6 = 6n$$

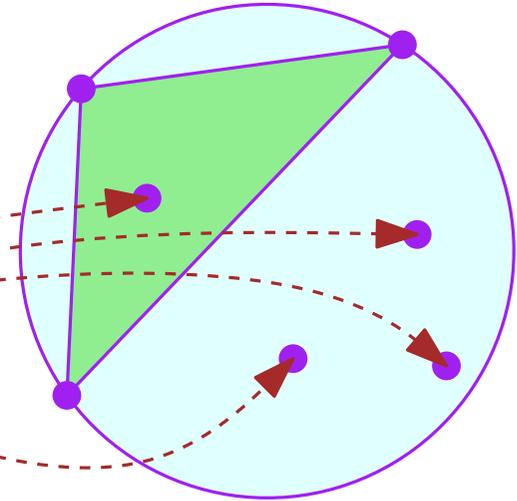
Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers

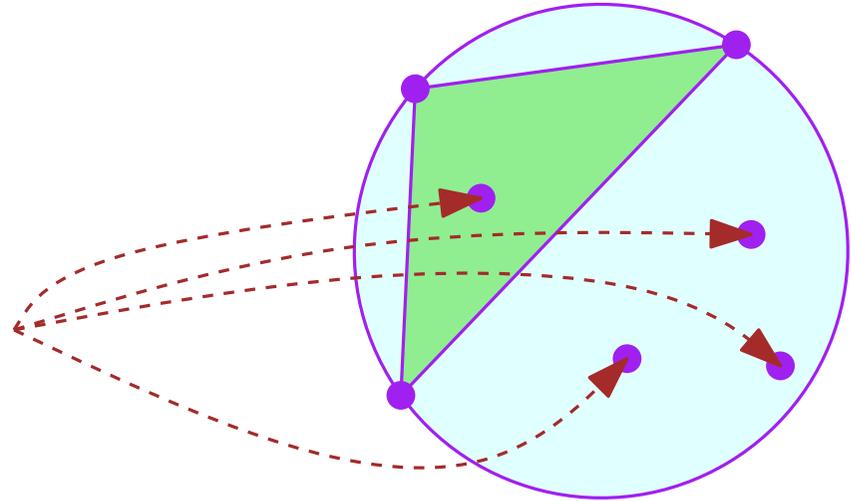


Probability that it exists in the triangulation of a sample of size  $\alpha n$

$$\simeq \alpha^3 (1 - \alpha)^j \geq \alpha^3 (1 - \alpha)^{\frac{1}{\alpha}} \geq \frac{1}{4} \alpha^3 \quad \text{if } 2 \leq j \leq \frac{1}{\alpha}$$

## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



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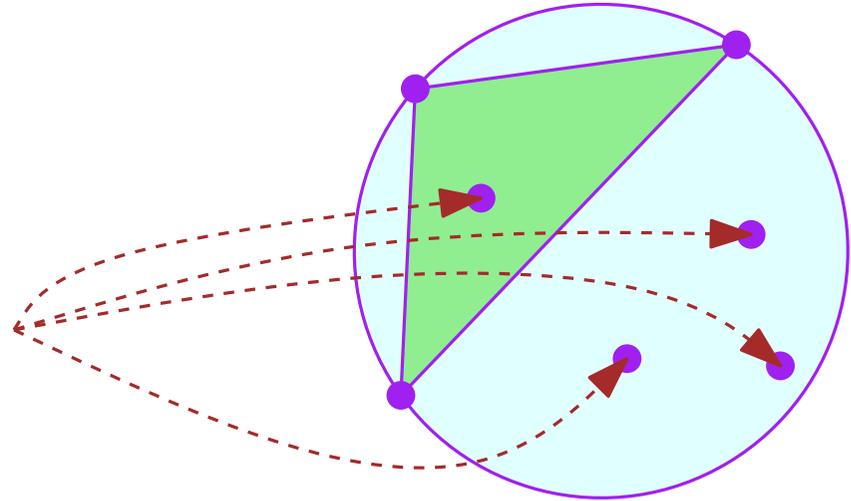
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Size of the triangulation of the sample

$$= \sum_{j=0}^n \mathbb{P} [\Delta \text{ with } j \text{ stoppers is there}] \times \#\Delta \text{ with } j \text{ stoppers}$$

## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



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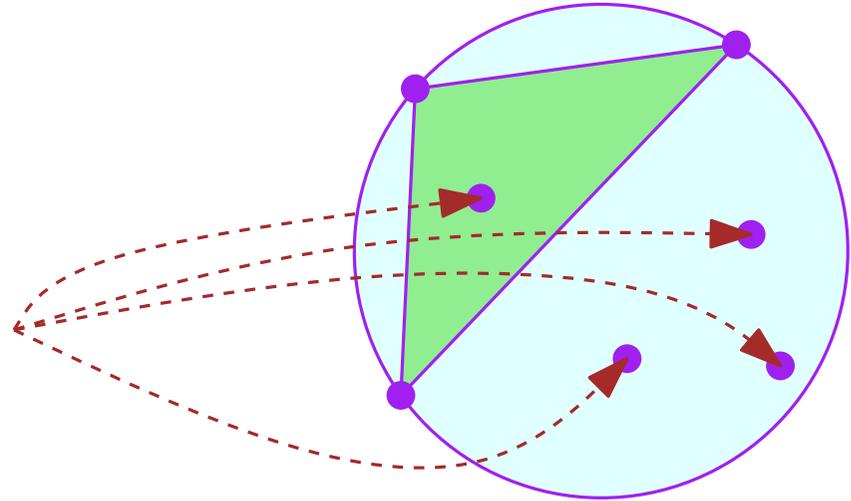
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Size of the triangulation of the sample

$$\begin{aligned} &= \sum_{j=0}^n \mathbb{P} [\Delta \text{ with } j \text{ stoppers is there}] \times \#\Delta \text{ with } j \text{ stoppers} \\ &\geq \sum_{j=0}^{1/\alpha} \frac{\alpha^3}{4} \times \#\Delta \text{ with } j \text{ stoppers} \end{aligned}$$

## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists in the triangulation of a sample of size  $\alpha n$

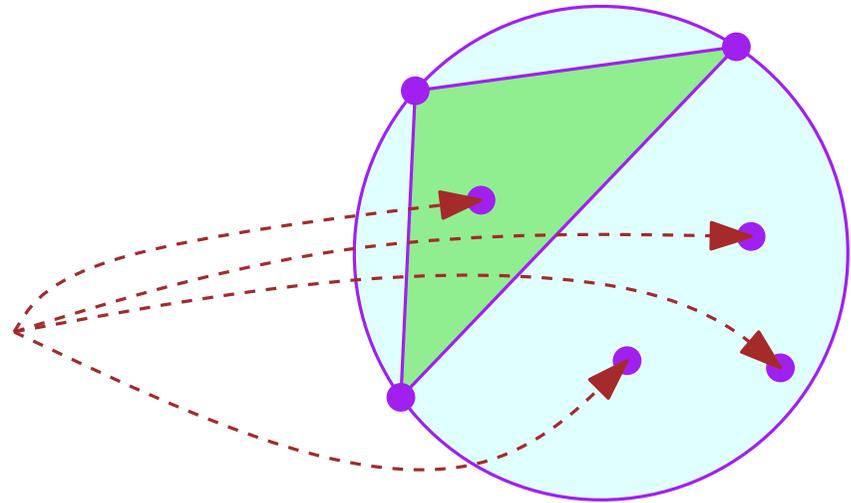
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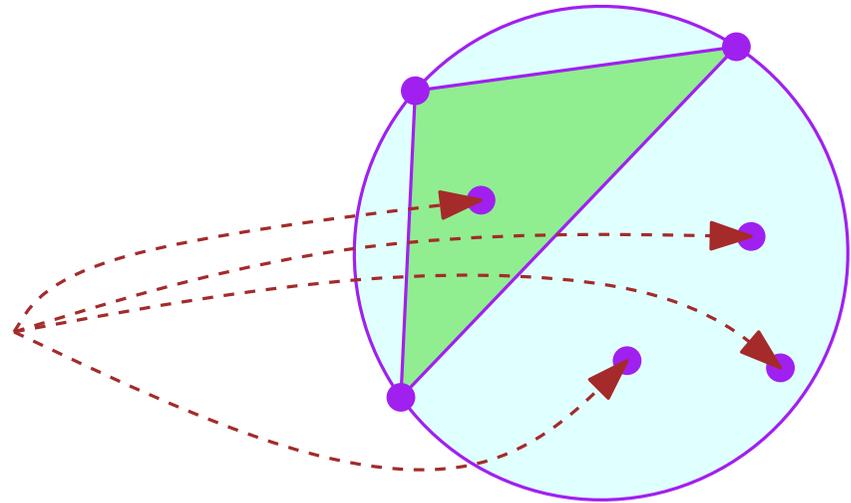
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Size of the triangulation of the sample

$$\begin{aligned} &= \sum_{j=0}^n \mathbb{P} [\Delta \text{ with } j \text{ stoppers is there}] \times \#\Delta \text{ with } j \text{ stoppers} &&= O(\alpha n) \\ &\geq \sum_{j=0}^{1/\alpha} \frac{\alpha^3}{4} \times \#\Delta \text{ with } j \text{ stoppers} = \alpha^3 \#\Delta \text{ with } \leq \frac{1}{\alpha} \text{ stoppers} \end{aligned}$$

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Triangle  $\Delta$  with  $j$  stoppers



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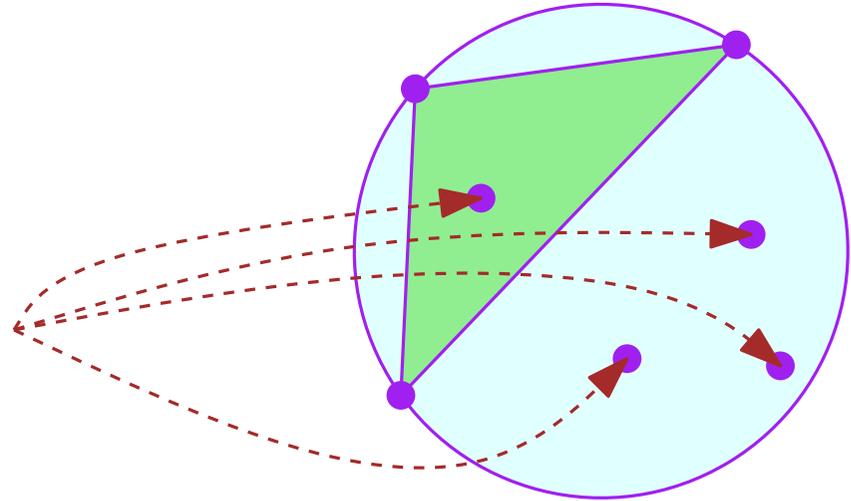
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11 - 7 Size (order  $\leq k$  Voronoi)  $\leq \frac{\alpha n}{\alpha^3} = nk^2$

Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers

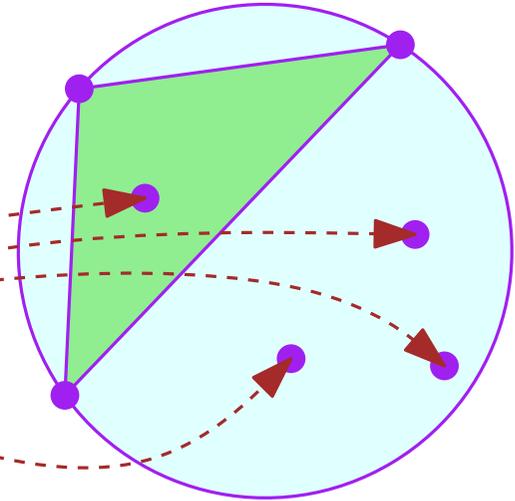


Probability that it exists during the construction

$$= \frac{3}{j+3} \frac{2}{j+2} \frac{1}{j+1}$$

## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists during the construction

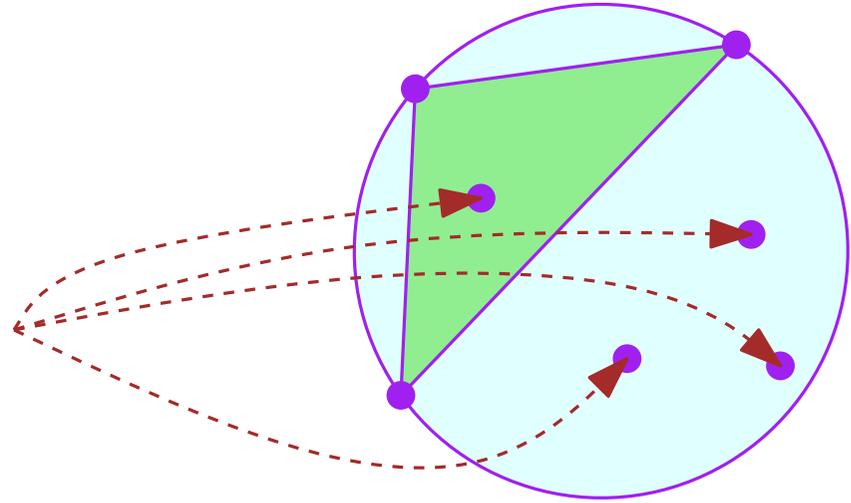
$$= \frac{3}{j+3} \frac{2}{j+2} \frac{1}{j+1}$$

# of created triangles

$$= \sum_{j=0}^n \mathbb{P} [\Delta \text{ with } j \text{ stoppers appears}] \times \#\Delta \text{ with } j \text{ stoppers}$$

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Triangle  $\Delta$  with  $j$  stoppers



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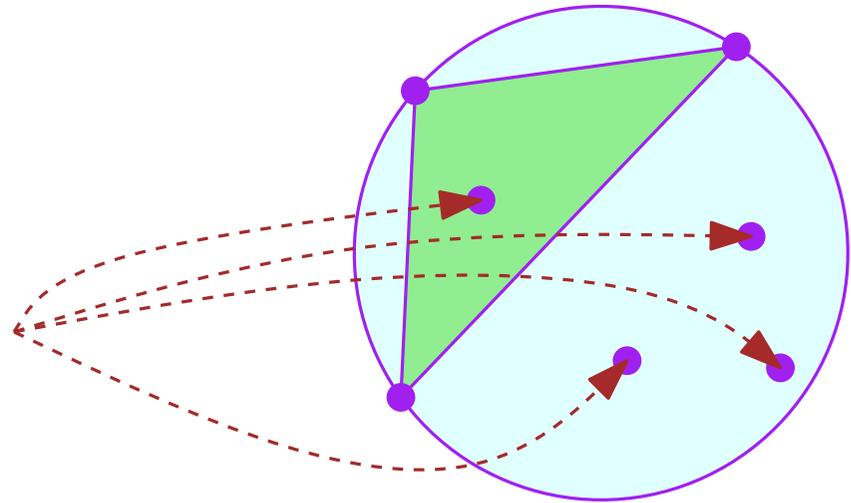
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Triangle  $\Delta$  with  $j$  stoppers



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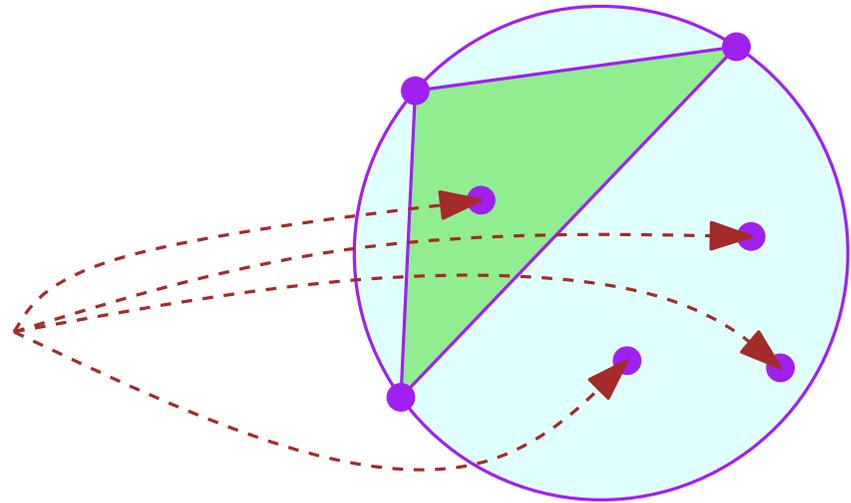
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$$\approx \sum_{j=0}^n \frac{18}{j^4} \times nj^2 = O\left(n \sum_{j=0}^n \frac{1}{j^2}\right) = O(n)$$

Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers

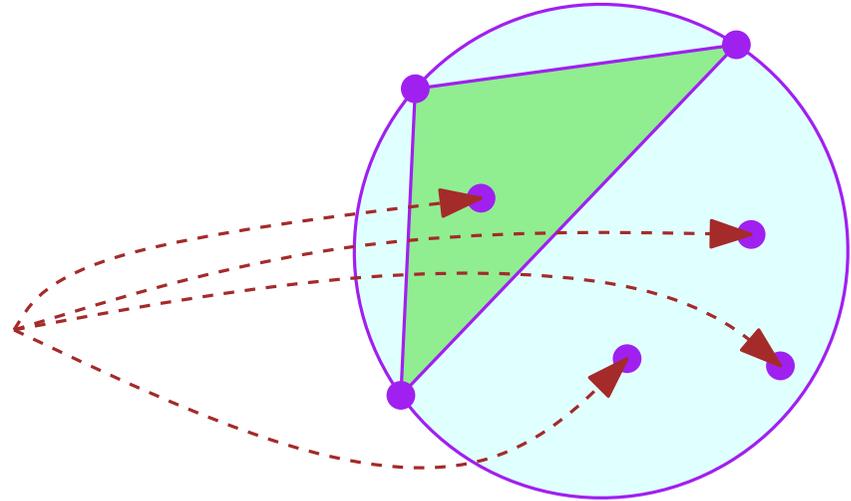


Conflict graph / History graph

It remains to analyze conflict location

## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists during the construction

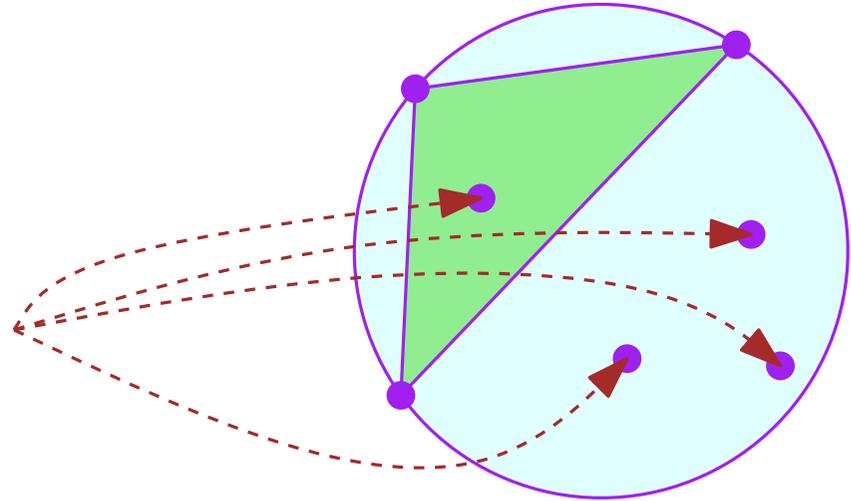
$$= \frac{3}{j+3} \frac{2}{j+2} \frac{1}{j+1}$$

# of conflicts occurring

$$= \sum_{j=0}^n j \times \mathbb{P}[\Delta \text{ with } j \text{ stoppers appears}] \times \#\Delta \text{ with } j \text{ stoppers}$$

## Alternative analysis

Triangle  $\Delta$  with  $j$  stoppers



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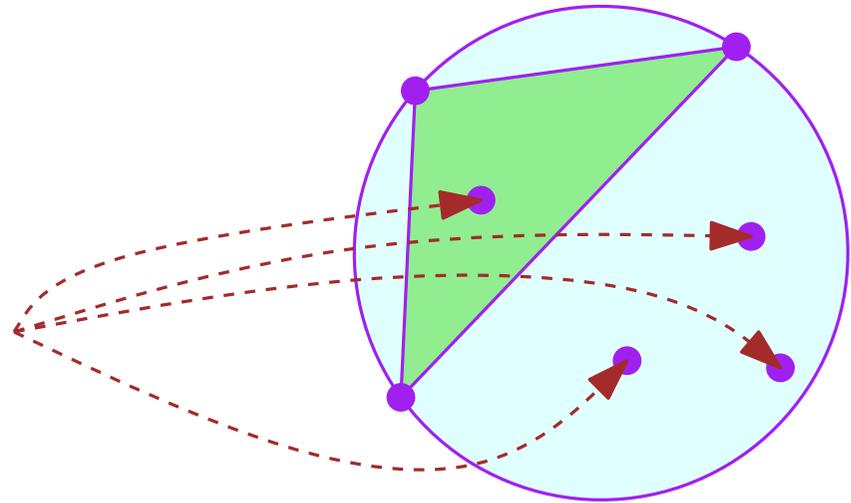
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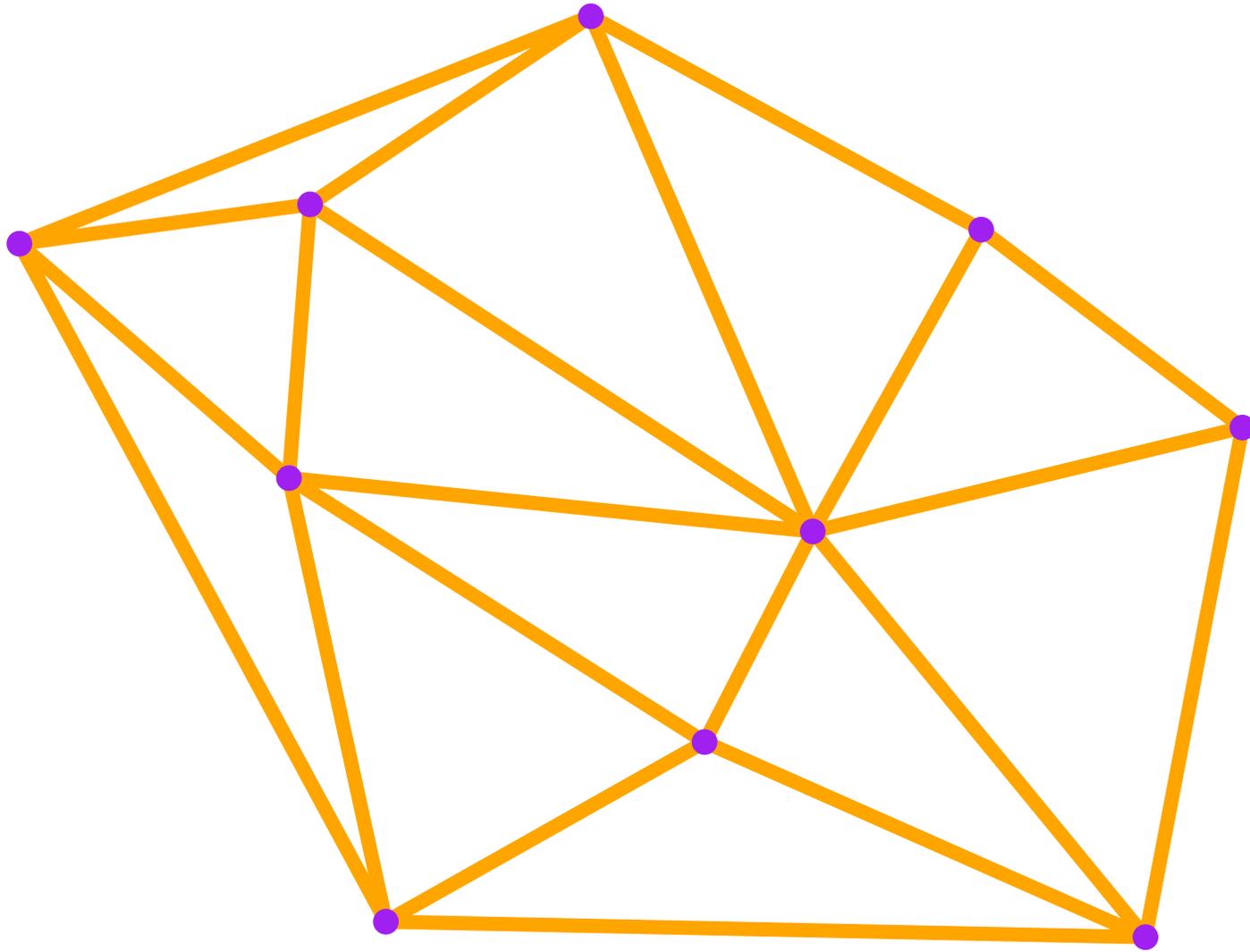
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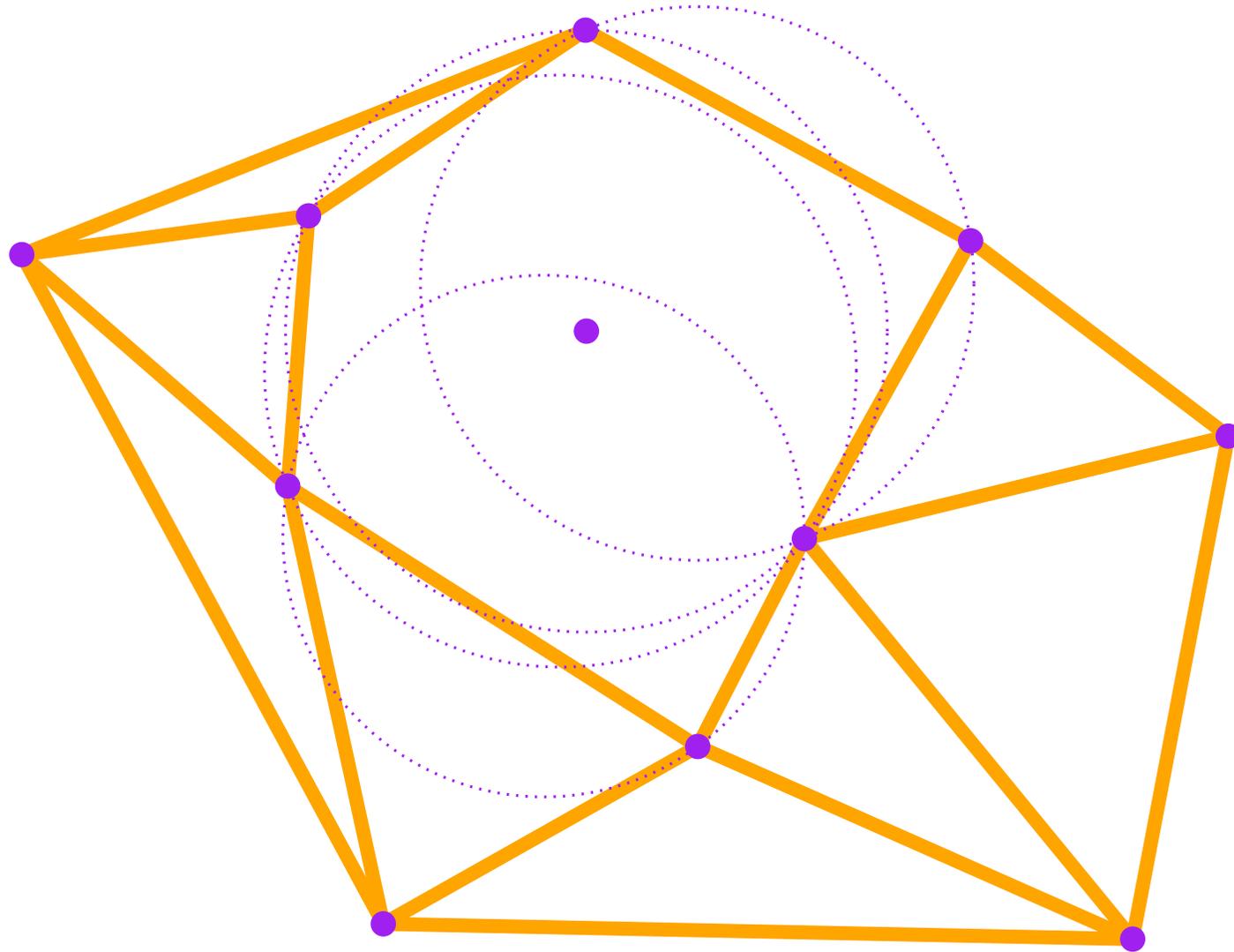
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$$\approx \sum_{j=0}^n j \times \frac{18}{j^4} \times nj^2 = O\left(n \sum_{j=1}^n \frac{1}{j}\right) = O(n \log n)$$

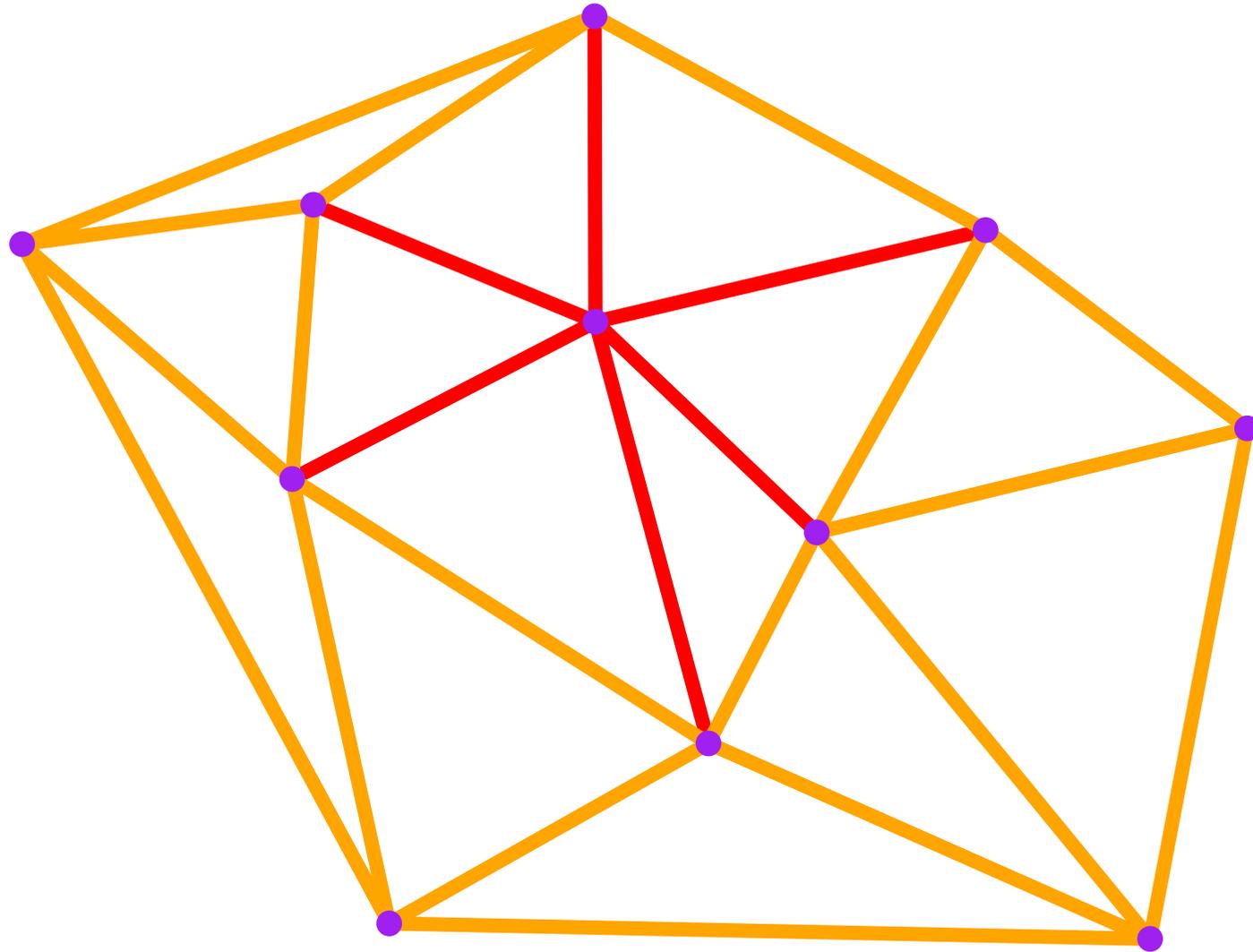
# History graph



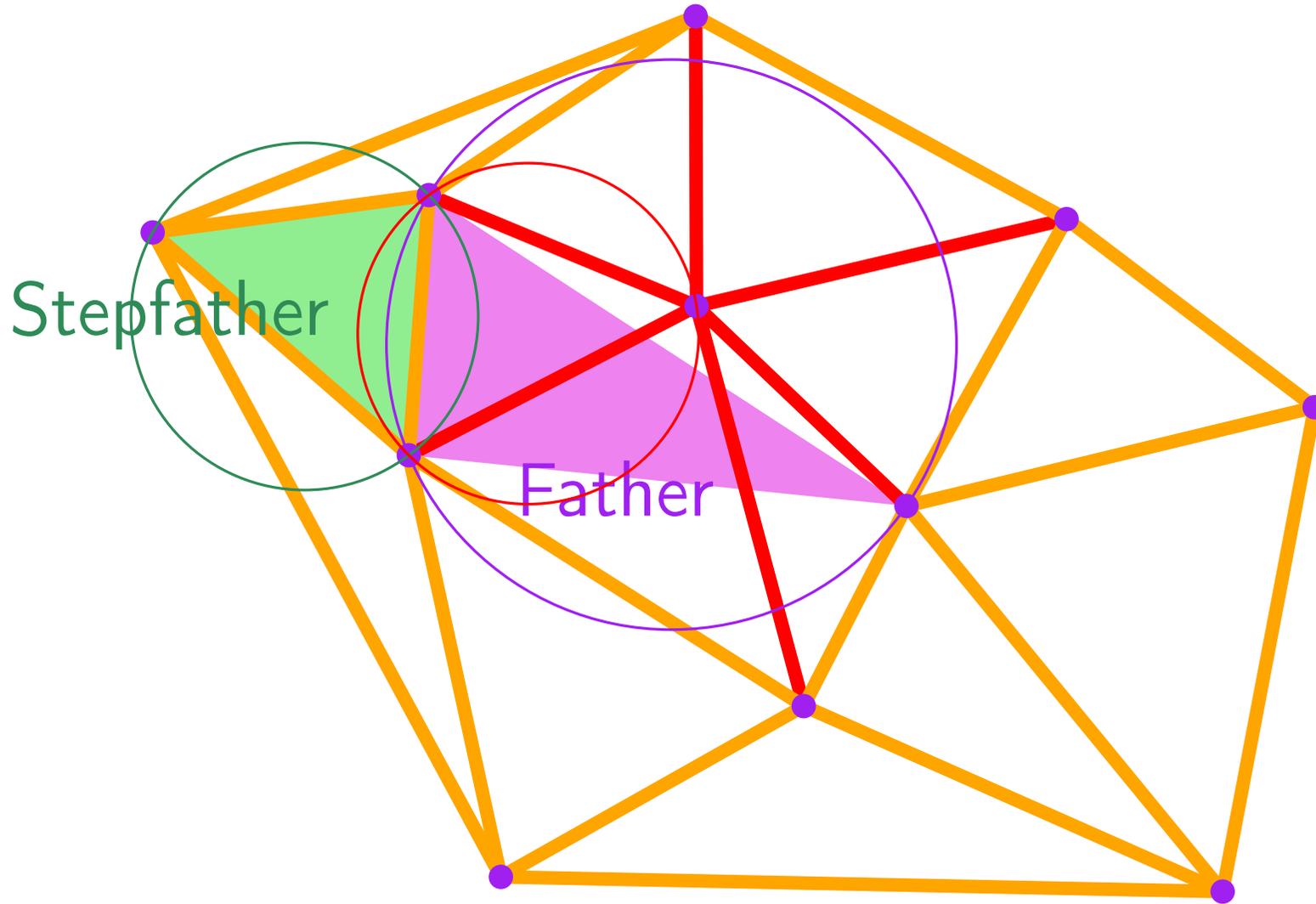
# History graph



# History graph

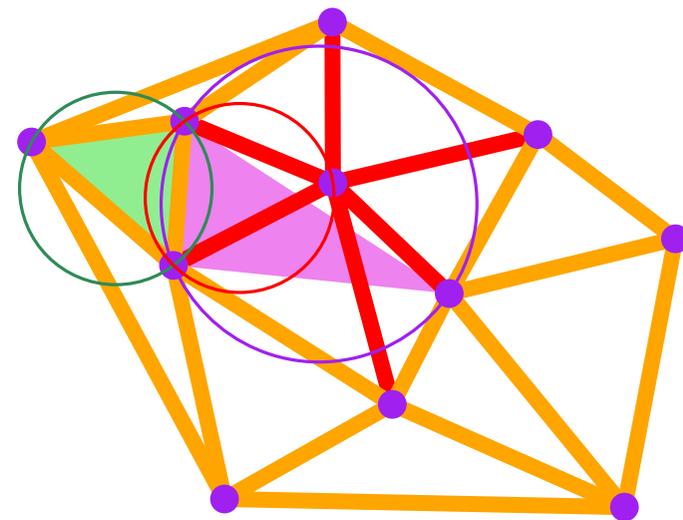
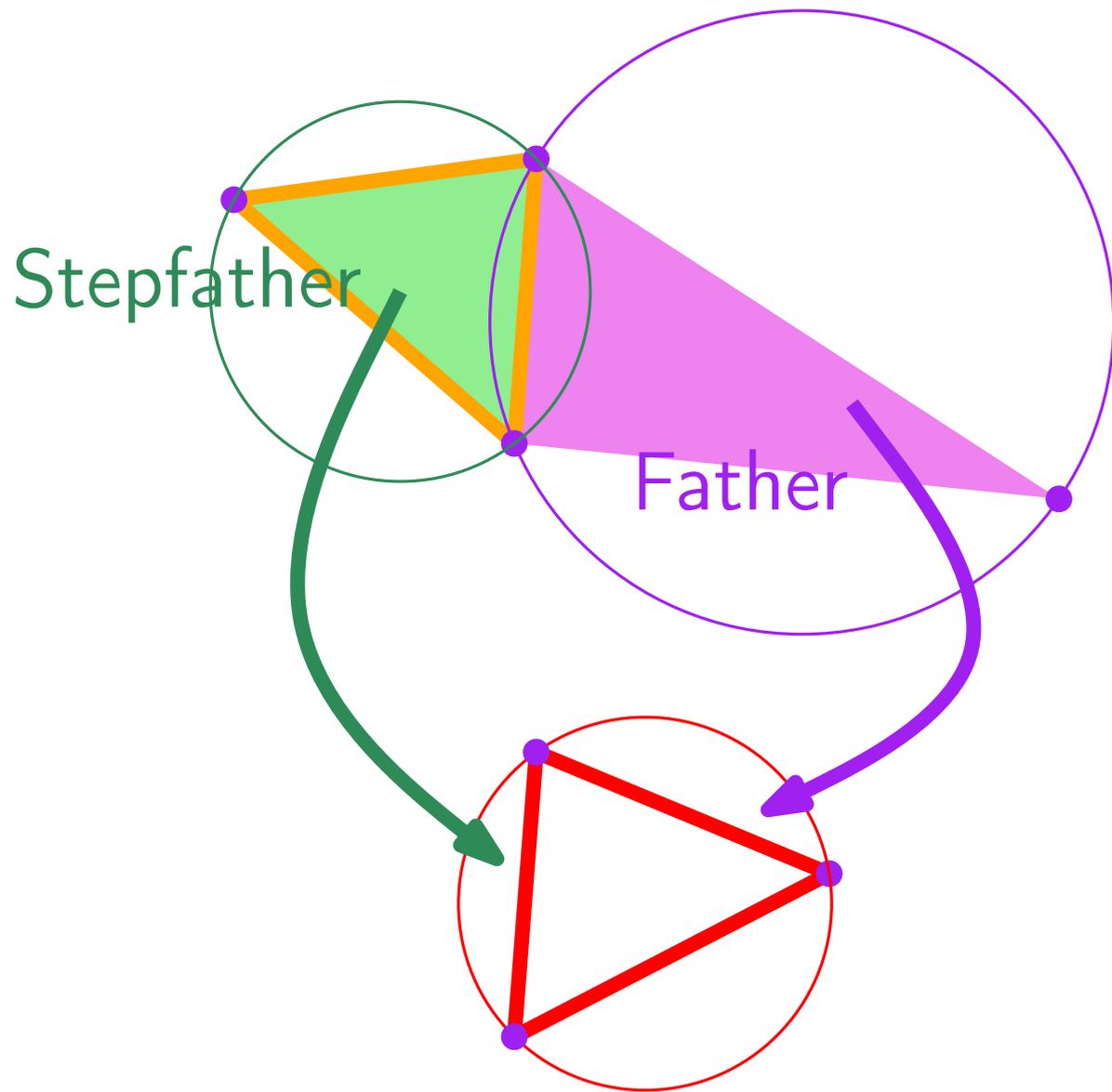


# History graph



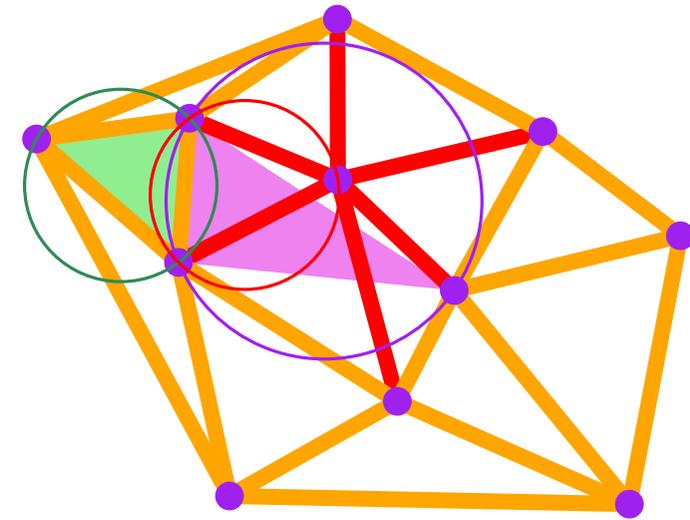
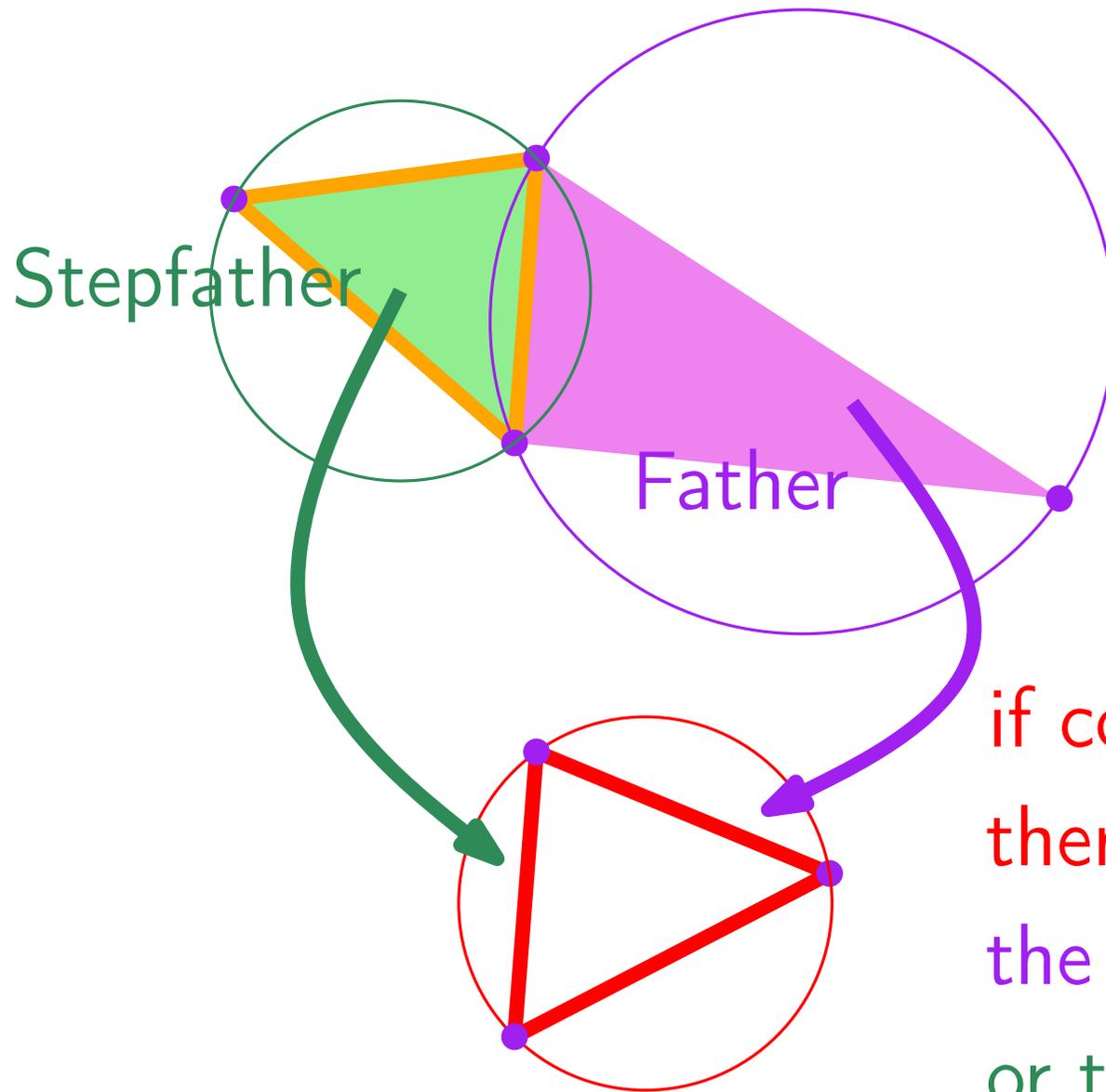
History graph

(Delaunay tree)



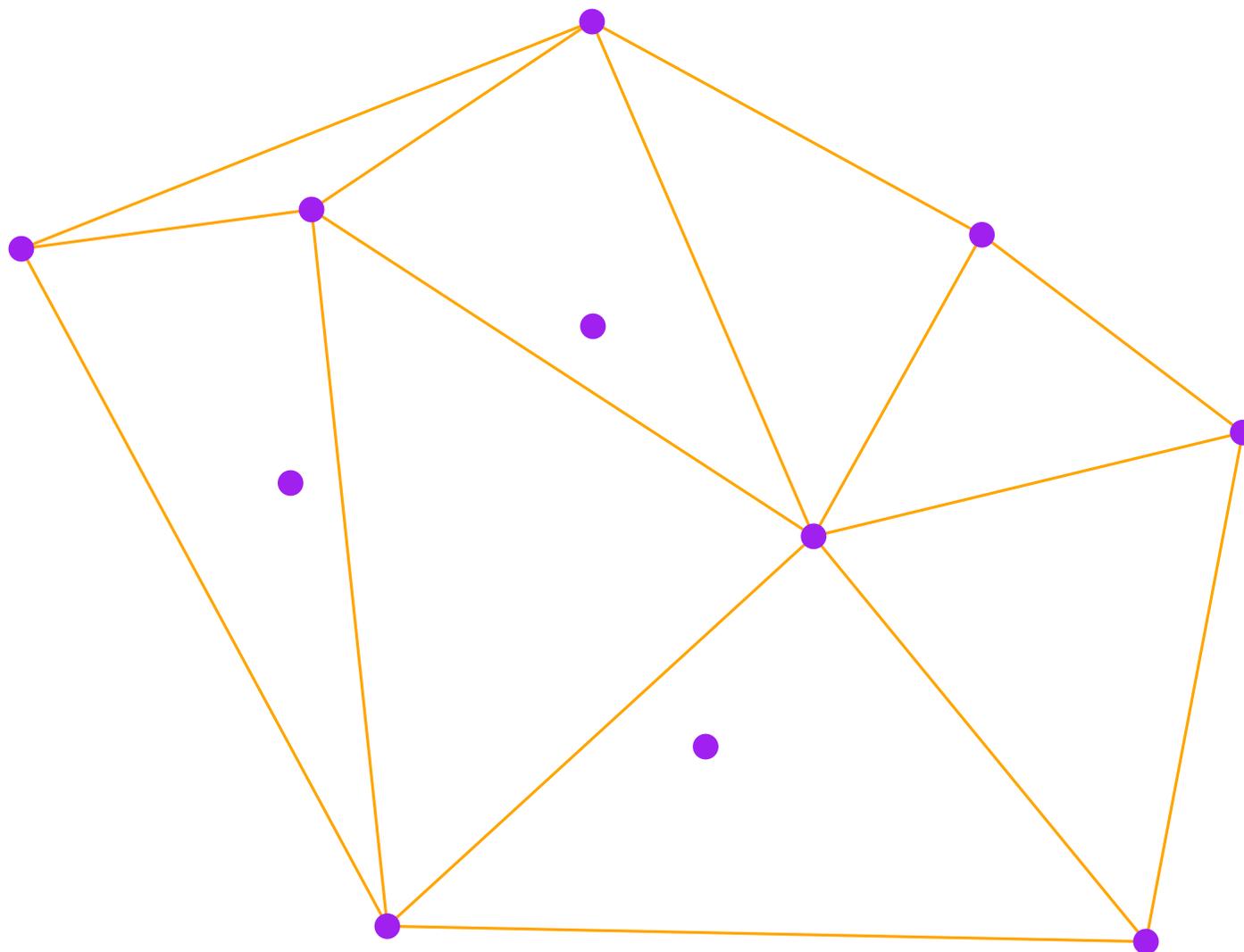
History graph

(Delaunay tree)

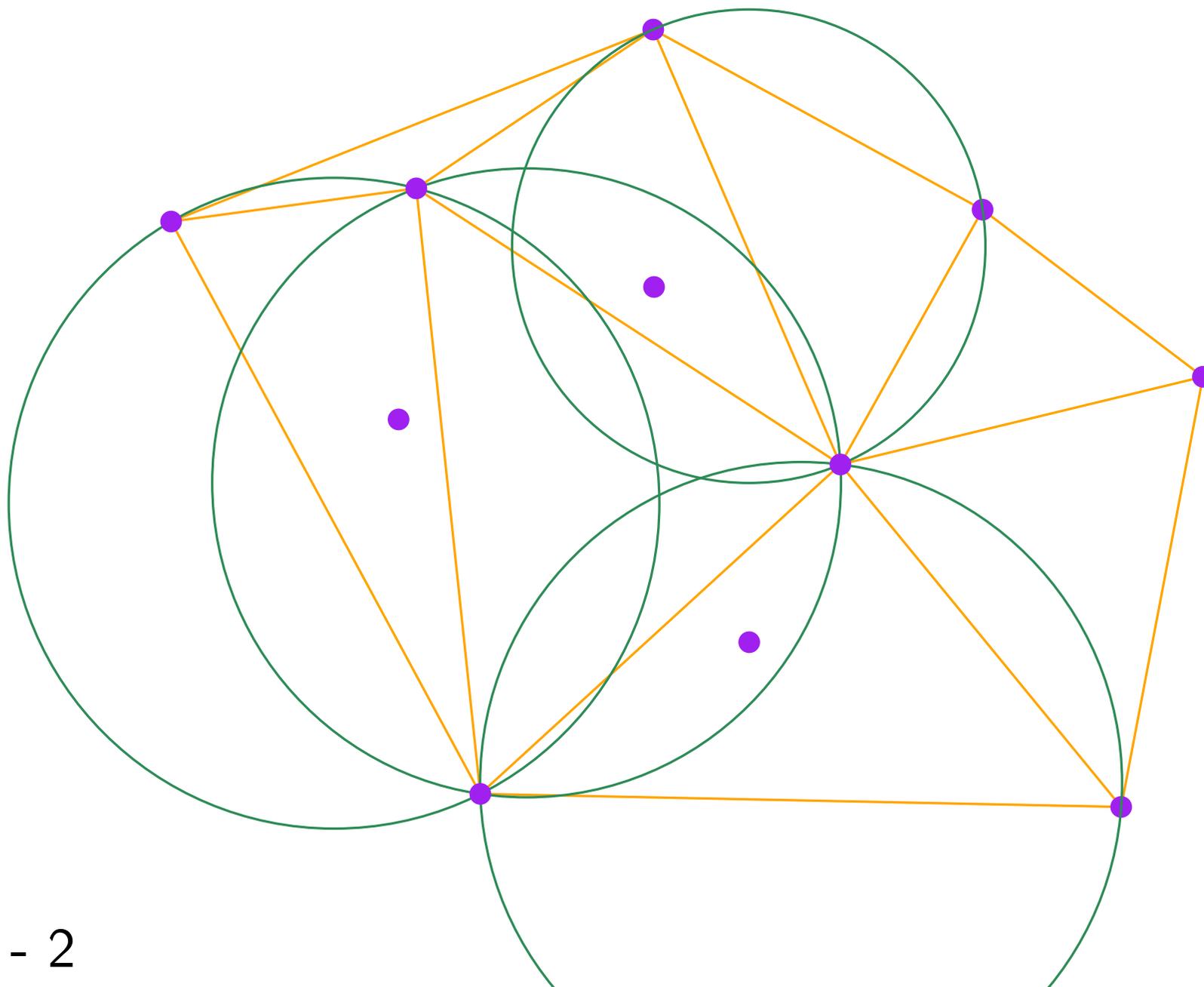


if conflict  
there was a conflict with  
the father  
or the stepfather  
or both

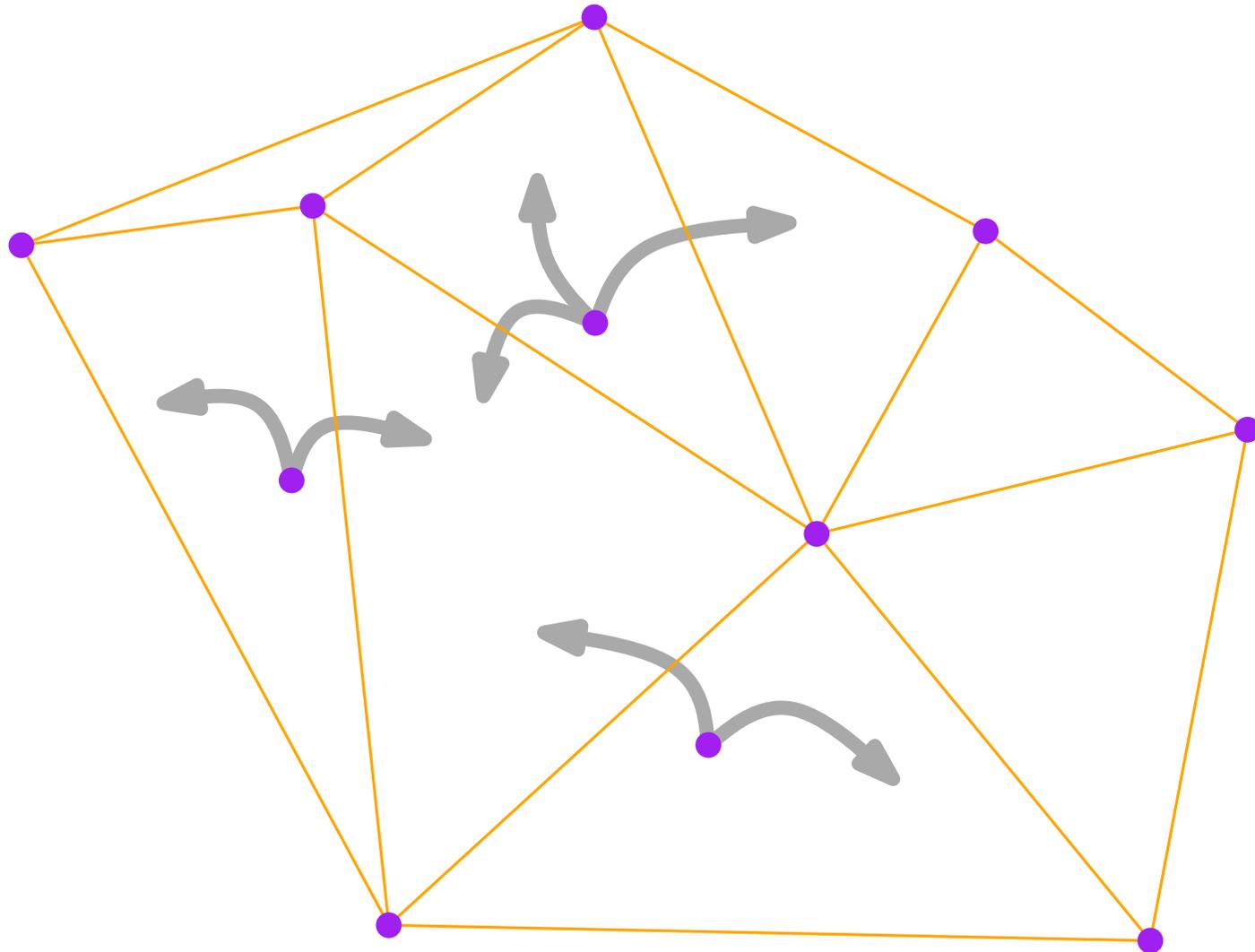
# Conflict graph



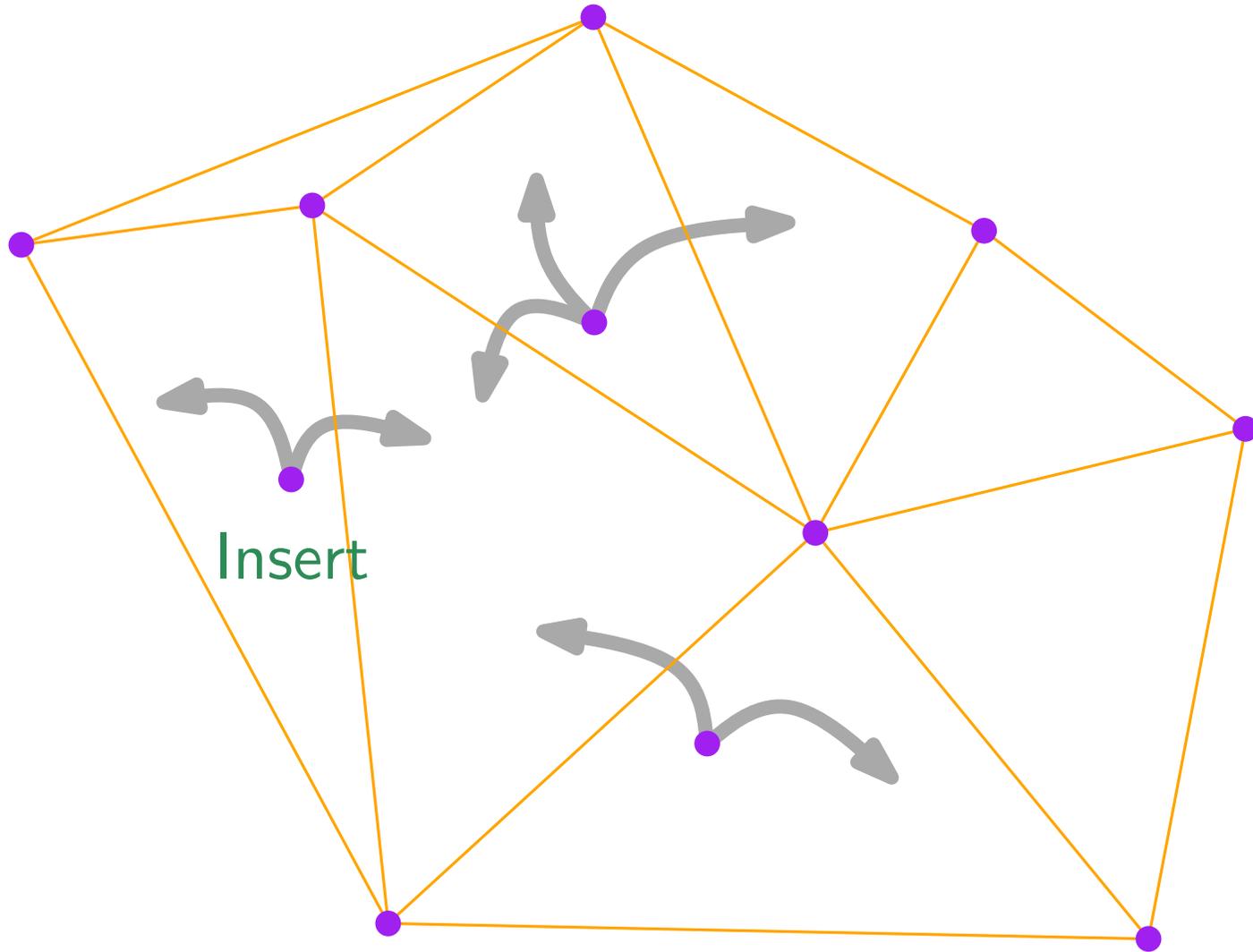
# Conflict graph



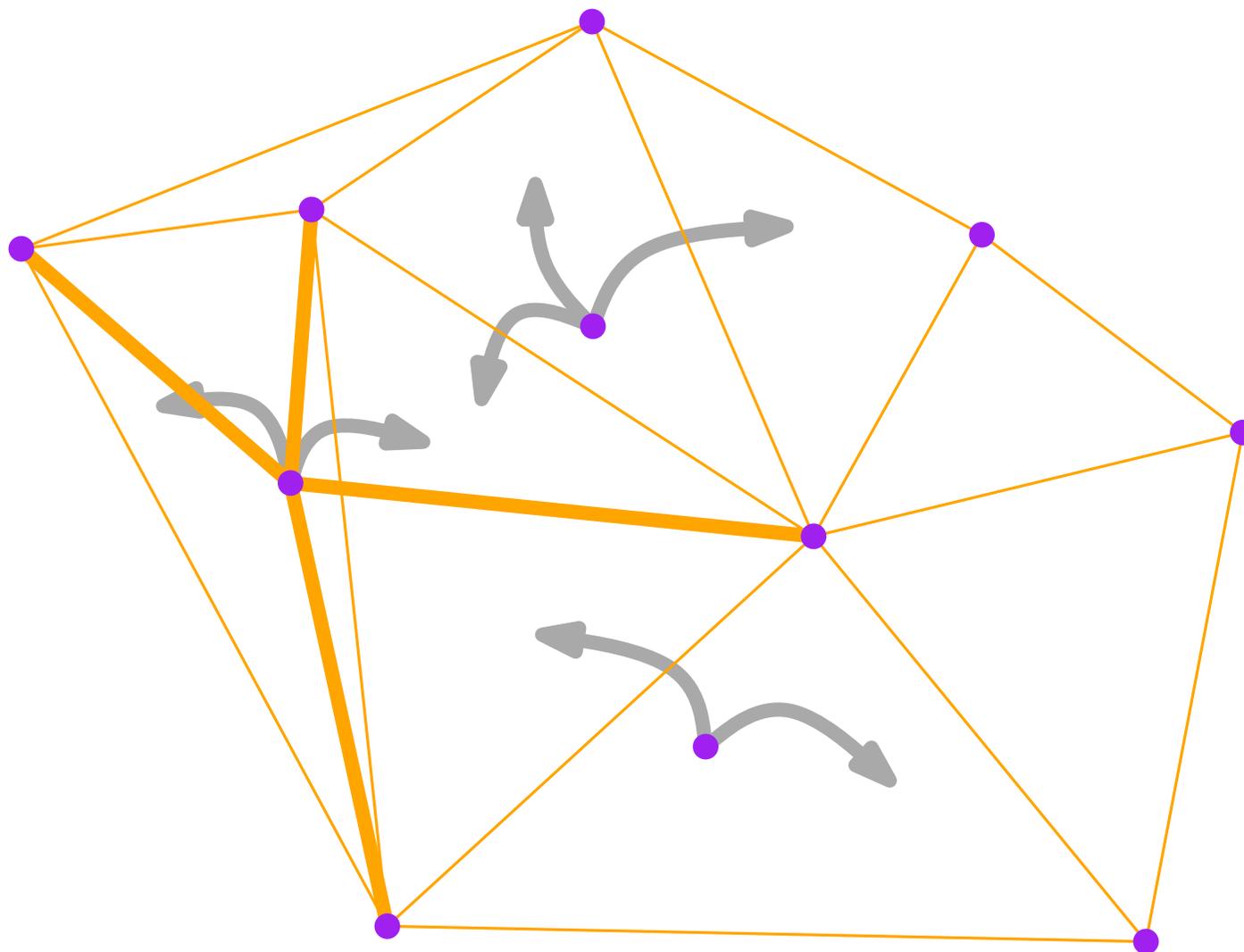
# Conflict graph



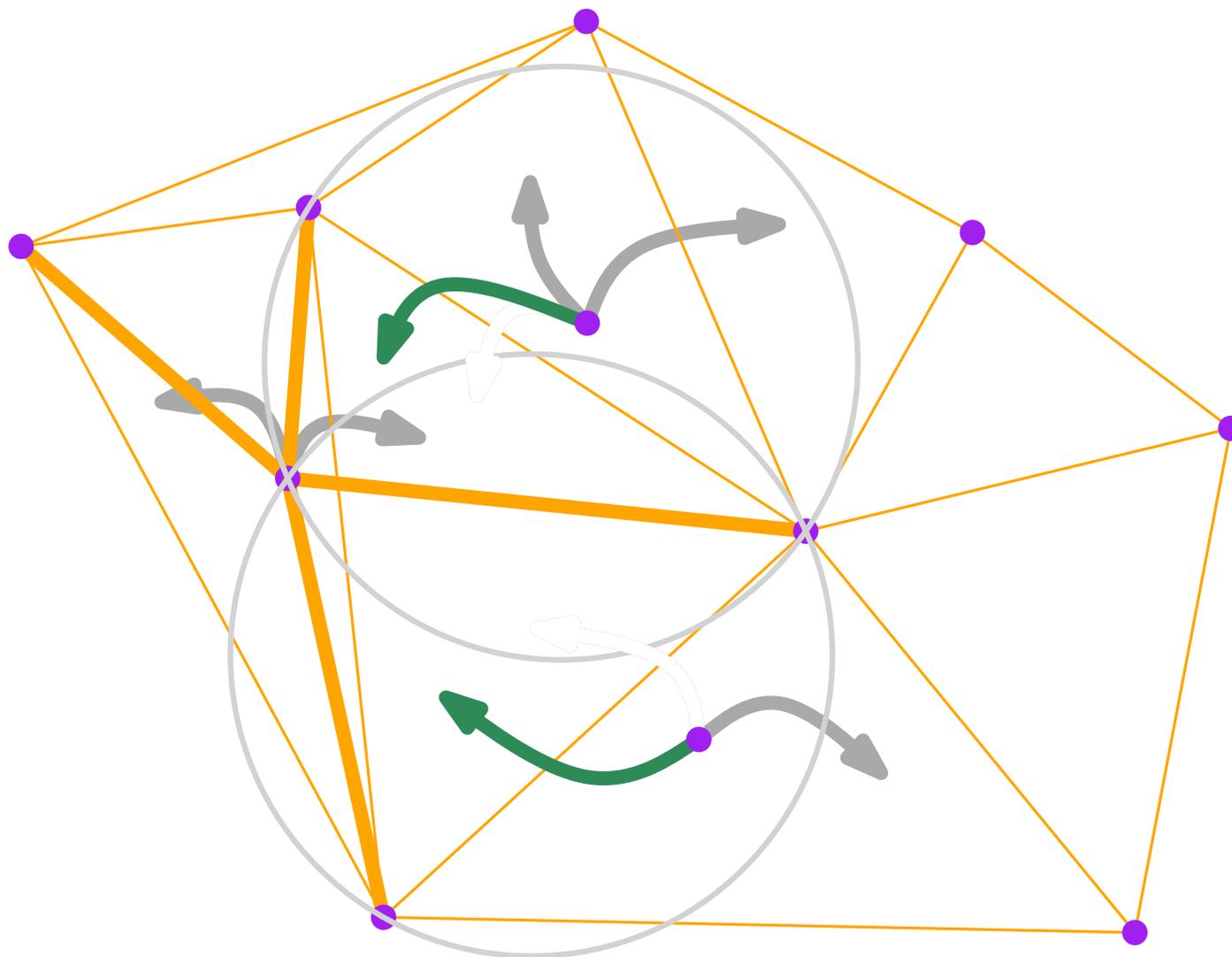
# Conflict graph



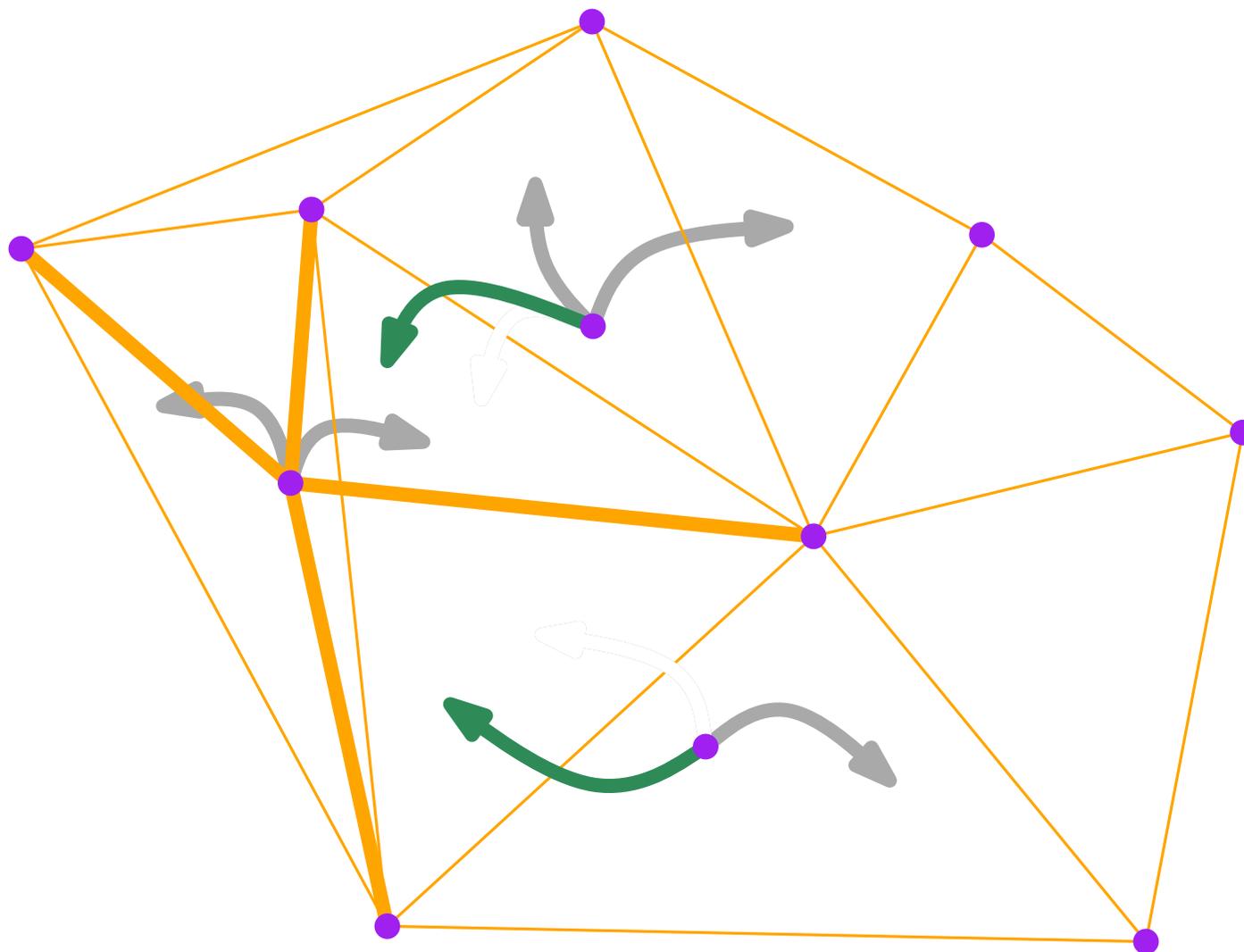
# Conflict graph



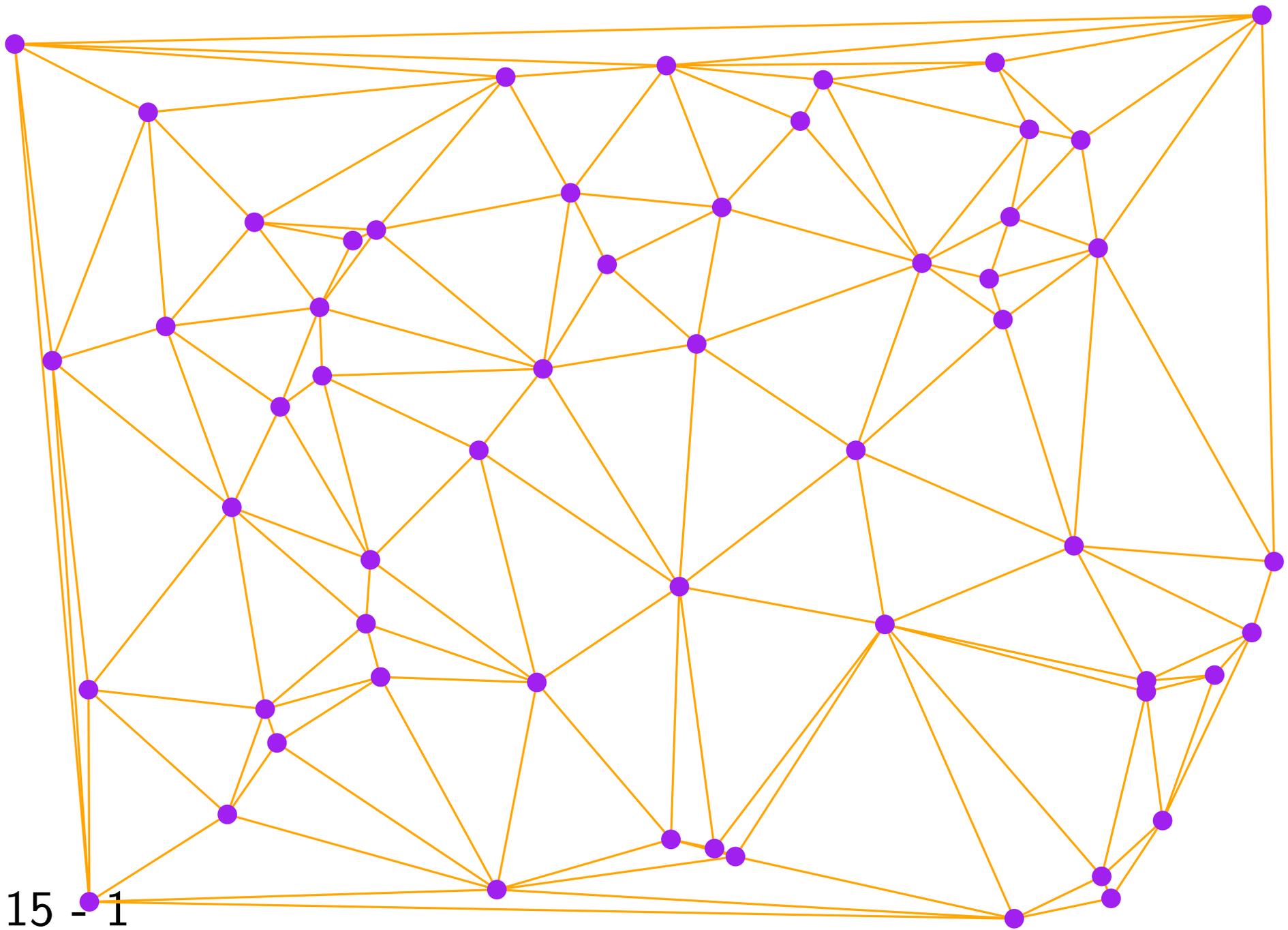
# Conflict graph



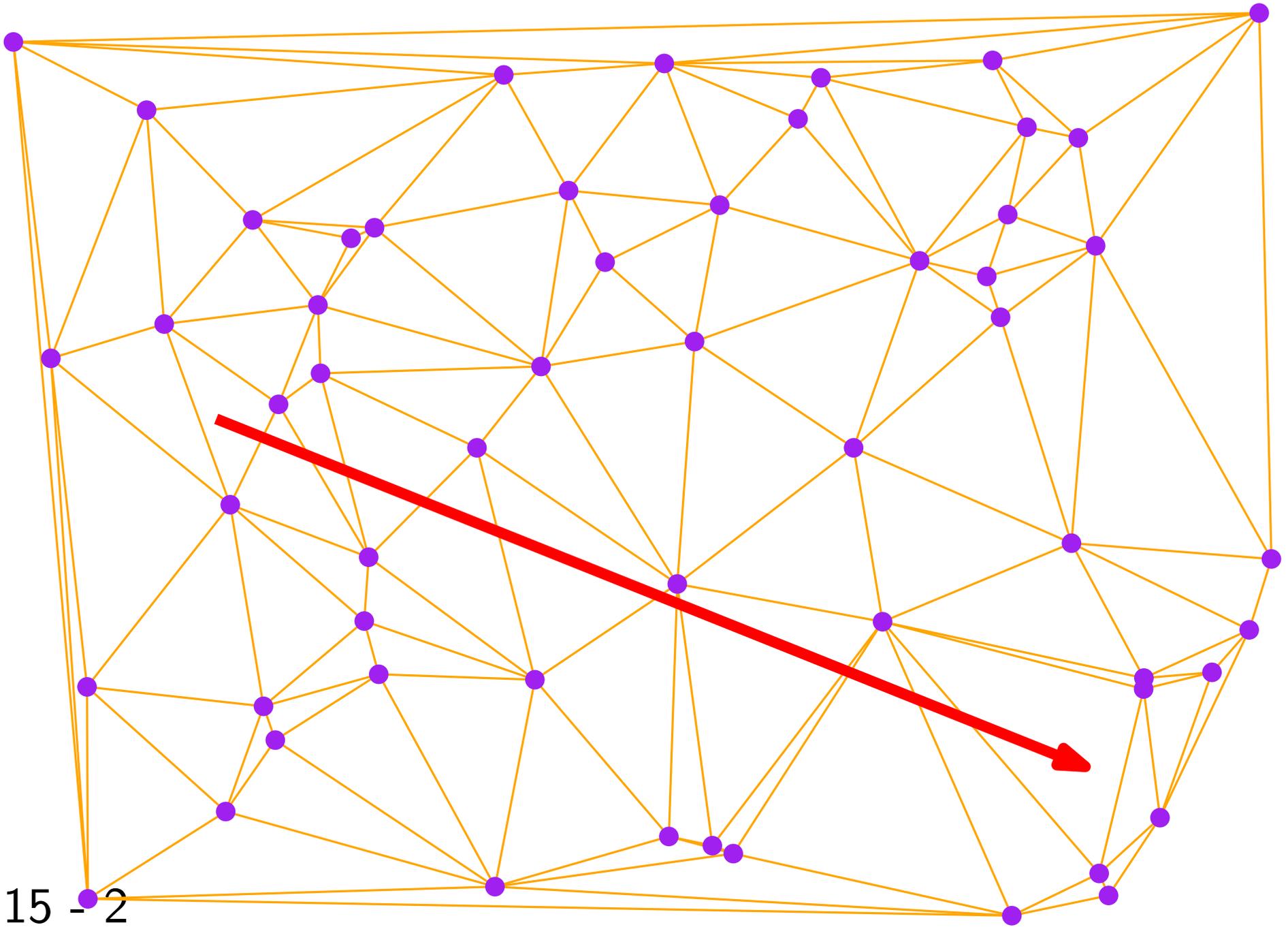
# Conflict graph



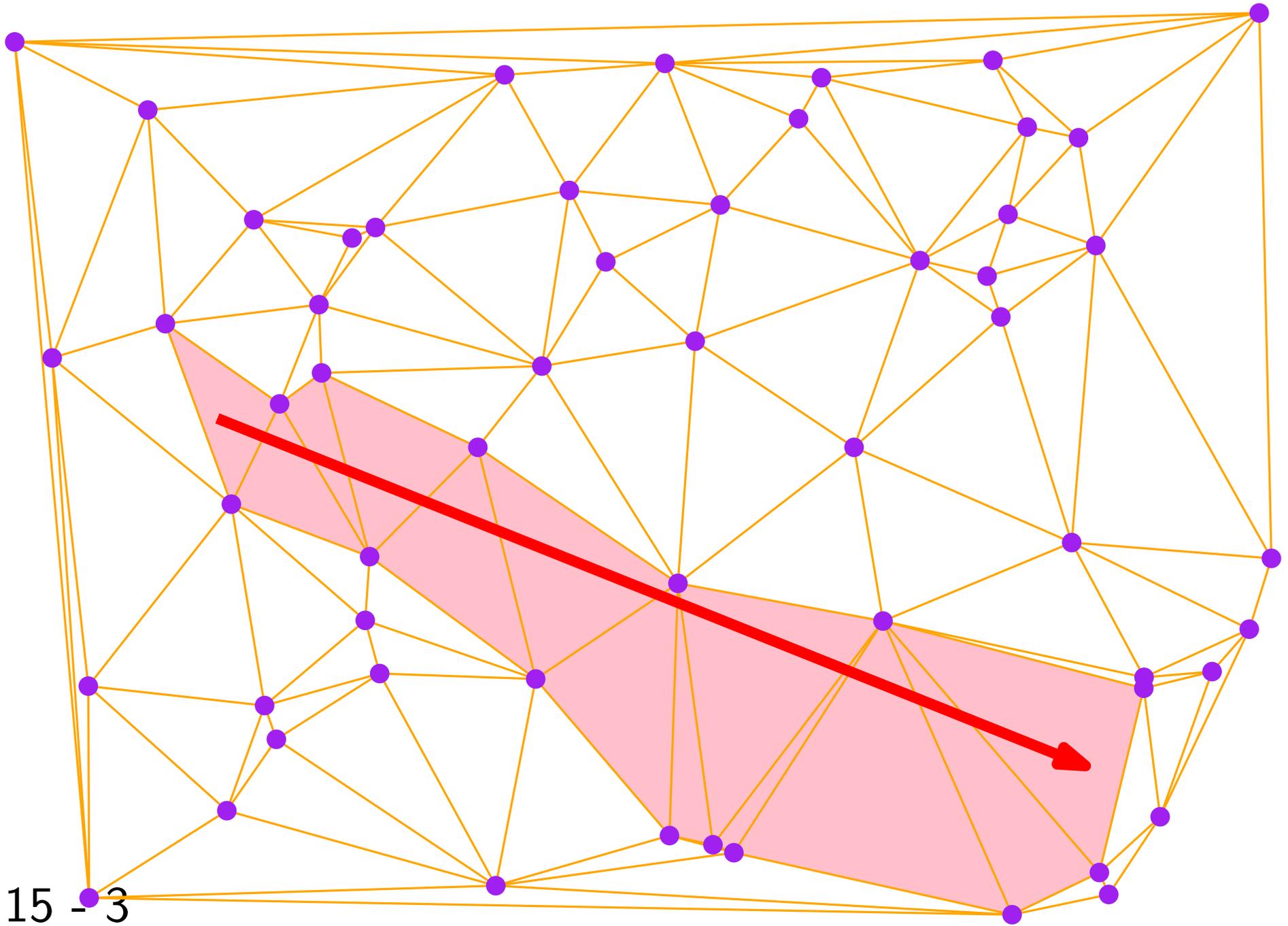
Walk



Walk

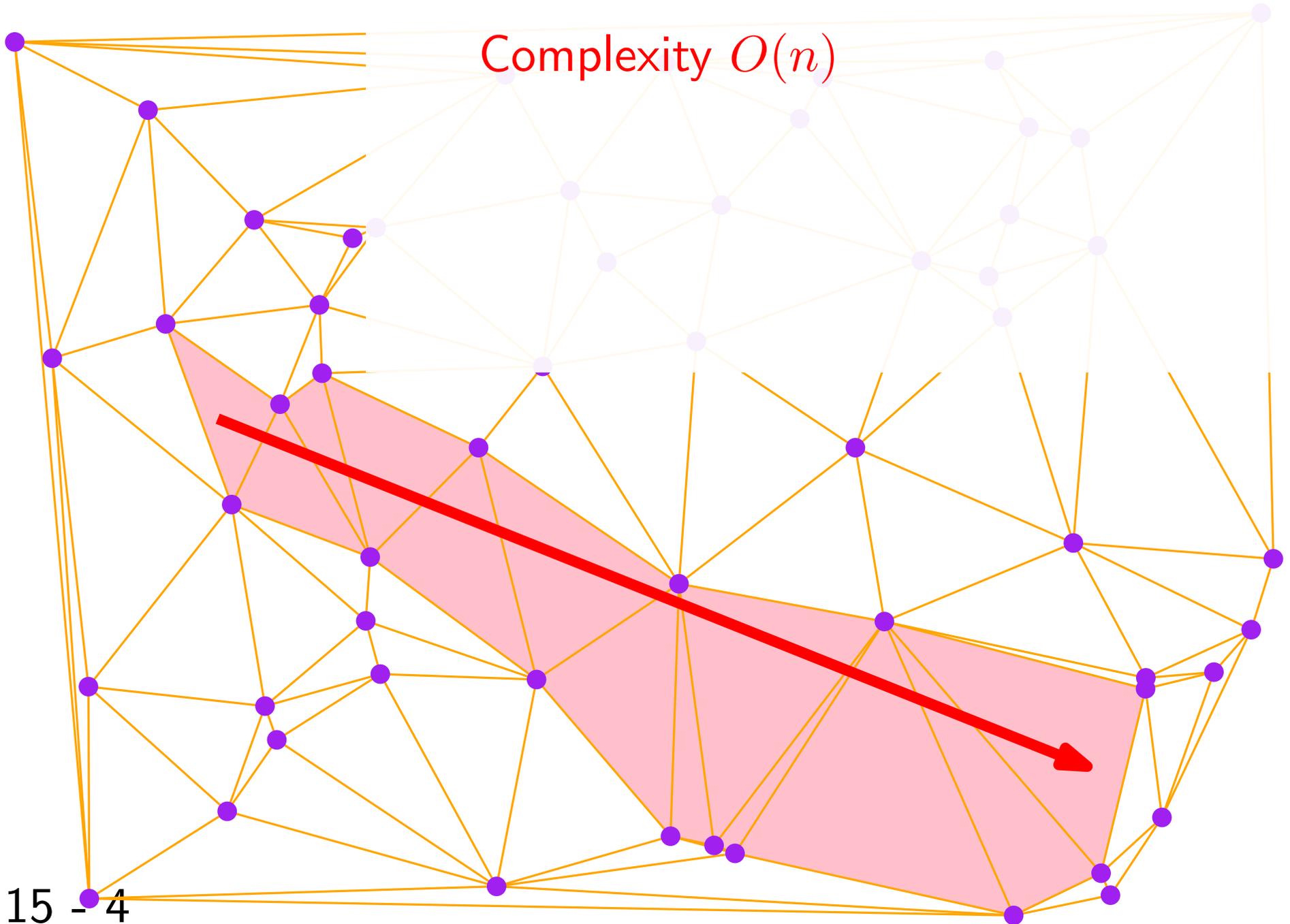


Walk



Walk

Complexity  $O(n)$



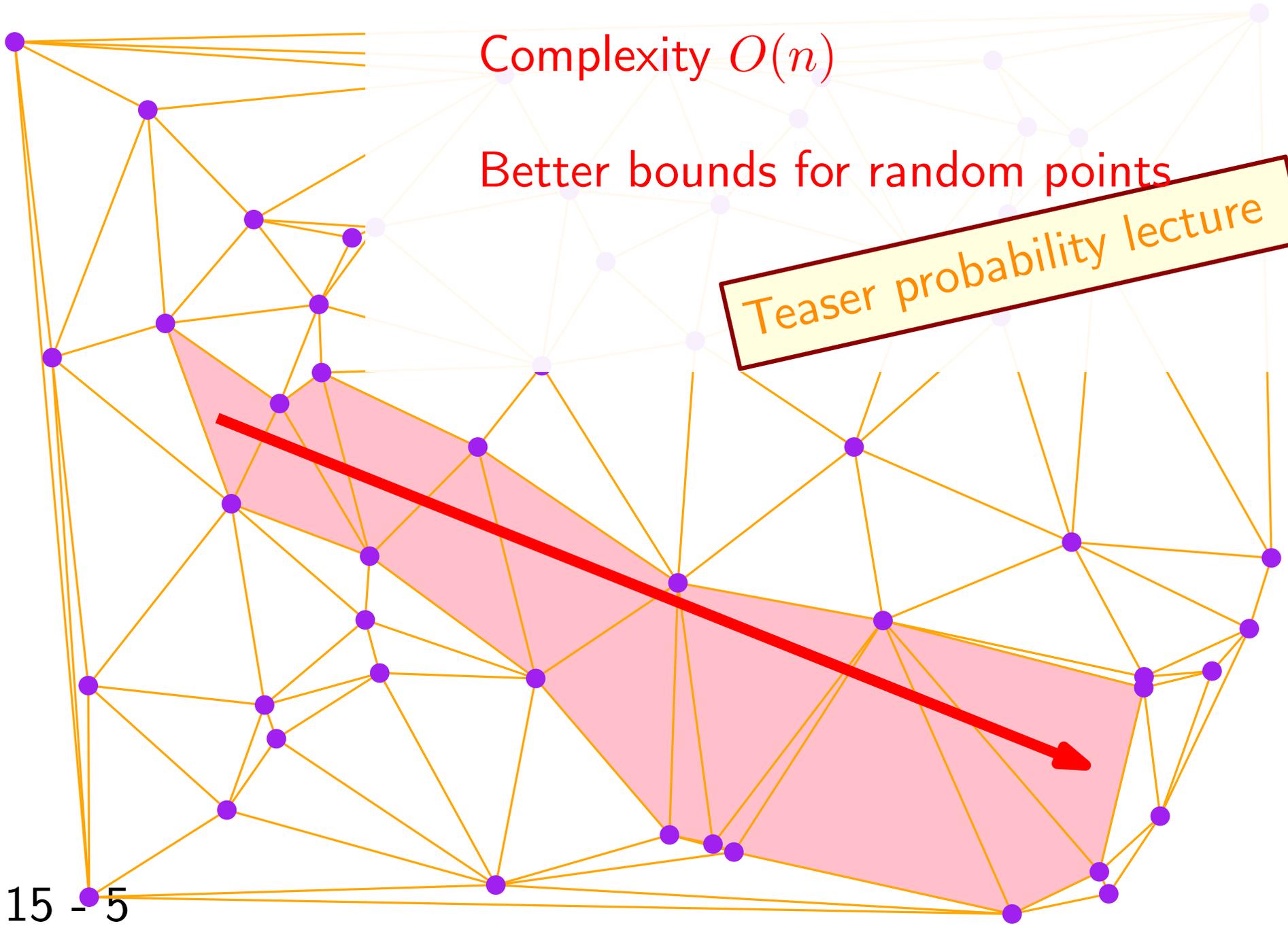
Walk

Complexity  $O(n)$

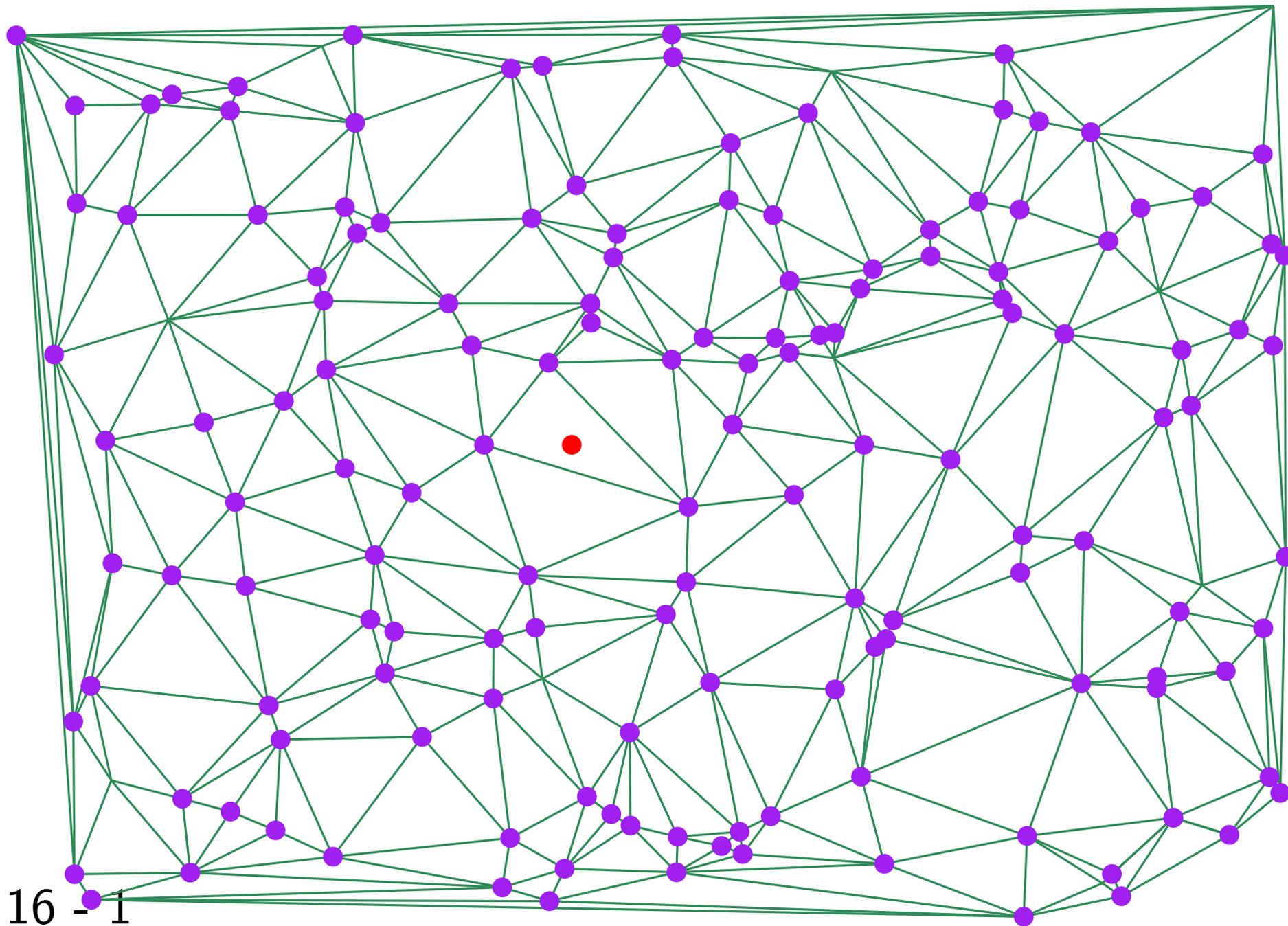
Better bounds for random points

Teaser probability lecture

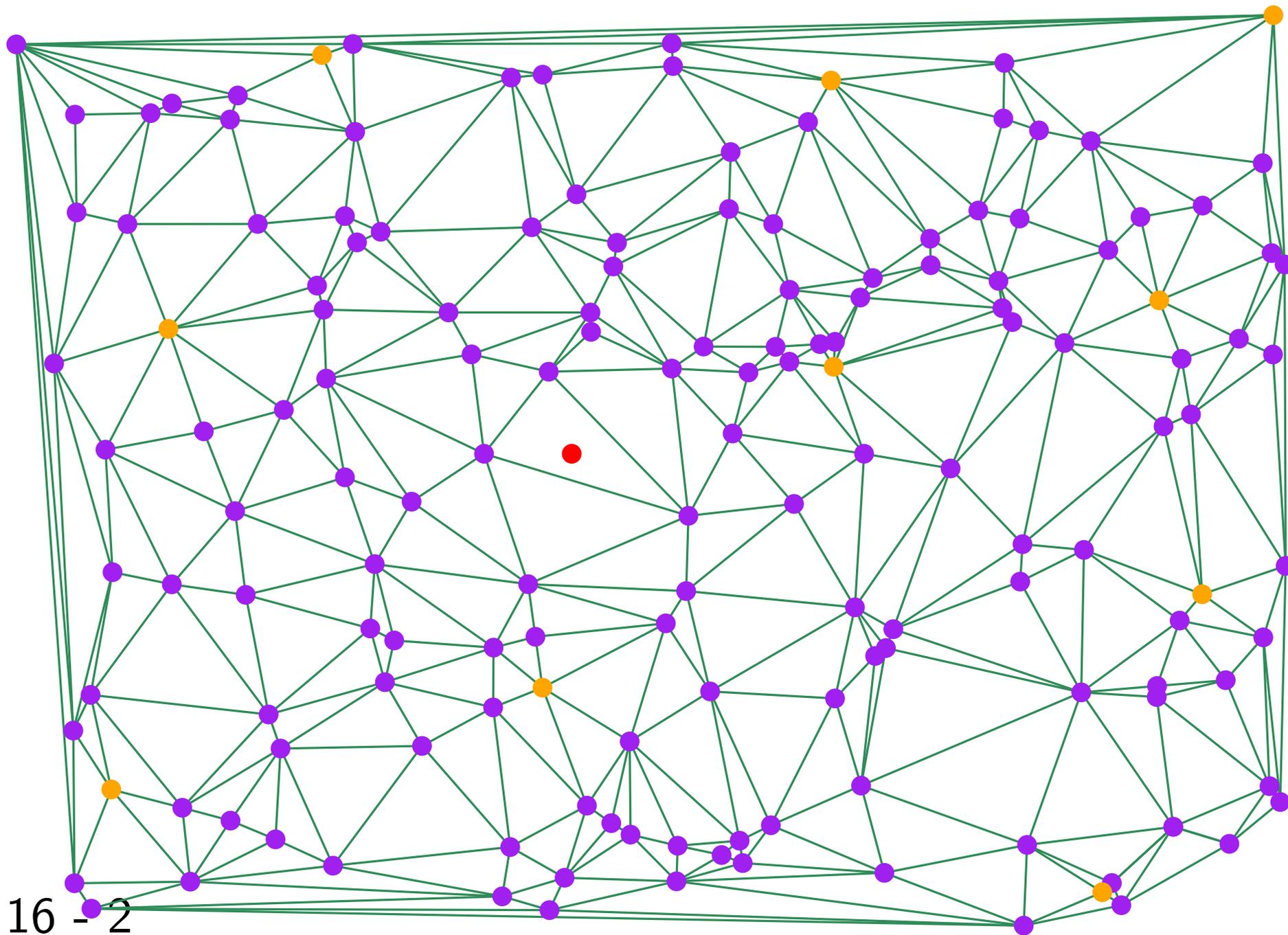
15 -5



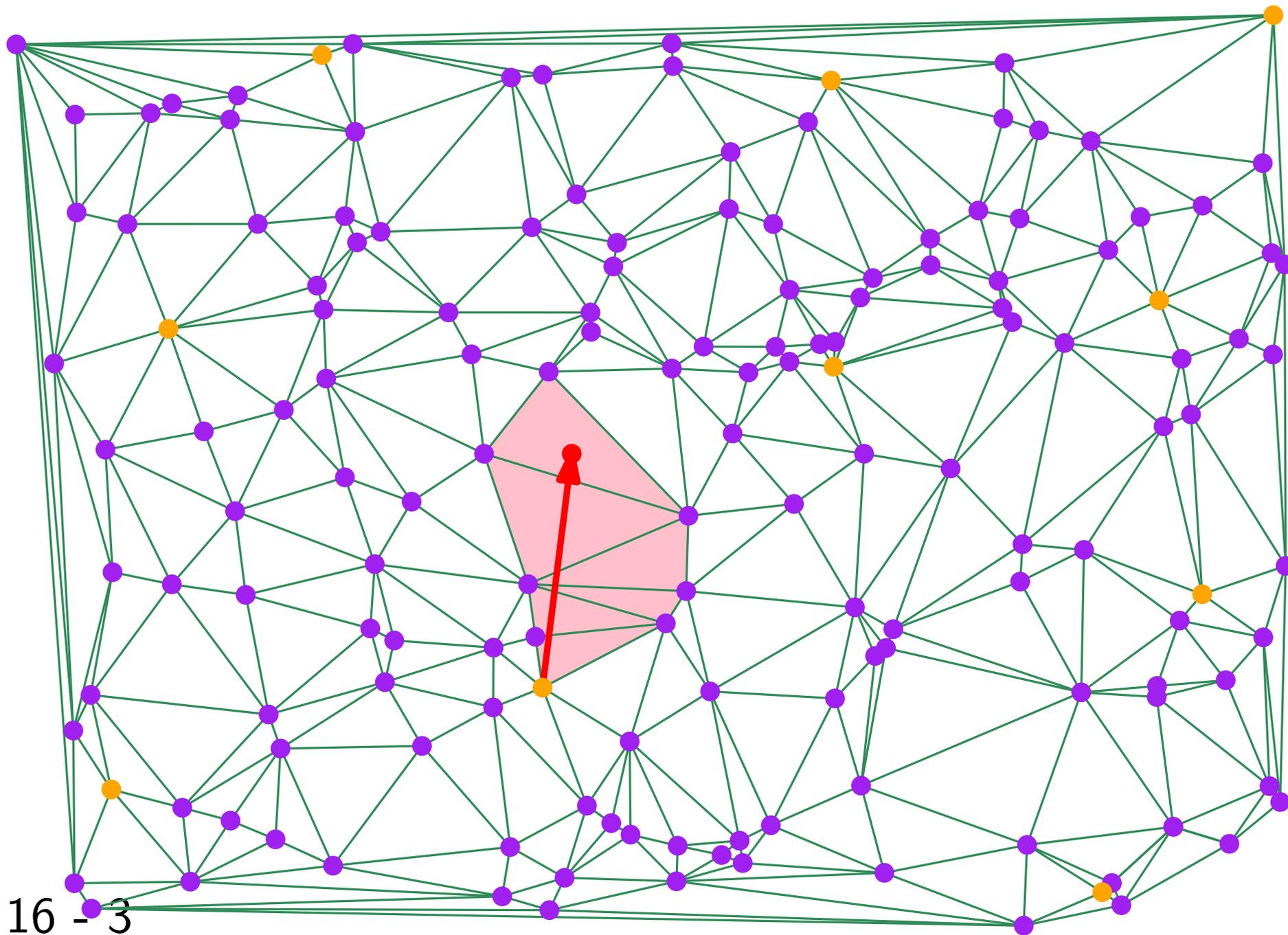
# Jump and walk



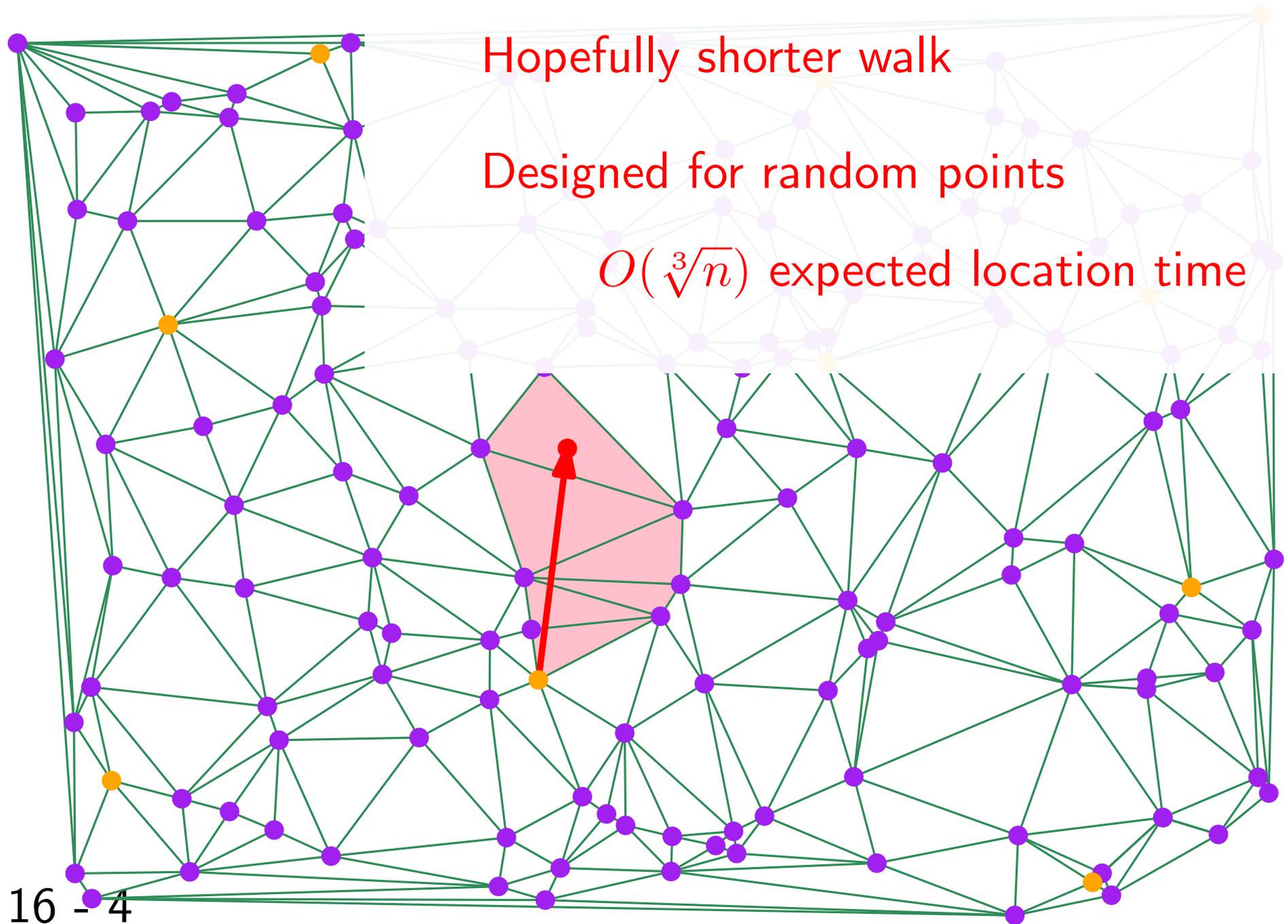
# Jump and walk



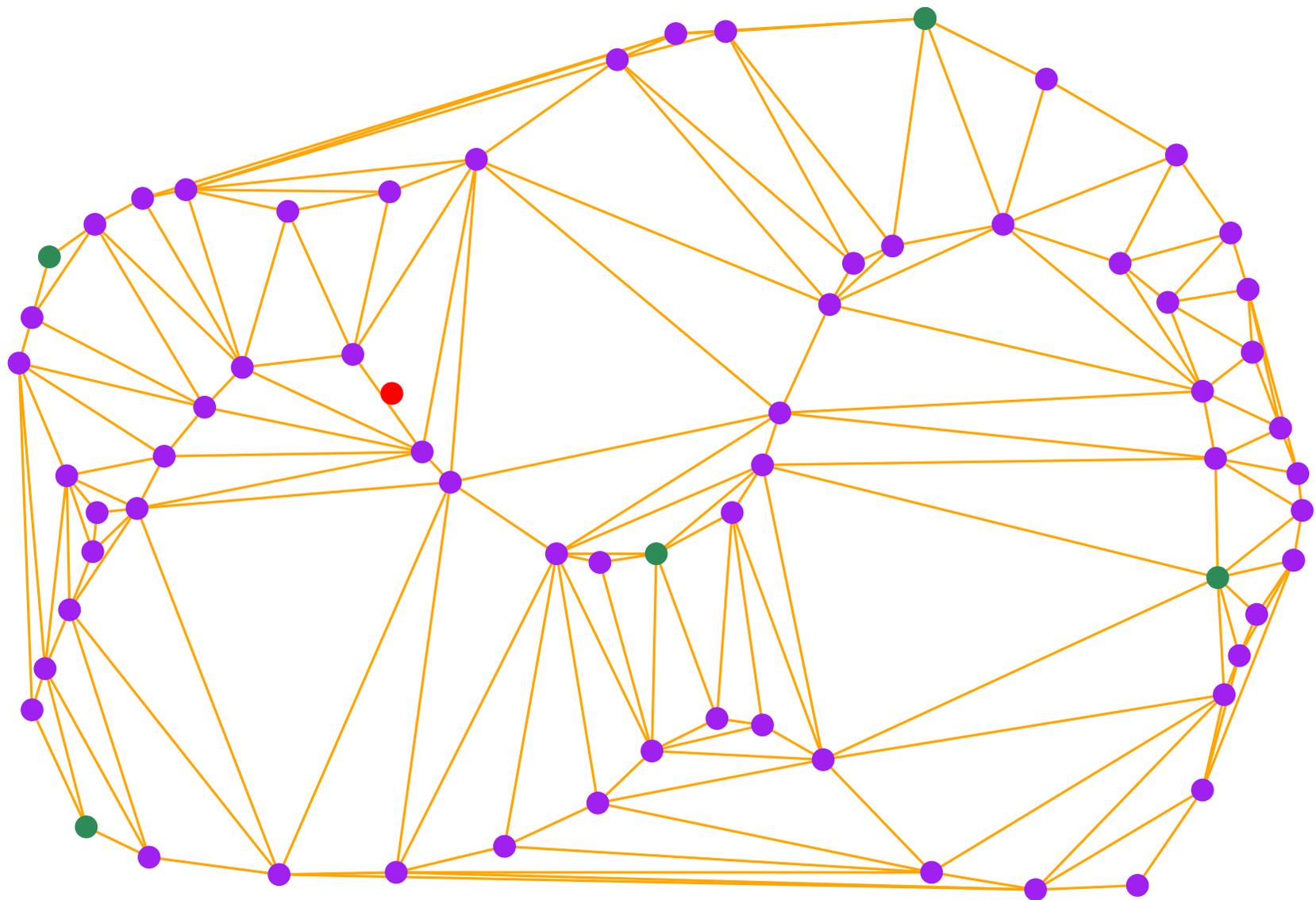
# Jump and walk



# Jump and walk

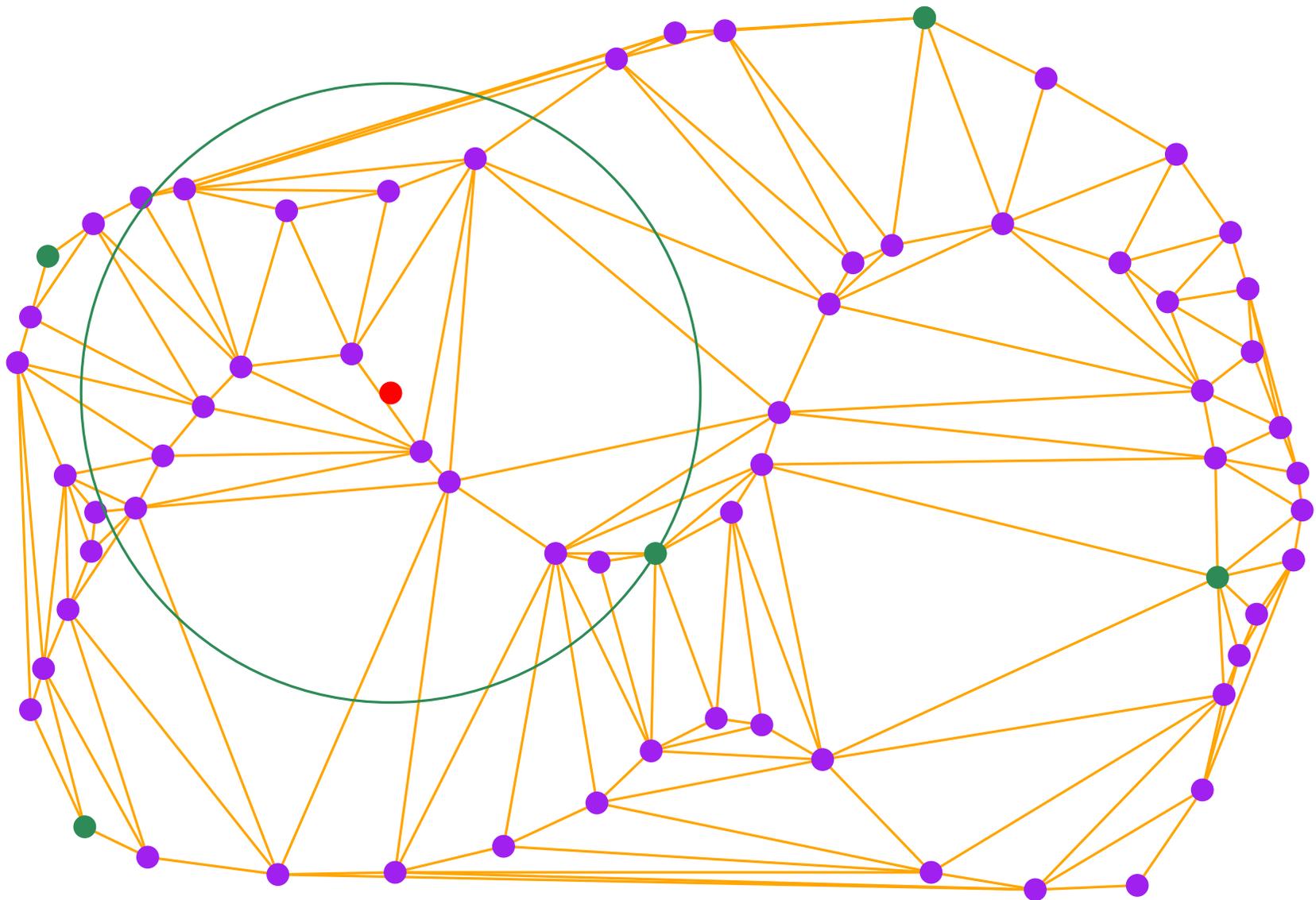


# Jump and walk (no distribution hypothesis)



# Jump and walk (no distribution hypothesis)

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

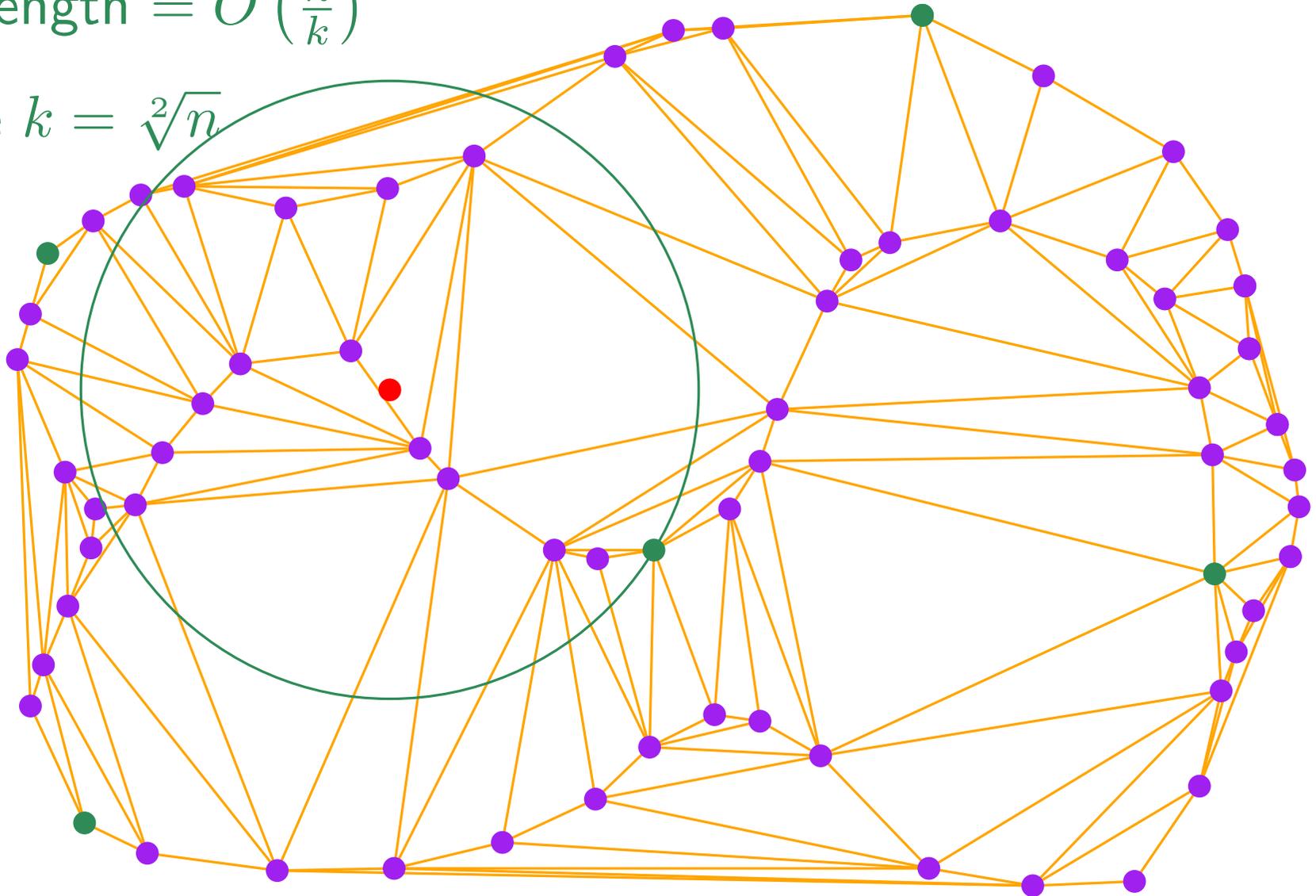


# Jump and walk (no distribution hypothesis)

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

$$\text{choose } k = \sqrt[2]{n}$$

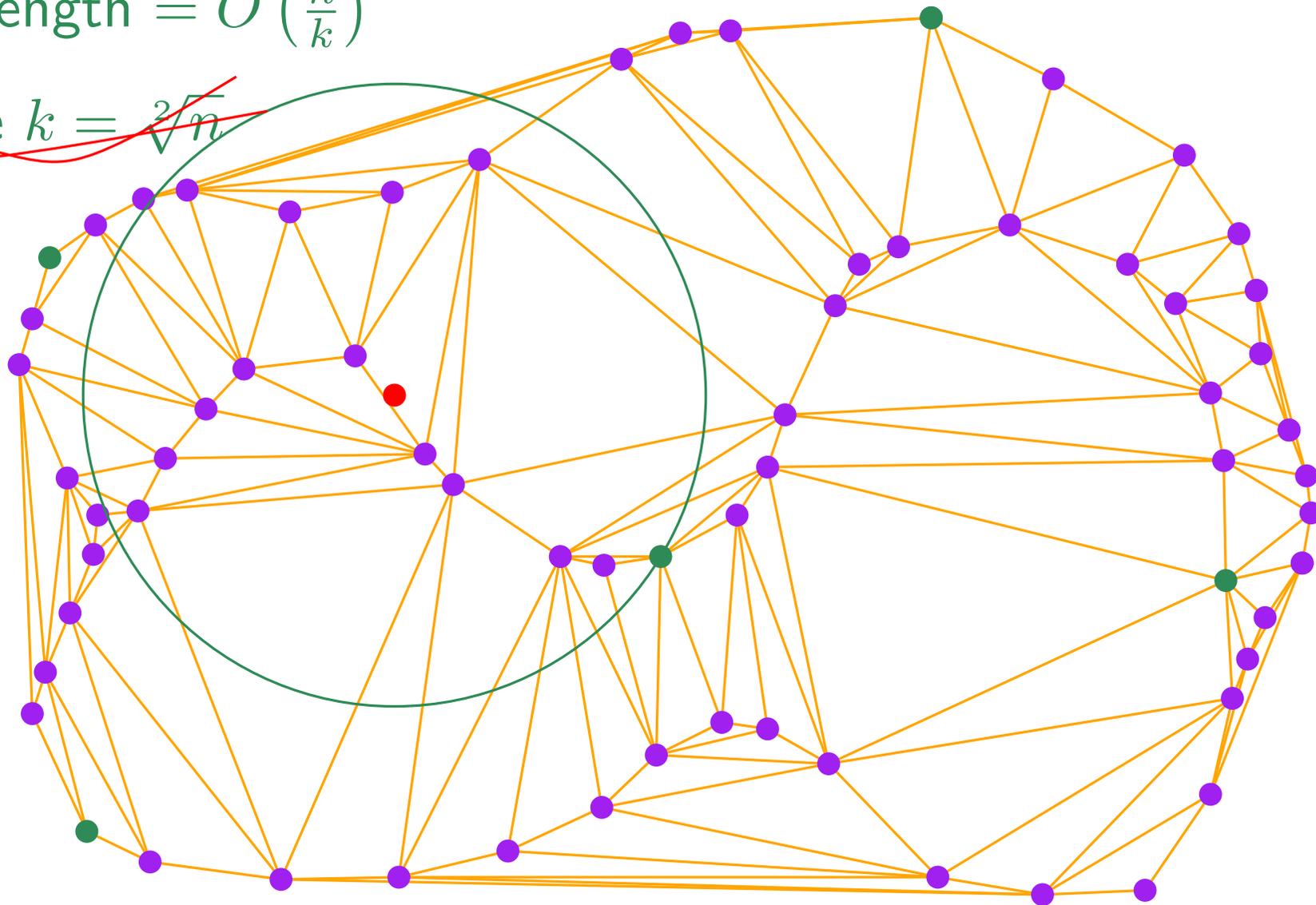


# Jump and walk (no distribution hypothesis) Delaunay hierarchy

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

choose  $k = \sqrt[2]{n}$



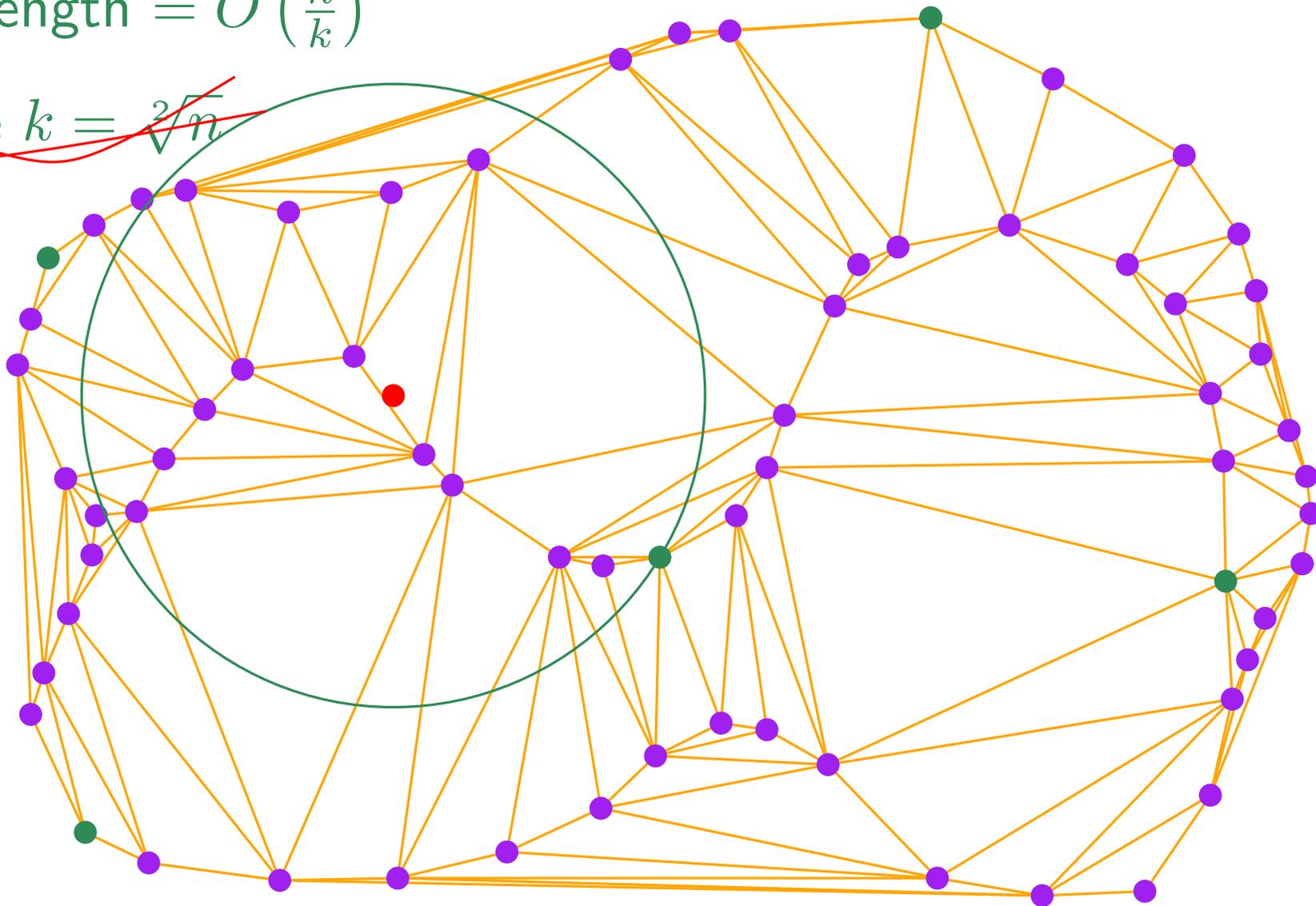
# Jump and walk (no distribution hypothesis) Delaunay hierarchy

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\frac{n}{k_1}$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

choose  $k = \sqrt[2]{n}$



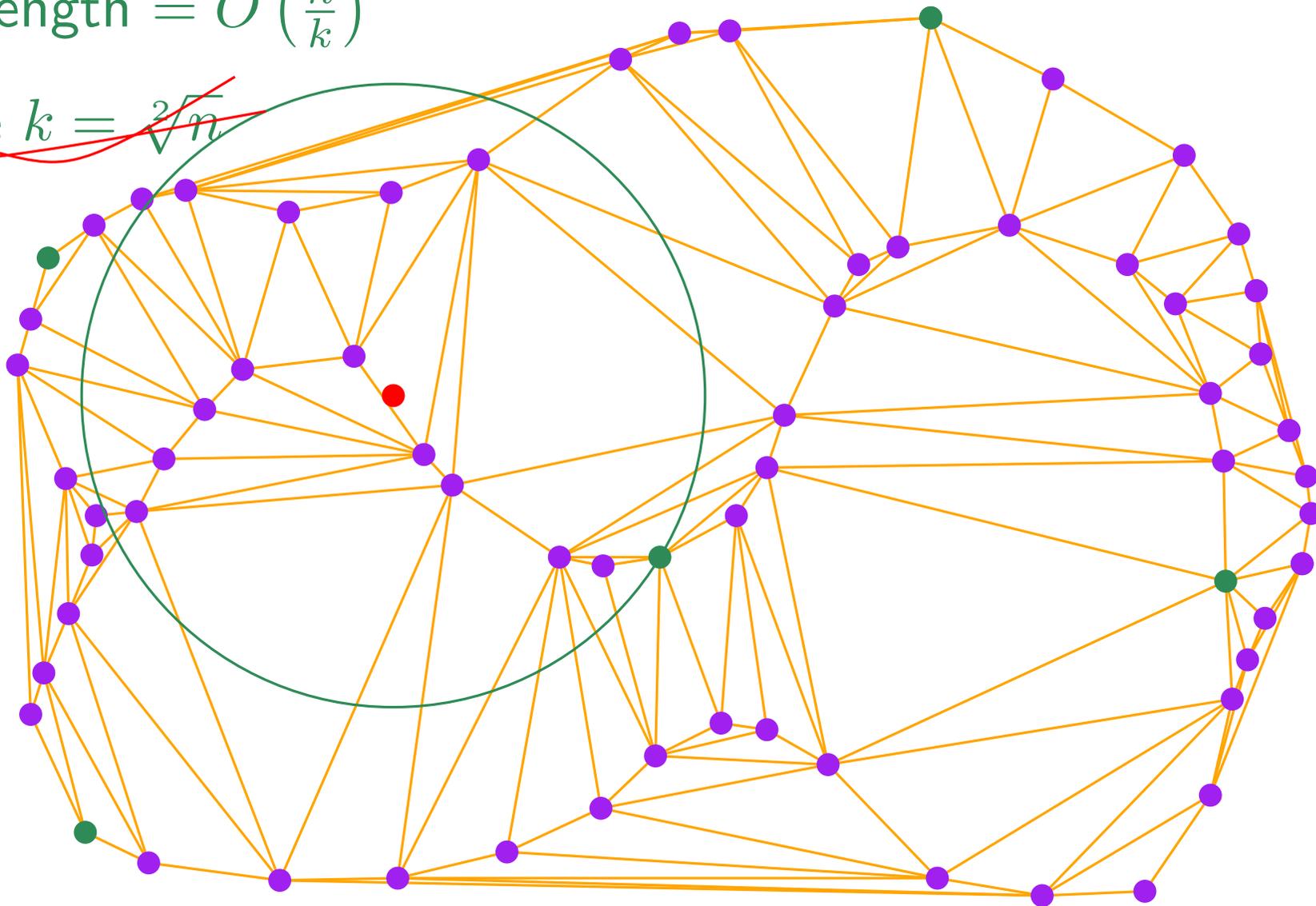
# Jump and walk (no distribution hypothesis) Delaunay hierarchy

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\frac{n}{k_1} + \frac{k_1}{k_2}$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

choose  $k = \sqrt[2]{n}$



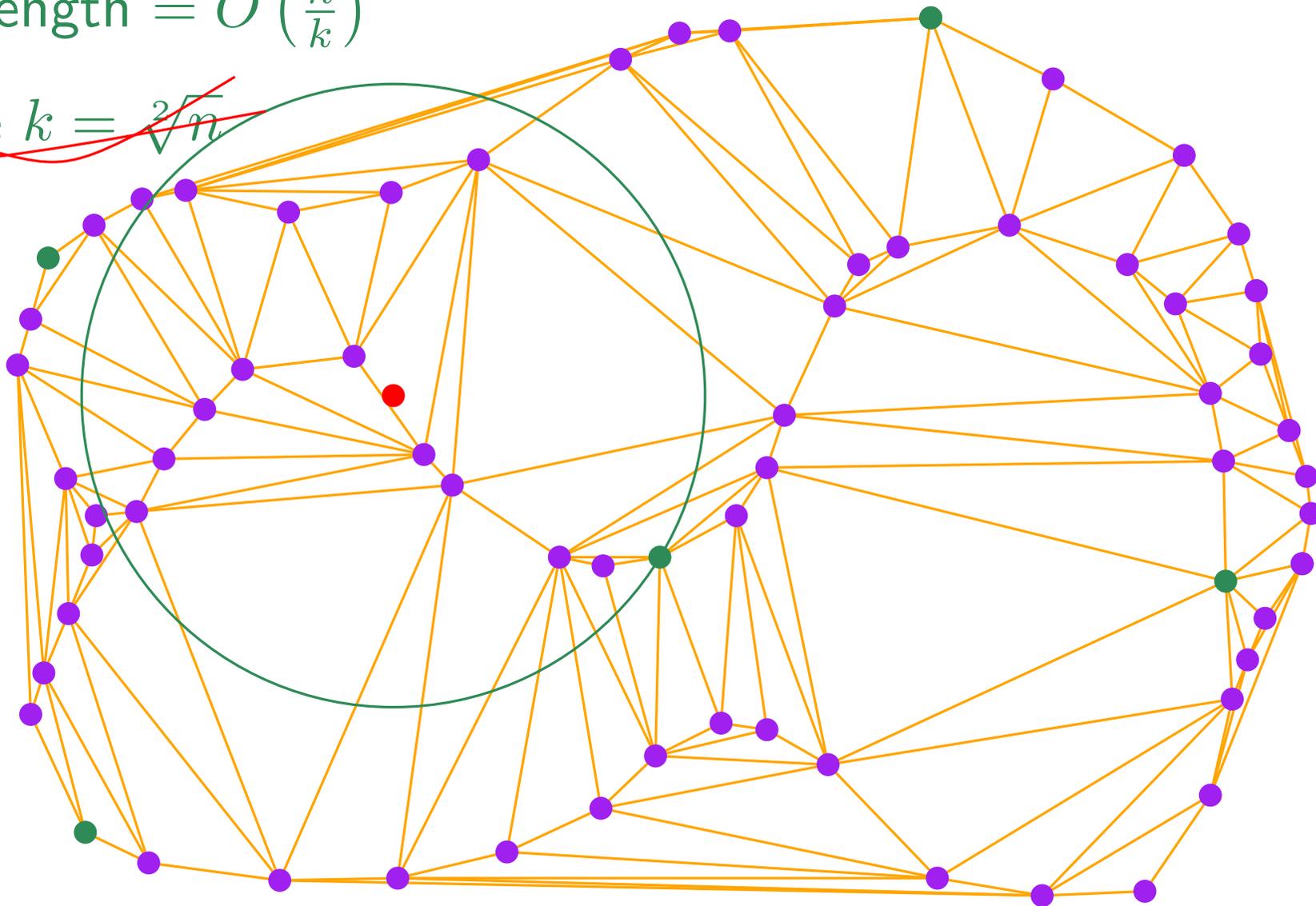
# Jump and walk (no distribution hypothesis) Delaunay hierarchy

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\frac{n}{k_1} + \frac{k_1}{k_2} + \frac{k_2}{k_3} + \dots$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

~~choose  $k = \sqrt[2]{n}$~~



# Jump and walk (no distribution hypothesis) Delaunay hierarchy

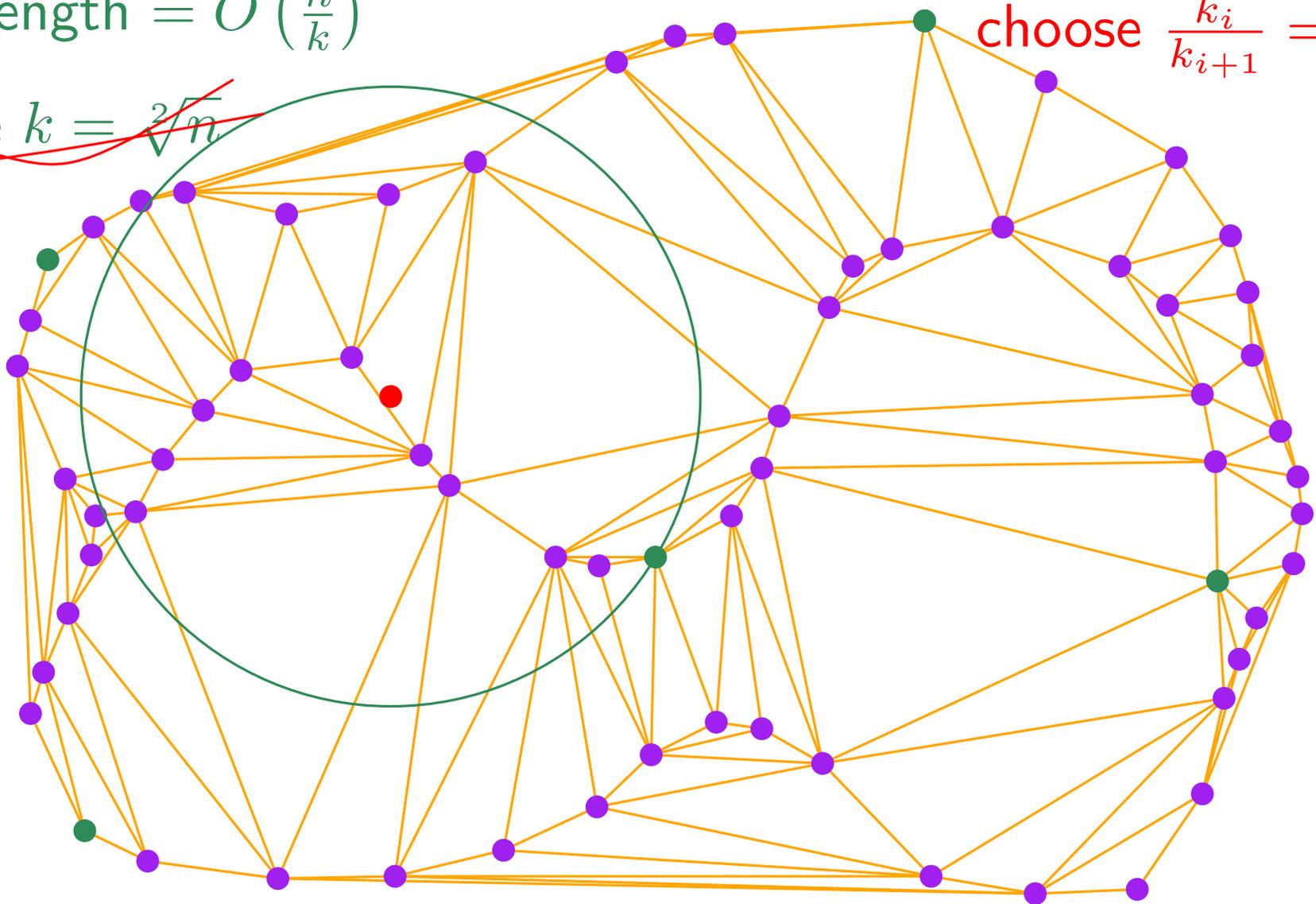
$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\frac{n}{k_1} + \frac{k_1}{k_2} + \frac{k_2}{k_3} + \dots$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

~~choose  $k = \sqrt[2]{n}$~~

choose  $\frac{k_i}{k_{i+1}} = \alpha$



# Jump and walk (no distribution hypothesis) Delaunay hierarchy

$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

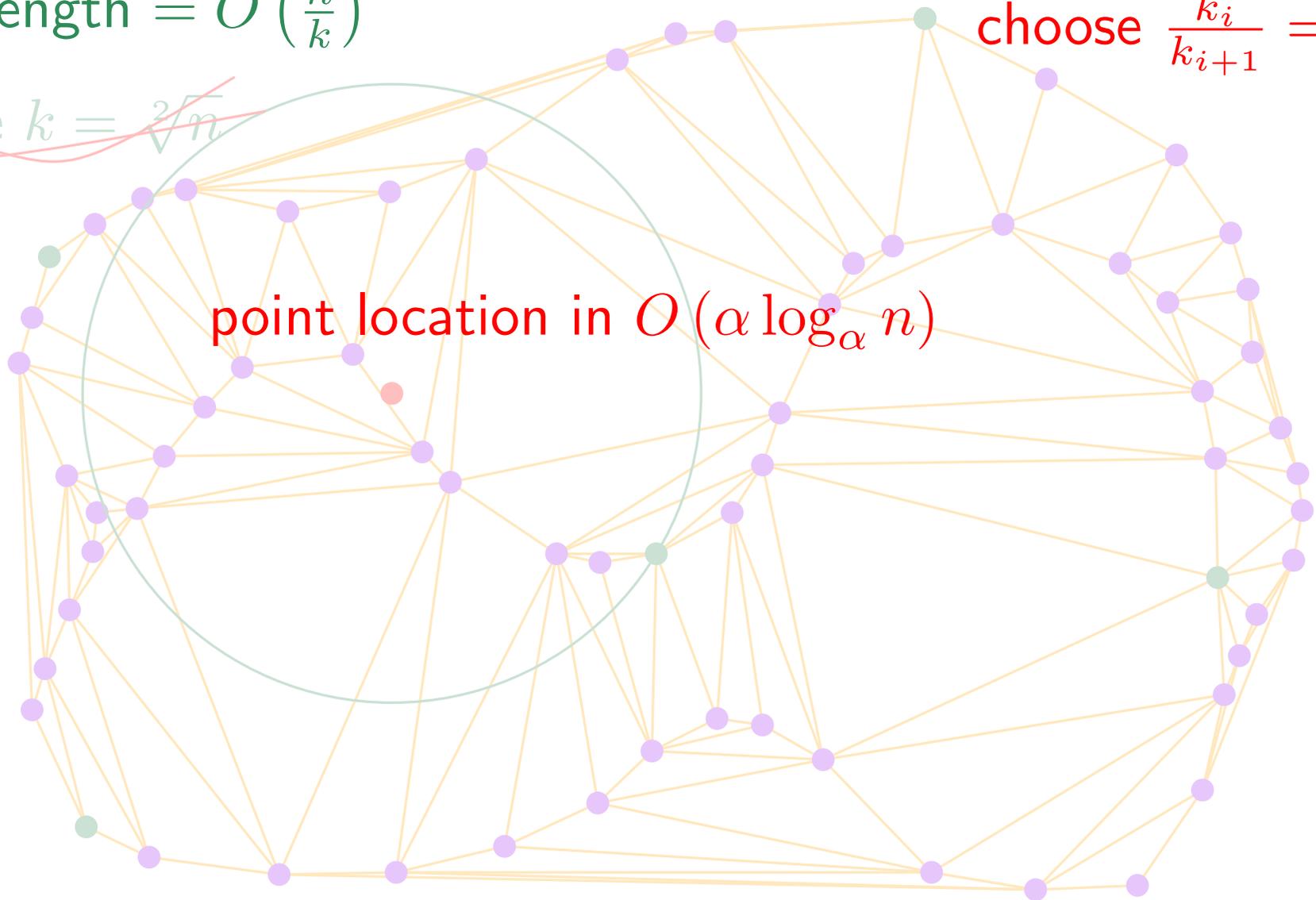
$$\frac{n}{k_1} + \frac{k_1}{k_2} + \frac{k_2}{k_3} + \dots$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

$$\text{choose } \frac{k_i}{k_{i+1}} = \alpha$$

~~choose  $k = \sqrt[3]{n}$~~

point location in  $O(\alpha \log_\alpha n)$



# Jump and walk (no distribution hypothesis) ~~Delaunay~~ hierarchy

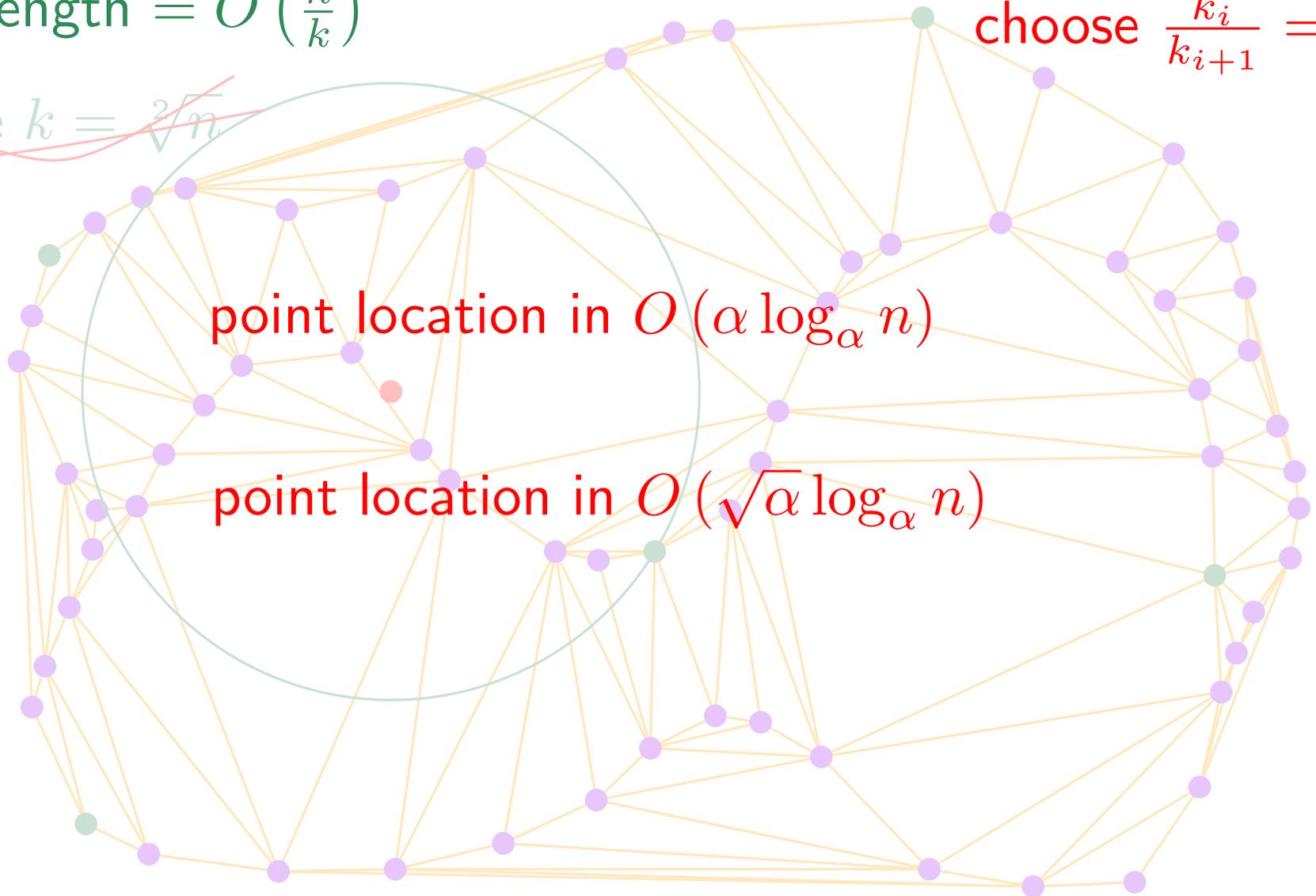
$$\mathbb{E} [\# \text{ of } \bullet \text{ in } \bigcirc] = \frac{n}{k}$$

$$\frac{n}{k_1} + \frac{k_1}{k_2} + \frac{k_2}{k_3} + \dots$$

$$\text{Walk length} = O\left(\frac{n}{k}\right)$$

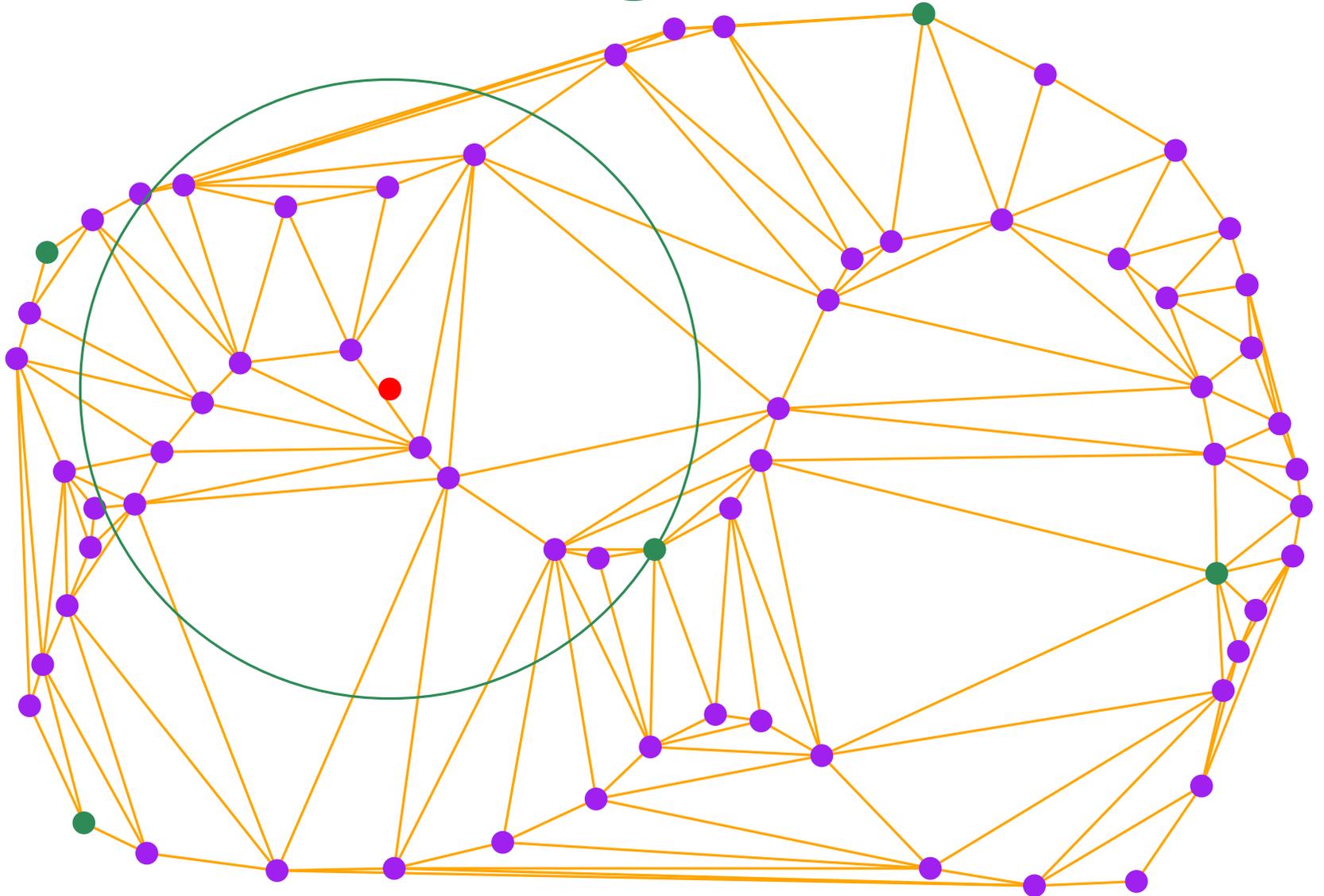
$$\text{choose } \frac{k_i}{k_{i+1}} = \alpha$$

~~choose  $k = \sqrt[3]{n}$~~



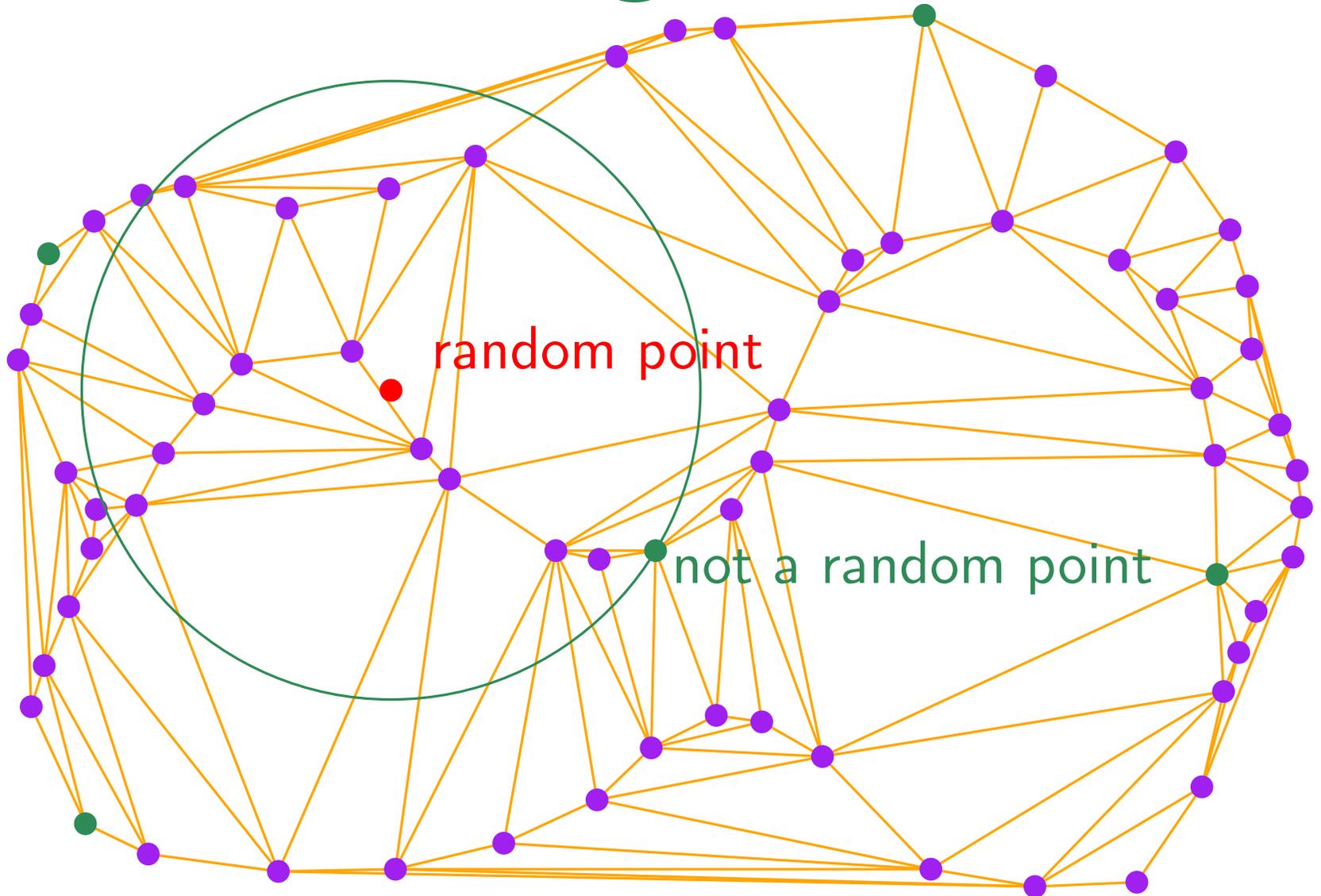
## Technical detail

$$\text{Walk length} = O\left(\# \text{ of } \bullet \text{ in } \bigcirc\right) = O\left(\frac{n}{k}\right)$$



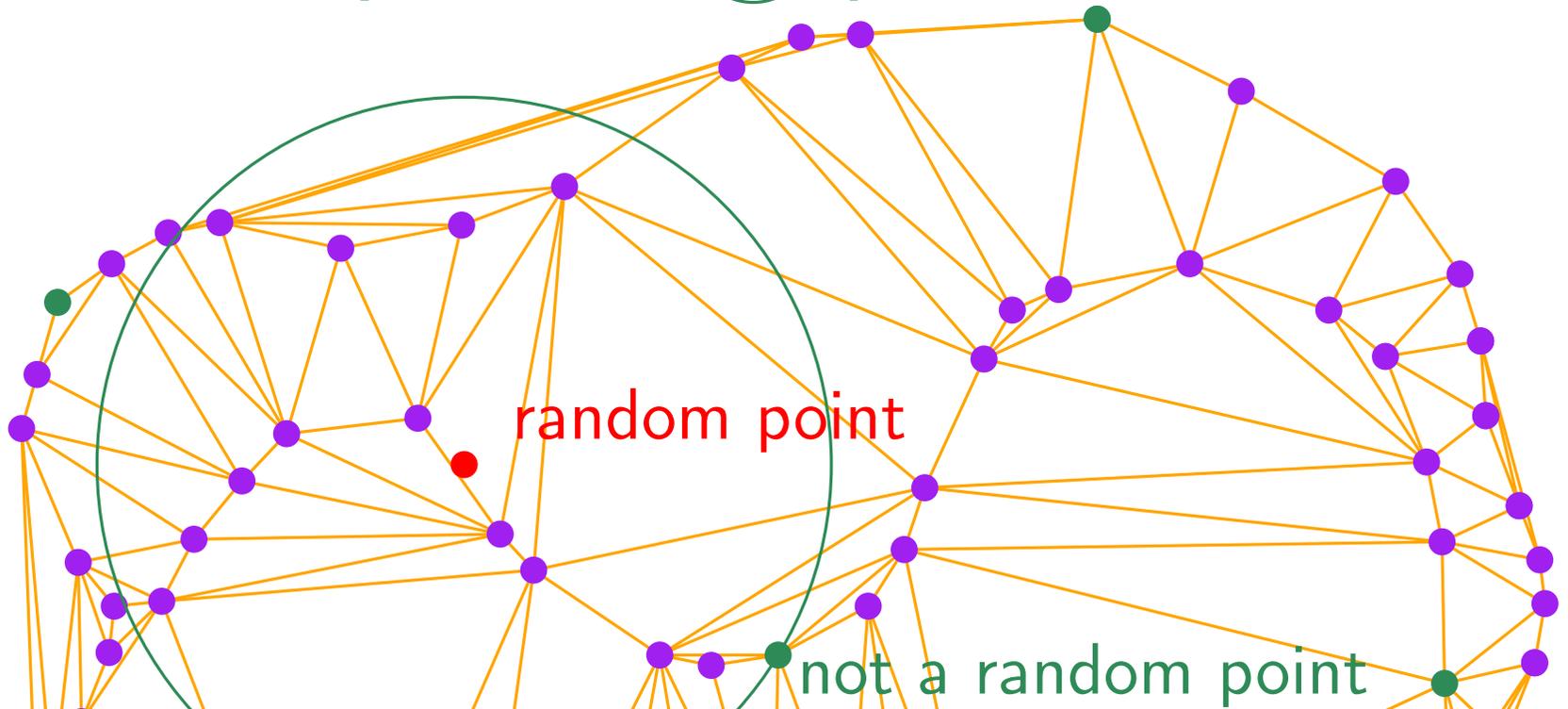
## Technical detail

$$\text{Walk length} = O\left(\# \text{ of } \bullet \text{ in } \left( \bullet \right) \right) = O\left(\frac{n}{k}\right)$$



# Technical detail

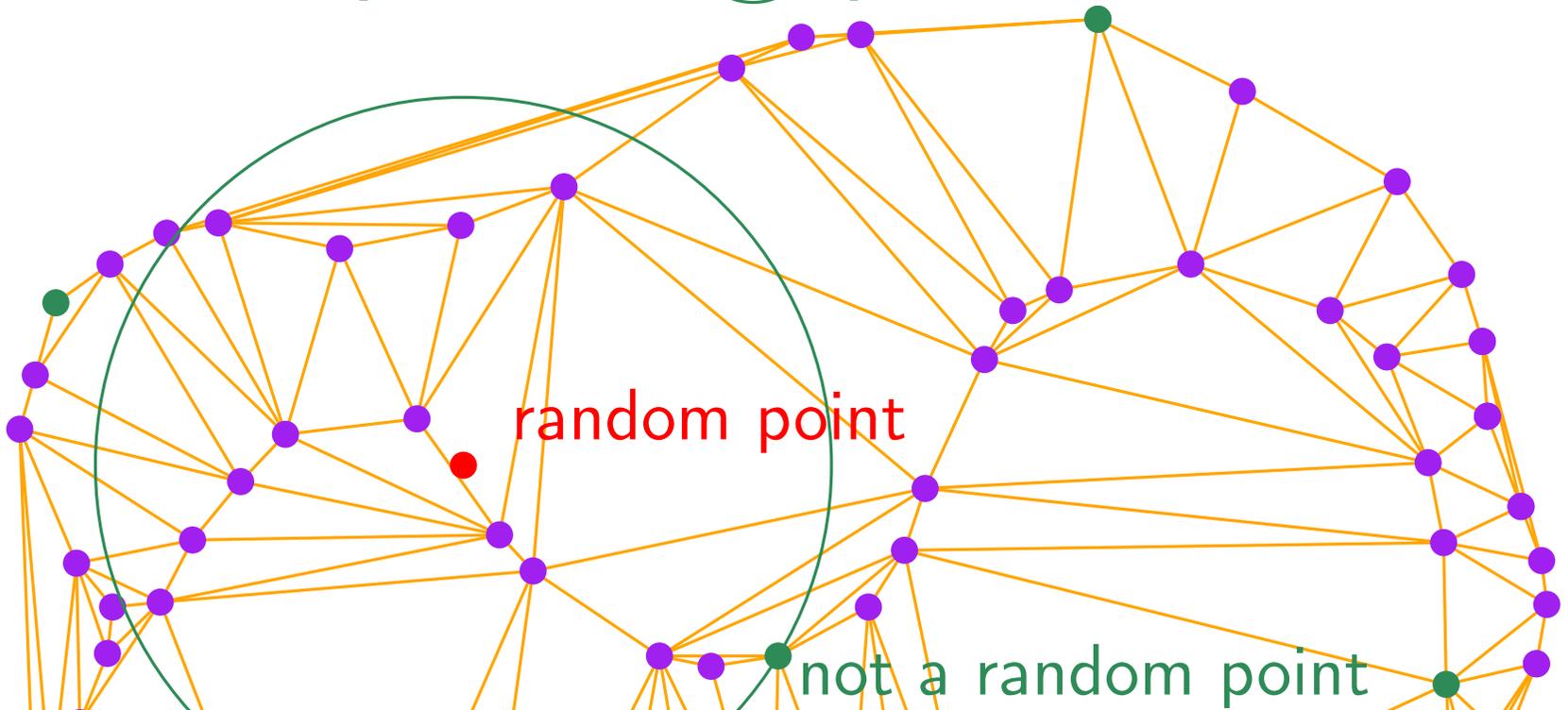
$$\text{Walk length} = O\left(\# \text{ of } \bullet \text{ in } \bigcirc\right) = O\left(\frac{n}{k}\right)$$



$$\begin{aligned} \mathbb{E}[d^\circ \bullet] &= \frac{1}{n} \sum_q d^\circ NN(q) = \frac{1}{n} \sum_q \sum_{v=NN(q)} d^\circ v \\ &= \frac{1}{n} \sum_v \sum_{q; v=NN(q)} d^\circ v \leq \frac{1}{n} \sum_v 6d^\circ v \leq 36 \end{aligned}$$

# Technical detail

$$\text{Walk length} = O\left(\overset{\sum d^\circ}{\# \text{ of } \bullet \text{ in } \bigcirc}\right) = O\left(\frac{n}{k}\right)$$



$$\begin{aligned} \mathbb{E}[d^\circ \bullet] &= \frac{1}{n} \sum_q d^\circ NN(q) = \frac{1}{n} \sum_q \sum_{v=NN(q)} d^\circ v \\ &= \frac{1}{n} \sum_v \sum_{q; v=NN(q)} d^\circ v \leq \frac{1}{n} \sum_v 6d^\circ v \leq 36 \end{aligned}$$

# Randomization

How many randomness is necessary?

If the data are not known in advance

shuffle locally

# Randomization

Drawbacks of random order

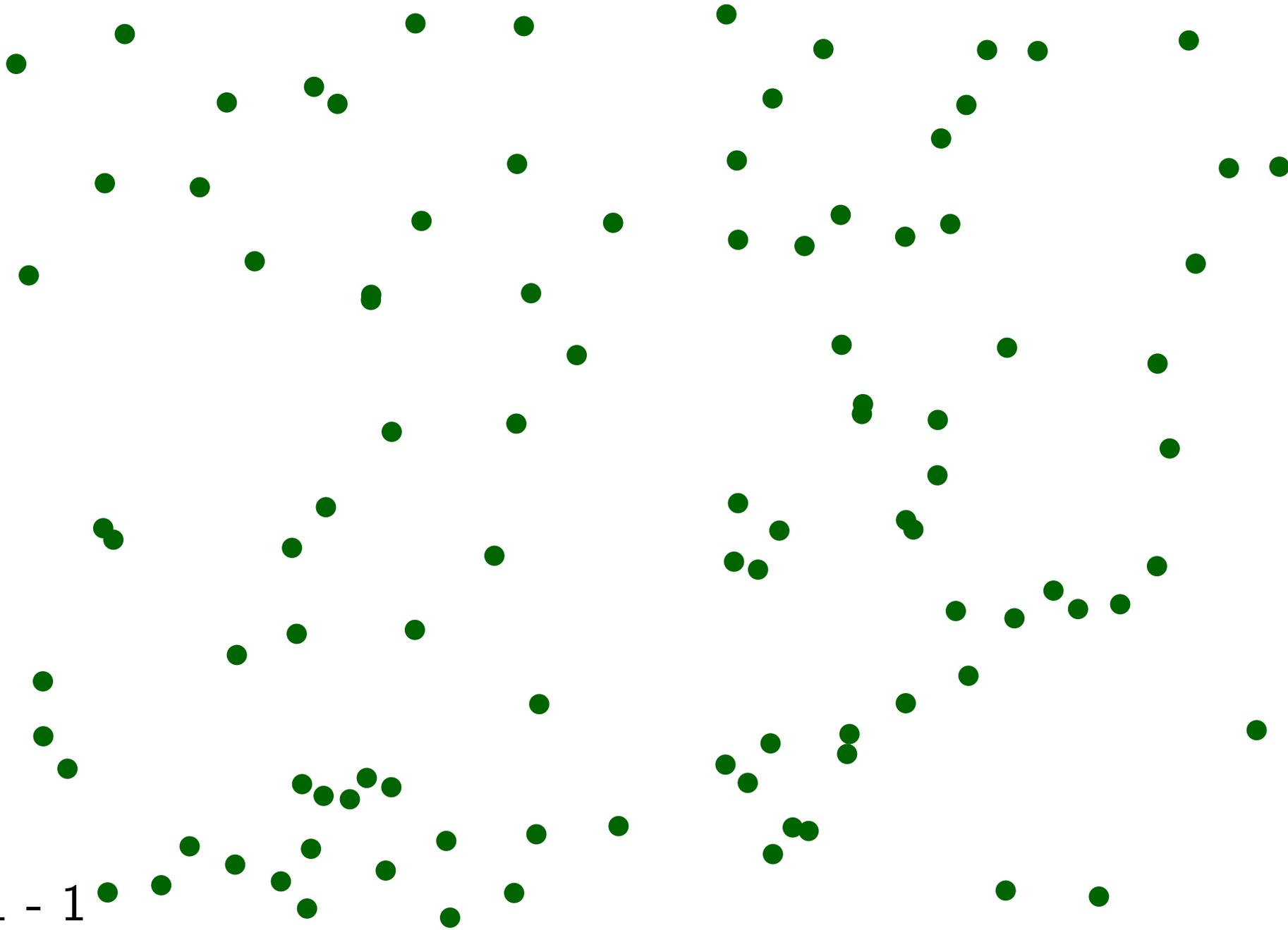
non locality of memory access

data structure for point location

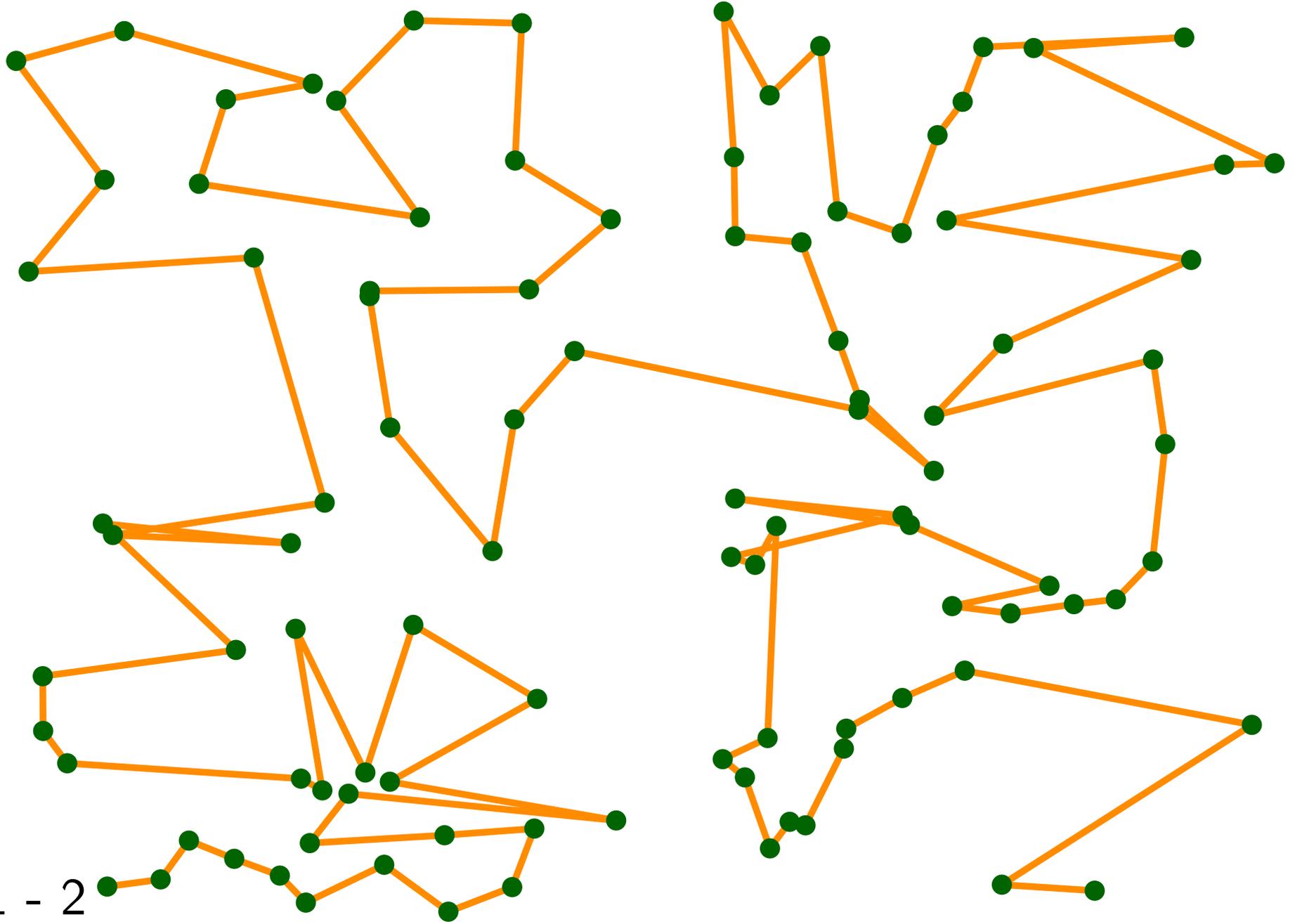


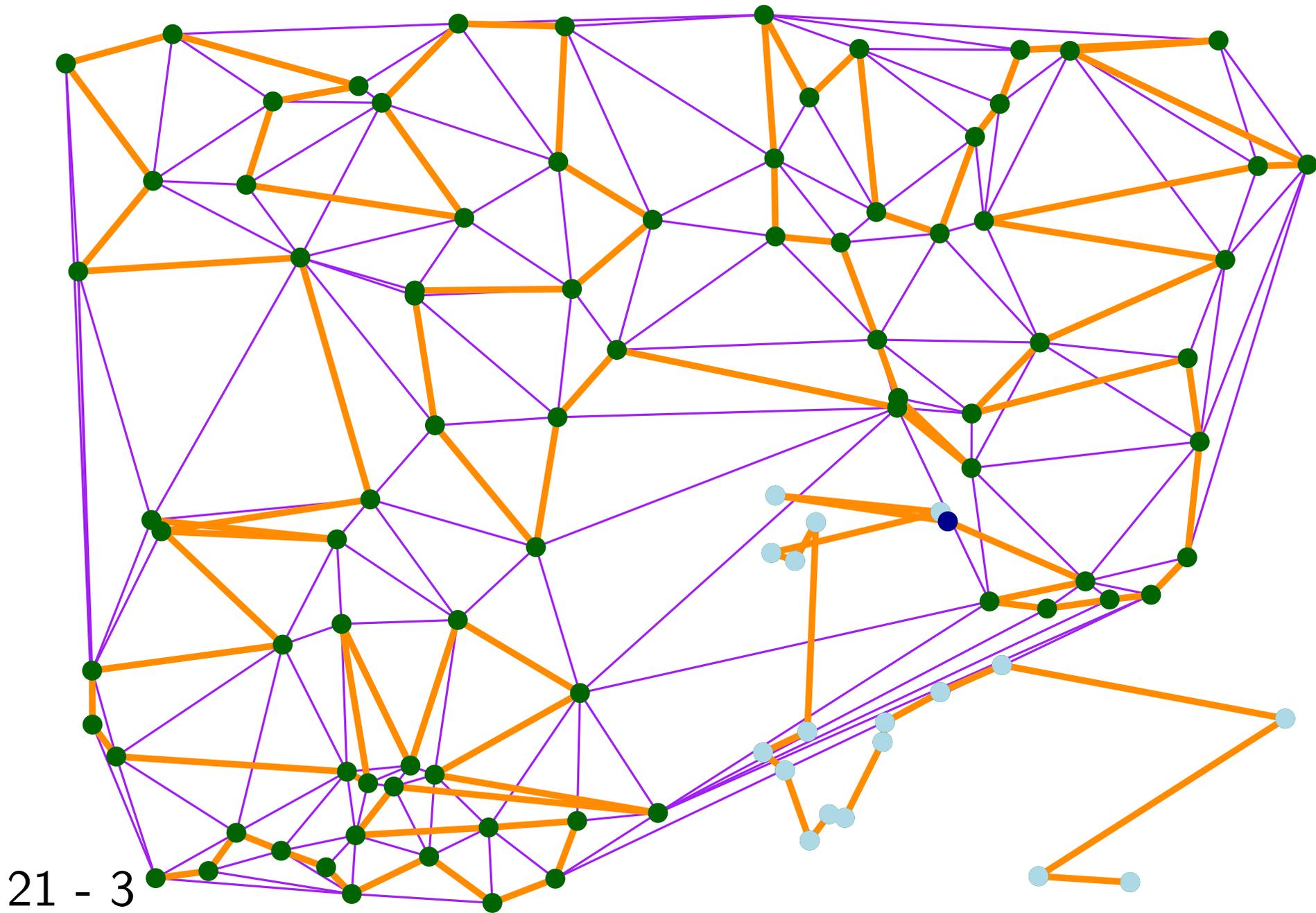
Hilbert sort

21 - 1

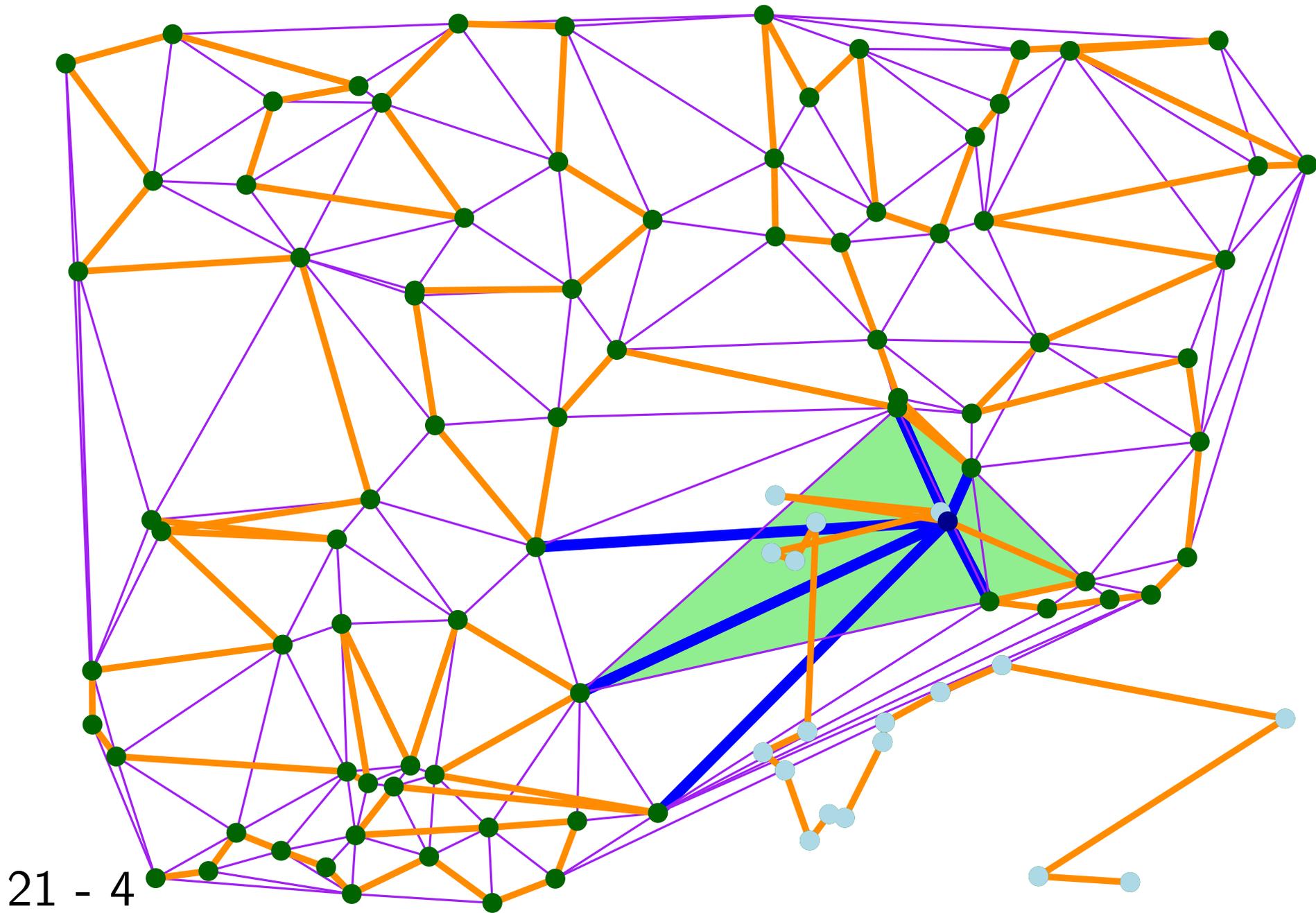


21 - 2





21 - 3



## Drawbacks of random order

non locality of memory access

data structure for point location

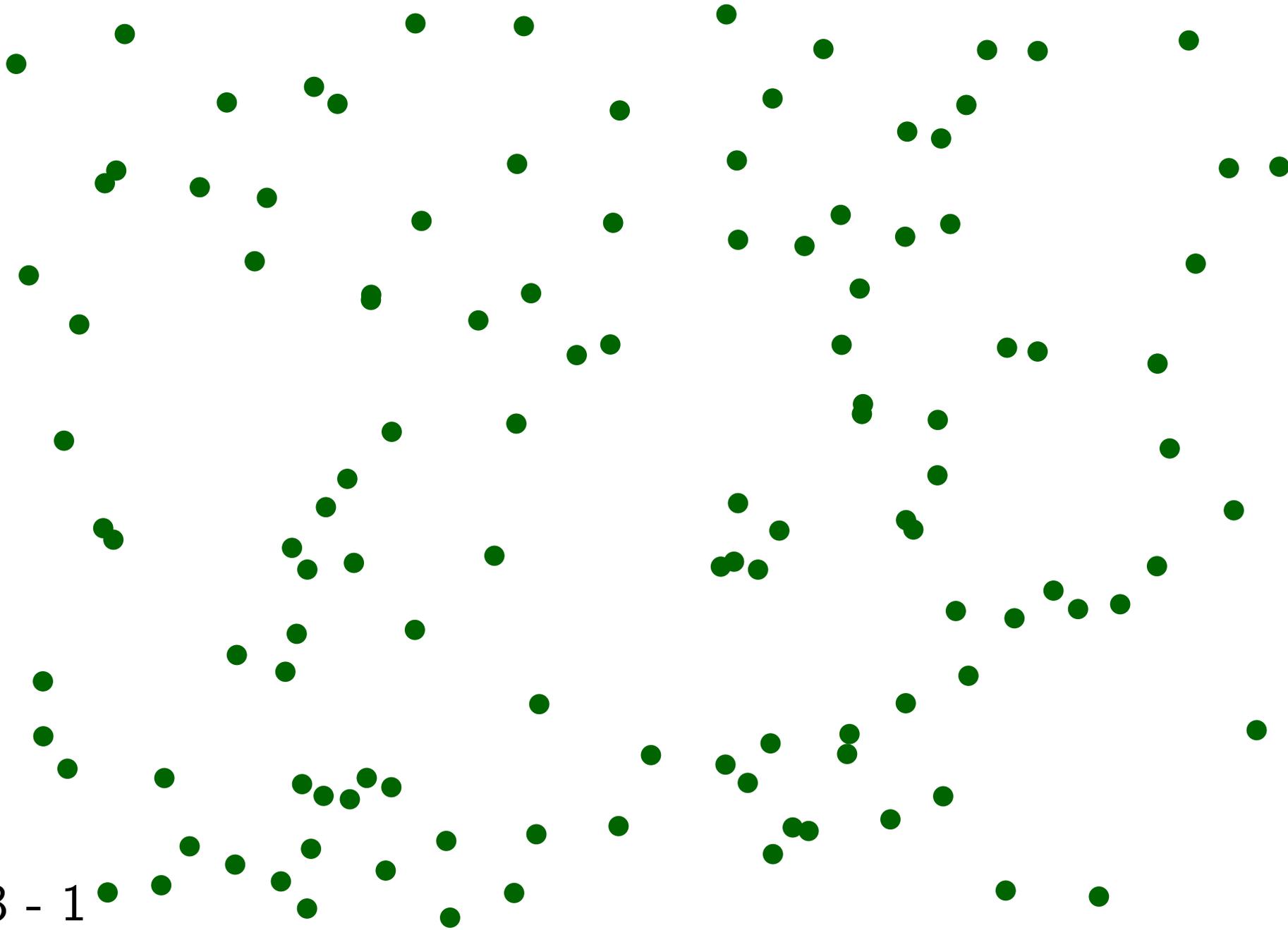
→ Hilbert sort

Walk should be fast

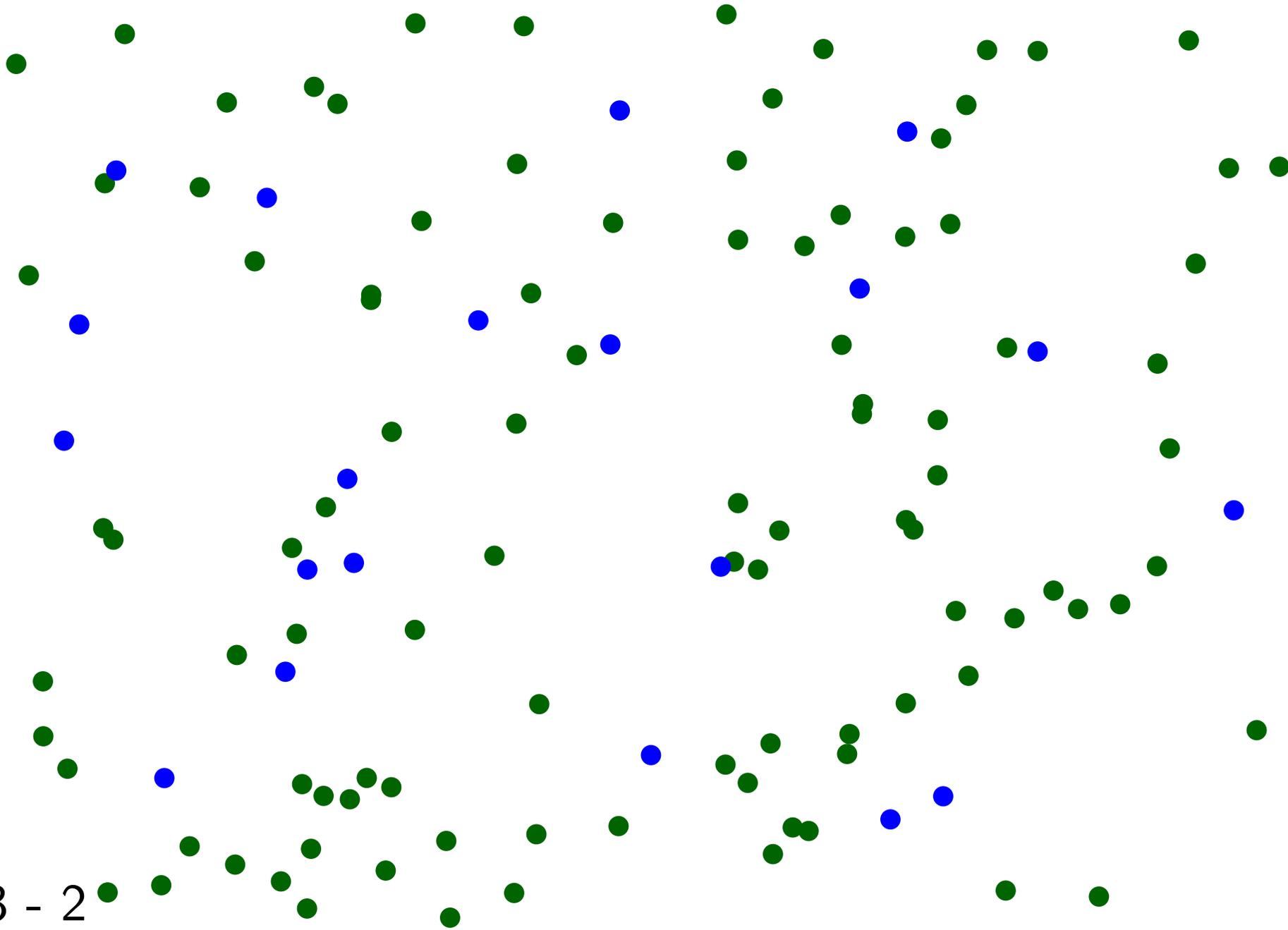
Last point is not at all a random point

→ no control of degree of last point

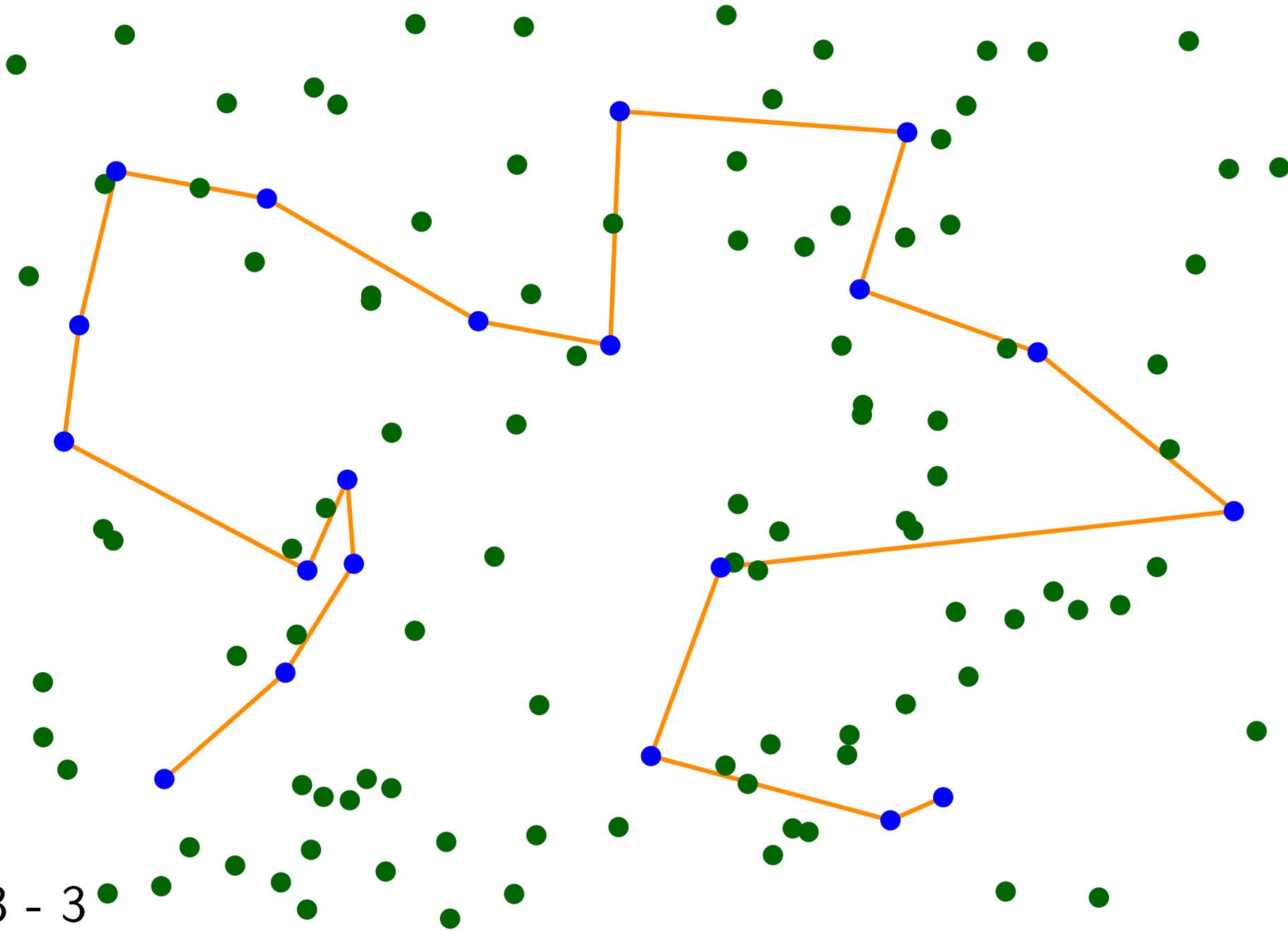
23 - 1



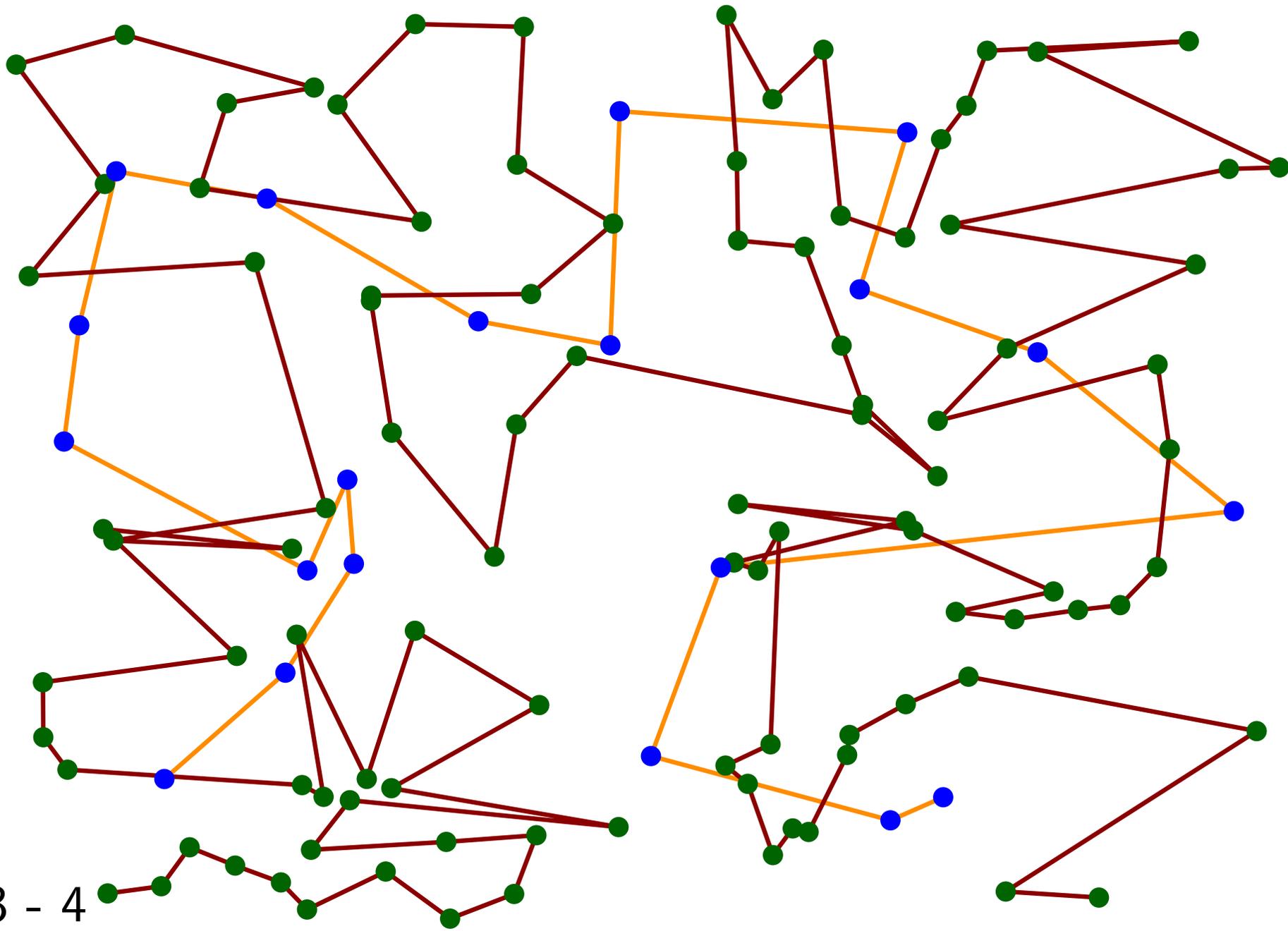
23 - 2



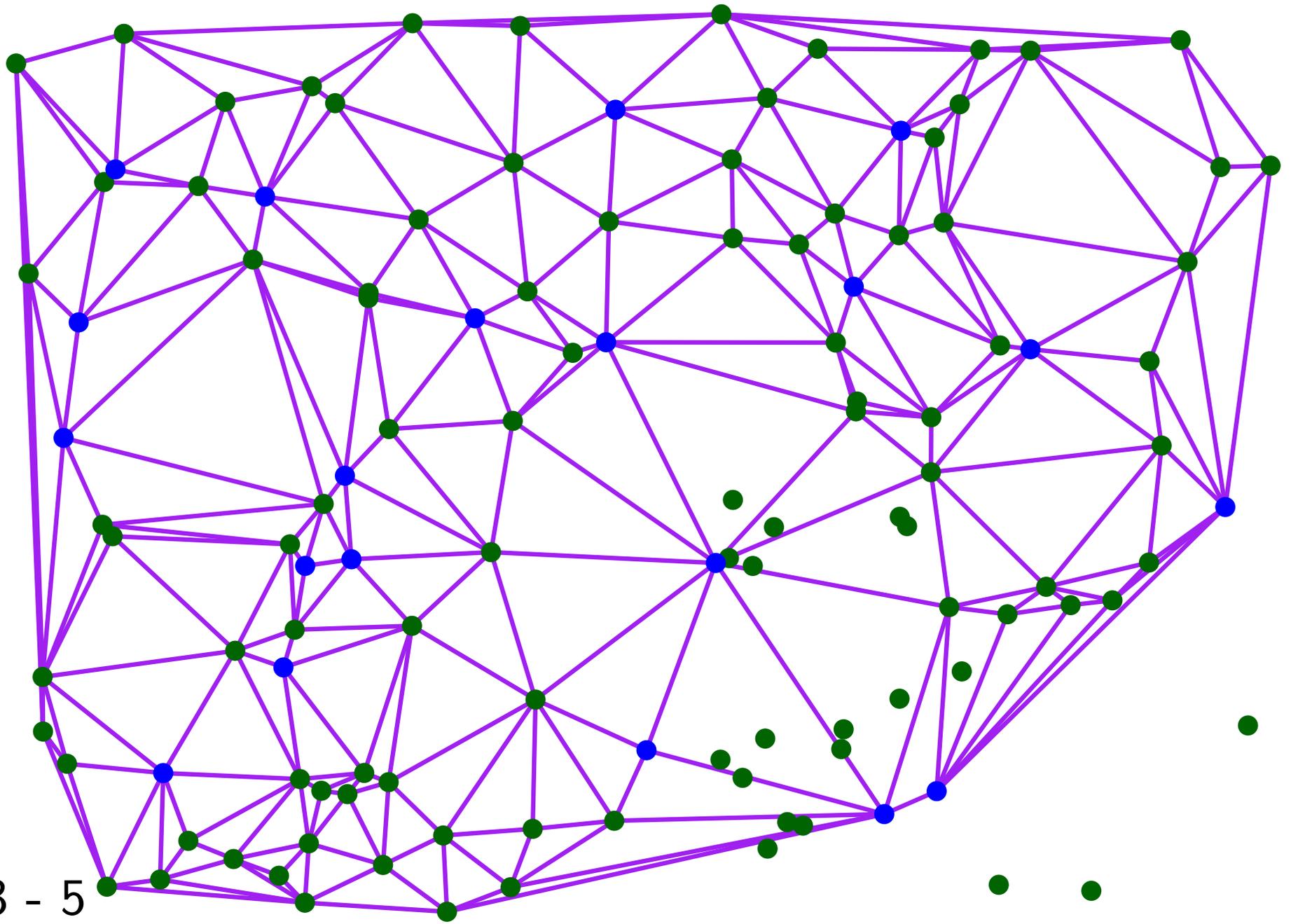
23 - 3

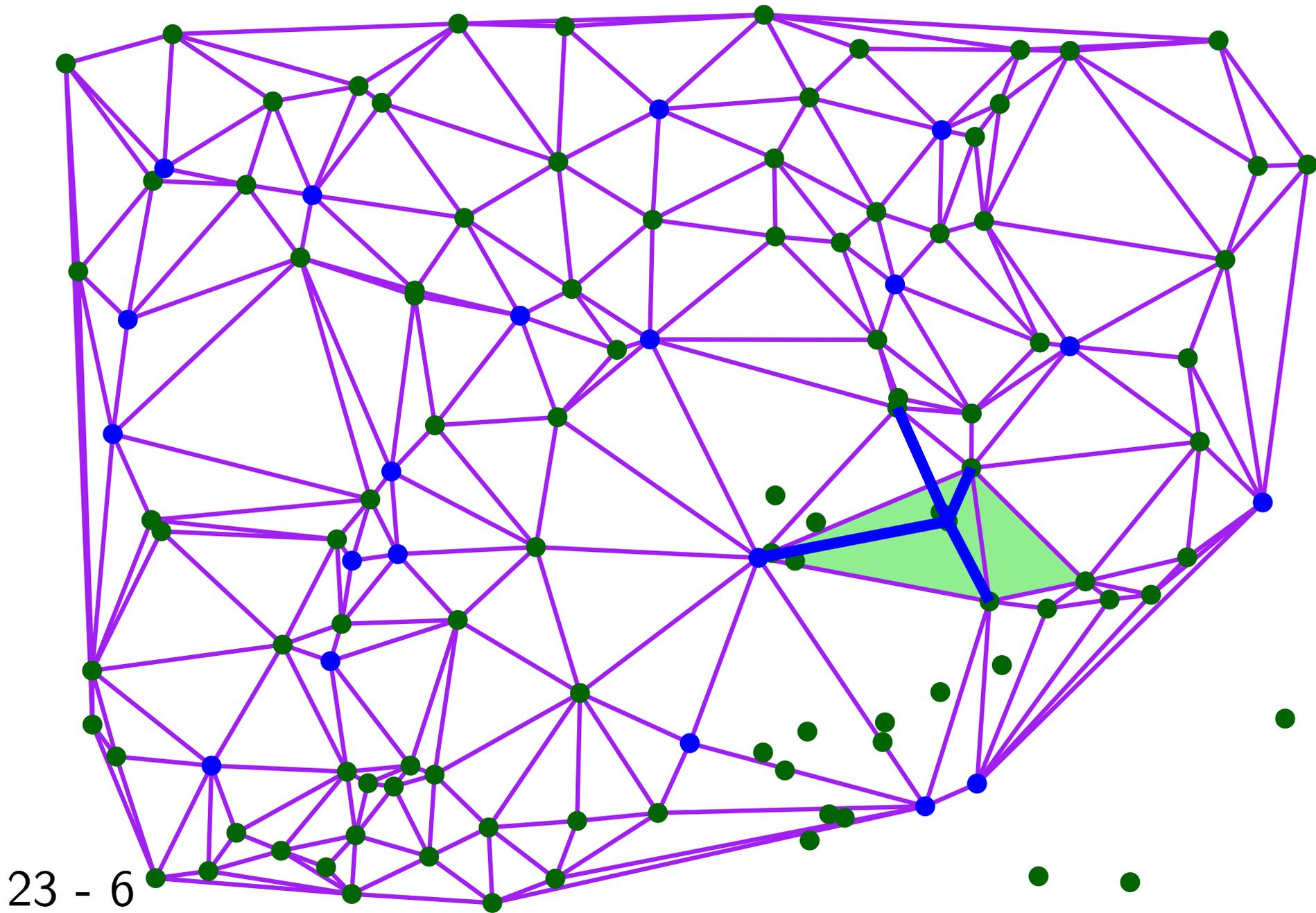


23 - 4



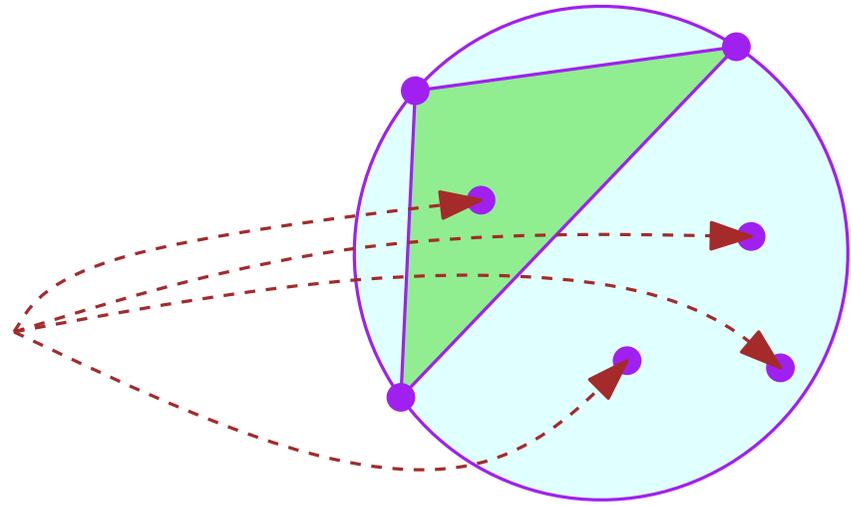
23 - 5



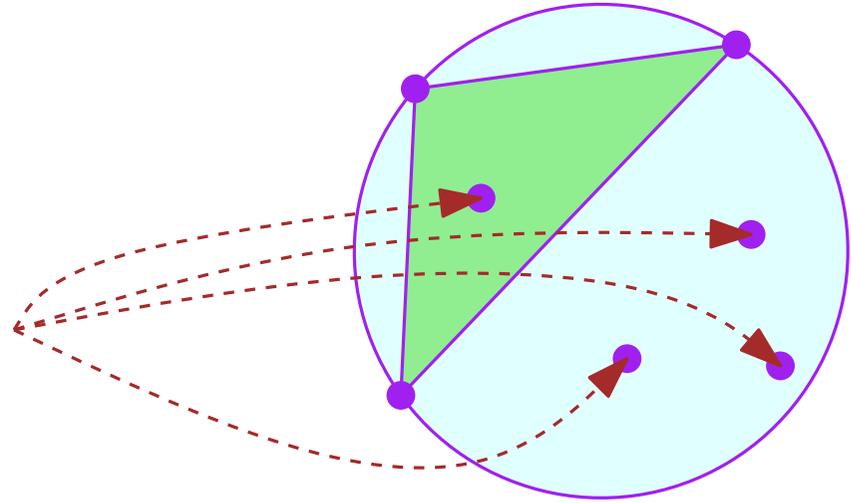


23 - 6

Triangle  $\Delta$  with  $j$  stoppers

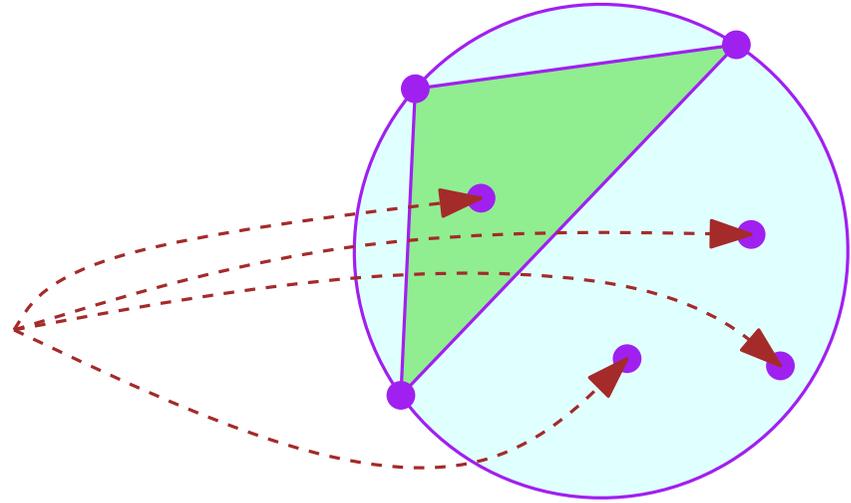


Triangle  $\Delta$  with  $j$  stoppers



$$\text{Size (order } \leq k \text{ Voronoi)} \leq \frac{\alpha n}{\alpha^3} = nk^2$$

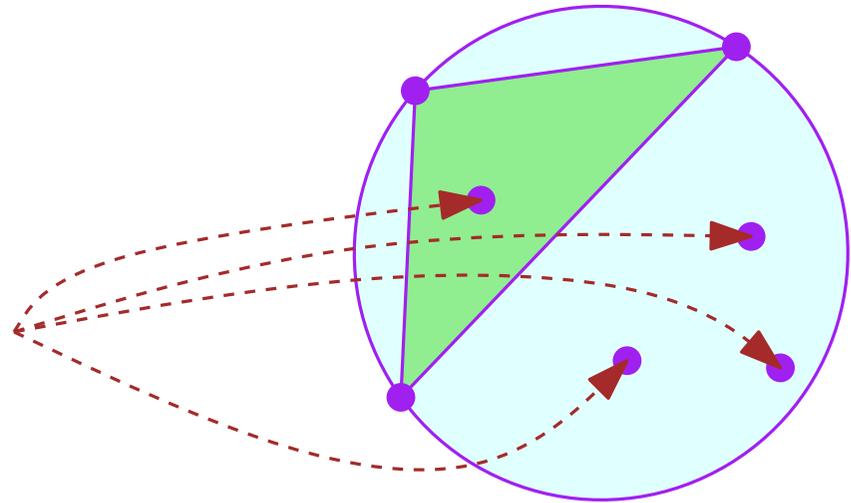
Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists during the construction

$$= \frac{3}{j+3} \frac{2}{j+2} \frac{1}{j+1}$$

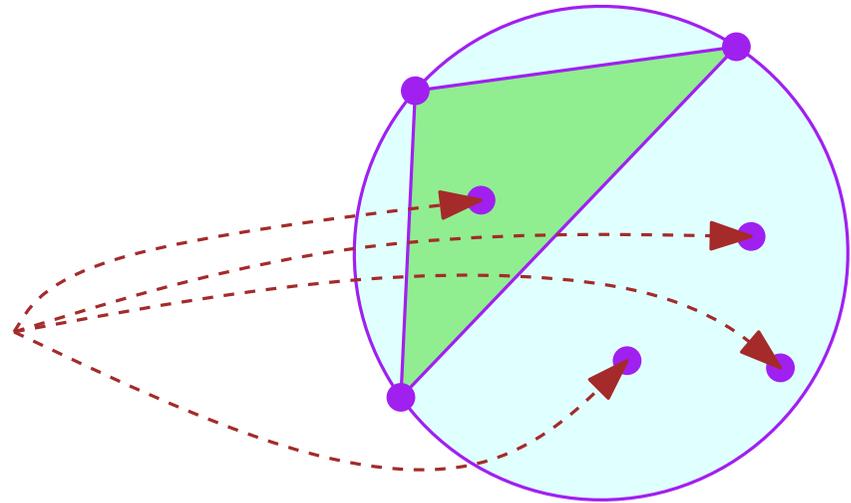
Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists during the construction

$$= \frac{\cancel{3}}{j+3} \frac{\cancel{2}}{j+2} \frac{\cancel{1}}{j+1} \quad \text{remains } \Theta(j^{-3})$$

Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists during the construction

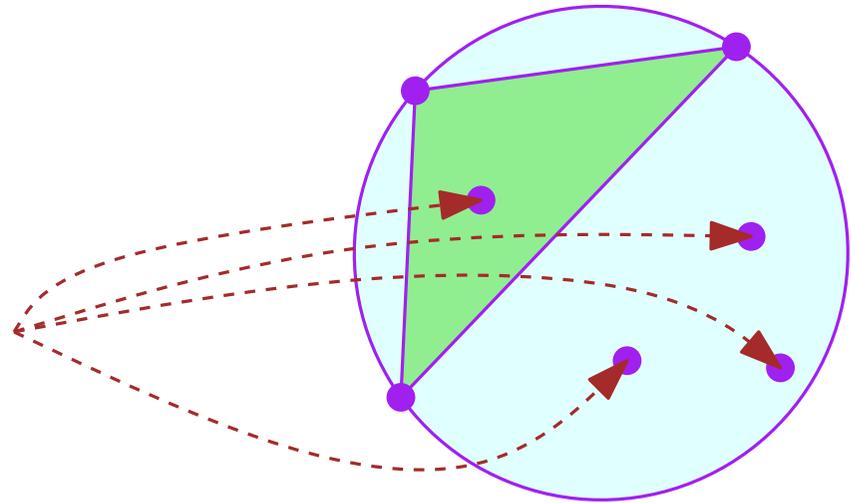
$$= \frac{\cancel{3}}{j+3} \frac{\cancel{2}}{j+2} \frac{\cancel{1}}{j+1} \quad \text{remains } \Theta(j^{-3})$$

# of created triangles

$$= \sum_{j=0}^n \mathbb{P}[\Delta \text{ with } j \text{ stoppers appears}] \times \#\Delta \text{ with } j \text{ stoppers}$$

$$\simeq O\left(\sum \frac{nj^2}{j^4}\right) = O(n)$$

Triangle  $\Delta$  with  $j$  stoppers



Probability that it exists during the construction

$$= \frac{\cancel{3}}{j+3} \frac{\cancel{2}}{j+2} \frac{\cancel{1}}{j+1} \quad \text{remains } \Theta(j^{-3})$$

# of conflicts occurring

$$= \sum_{j=0}^n j \times \mathbb{P}[\Delta \text{ with } j \text{ stoppers appears}] \times \#\Delta \text{ with } j \text{ stoppers}$$

$$\simeq O\left(\sum j \frac{nj^2}{j^4}\right) = O(n \log n)$$

# CGAL

Delaunay 2D 1M random points

locate using Delaunay hierarchy

6 seconds

random order (visibility walk)

157 seconds

$x$ -order

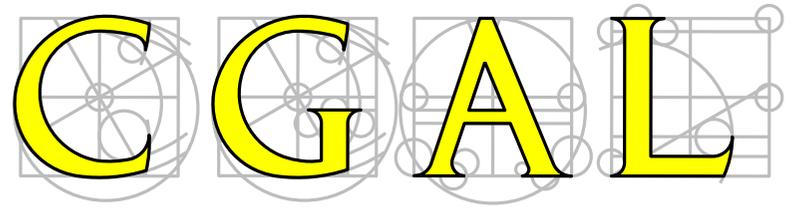
3 seconds

Hilbert order

0.8 seconds

Biased order (Spatial sorting)

0.7 seconds



Delaunay 2D 100K parabola points

locate using Delaunay hierarchy 0.3 seconds

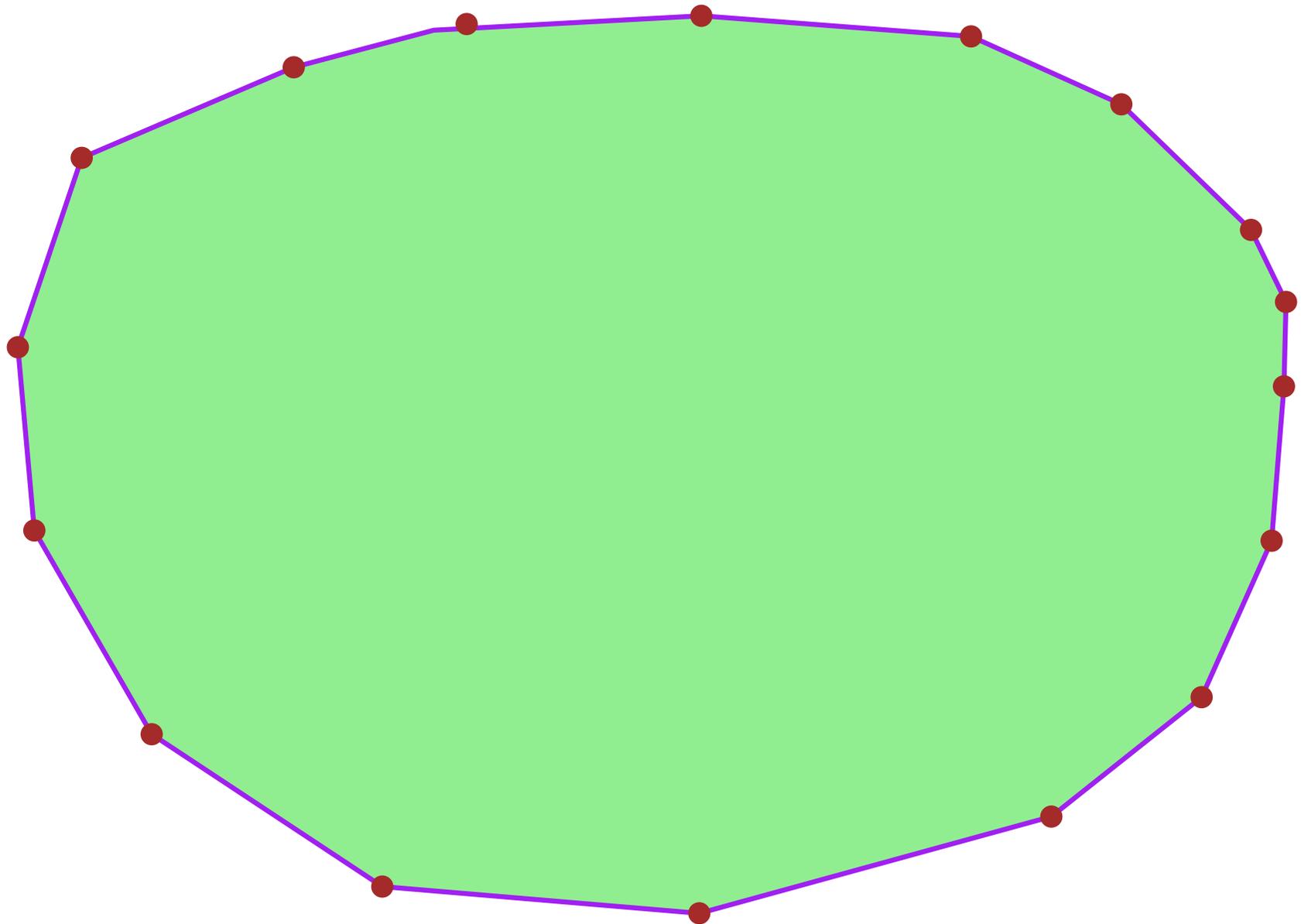
random order (visibility walk) 128 seconds

*x*-order 632 seconds

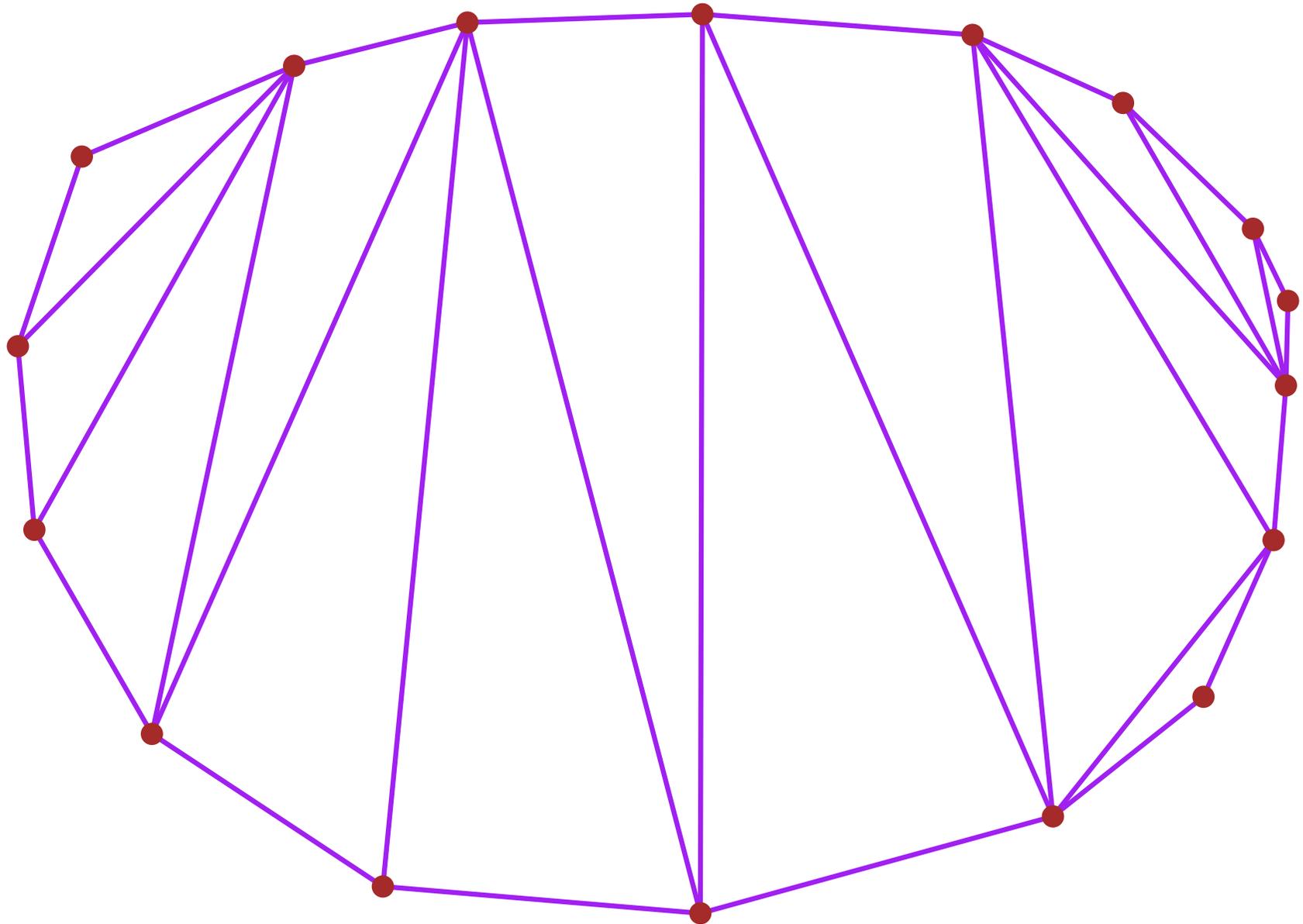
Hilbert order 46 seconds

Biased order (Spatial sorting) 0.3 seconds

# Delaunay of points in convex position



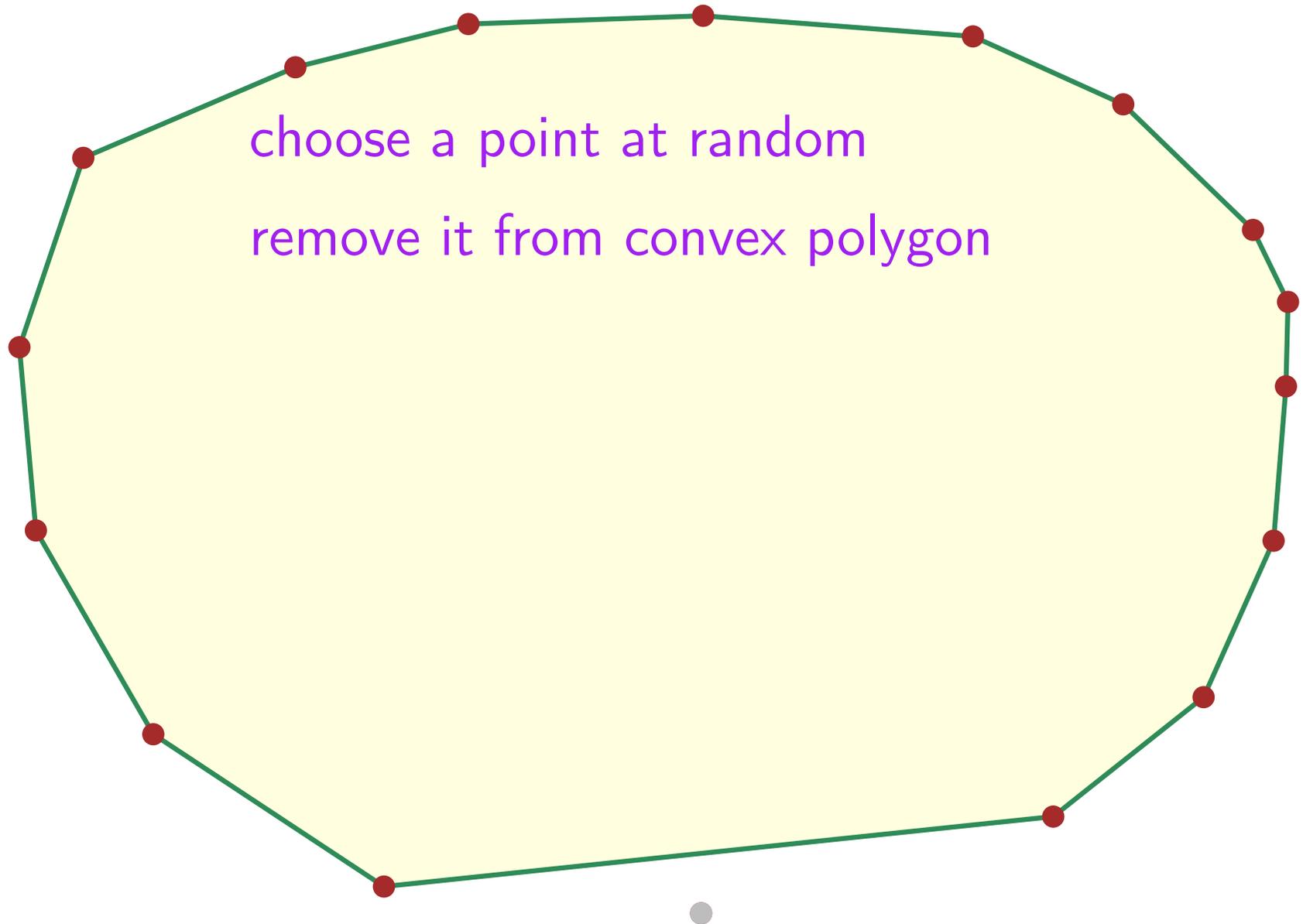
# Delaunay of points in convex position



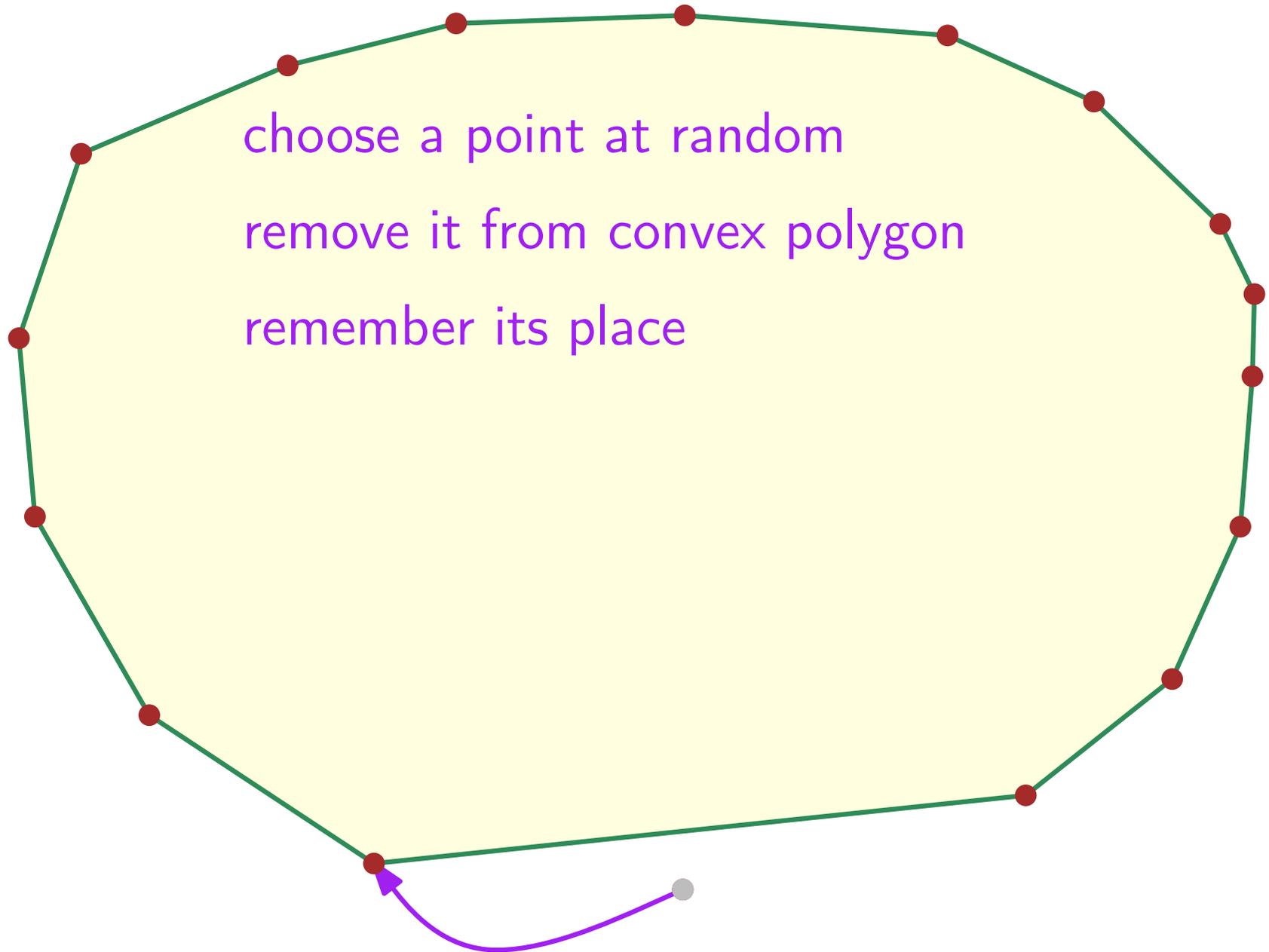
# Delaunay of points in convex position



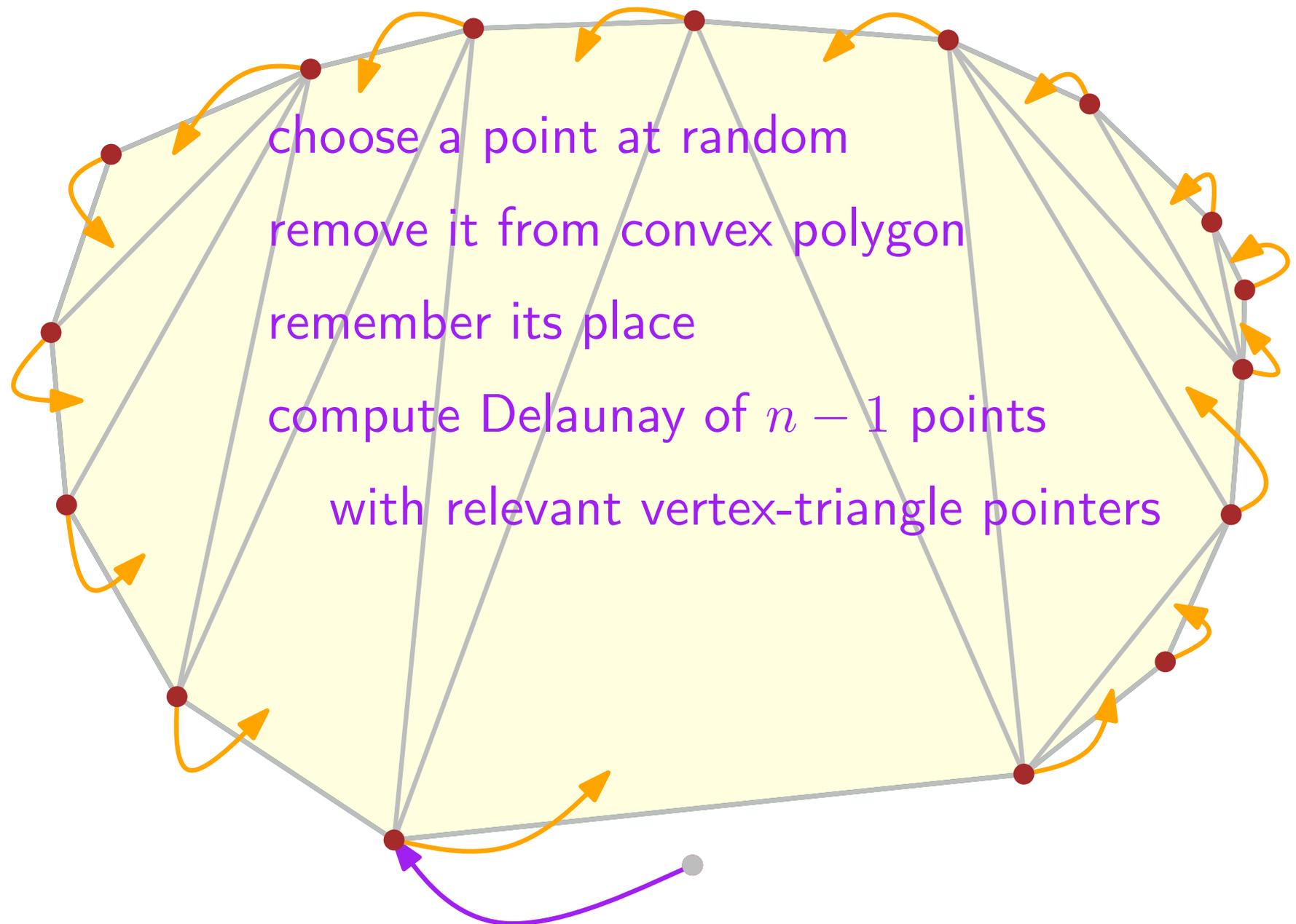
# Delaunay of points in convex position



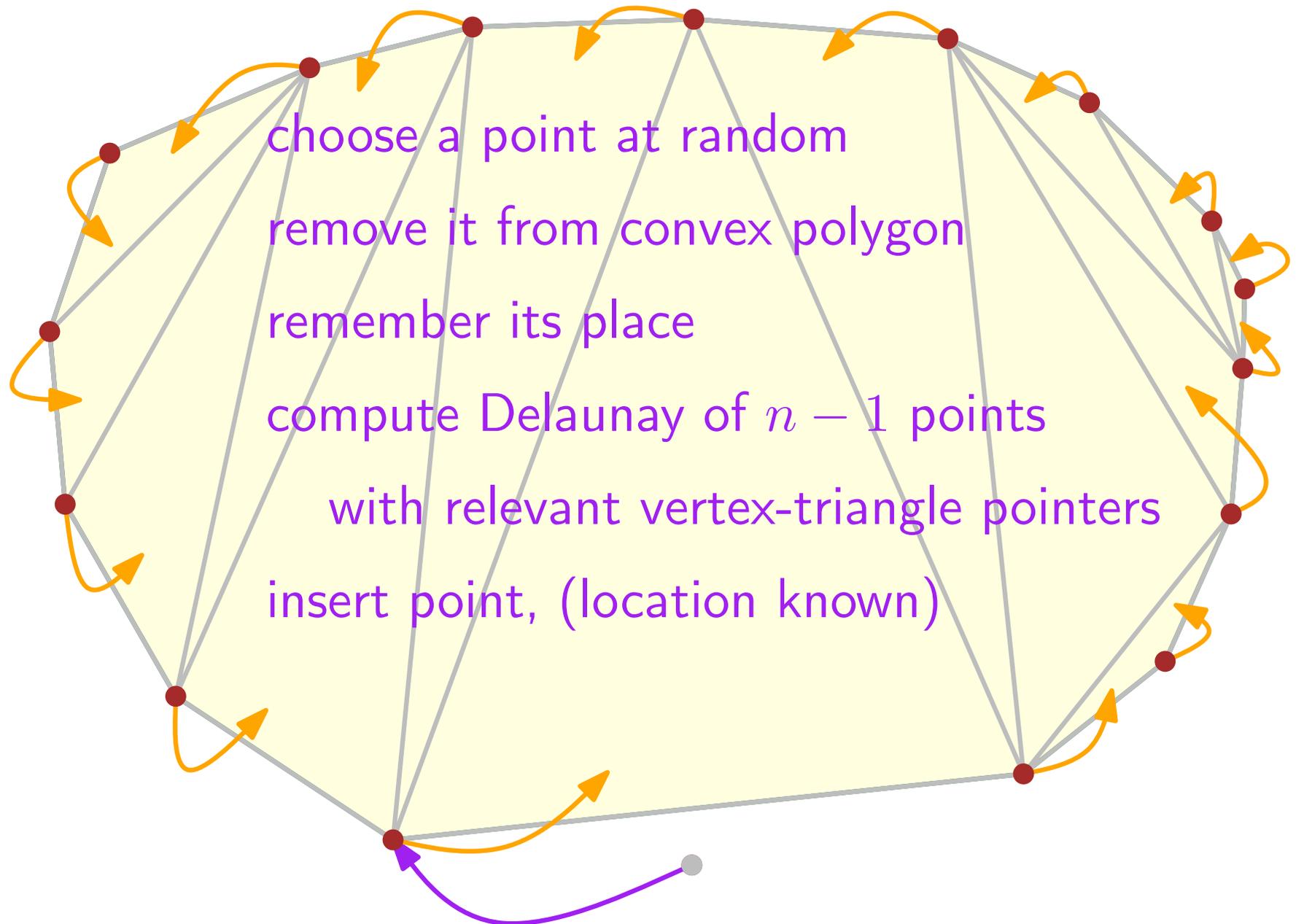
# Delaunay of points in convex position



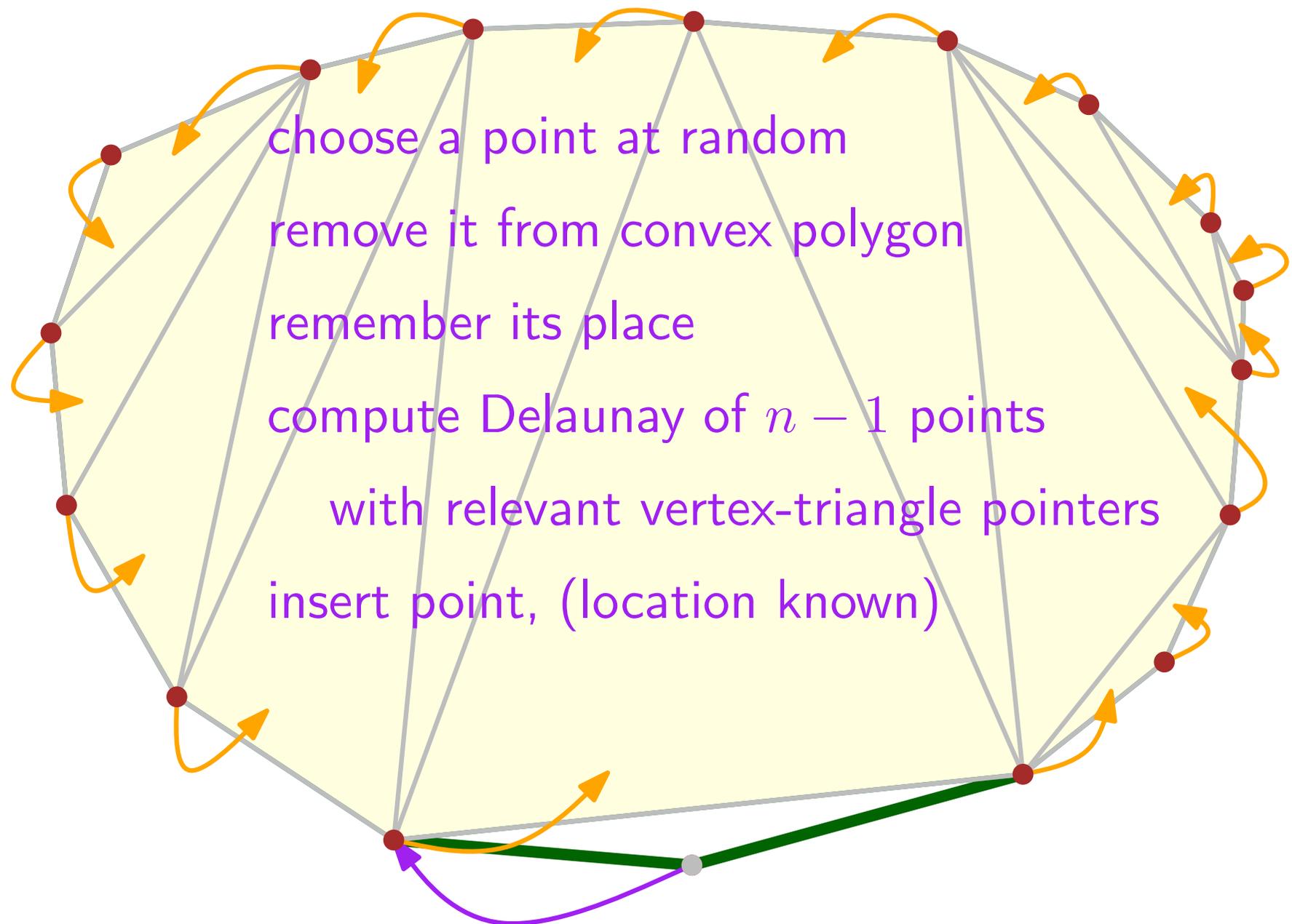
## Delaunay of points in convex position



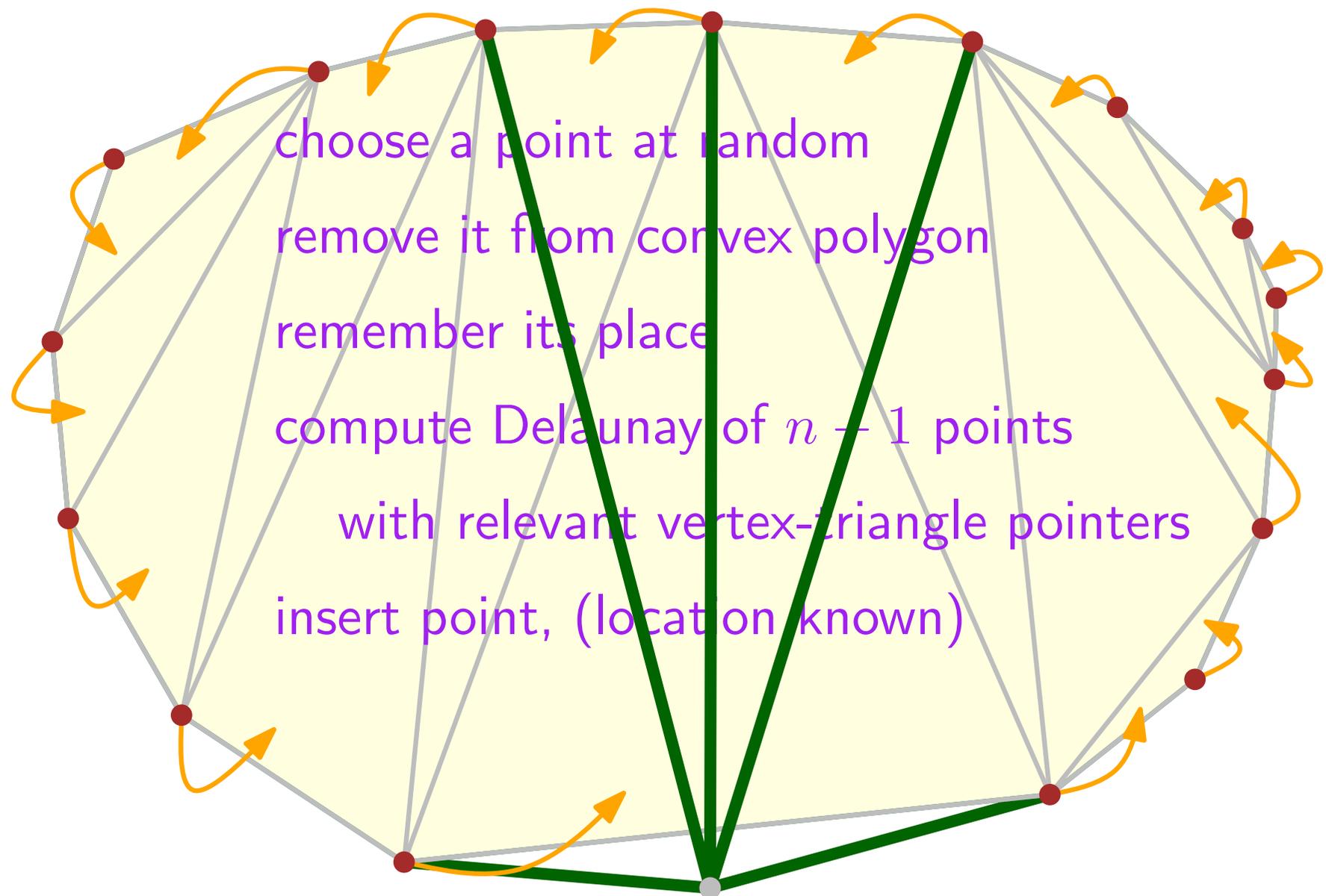
# Delaunay of points in convex position



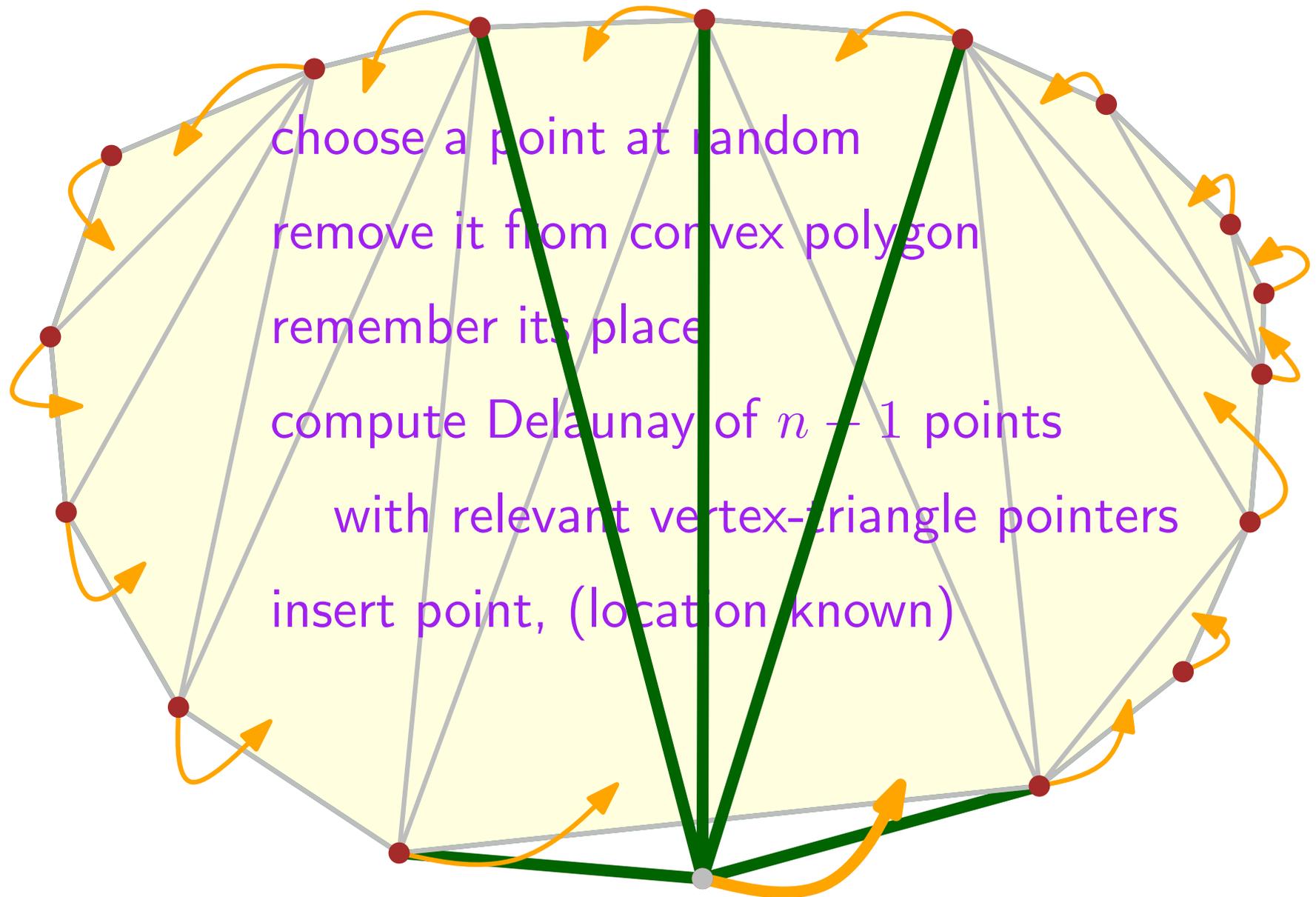
## Delaunay of points in convex position



## Delaunay of points in convex position



# Delaunay of points in convex position



# Delaunay of points in convex position

## Analysis

choose a point at random

remove it from convex polygon

remember its place

compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

# Delaunay of points in convex position

## Analysis

choose a point at random

$O(1)$  [model]

remove it from convex polygon

remember its place

compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

# Delaunay of points in convex position

## Analysis

choose a point at random

remove it from convex polygon

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compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

}  $O(1)$

# Delaunay of points in convex position

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choose a point at random

remove it from convex polygon

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compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

}  $O(1)$

$O(d^{\circ}p)$

# Delaunay of points in convex position

## Analysis

choose a point at random

remove it from convex polygon

remember its place

compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

}  $O(1)$

$O(d^{\circ}p) = O(1)$

# Delaunay of points in convex position

## Analysis

choose a point at random

remove it from convex polygon

remember its place

compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

}  $O(1)$

$f(n - 1)$

$O(d^{\circ}p) = O(1)$

# Delaunay of points in convex position

## Analysis

choose a point at random

remove it from convex polygon

remember its place

compute Delaunay of  $n - 1$  points

with relevant vertex-triangle pointers

insert point, (location known)

}  $O(1)$

$f(n - 1)$

$O(d^{\circ}p) = O(1)$

$$f(n) = f(n - 1) + O(1)$$

# Delaunay of points in convex position

## Analysis

choose a point at random

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$$f(n) = f(n - 1) + O(1) = O(n)$$

# Delaunay of points in convex position

## Analysis

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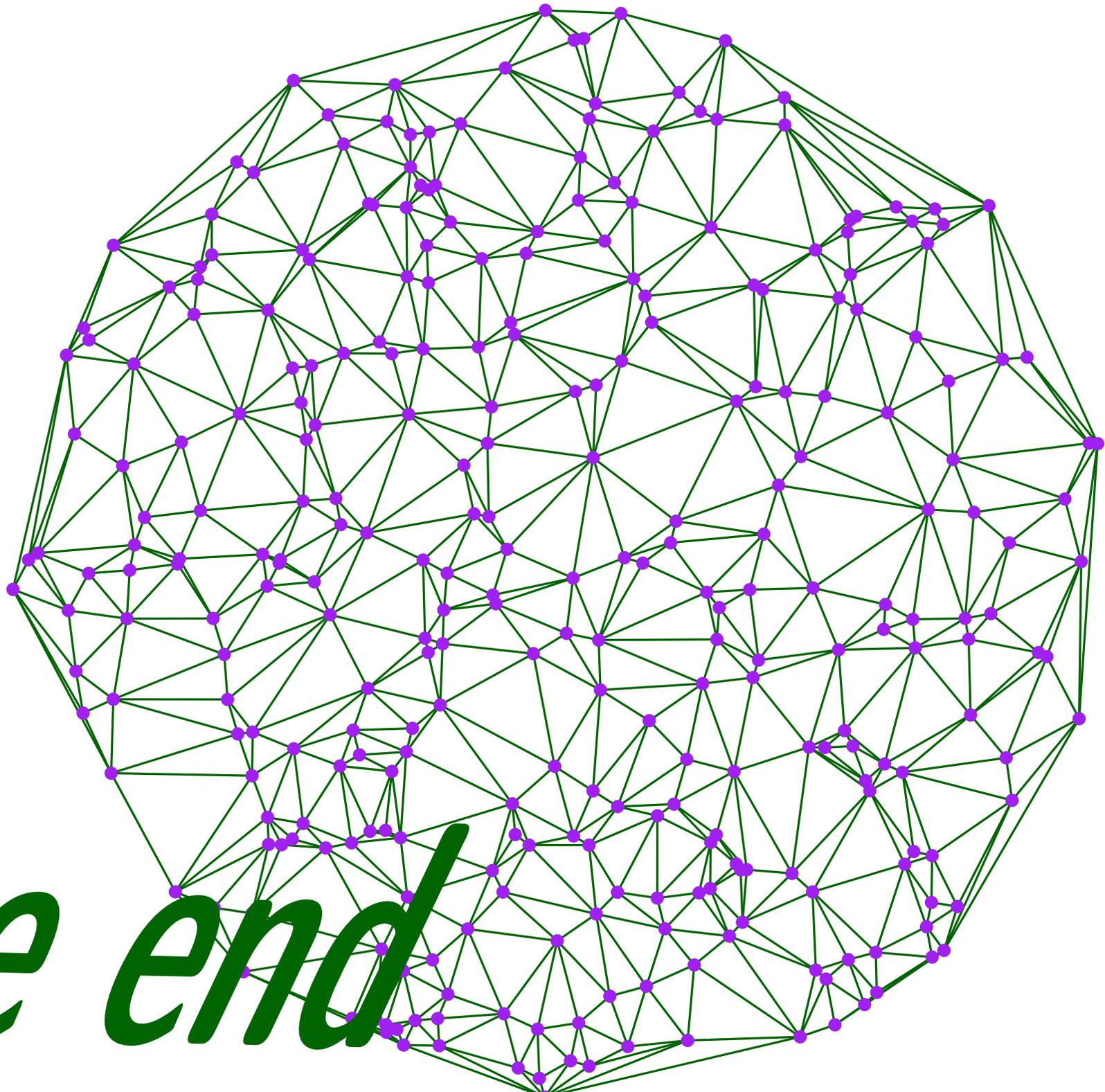
}  $O(1)$

$f(n - 1)$

$O(d^{\circ}p) = O(1)$

$$f(n) = f(n - 1) + O(1) = O(n)$$

[Chew 86]



*The end*