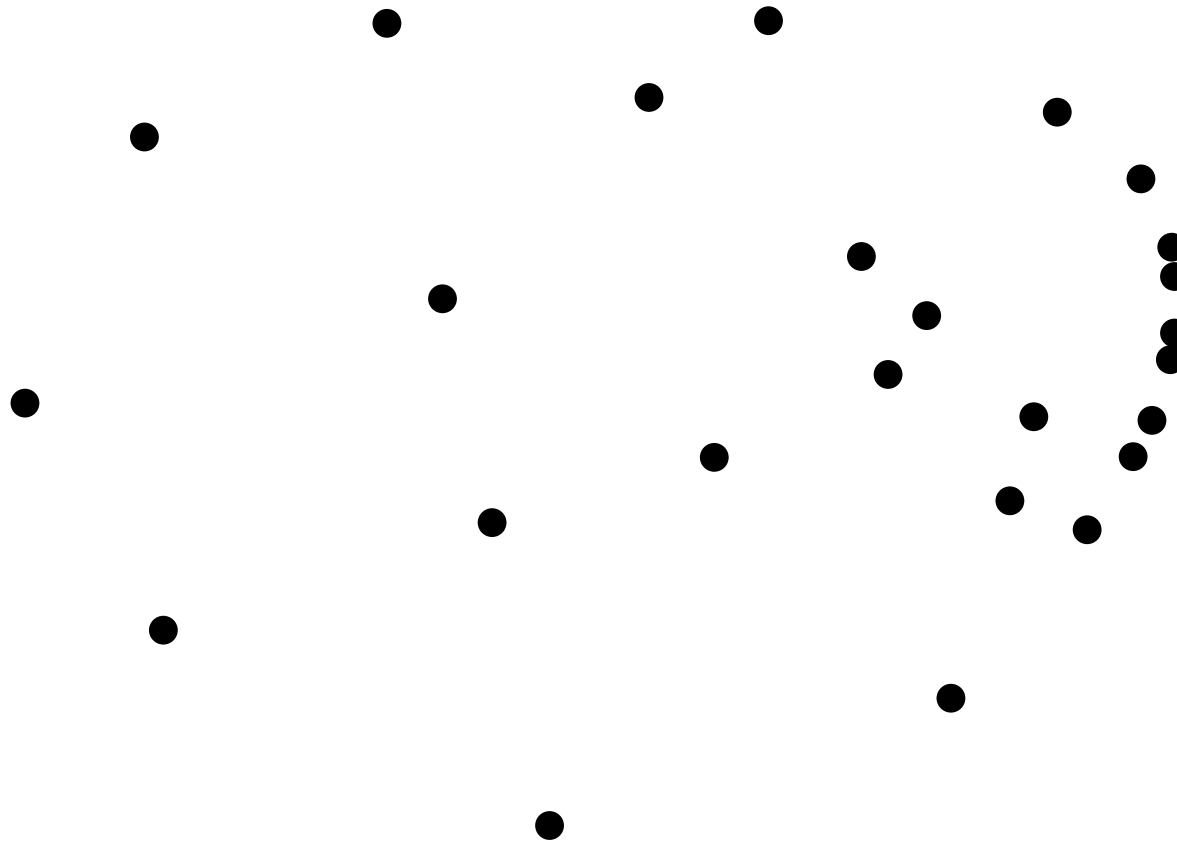
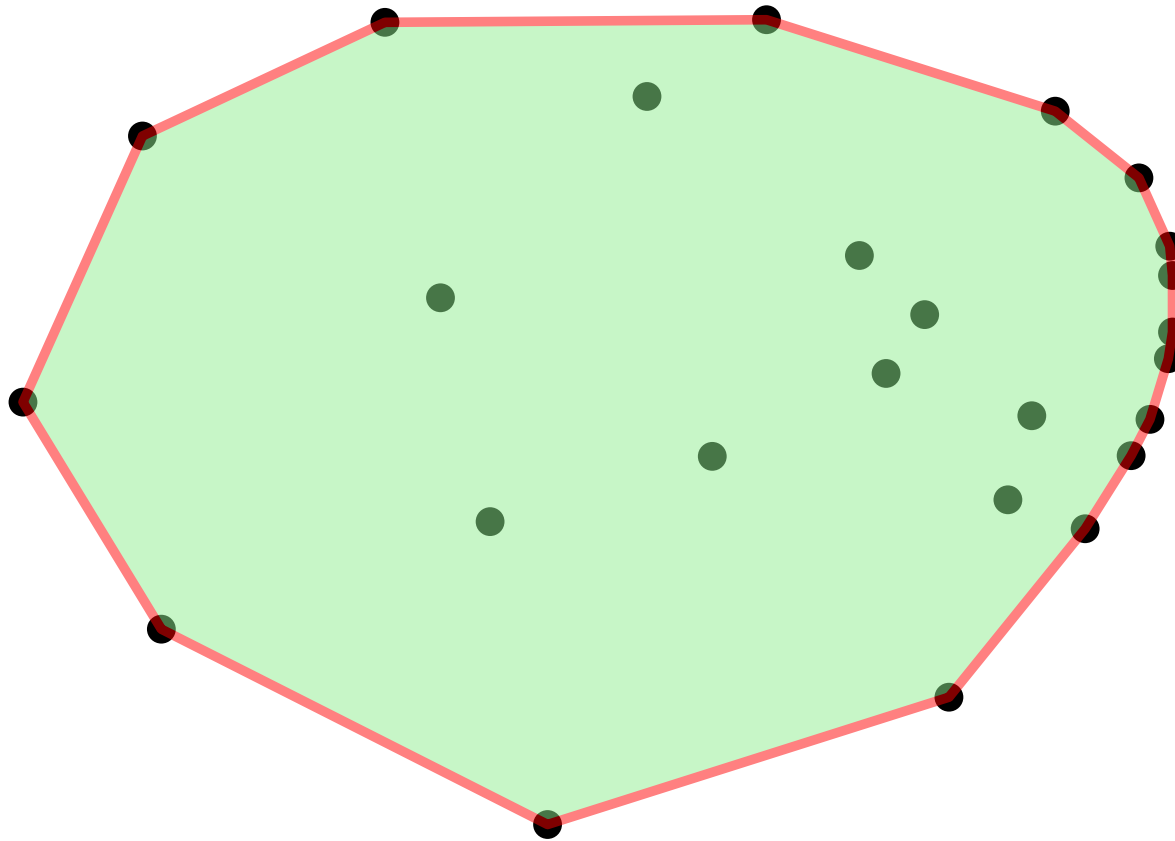


# Convex hull

# Convex hull



# Convex hull



# Convex hull

- Definition, extremal point
- Jarvis algorithm
- Orientation predicate
- Buggy degenerate example
- Real RAM model and general position hypothesis
- Graham algorithm
- Lower bound
- Three dimensions

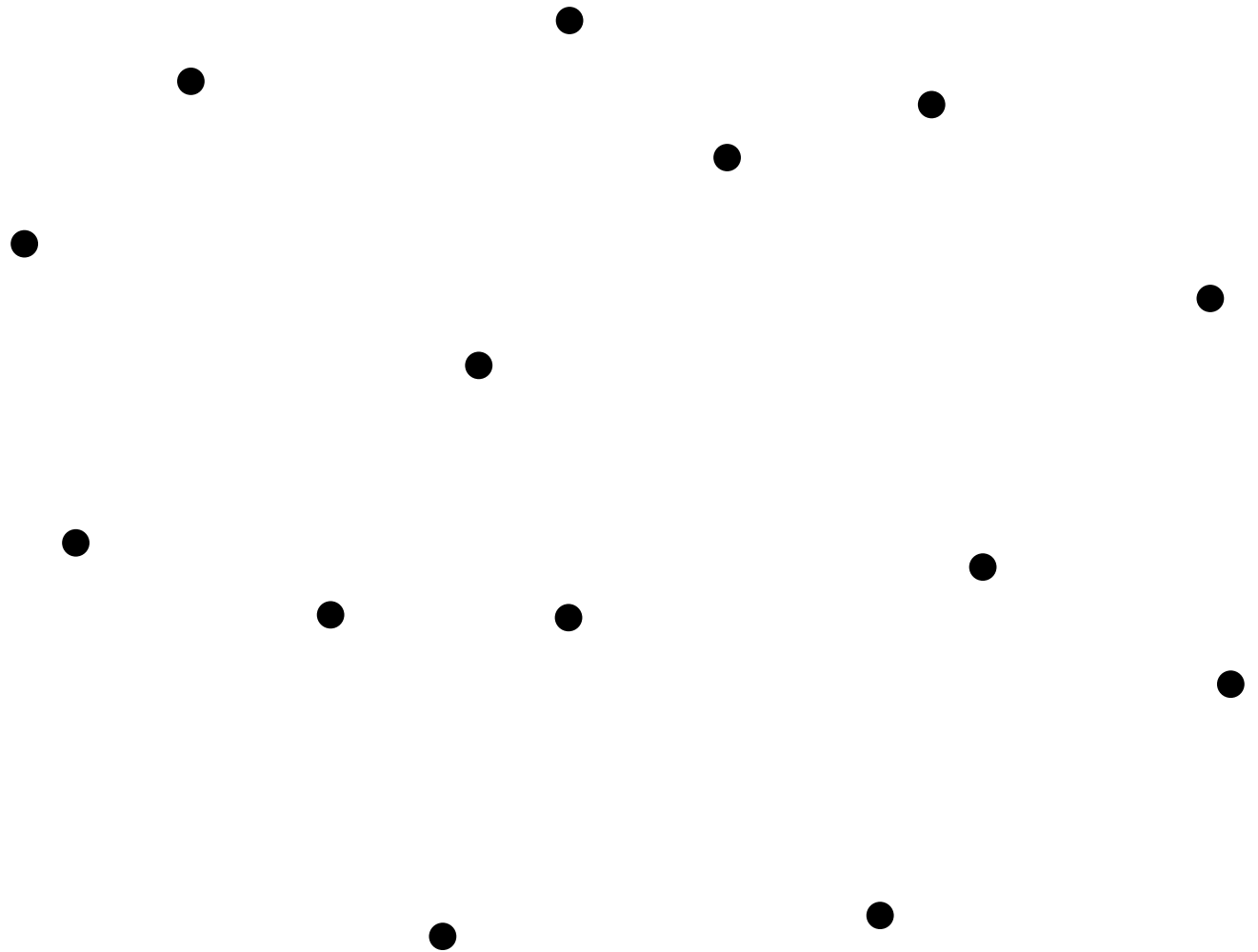
# Convex hull

Definition, extremal point

# Convex hull

Definition, extremal point

Set of points

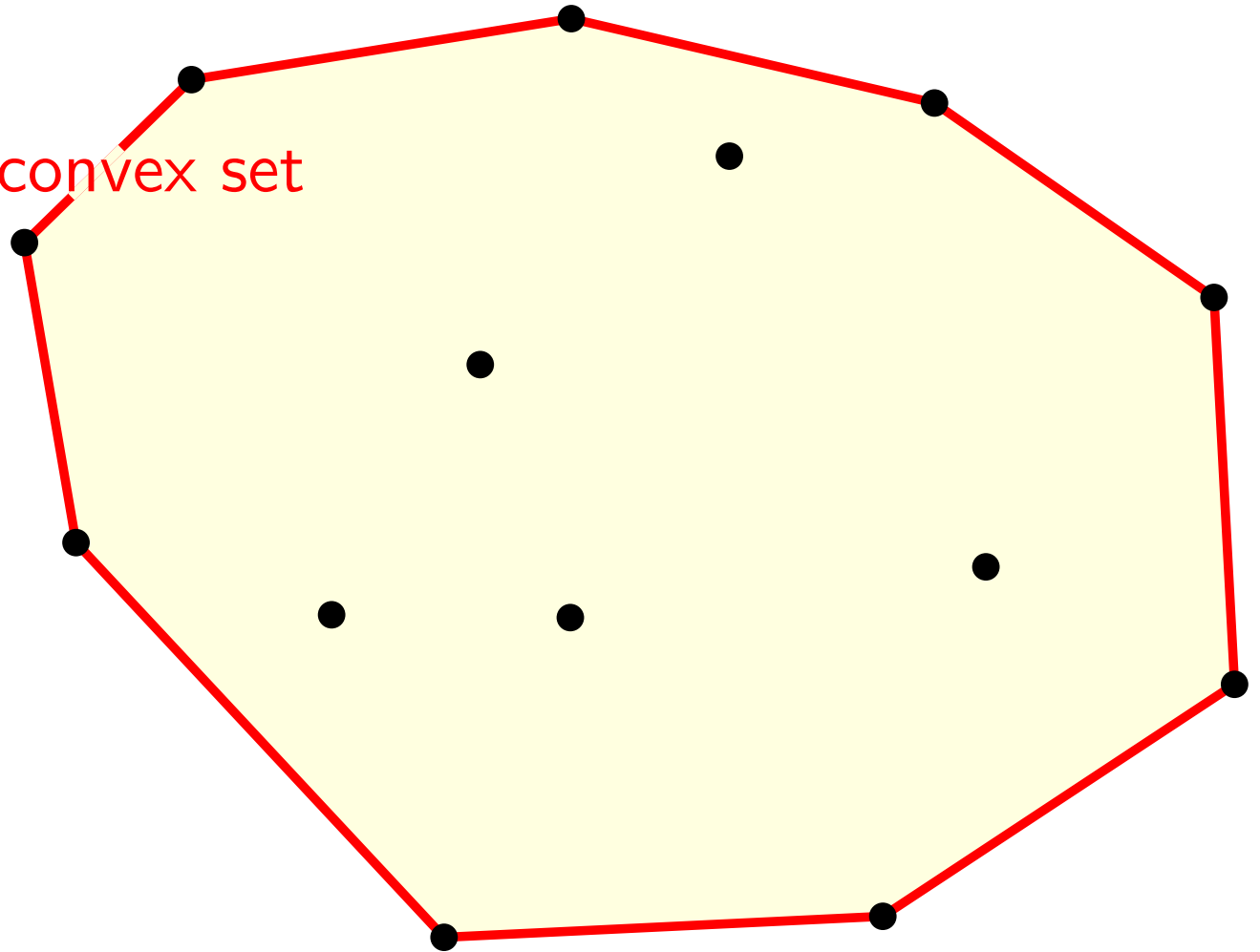


# Convex hull

Definition, extremal point

Set of points

Smallest enclosing convex set



# Convex hull

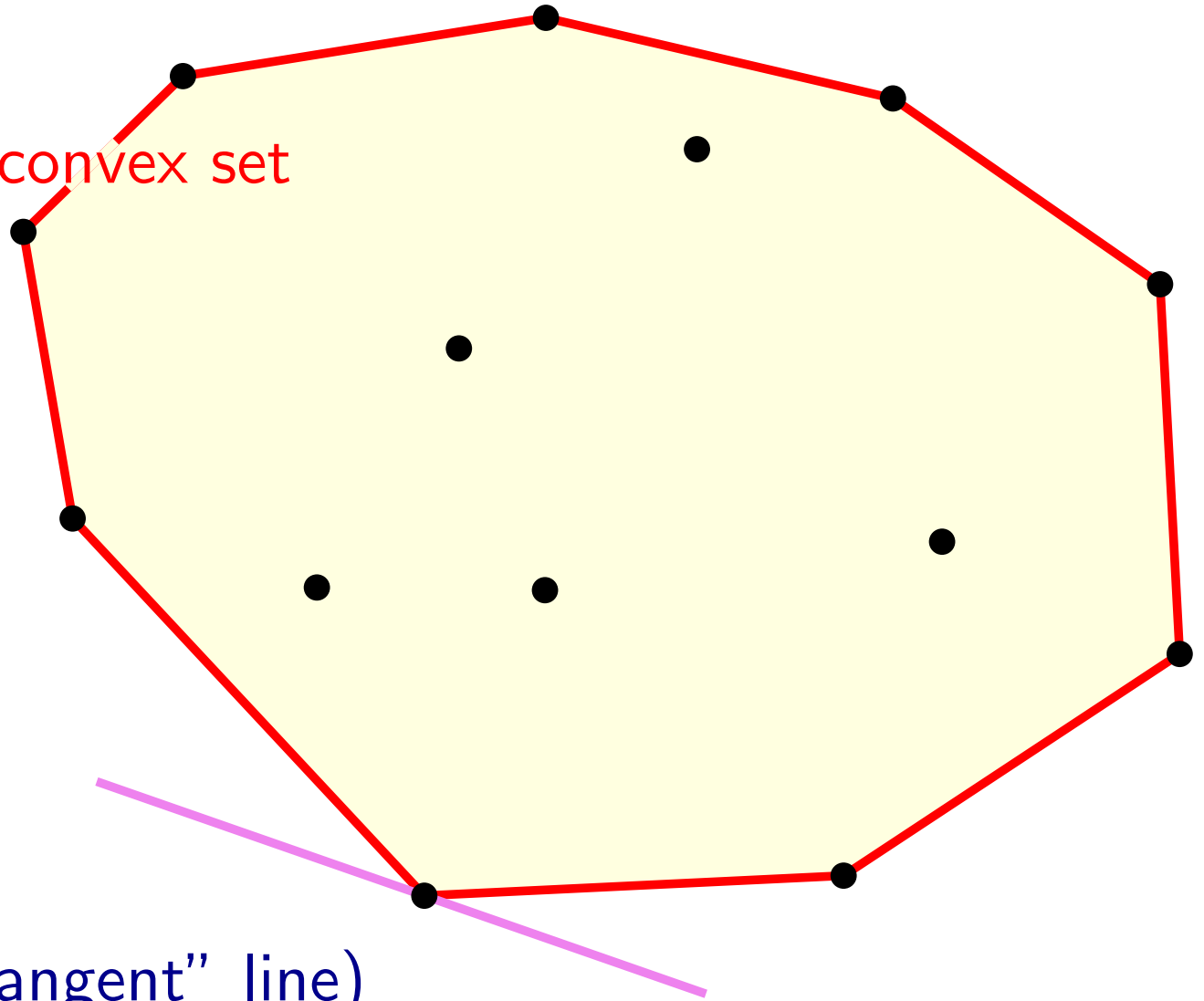
Definition, extremal point

Set of points

Smallest enclosing convex set

Extremal point

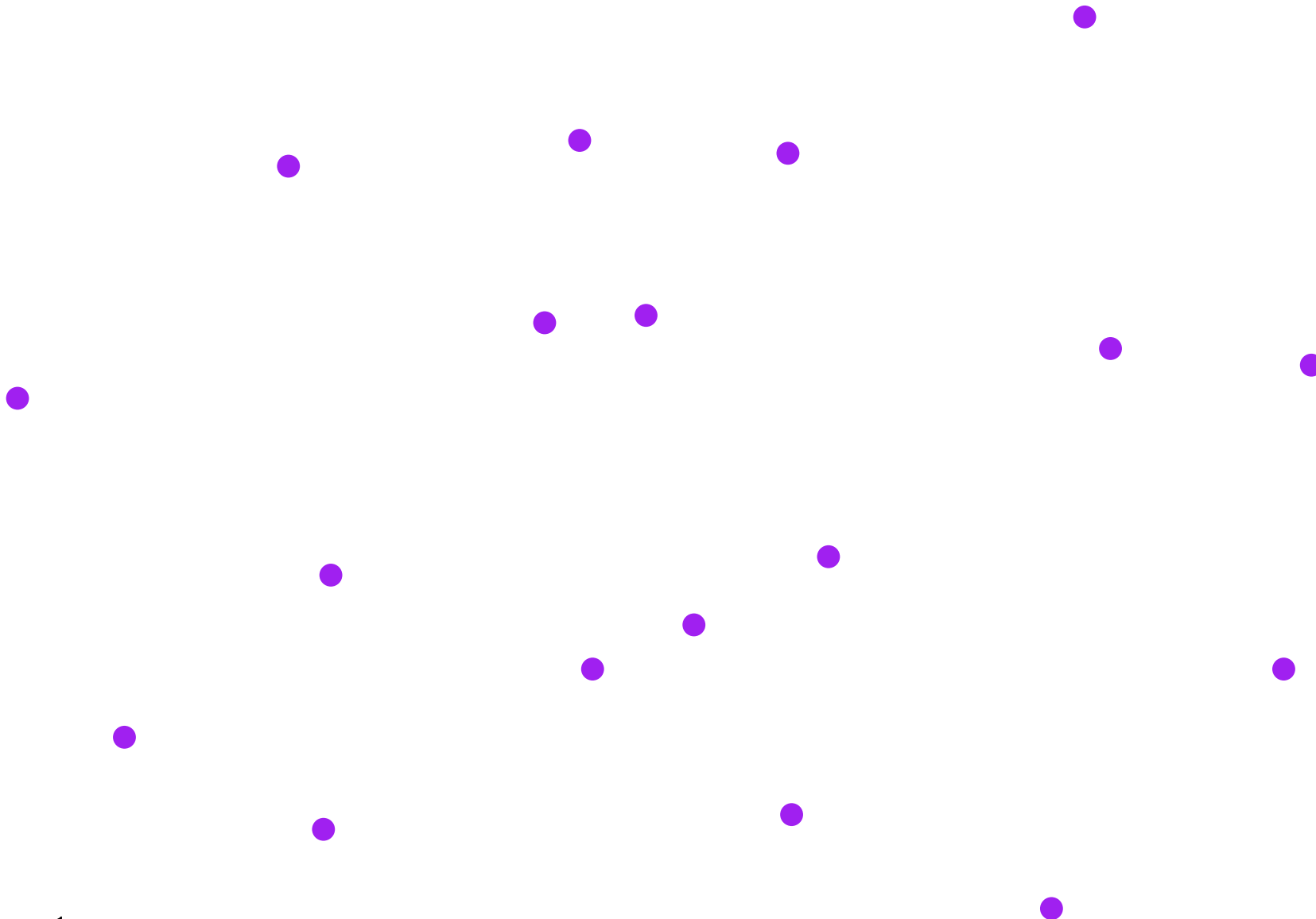
Supporting line ("tangent" line)





# Convex hull

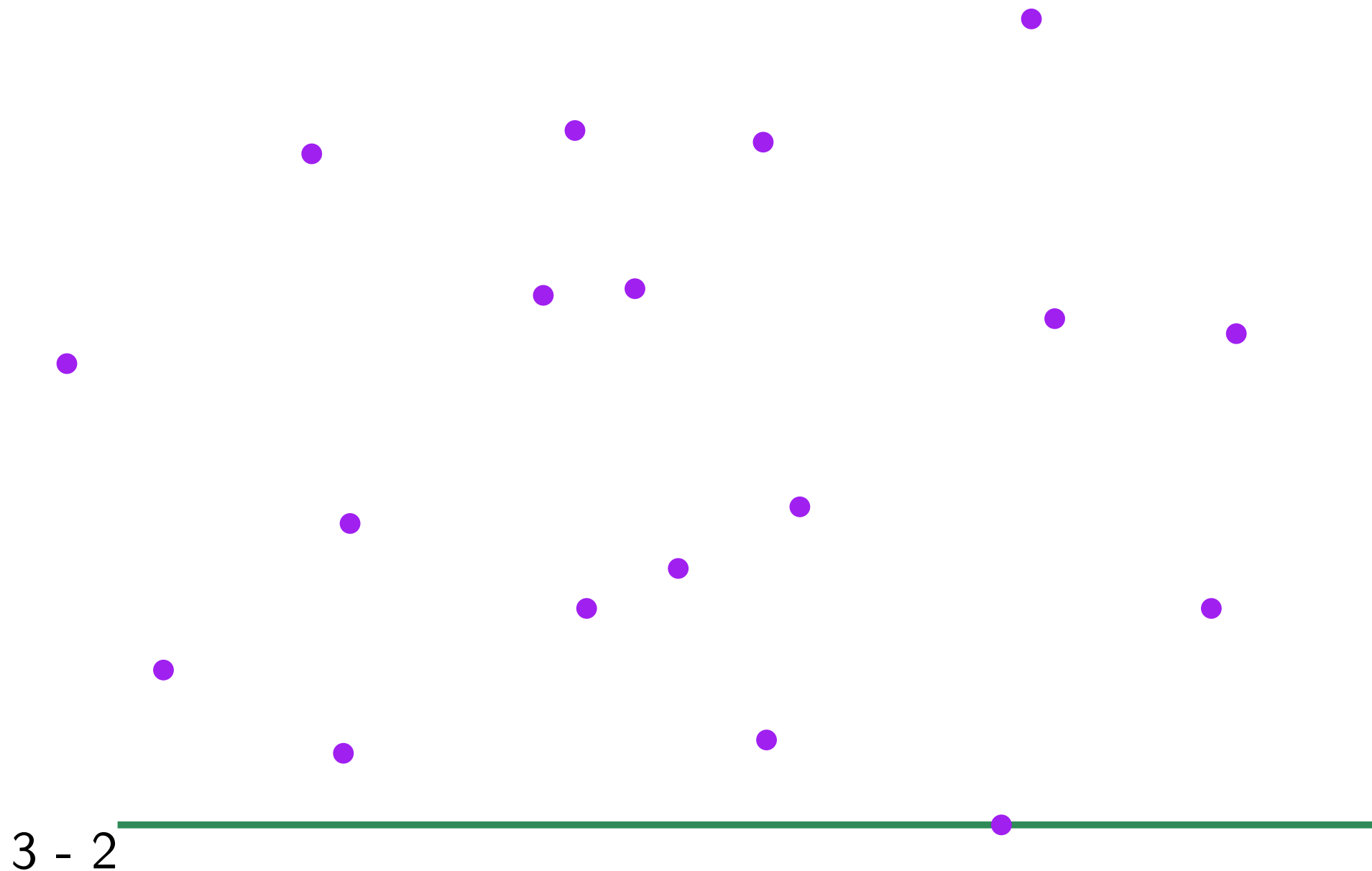
Jarvis algorithm



# Convex hull

lowest point is extremal

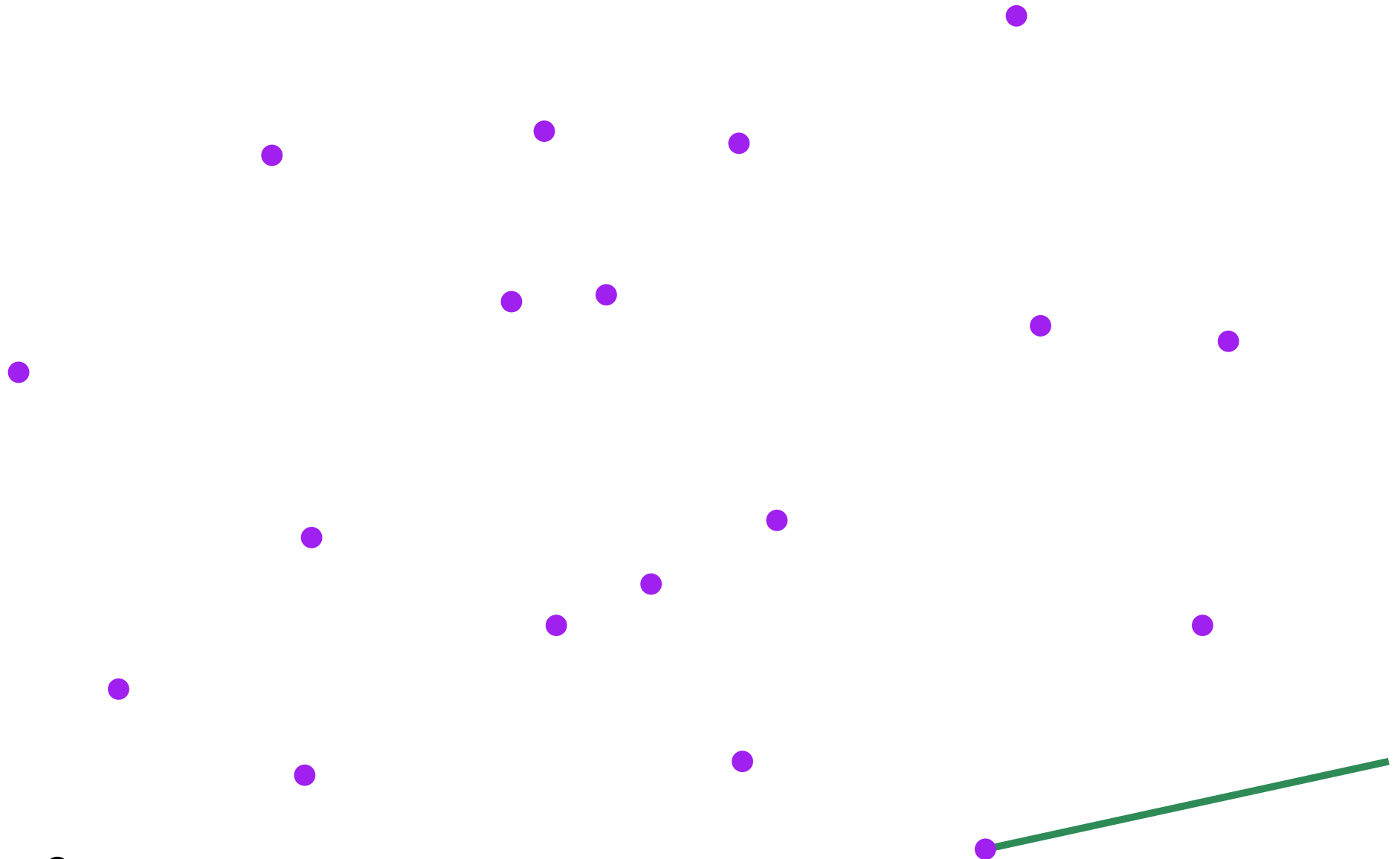
Jarvis algorithm



# Convex hull

rotate

Jarvis algorithm



# Convex hull

rotate

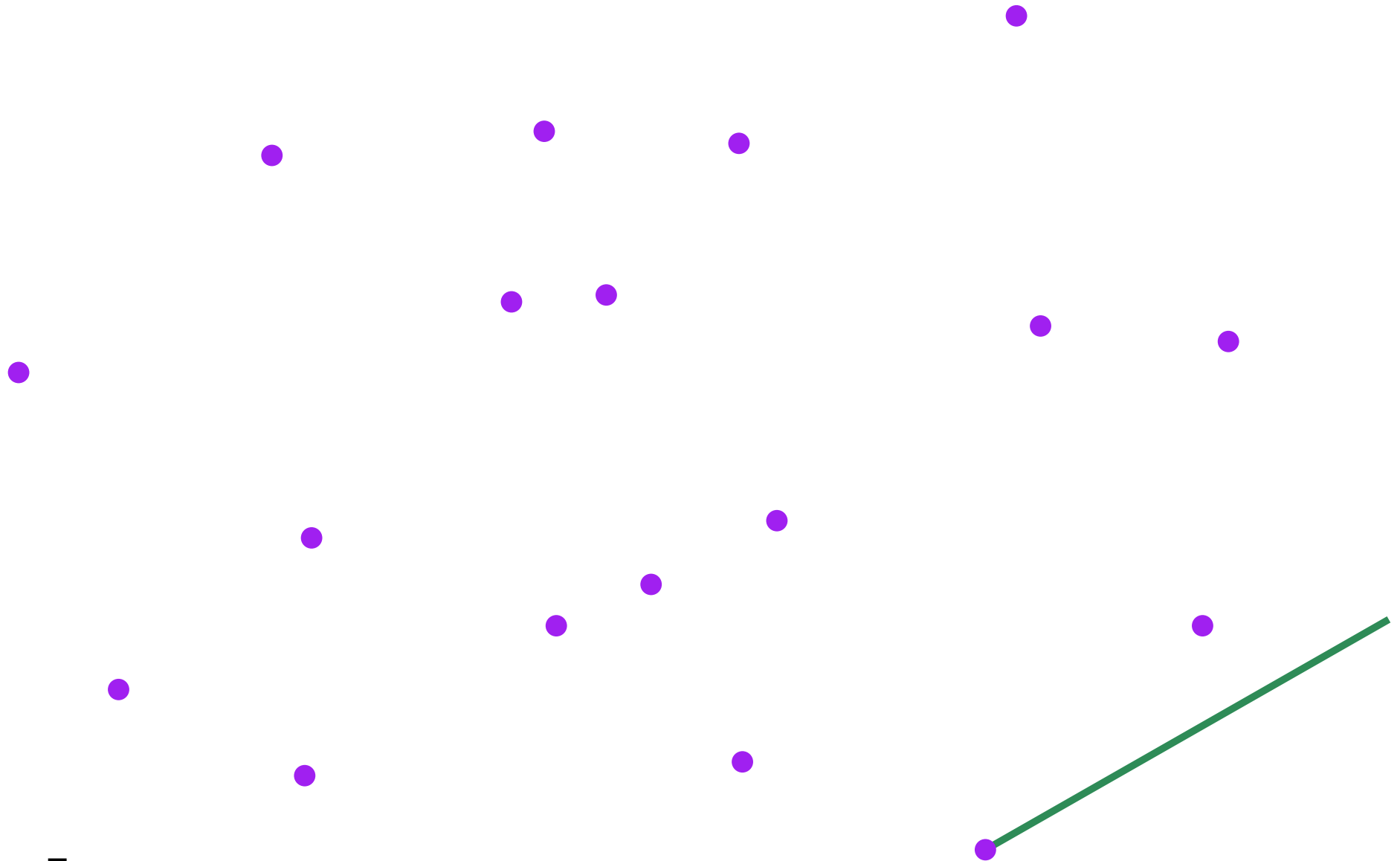
Jarvis algorithm



# Convex hull

rotate

Jarvis algorithm

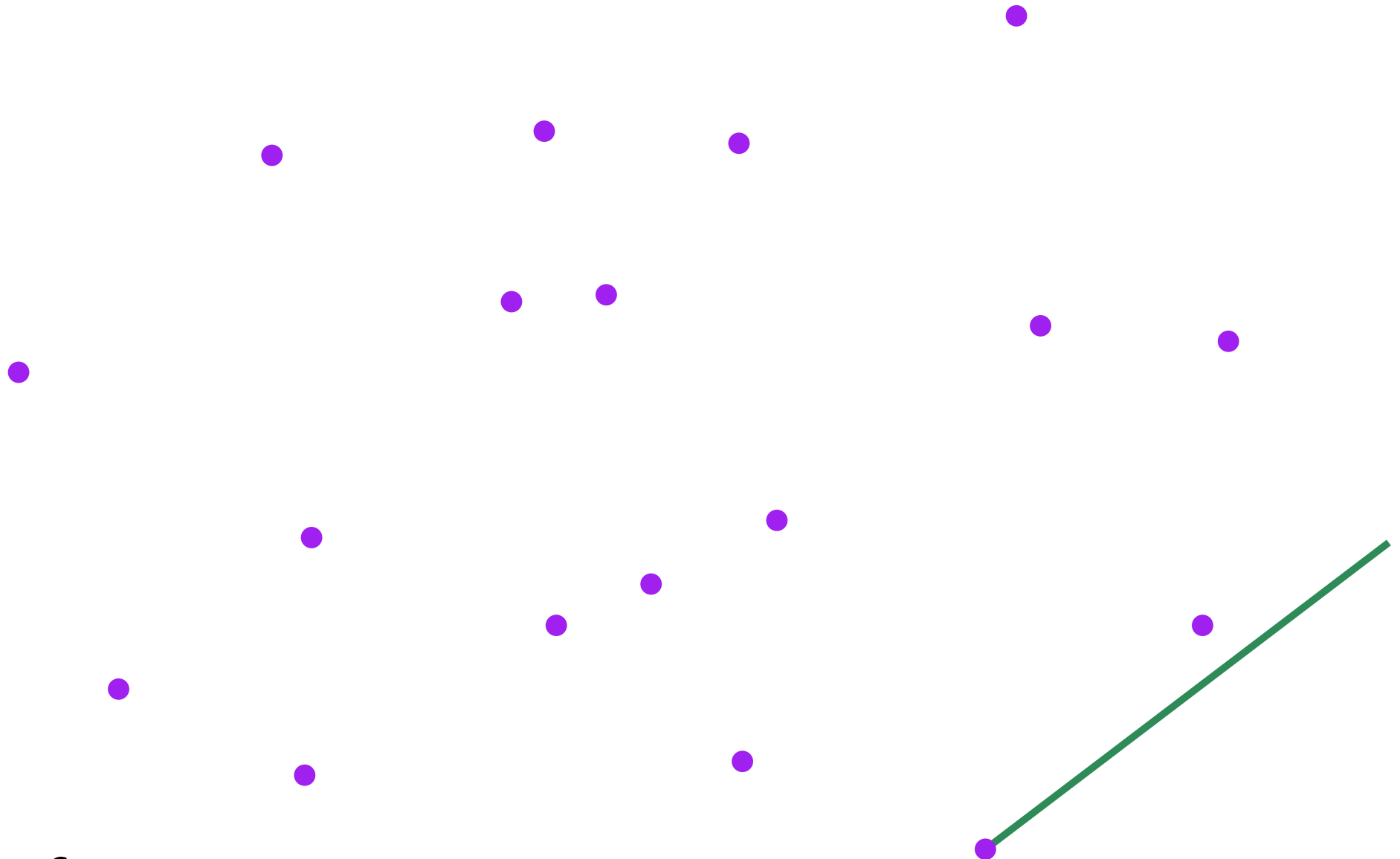


3 - 5

# Convex hull

rotate

Jarvis algorithm

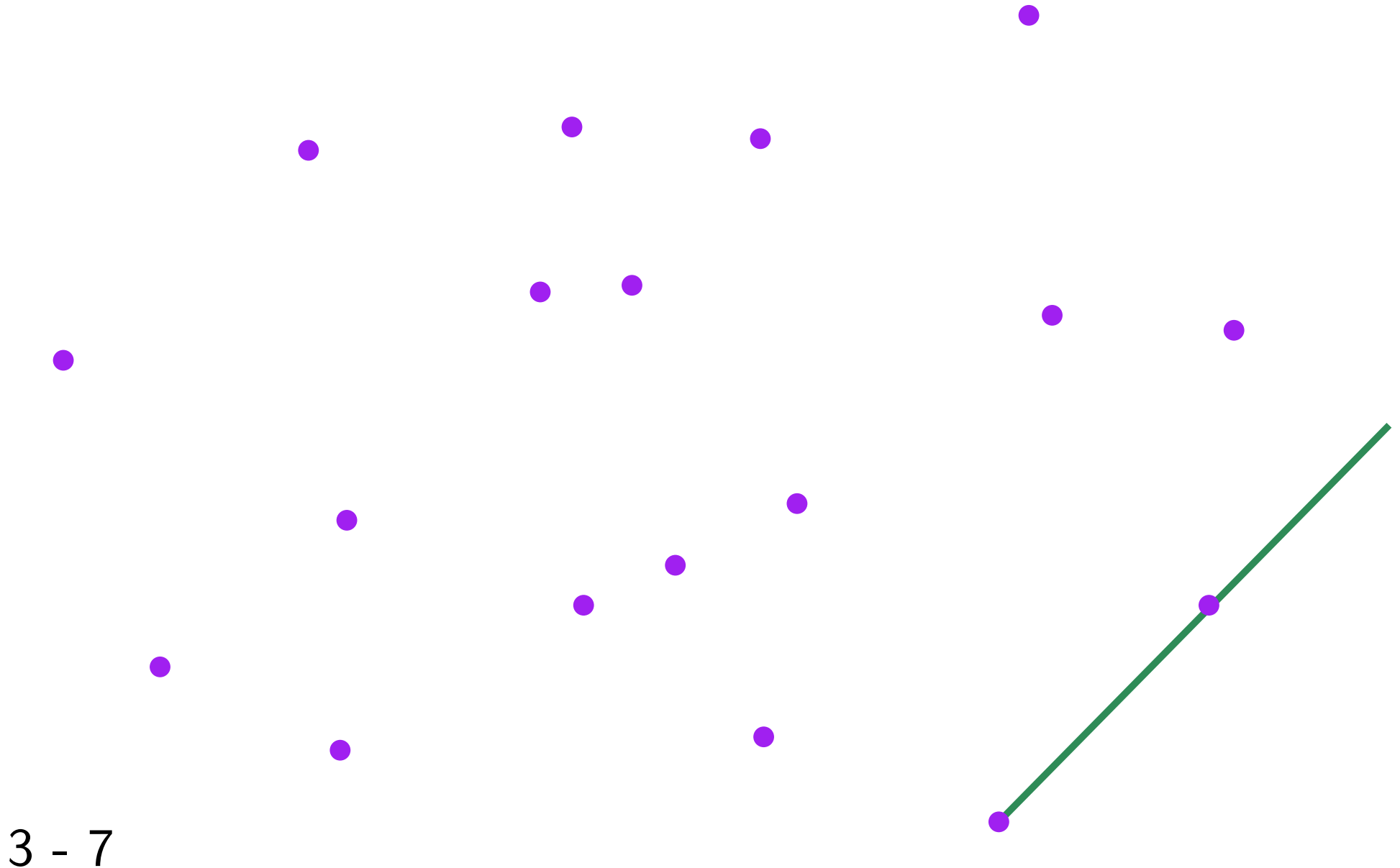


3 - 6

# Convex hull

next vertex found

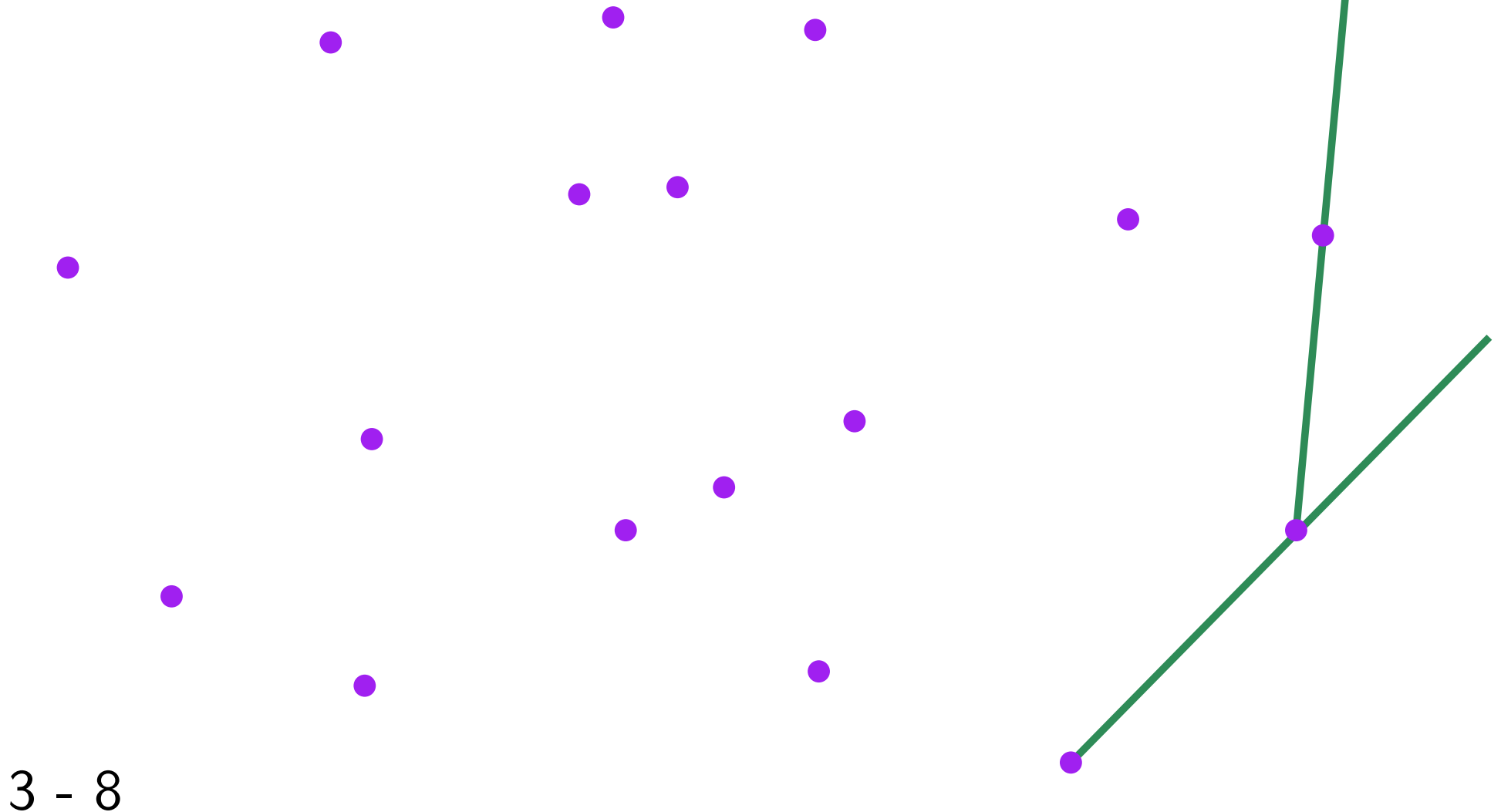
Jarvis algorithm



# Convex hull

next vertex found  
and next one

Jarvis algorithm





# Convex hull

Jarvis algorithm

next vertex found  
and next one

until back to starting point



# Convex hull

## Jarvis algorithm

Input : point set  $S$

$u =$  lowest point in  $S$ ;  $min = \infty$

For each  $w \in S \setminus \{u\}$

    if  $angle(ux, uw) < min$

        then  $min = angle(ux, uw)$ ;  $v = w$ ;

$u.next = v$ ;

Do

$S = S \setminus \{v\}$

    For each  $w \in S$

$min = \infty$

        if  $angle(v.pred\ v, vw) < min$

            then  $min = angle(v.pred\ v, vw)$ ;  $v.next = w$ ;

$v = v.next$ ;

While  $v \neq u$

# Convex hull

Complexity ?

Jarvis algorithm

Input : point set  $S$

$u =$  lowest point in  $S$ ;  $min = \infty$

For each  $w \in S \setminus \{u\}$

if  $angle(ux, uw) < min$

then  $min = angle(ux, uw)$ ;  $v = w$ ;

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Do

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For each  $w \in S$

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While  $v \neq u$

$O(n)$

# Convex hull

Complexity ?

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# Convex hull

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$v = v.next$ ;

While  $v \neq u$

$O(n)$

# Convex hull

Complexity ?

Jarvis algorithm

Input : point set  $S$

$u =$  lowest point in  $S$ ;  $min = \infty$

For each  $w \in S \setminus \{u\}$

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        if  $angle(v.pred\ v, vw) < min$

            then  $min = angle(v.pred\ v, vw)$ ;  $v.next = w$ ;

$v = v.next$ ;

While  $v \neq u$

$O(n^2)$



# Convex hull

Complexity ?

Jarvis algorithm

Input : point set  $S$

$u =$  lowest point in  $S$ ;  $min = \infty$

For each  $w \in S \setminus \{u\}$

if  $angle(ux, uw) < min$

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$u.next = v$ ;

Do

$S = S \setminus \{v\}$

For each  $w \in S$

$min = \infty$

if  $angle(v.pred\ v, vw) < min$

then  $min = angle(v.pred\ v, vw)$ ;  $v.next = w$ ;

$v = v.next$ ;

While  $v \neq u$

$O(n^2)$

$O(nh)$

# Convex hull

Input : point set  $S$

$u =$  lowest point in  $S$ ;  $min = \infty$

For each  $w \in S \setminus \{u\}$

if  $angle(ux, uw) < min$

then  $min = angle(ux, uw)$ ;  $v = w$ ;

$u.next = v$ ;

Do

$S = S \setminus \{v\}$

For each  $w \in S$

$min = \infty$

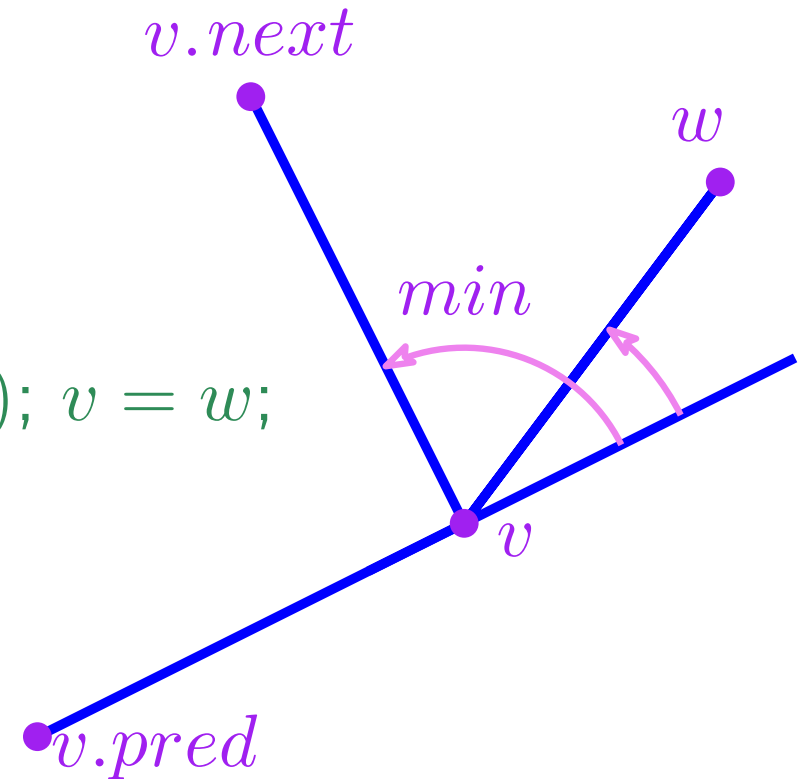
if  $angle(v.pred\ v, vw) < min$

then  $min = angle(v.pred\ v, vw)$ ;  $v.next = w$ ;

$v = v.next$ ;

While  $v \neq u$

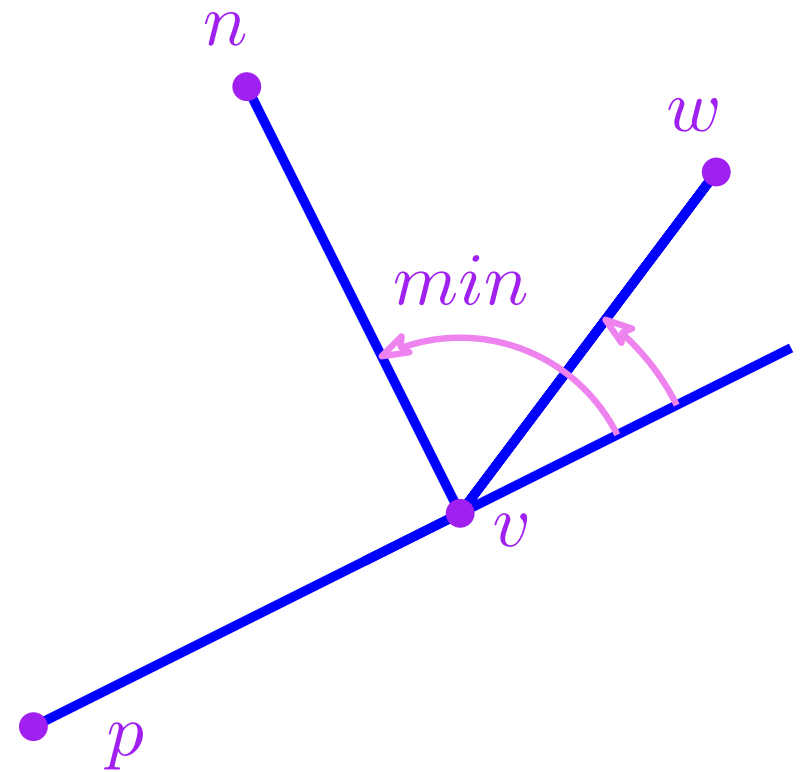
Orientation predicate



# Convex hull

if  $\text{angle}(pv, vw) < \text{min}$

Orientation predicate



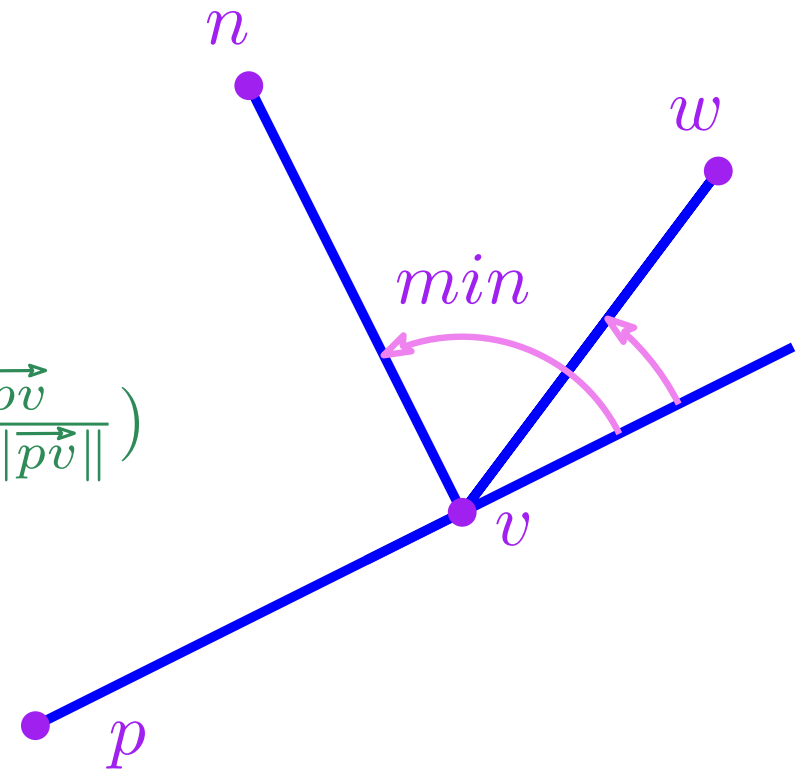
# Convex hull

if  $\text{angle}(pv, vw) < \text{min}$

$$\text{angle}(pv, vw) = \arccos\left(\frac{\vec{vw} \cdot \vec{pv}}{\|\vec{vw}\| \cdot \|\vec{pv}\|}\right)$$



Orientation predicate

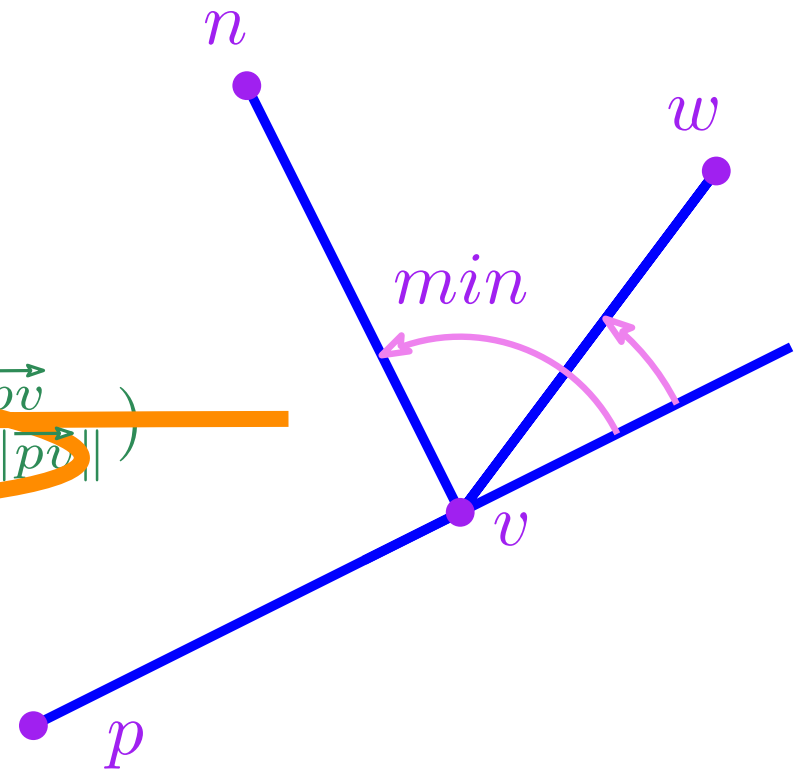


# Convex hull

if  $\text{angle}(pv, vw) < \text{min}$

$$\text{angle}(pv, vw) = \arccos\left(\frac{\vec{vw} \cdot \vec{pv}}{\|\vec{vw}\| \cdot \|\vec{pv}\|}\right)$$

Orientation predicate



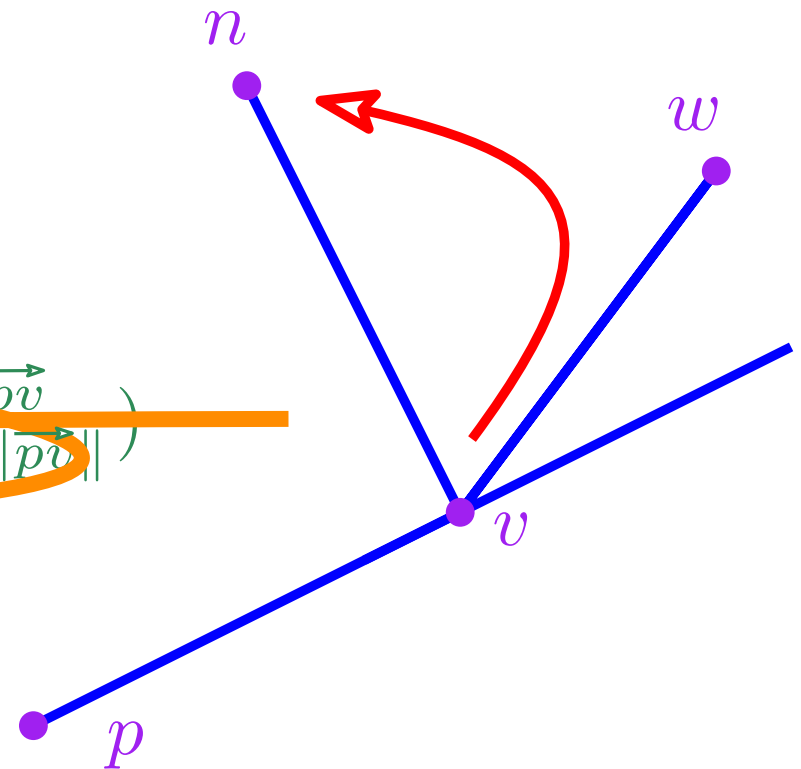
# Convex hull

if  $\text{angle}(pv, vw) < \min$

$$\text{angle}(pv, vw) = \arccos\left(\frac{\vec{vw} \cdot \vec{pv}}{\|\vec{vw}\| \cdot \|\vec{pv}\|}\right)$$

if  $vwn$  turn left

Orientation predicate

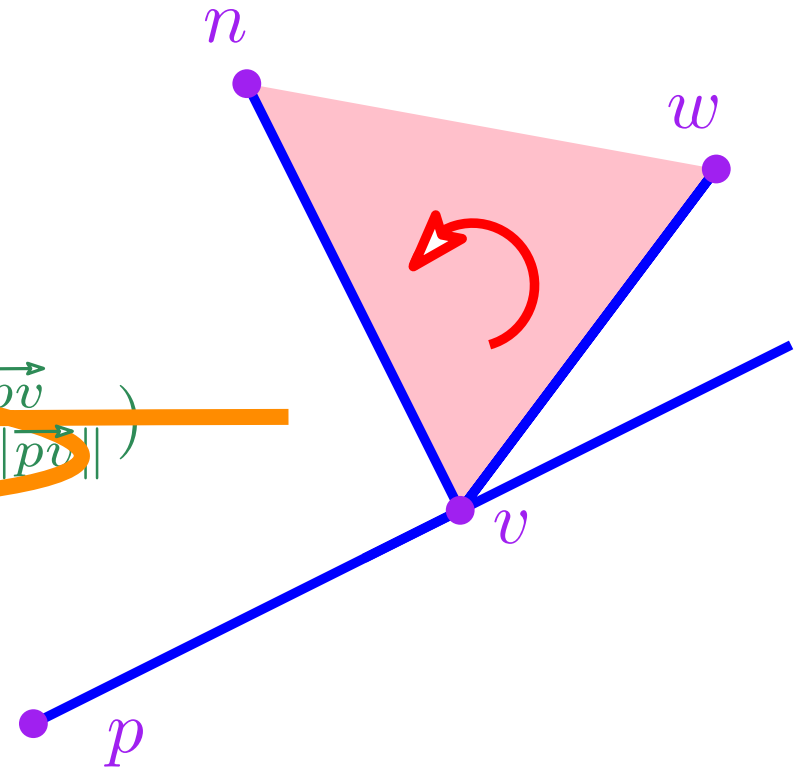


# Convex hull

if  $\text{angle}(pv, vw) < \min$

$$\text{angle}(pv, vw) = \arccos\left(\frac{\vec{vw} \cdot \vec{pv}}{\|\vec{vw}\| \cdot \|\vec{pv}\|}\right)$$

Orientation predicate



if  $vwn$  turn left

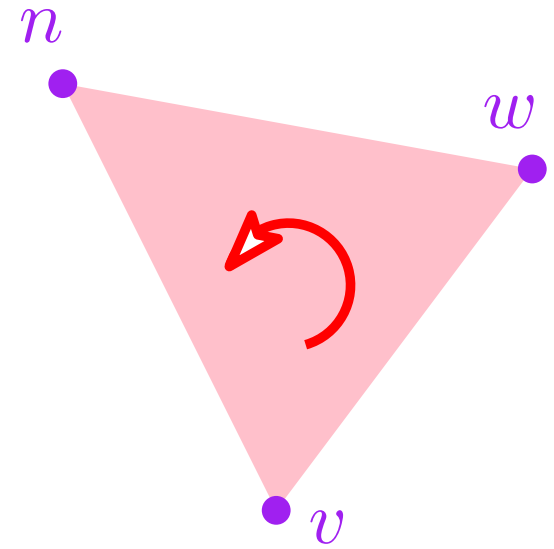
if triangle  $vwn$  counterclockwise (ccw)

if triangle  $vwn$  positively oriented

# Convex hull

$vwn + ?$

Orientation predicate



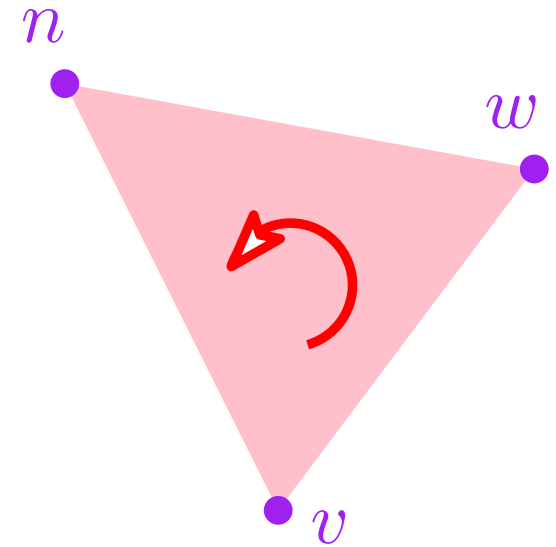


# Convex hull

$vwn + ?$

$$\begin{vmatrix} x_w - x_v & x_n - x_v \\ y_w - y_v & y_n - y_v \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} > 0$$

## Orientation predicate



# Convex hull

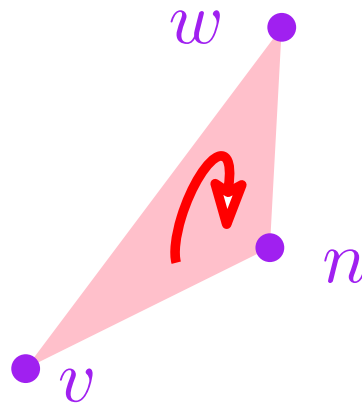
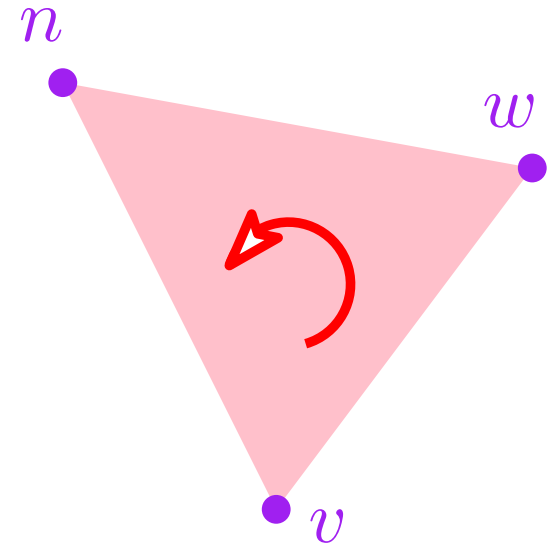
## Orientation predicate

$vwn + ?$

$$\begin{vmatrix} x_w - x_v & x_n - x_v \\ y_w - y_v & y_n - y_v \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} > 0$$

$vwn - ?$

$$\begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} < 0$$

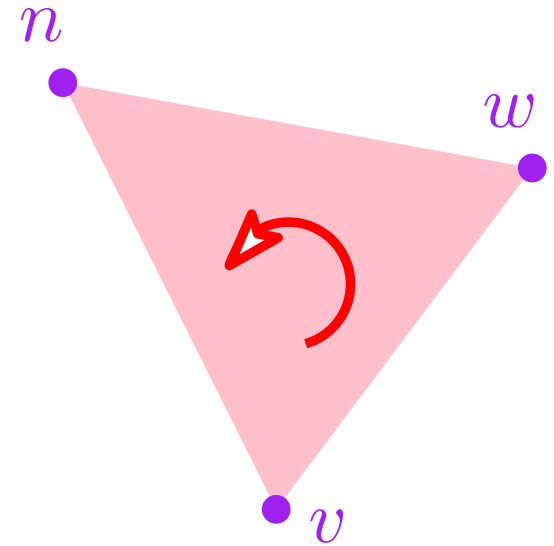


# Convex hull

## Orientation predicate

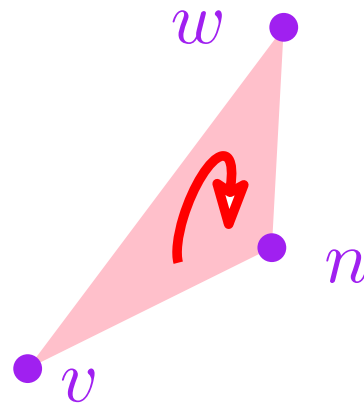
$vwn + ?$

$$\begin{vmatrix} x_w - x_v & x_n - x_v \\ y_w - y_v & y_n - y_v \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} > 0$$



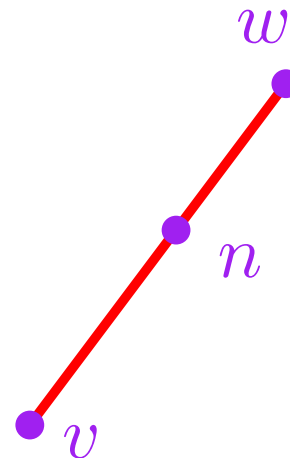
$vwn - ?$

$$\begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} < 0$$



$vwn 0 ?$

$$\begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} = 0$$



# Convex hull

## Orientation predicate

$vwn + ?$

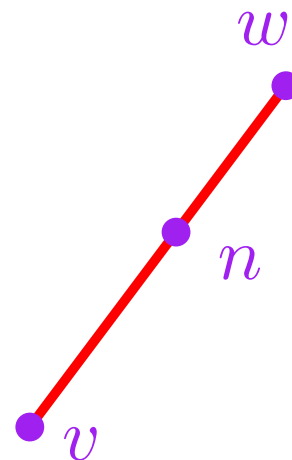
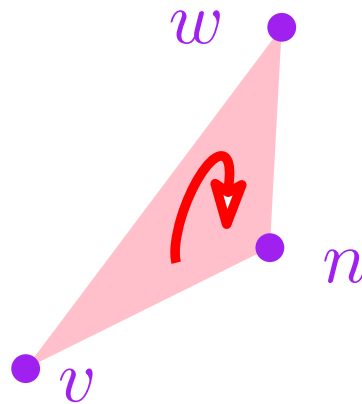
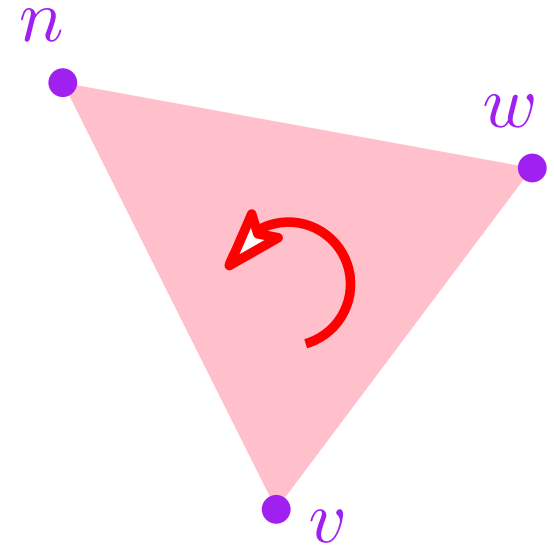
$$\begin{vmatrix} x_w - x_v & x_n - x_v \\ y_w - y_v & y_n - y_v \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} > 0$$

$vwn - ?$

$$\begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} < 0$$

$vwn 0 ?$

$$\begin{vmatrix} 1 & 1 & 1 \\ x_v & x_w & x_n \\ y_v & y_w & y_n \end{vmatrix} = 0$$



degenerate case

# Convex hull

## Orientation predicate

$vwn + ?$

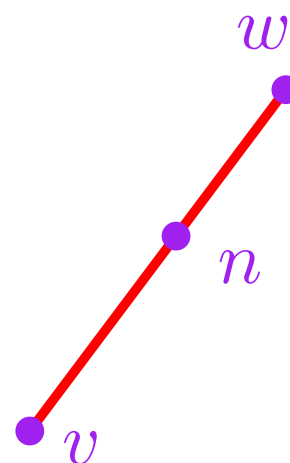
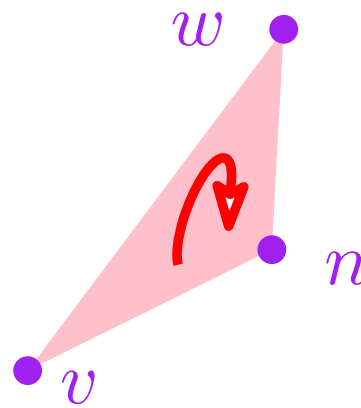
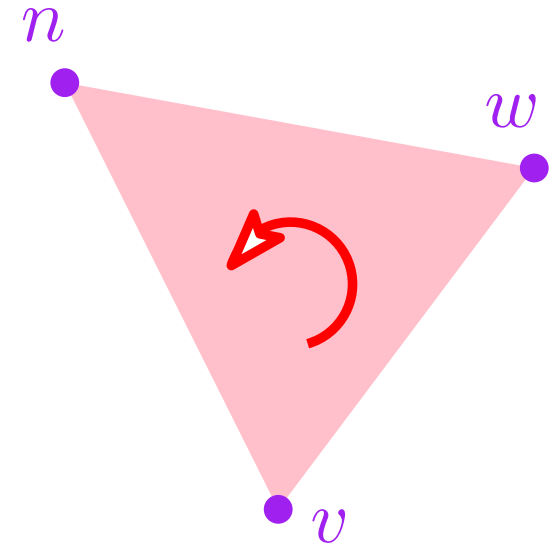
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rounding errors



# Convex hull

Rounding errors possible

Orientation predicate

$$p = \left(\frac{1}{2} + x.u, \frac{1}{2} + y.u\right)$$

$$0 \leq x, y \leq 256, u = 2^{-53}$$

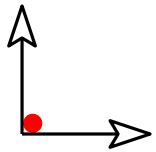
$$q = (12, 12)$$

$$r = (24, 24)$$

Teaser robustness lecture

$orientation(p, q, r)$

evaluated with double



# Convex hull

Rounding errors possible

Orientation predicate

$$p = \left(\frac{1}{2} + x.u, \frac{1}{2} + y.u\right)$$

$$0 \leq x, y \leq 256, u = 2^{-53}$$

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Teaser robustness lecture

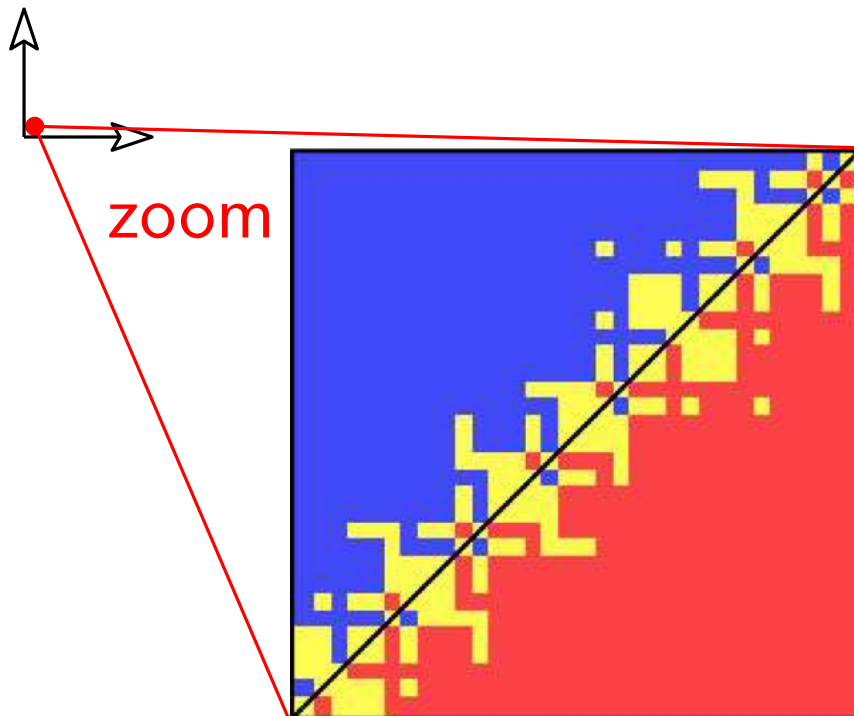
$orientation(p, q, r)$

evaluated with double

$$\leq 0$$

$$0$$

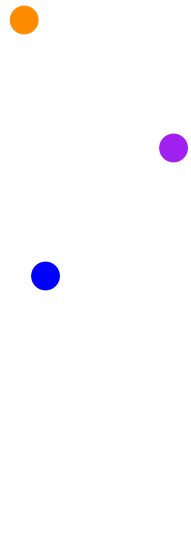
$$\geq 0$$



# Convex hull

Teaser robustness lecture

Buggy degenerate example  
(single precision)



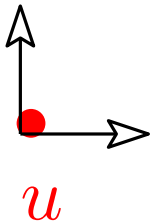
$$w_1 = (12, 12)$$

$$w_2 = (24, 24)$$

$$w_3 = (30, 30.000001)$$

$$w_4 = (23, 36)$$

$$w_5 = (0.5000029, 0.5000027)$$

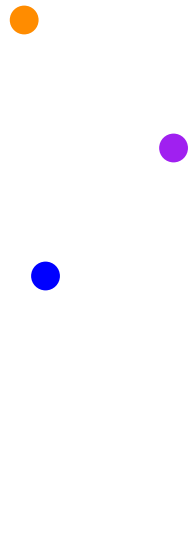




# Convex hull

Teaser robustness lecture

Buggy degenerate example  
(single precision)



$$w_1 = (12, 12)$$

$$w_2 = (24, 24)$$

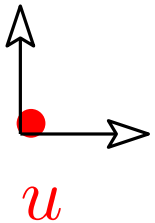
$$w_3 = (30, 30.0000001)$$

$$w_4 = (23, 36)$$

$$w_5 = (0.5000029, 0.5000027)$$

Input : point set  $S$

$u = v =$  lowest point in  $S$ ;

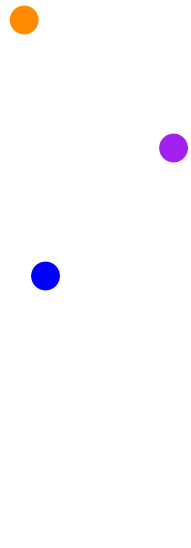


Jarvis

# Convex hull

Teaser robustness lecture

Buggy degenerate example  
(single precision)



$$w_1 = (12, 12)$$

$$w_2 = (24, 24)$$

$$w_3 = (30, 30.0000001)$$

$$w_4 = (23, 36)$$

$$w_5 = (0.50000029, 0.50000027)$$

Do

$n = \text{first in } S;$

For each  $w \in S$

if  $vwn$  positive

then  $n = w;$

$v.next = n; v = n;$

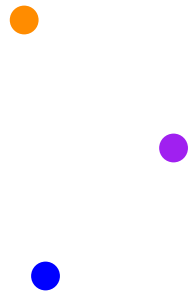
$S = S \setminus \{v\}$

While  $v \neq u$

# Convex hull

Teaser robustness lecture

Buggy degenerate example  
(single precision)



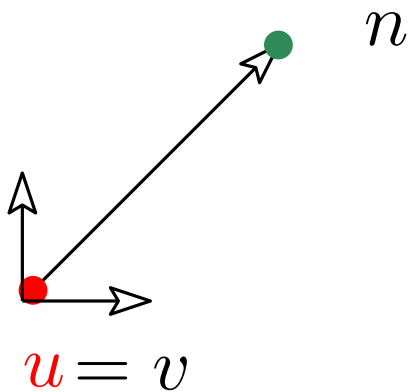
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$$w_2 = (24, 24)$$

$$w_3 = (30, 30.0000001)$$

$$w_4 = (23, 36)$$

$$w_5 = (0.50000029, 0.50000027)$$



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$n = \text{first in } S;$

For each  $w \in S$

if  $vwn$  positive

then  $n = w;$

$v.next = n; v = n;$

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While  $v \neq u$

# Convex hull

Teaser robustness lecture

Buggy degenerate example  
(single precision)

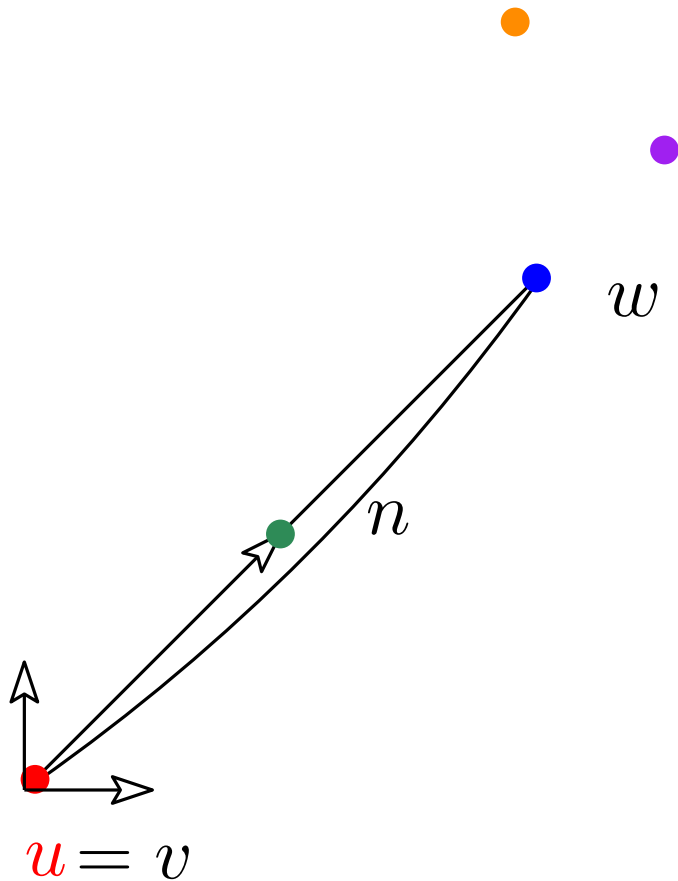
$$w_1 = (12, 12)$$

$$w_2 = (24, 24)$$

$$w_3 = (30, 30.0000001)$$

$$w_4 = (23, 36)$$

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Do

$n = \text{first in } S;$

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if  $vwn$  positive

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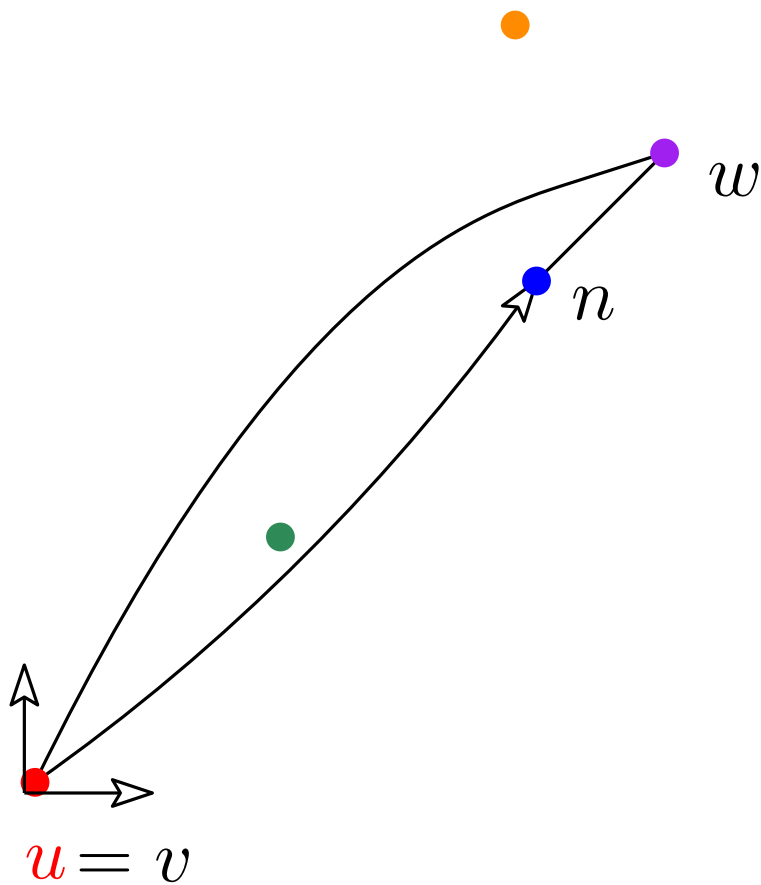
$S = S \setminus \{v\}$

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# Convex hull

Teaser robustness lecture

Buggy degenerate example  
(single precision)



$$w_1 = (12, 12)$$

$$w_2 = (24, 24)$$

$$w_3 = (30, 30.0000001)$$

$$w_4 = (23, 36)$$

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Do

$n = \text{first in } S;$

For each  $w \in S$

if  $vwn$  positive

then  $n = w;$

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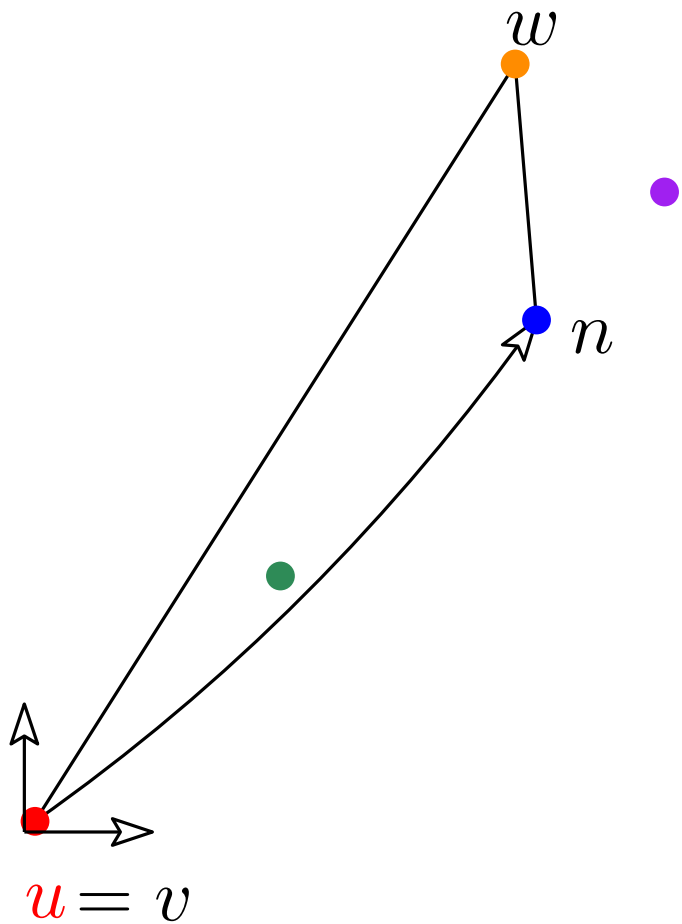
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While  $v \neq u$

# Convex hull

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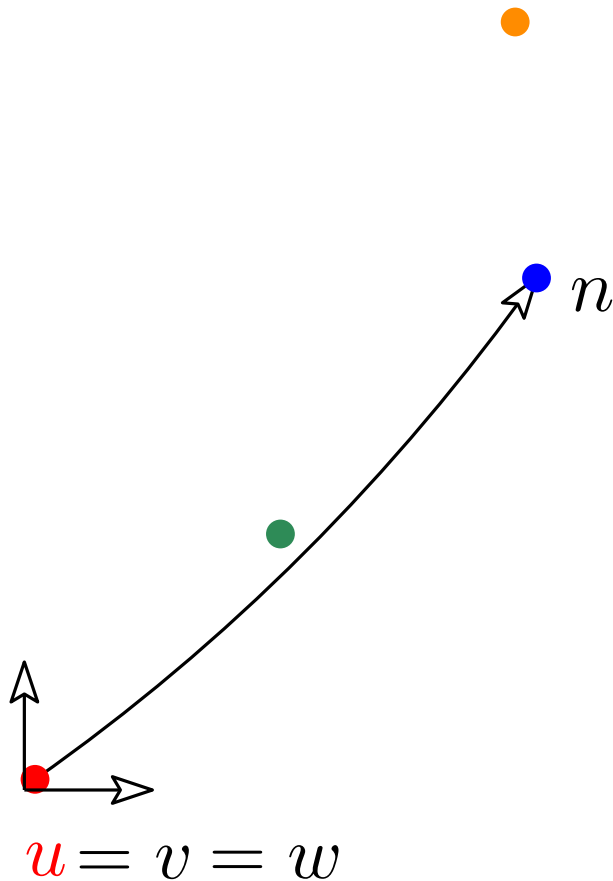
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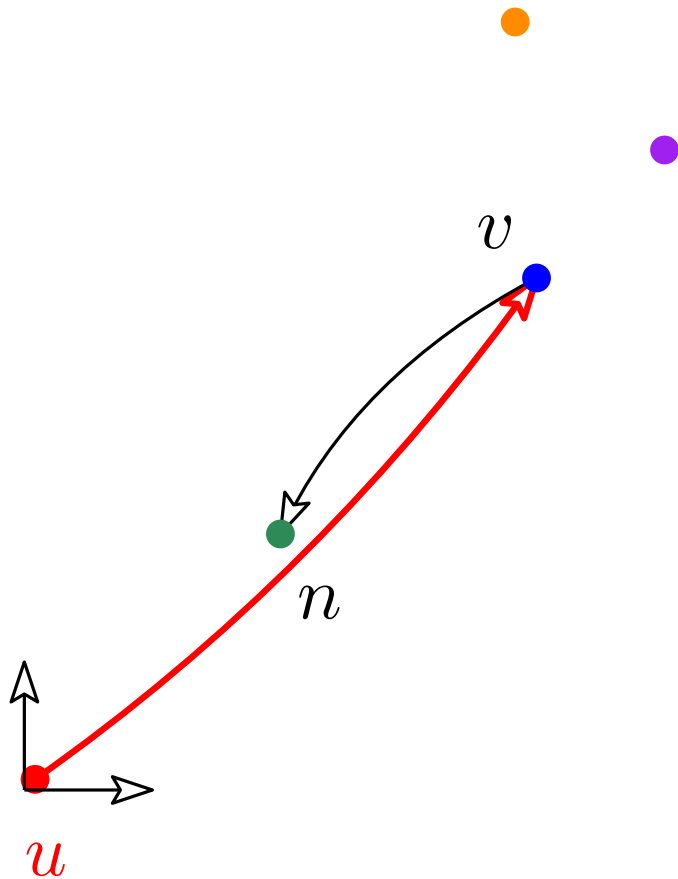
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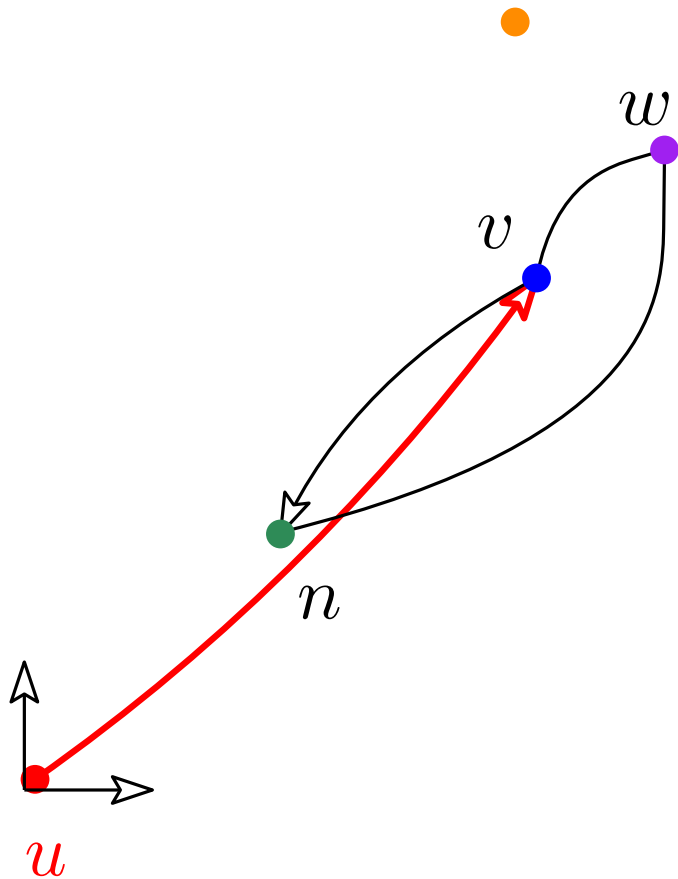
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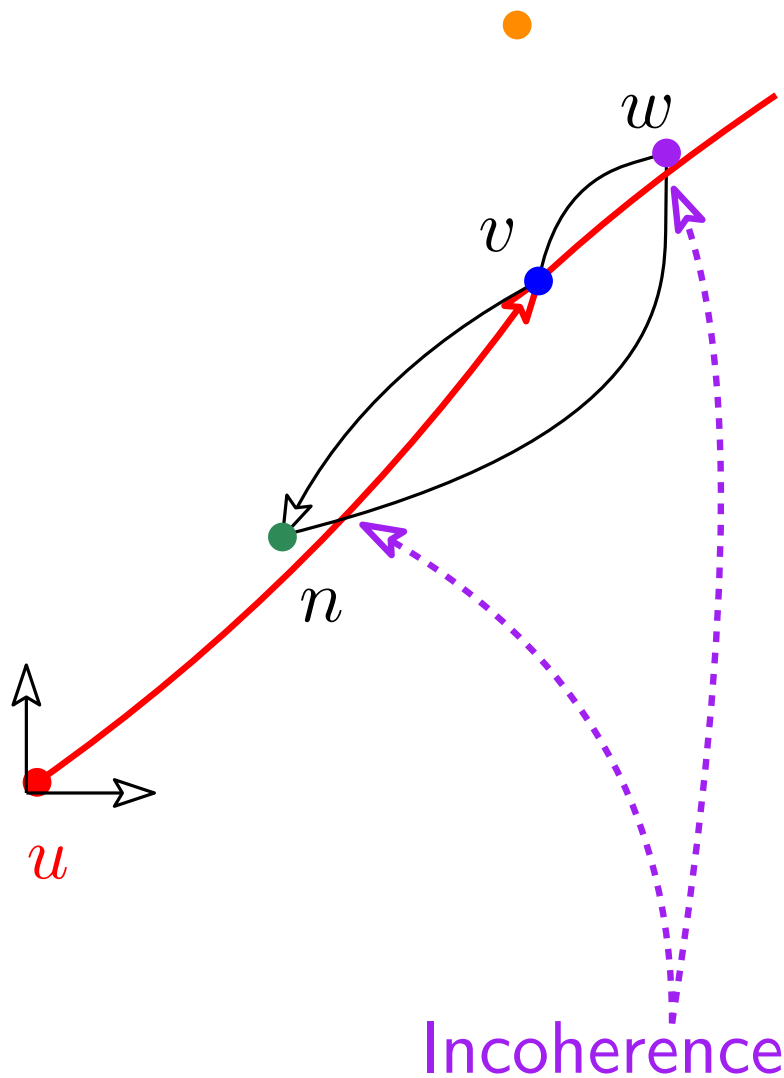
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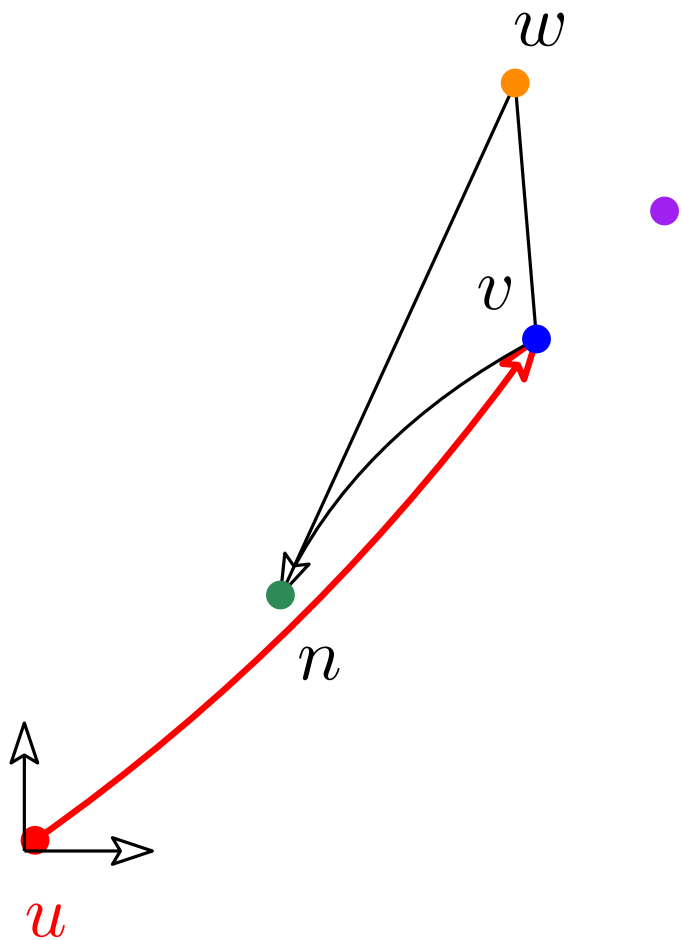
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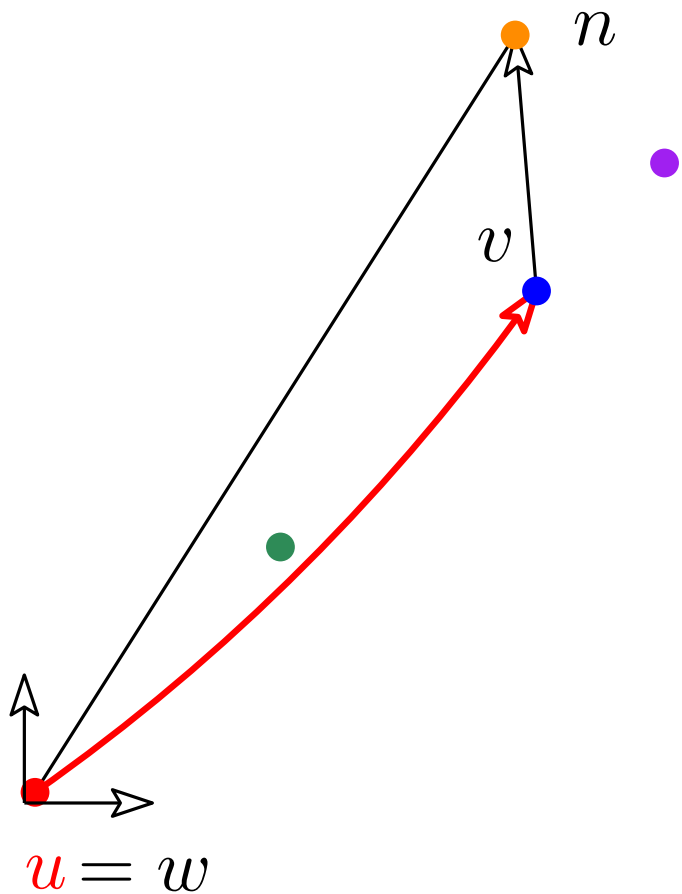
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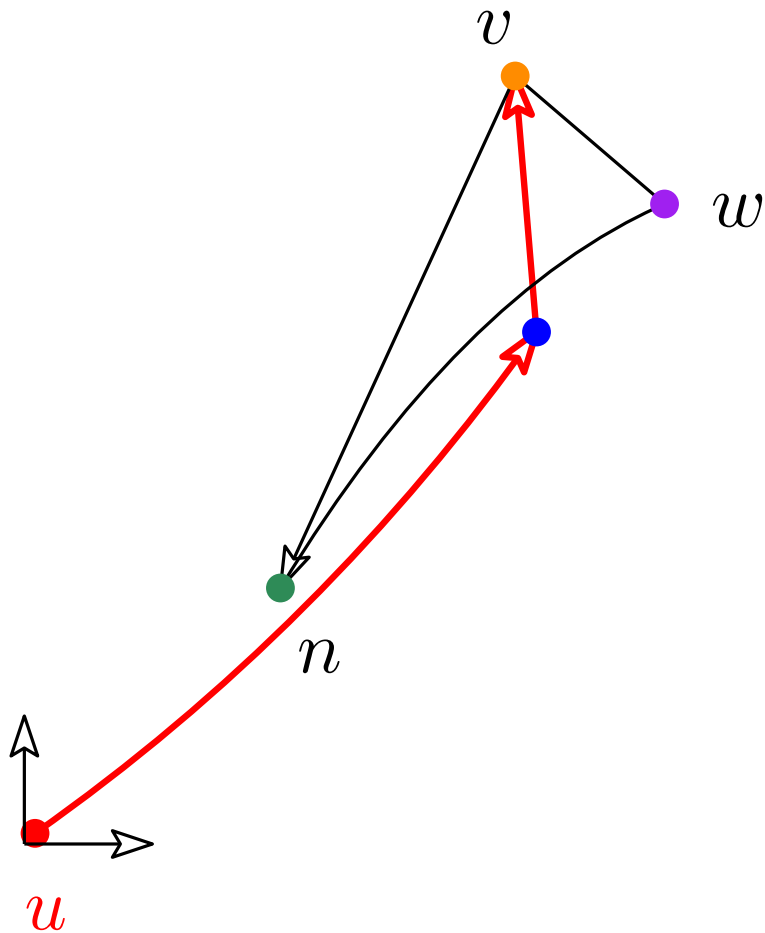
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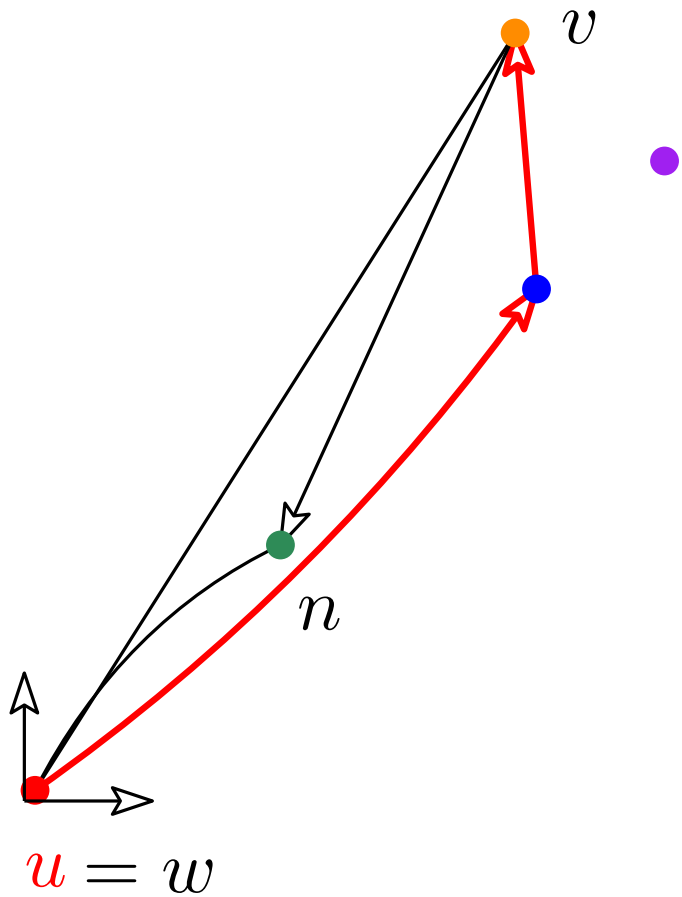
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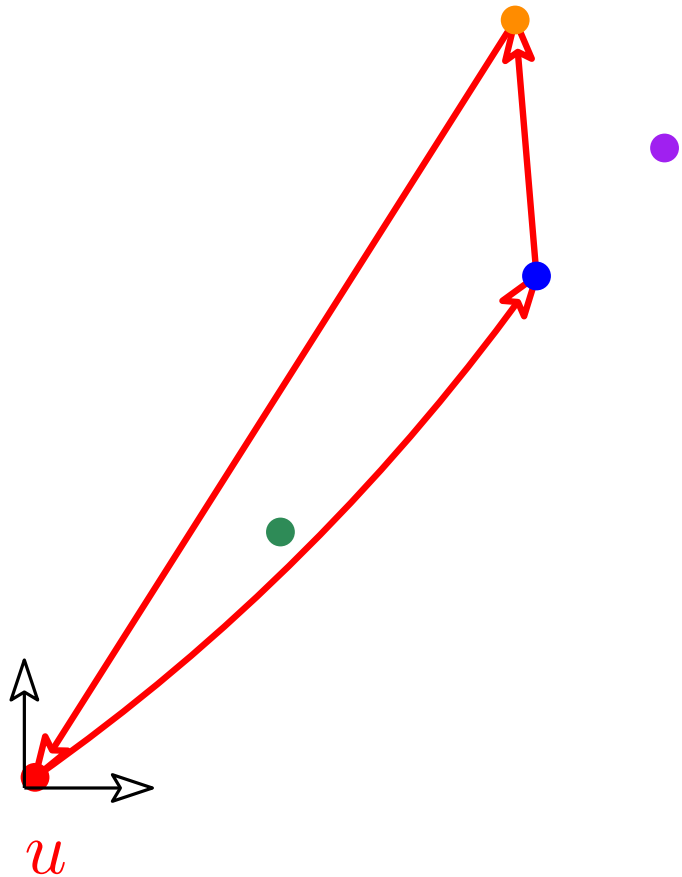
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Do

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For each  $w \in S$   
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```

While  $v \neq u$

# Convex hull

Teaser robustness lecture

Buggy degenerate example  
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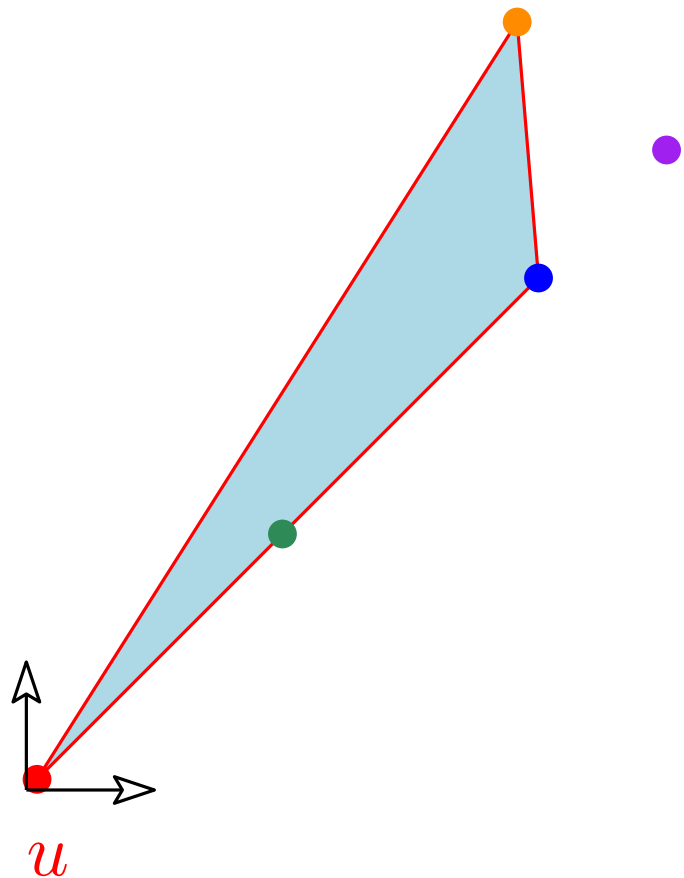
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Result is really wrong



# Convex hull

Real RAM model and  
general position hypothesis

Real Random Access Memory model

Assume exact computation on real numbers

constant time for single operations:  $+$ ,  $-$ ,  $\sqrt{\phantom{x}}$ ,  $\sin \dots$

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General position hypotheses

Predicate:  $\text{Input} \mapsto \{-1, 0, 1\}$

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2D convex hull: no three points colinear

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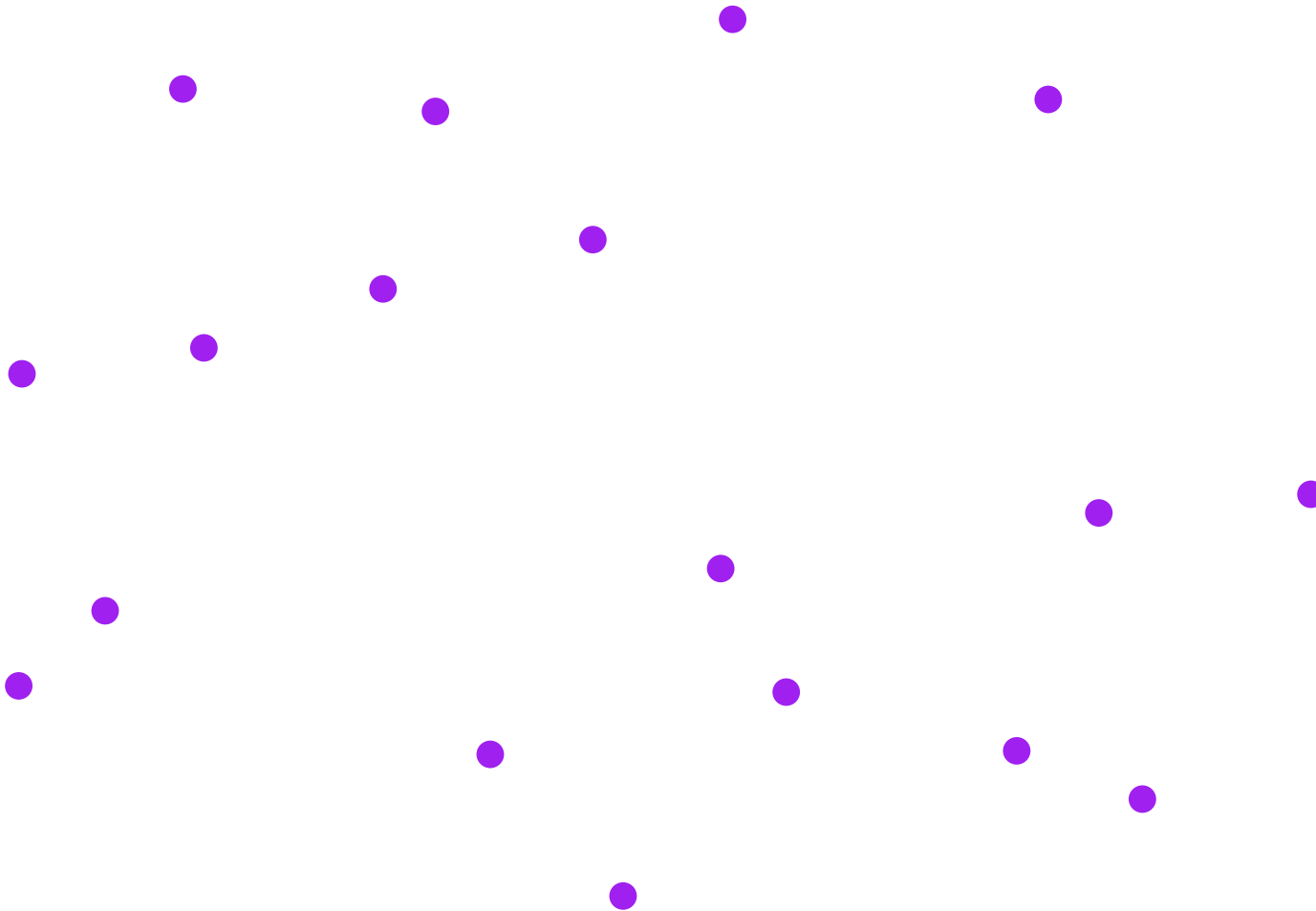
Predicate: Input  $\mapsto \{-1, 0, 1\}$

2D convex hull: no three points colinear

possibly: no 2 points with same  $x$

# Convex hull

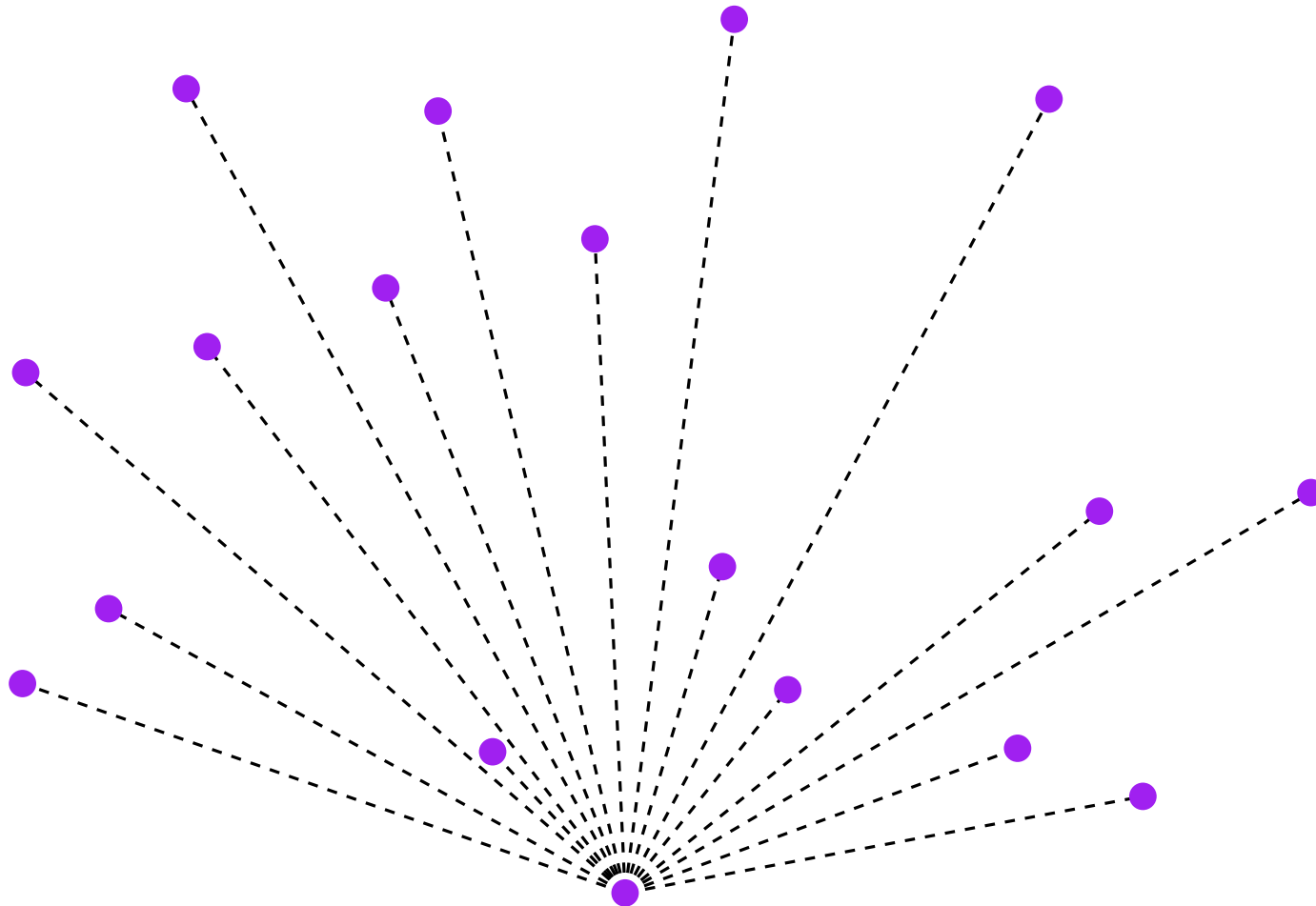
Graham algorithm



# Convex hull

Graham algorithm

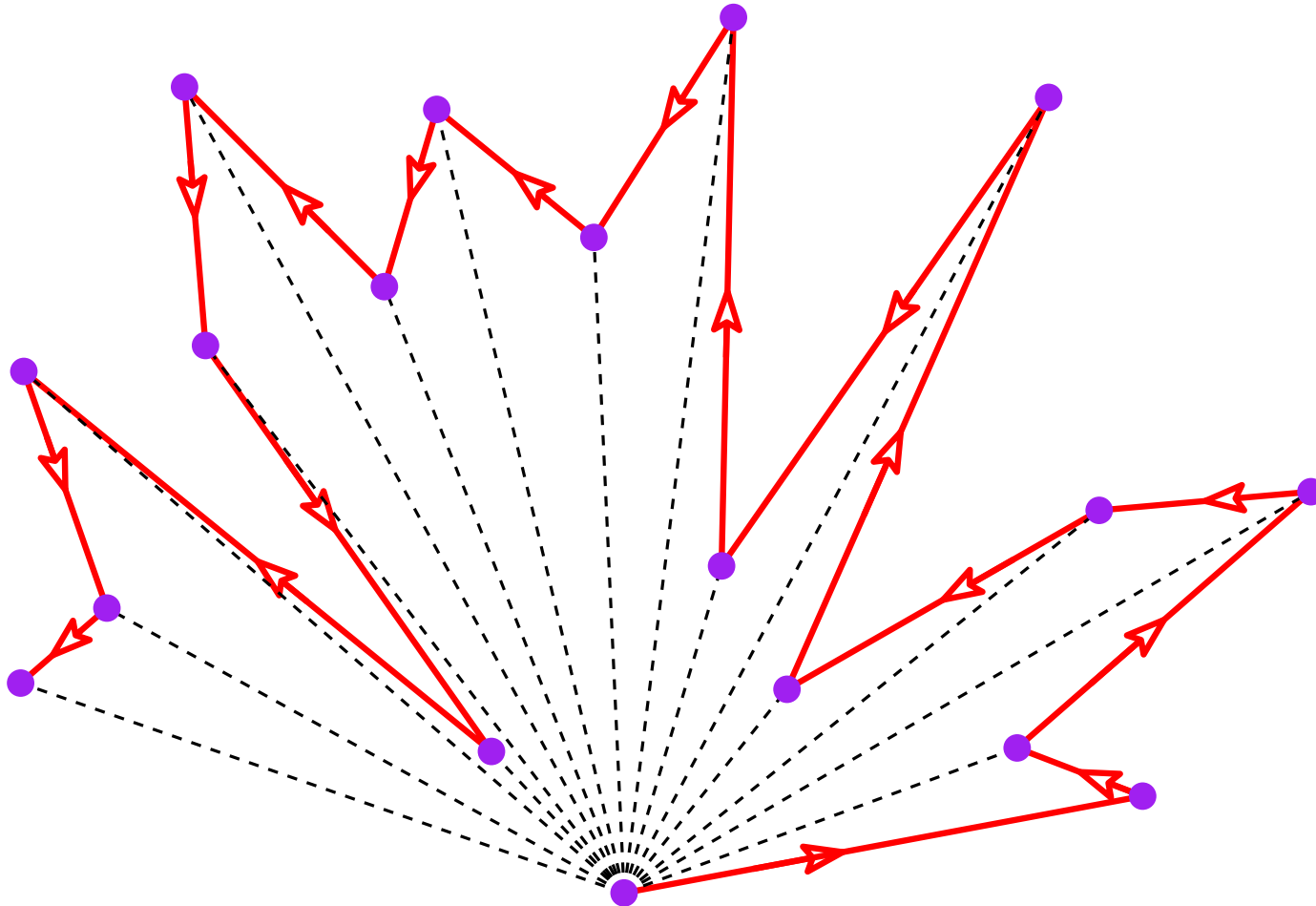
sort around a point (e.g. lowest point)



# Convex hull

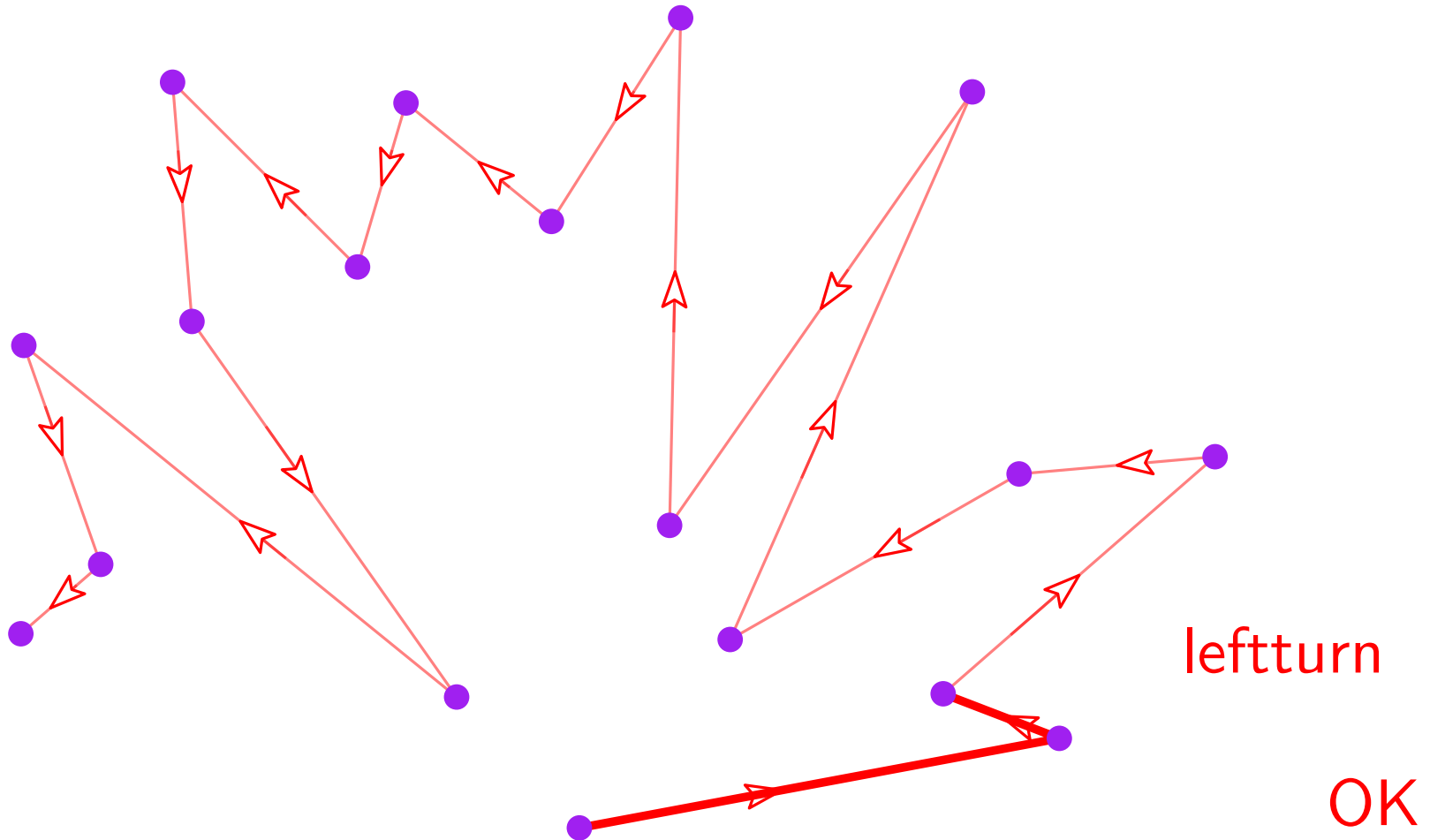
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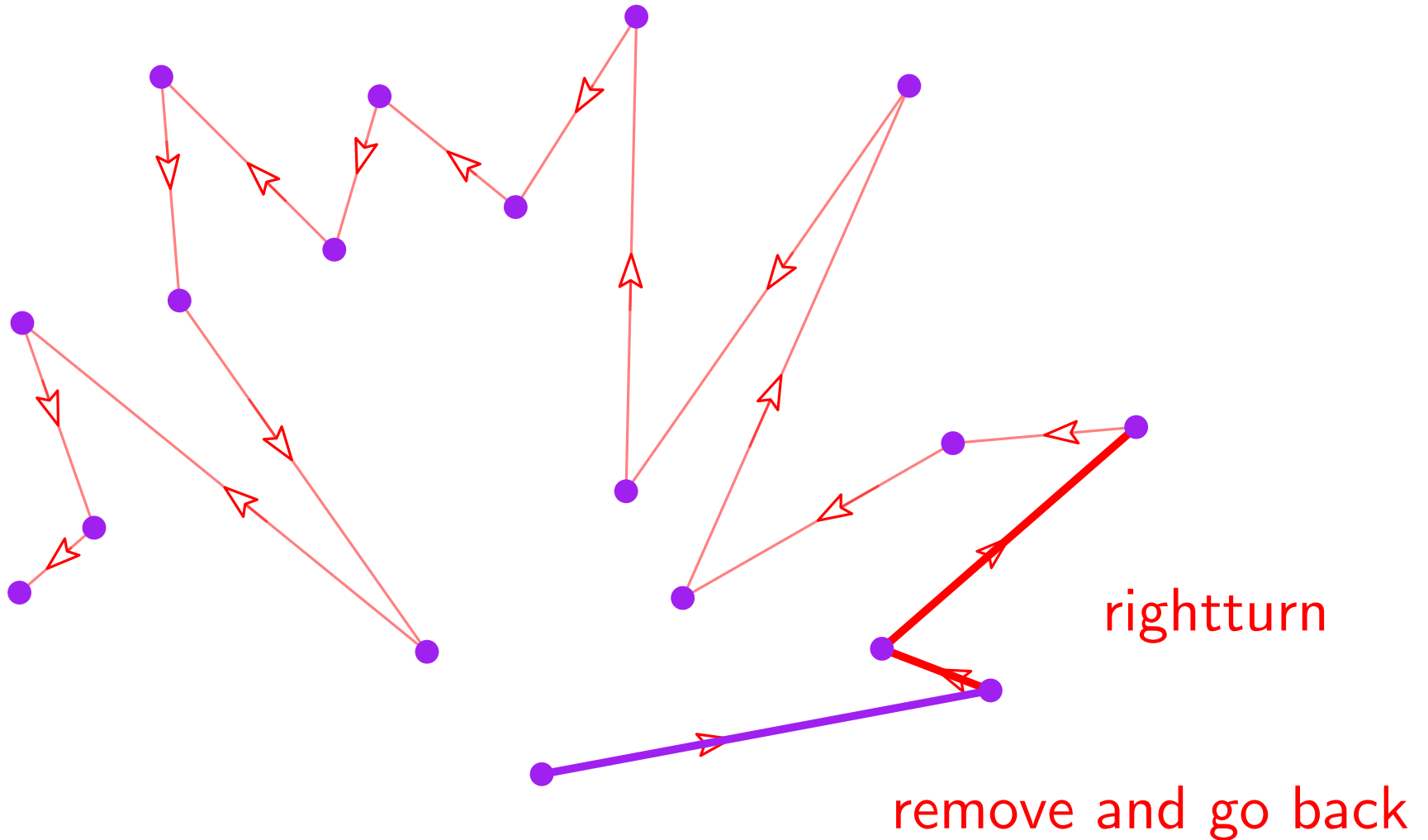
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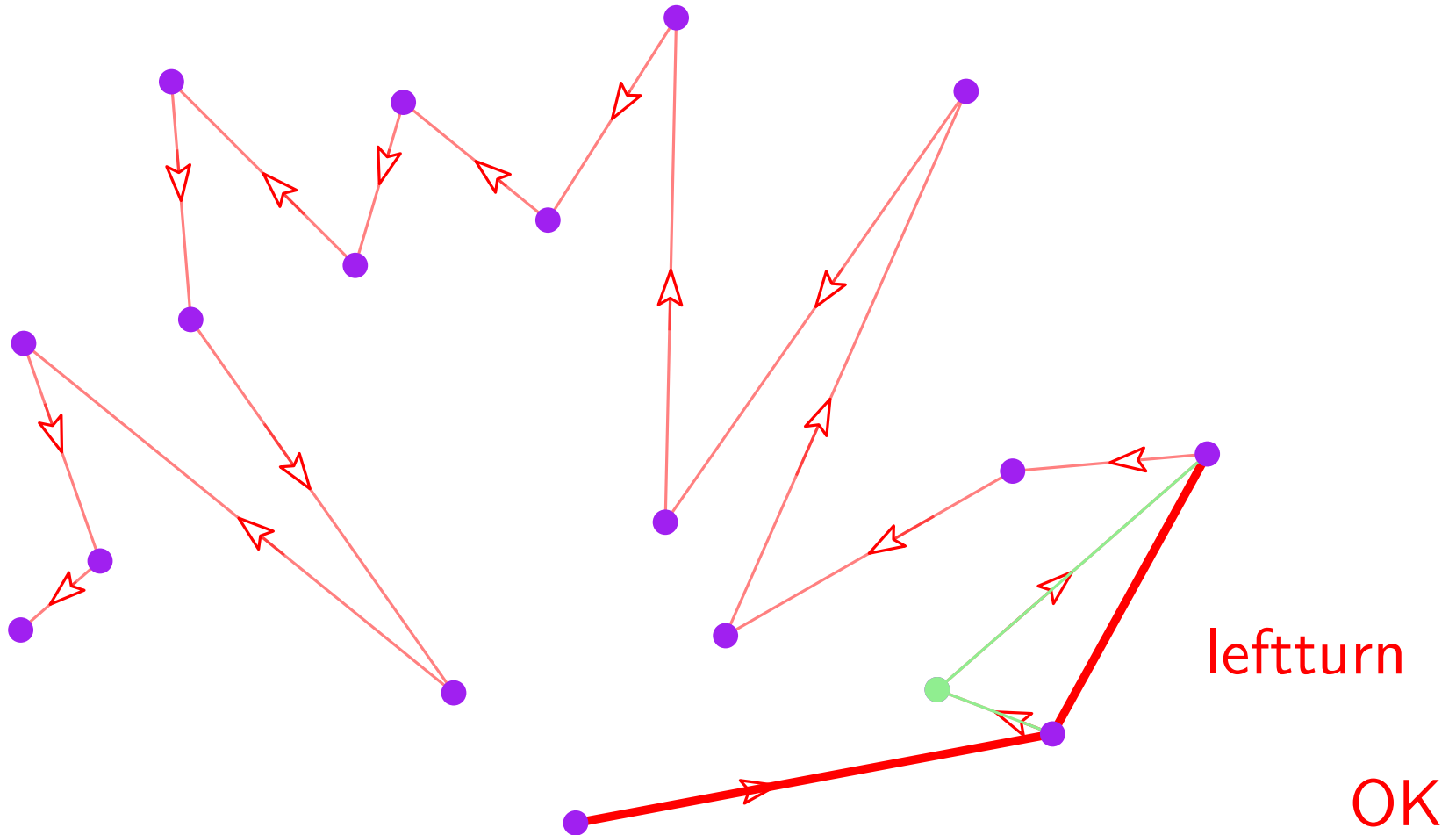
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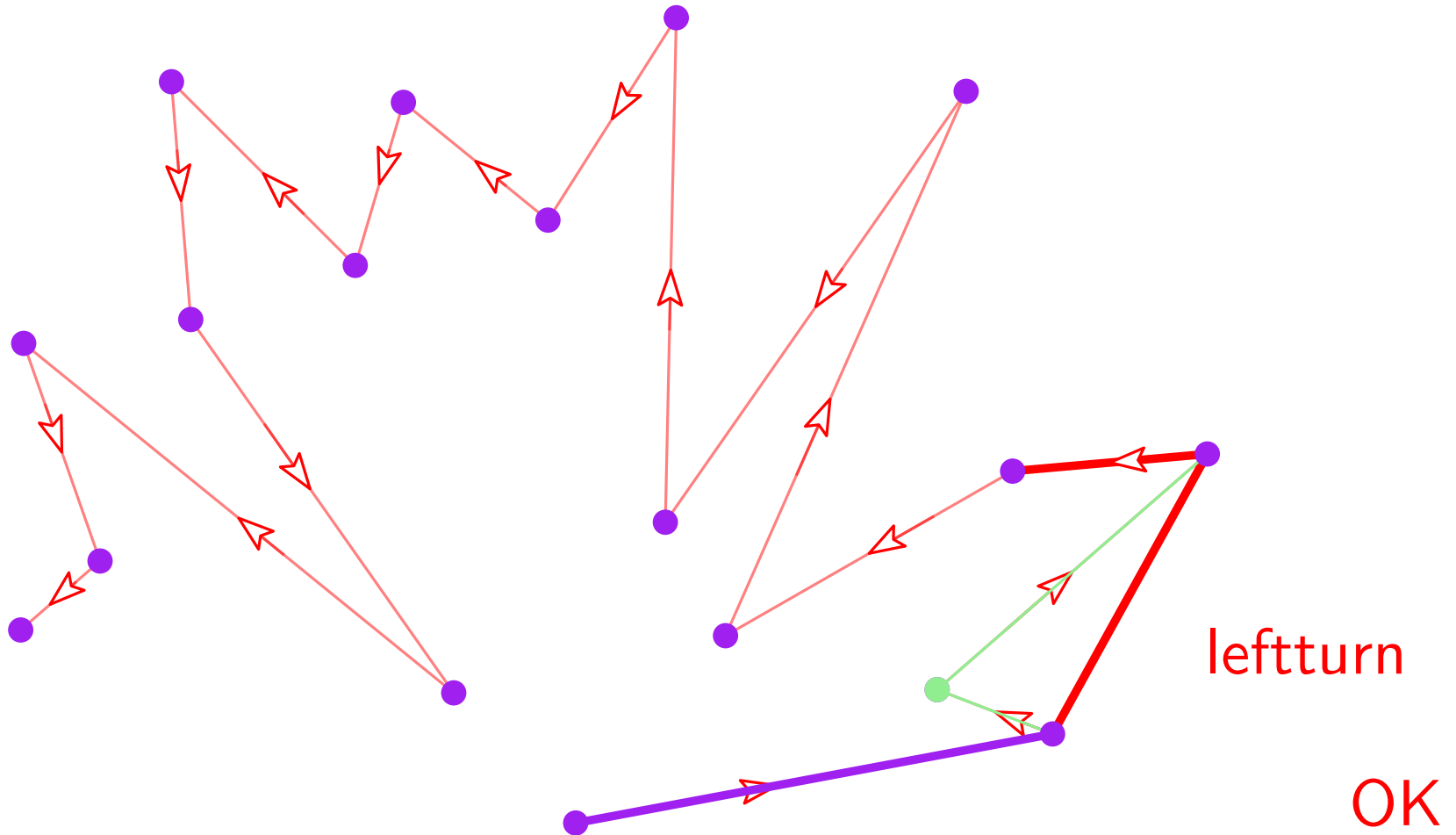
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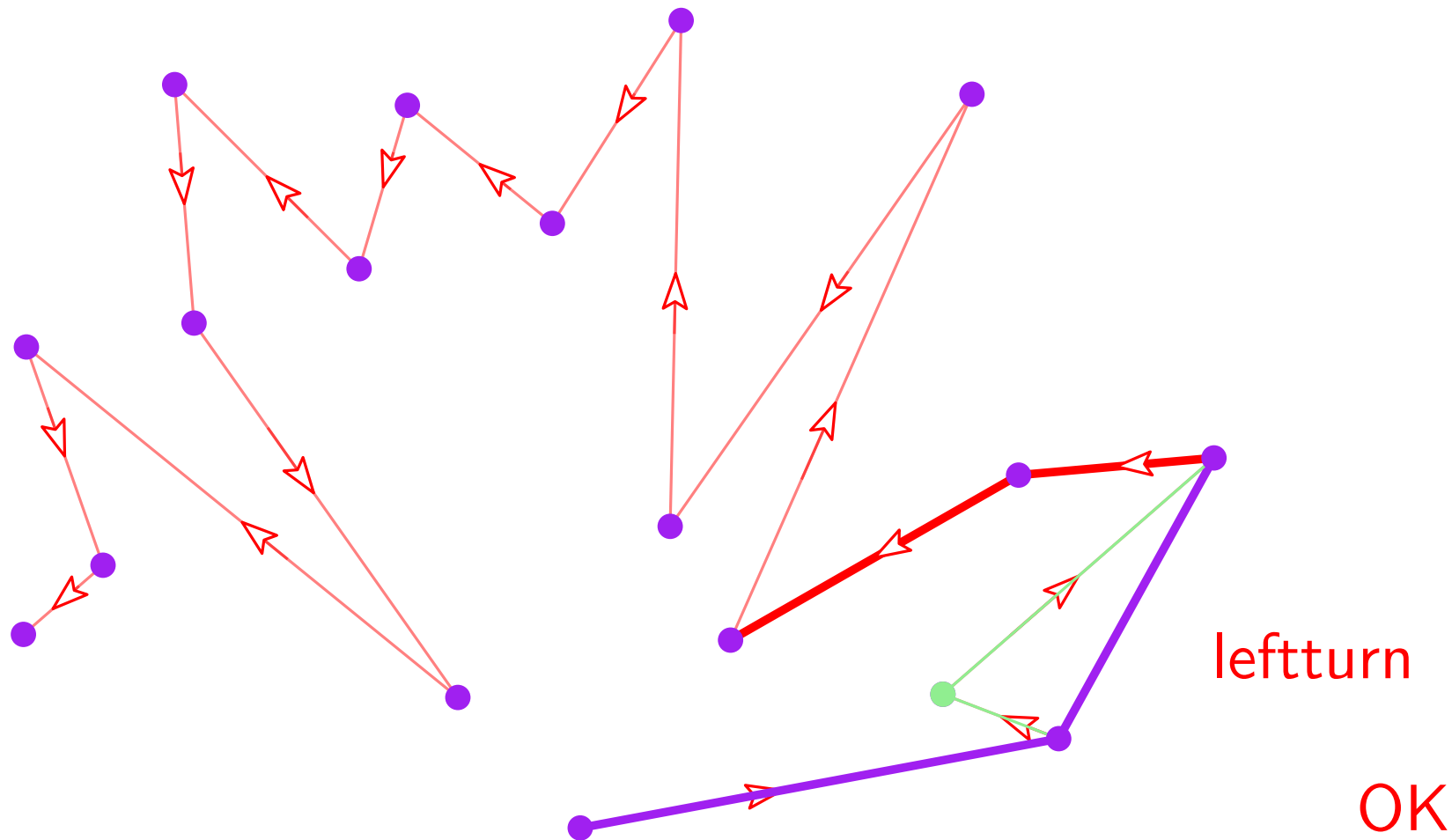
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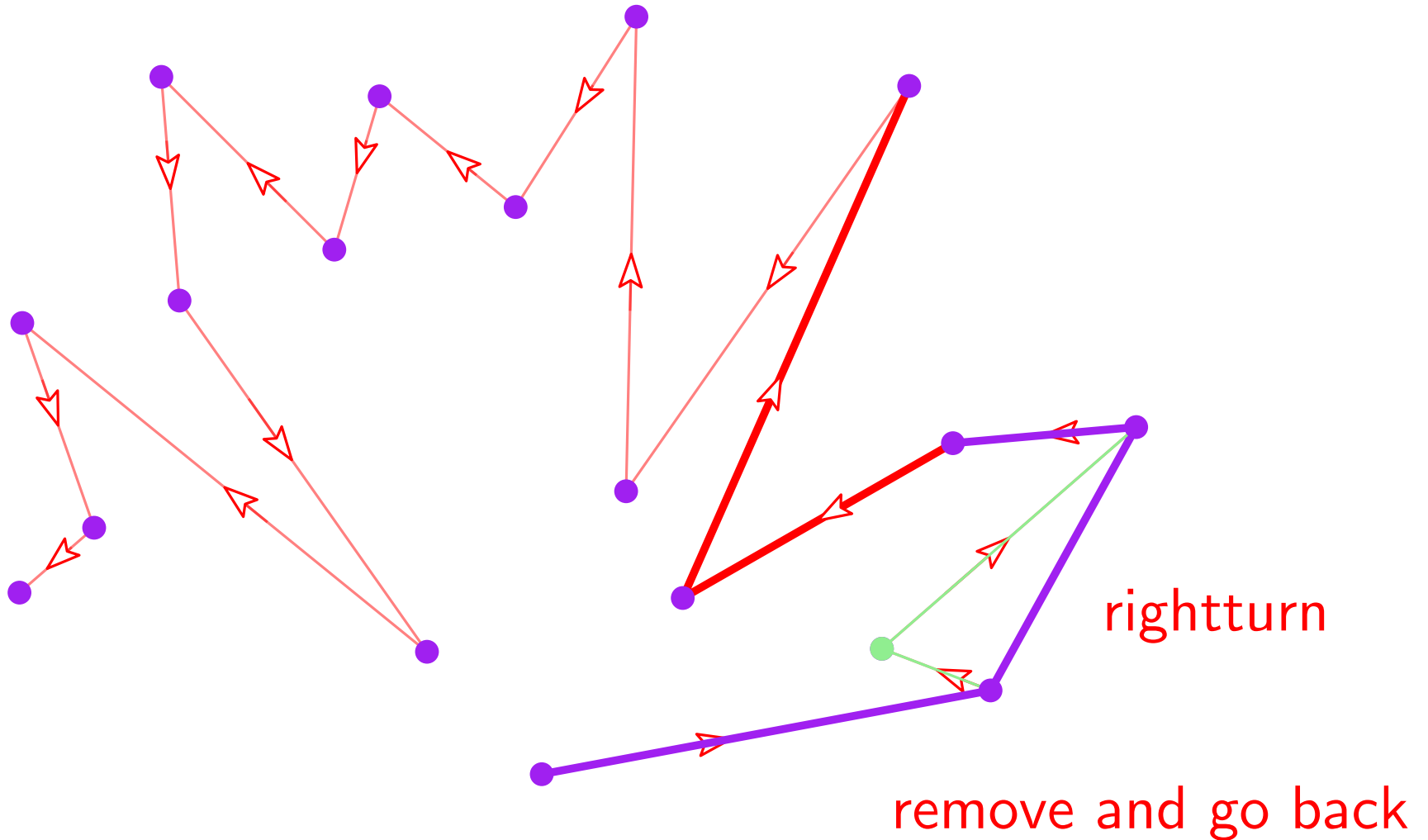
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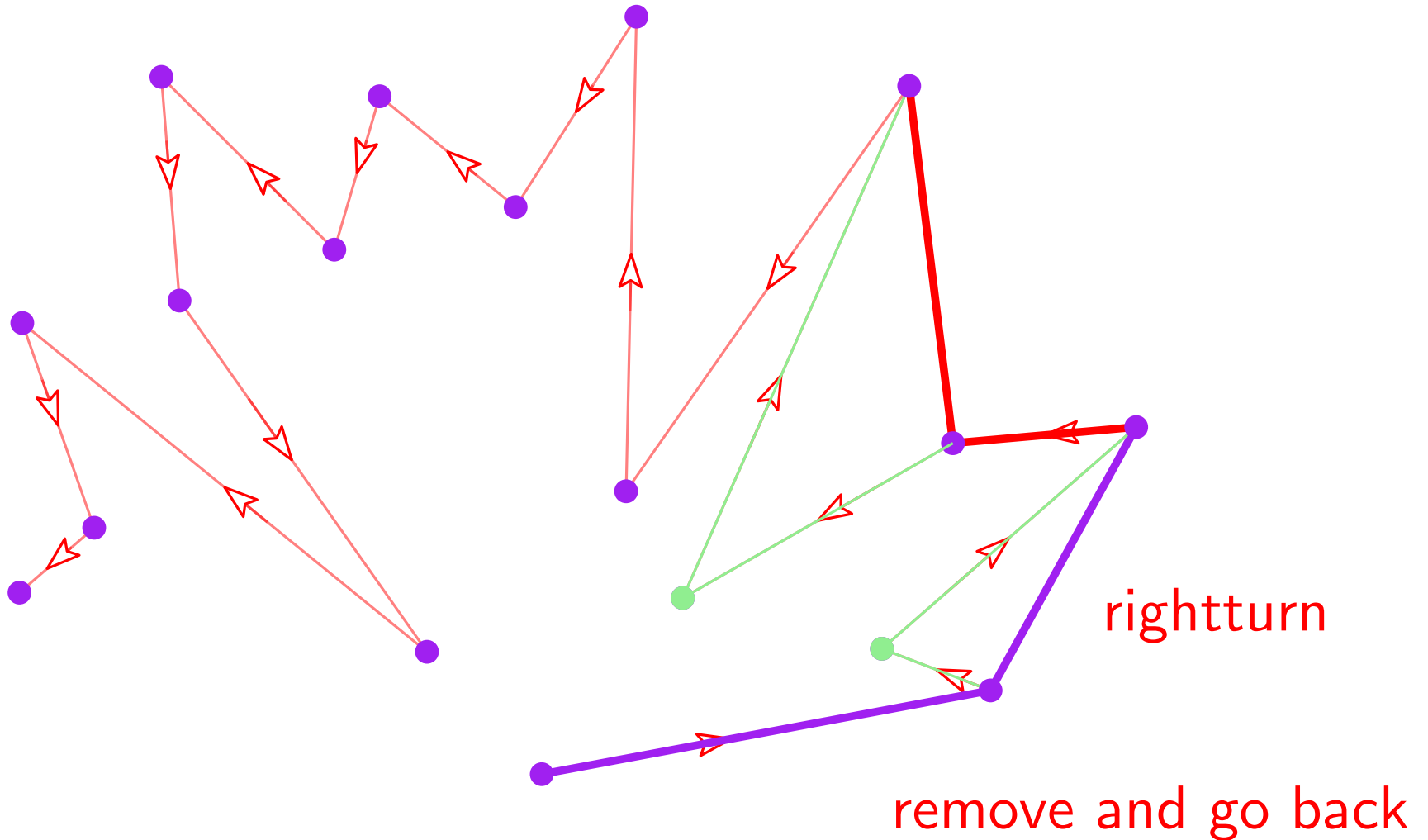
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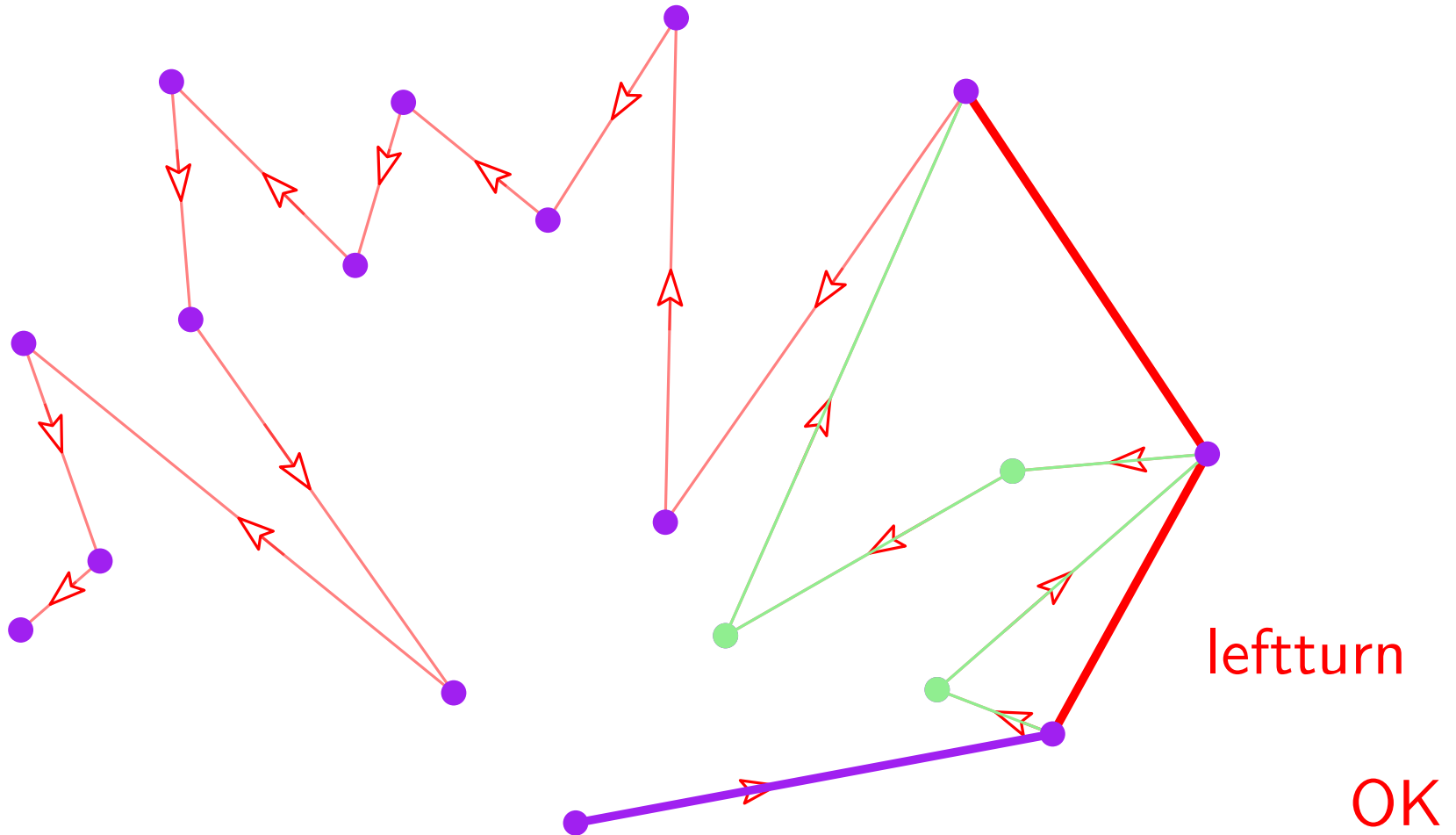
Graham algorithm



10 - 10

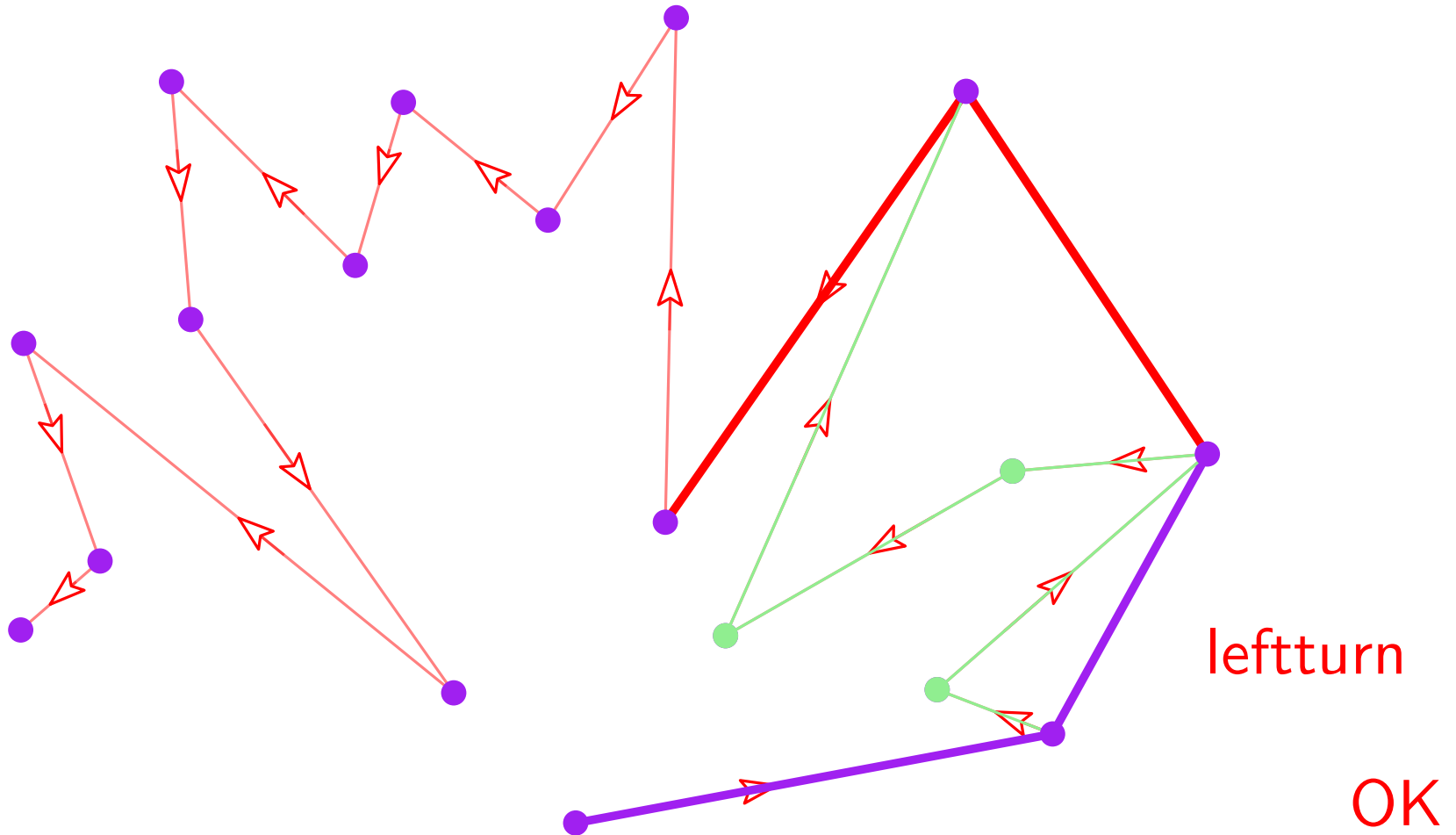
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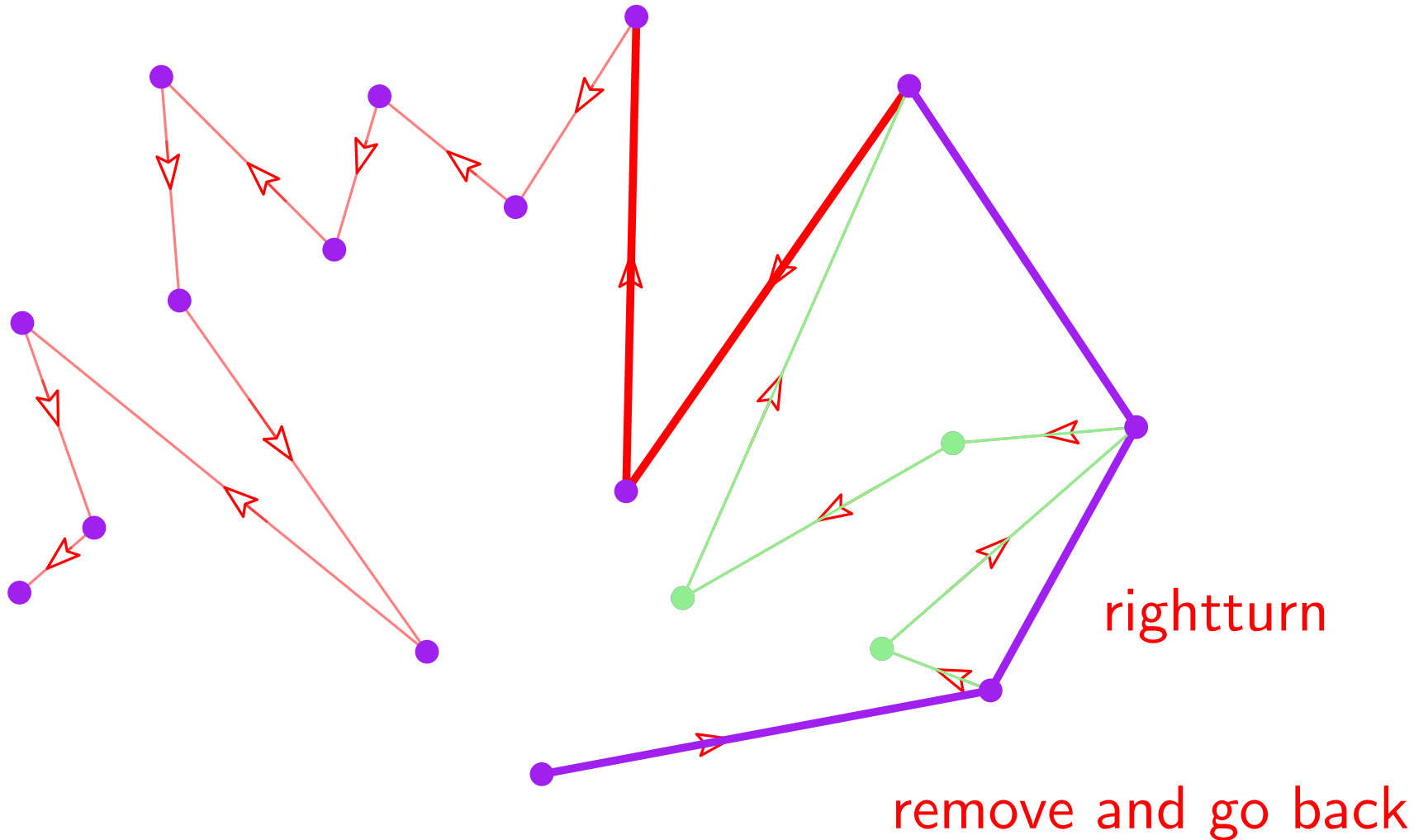
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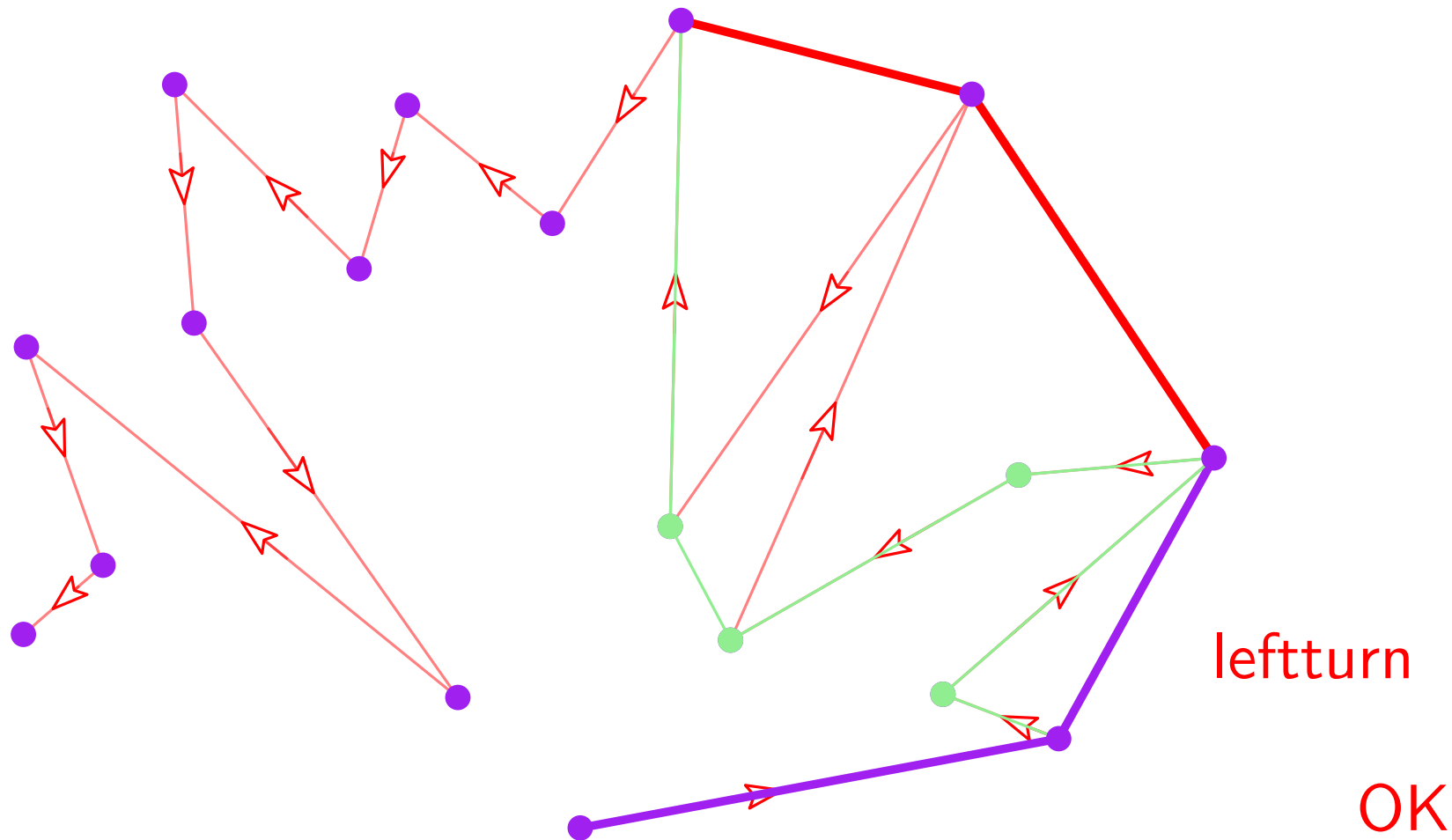
Graham algorithm



10 - 13

# Convex hull

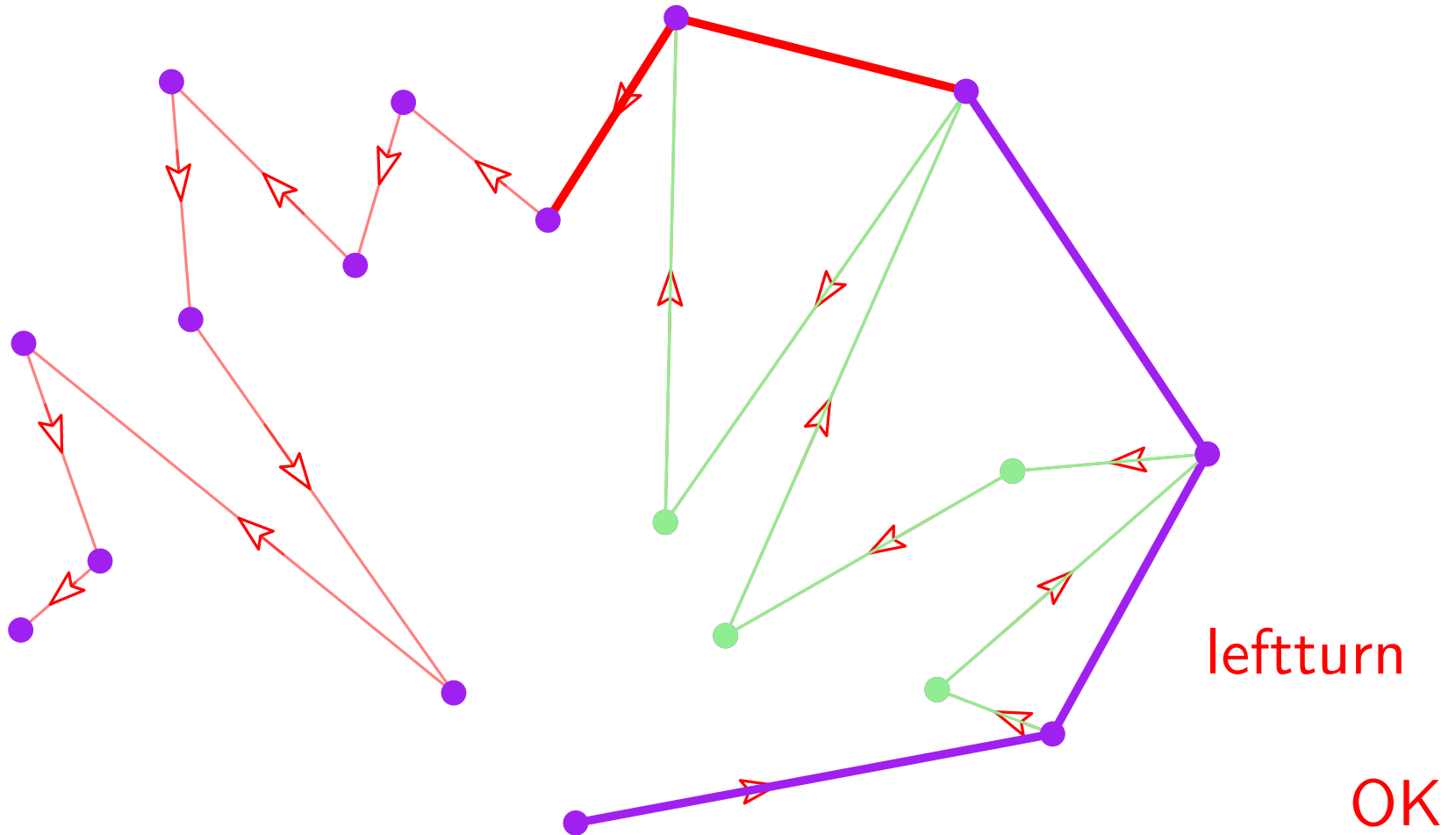
Graham algorithm



10 - 14

# Convex hull

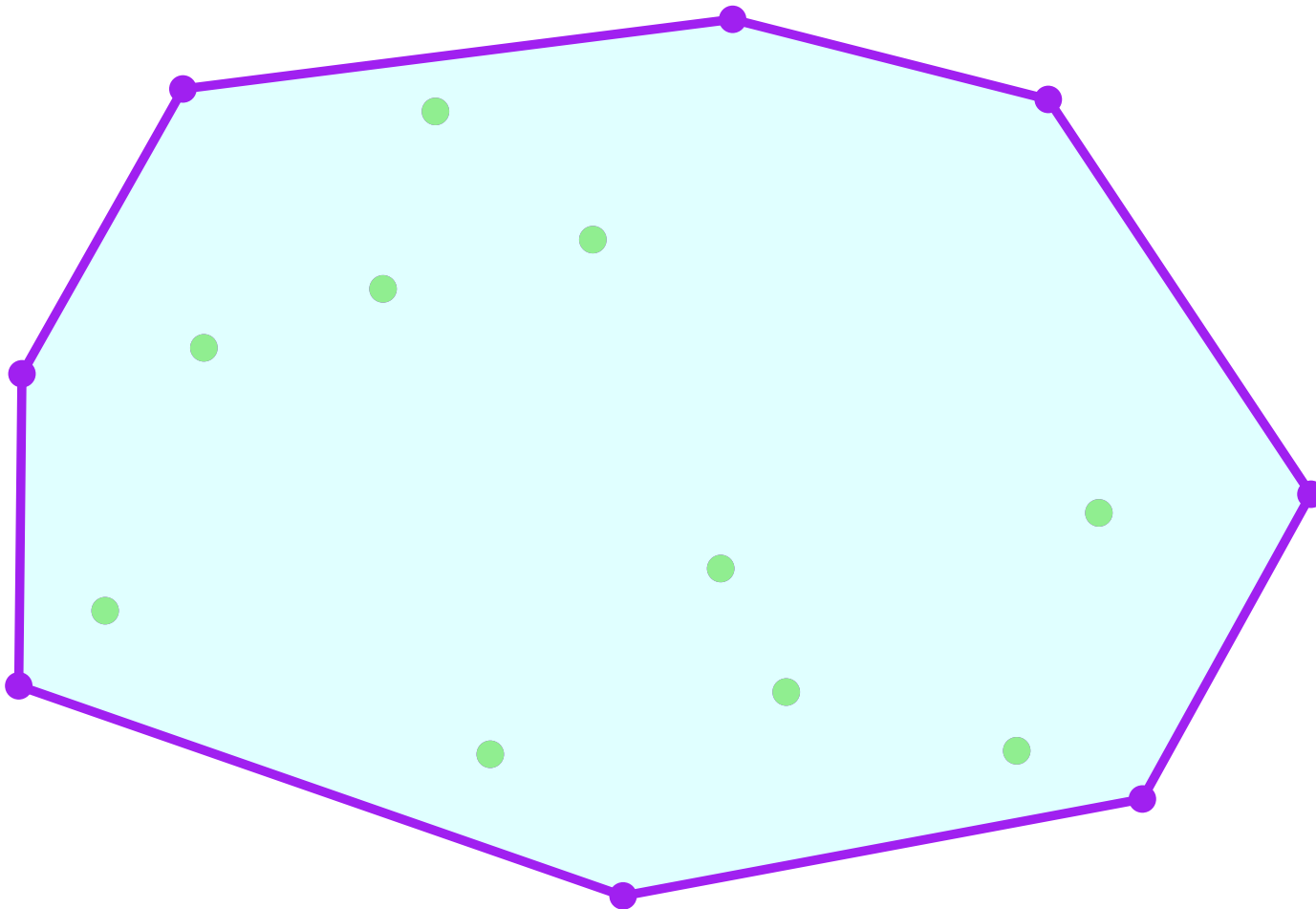
Graham algorithm



10 - 15

# Convex hull

Graham algorithm



# Convex hull

Complexity

Graham algorithm

Input: point set  $S$

$u$  lowest point of  $S$ ;

sort  $S$  around  $u$  in a circular list including  $u$ ;

$v = u$ ;

while  $v.next \neq u$

    if  $(v, v.next, v.next.next)$  ccw

$v = v.next$ ;

    else

$v.next = v.next.next$ ;  $v.next.previous = v$ ;

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$O(n)$

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$O(n \log n)$

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delete one point  
at most  $n$  times

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$O(n \log n)$

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# Convex hull

Lower bound

Problem lower bound is  $\Omega(f(n))$

Iff there is **NO** algorithm

solving all size  $n$  problems

using less than  $Cf(n)$  operations

$\forall n$

$C$  constant independent of  $n$

# Sorting

Lower bound

Input:  $n$  real (positive) numbers

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Output: sorting permutation

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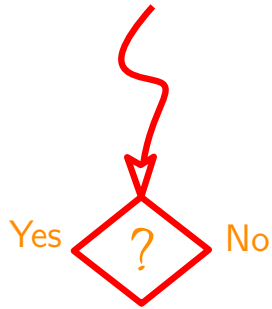
Monitoring execution



# Sorting

Lower bound

Input:  $n$  real (positive) numbers



Output: sorting permutation

Monitoring execution

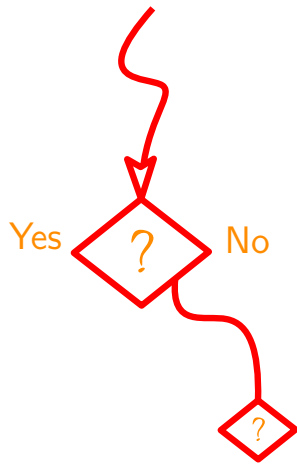
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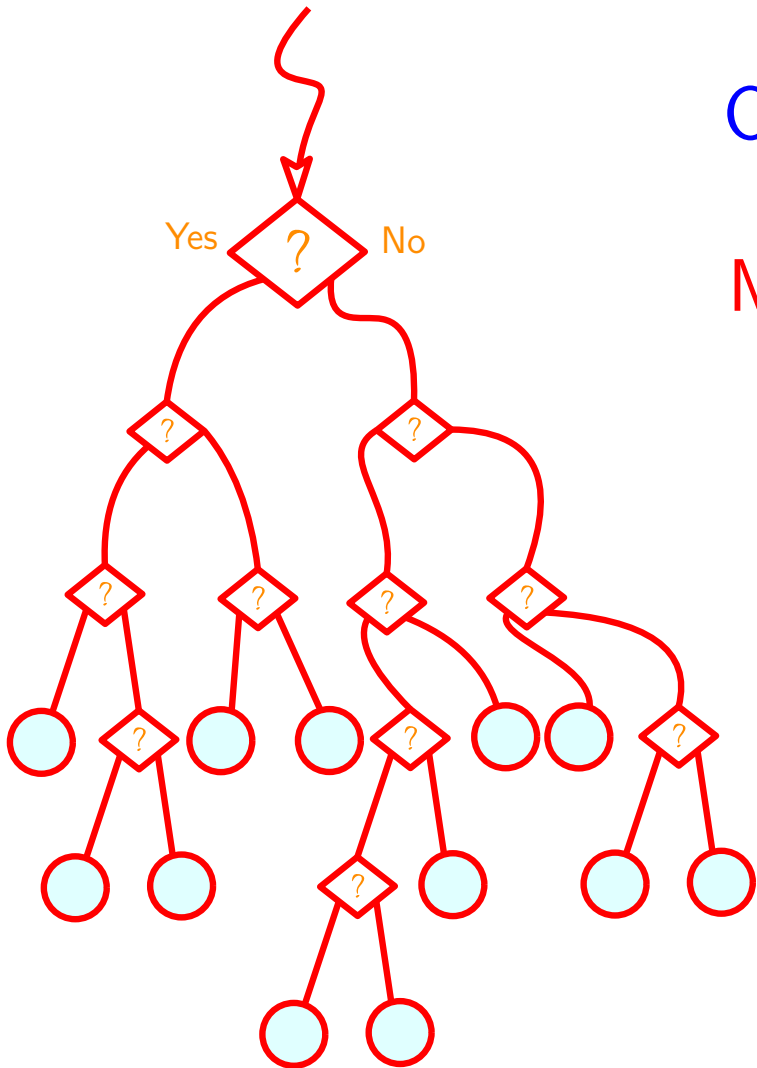
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Lower bound

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Monitoring execution



13 - 6

# Sorting

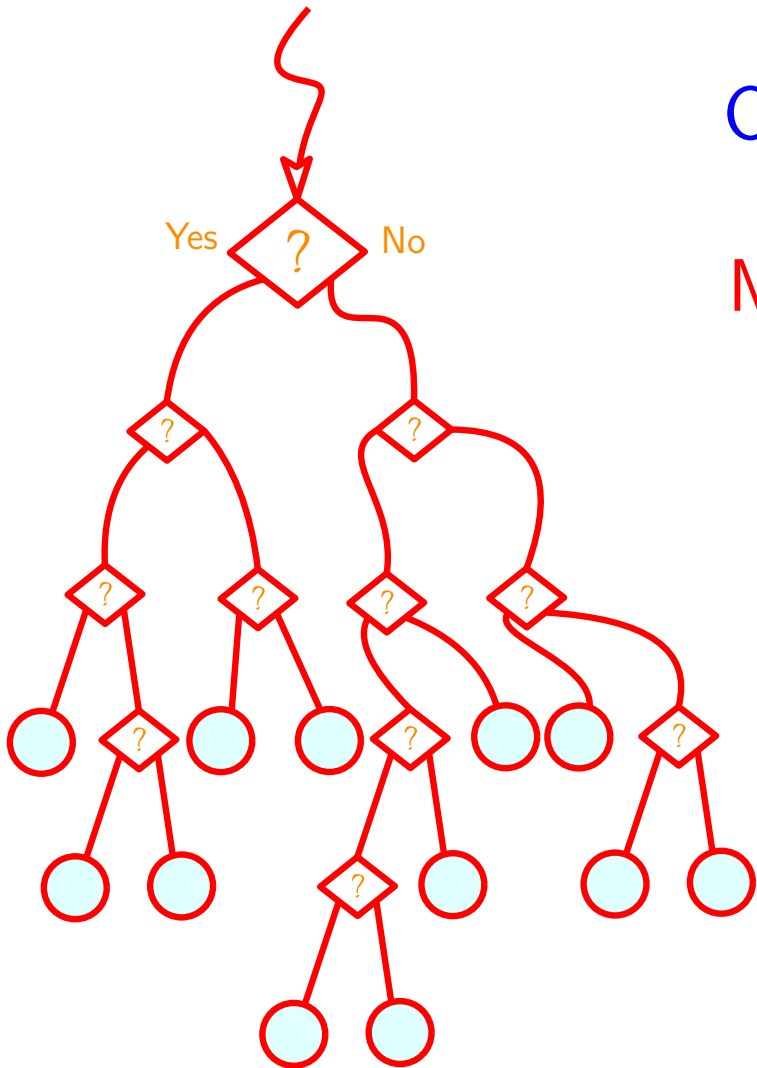
Lower bound

Input:  $n$  real (positive) numbers

Output: sorting permutation

Monitoring execution

# leaves  $\geq$  # permutations



# Sorting

Lower bound

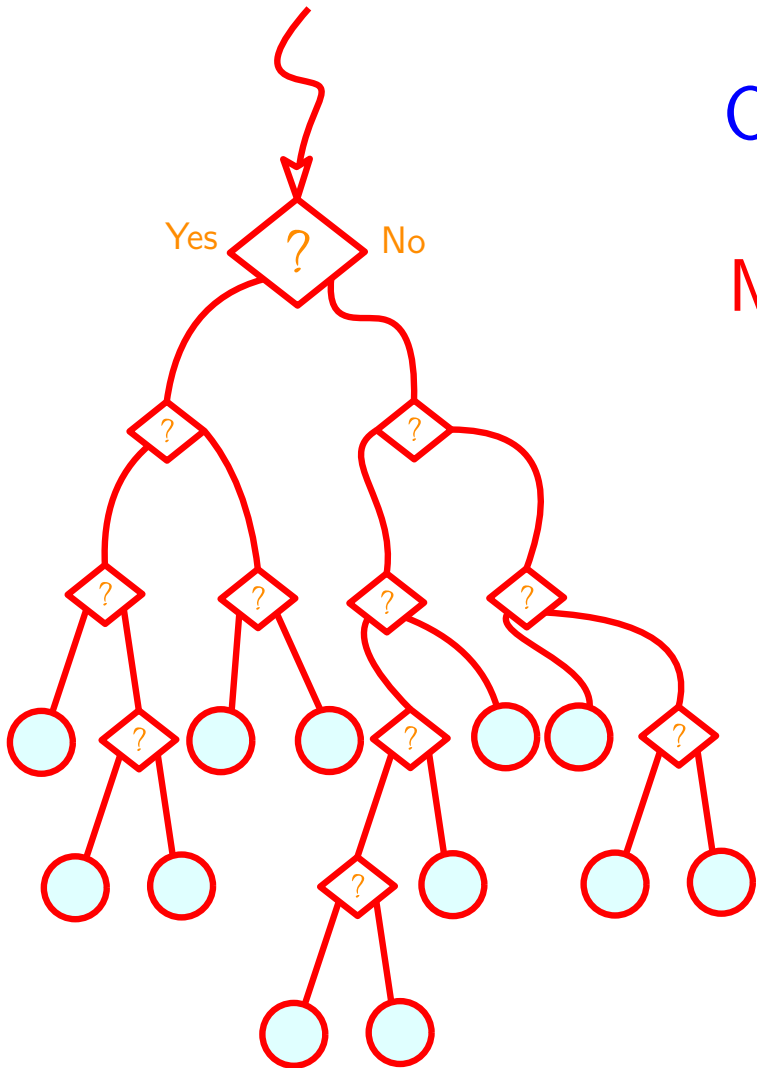
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Monitoring execution

# leaves  $\geq$  # permutations

There are  $n!$  permutations



# Sorting

Lower bound

Input:  $n$  real (positive) numbers

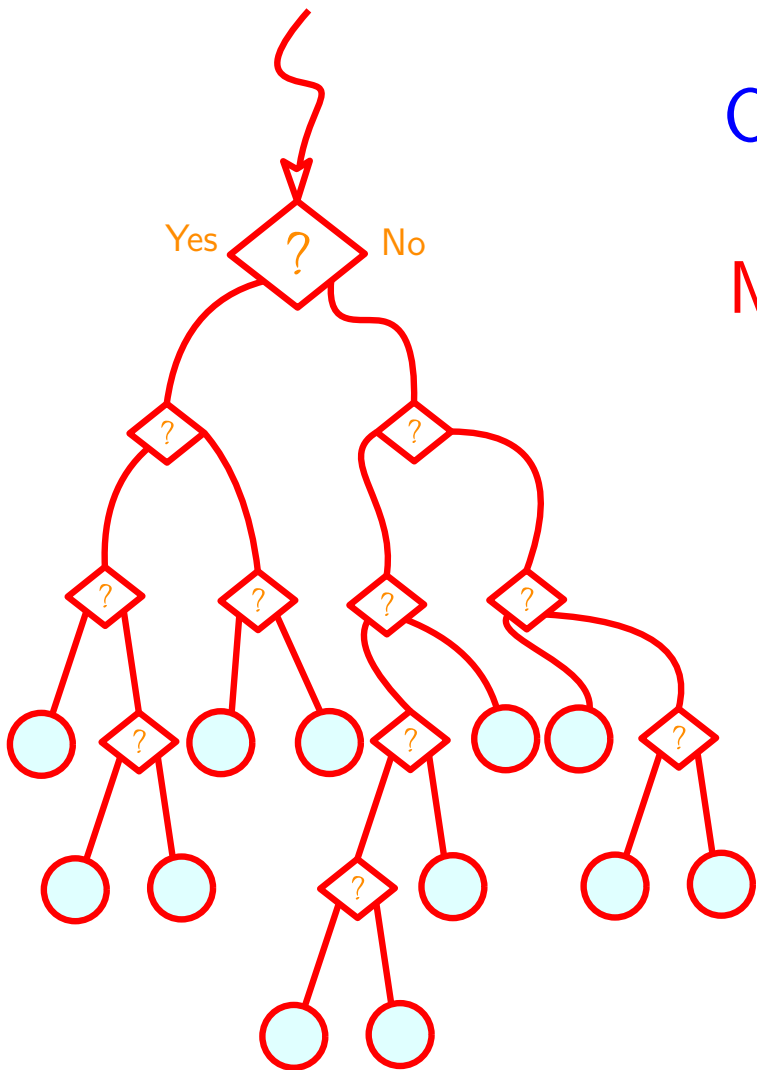
Output: sorting permutation

Monitoring execution

# leaves  $\geq$  # permutations

There are  $n!$  permutations

Tree height is at least  $\log_2$  # leaves



# Sorting

Lower bound

Input:  $n$  real (positive) numbers

Output: sorting permutation

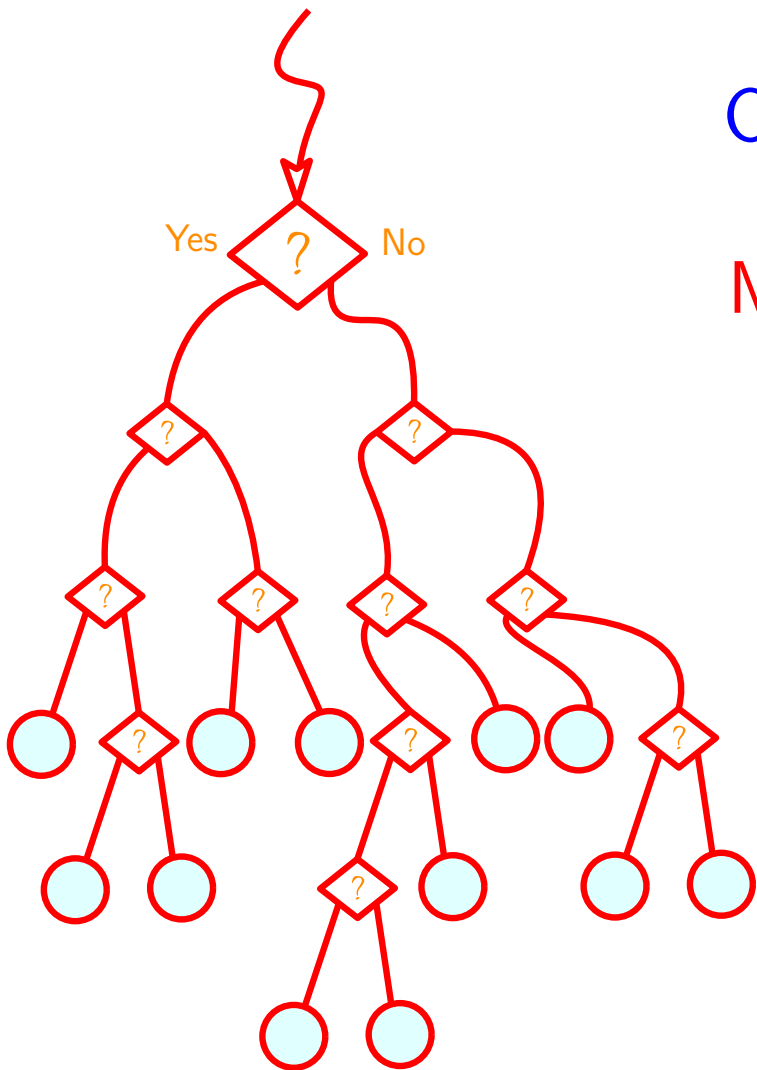
Monitoring execution

# leaves  $\geq$  # permutations

There are  $n!$  permutations

Tree height is at least  $\log_2$  # leaves

# comparisons  $\leq \log_2 n! \simeq n \log_2 n$



# Convex hull

Lower bound

Input:  $n$  2D points (real coordinates)

Output: list of points along the convex hull



# Convex hull

Lower bound

A stupid algorithm for sorting numbers

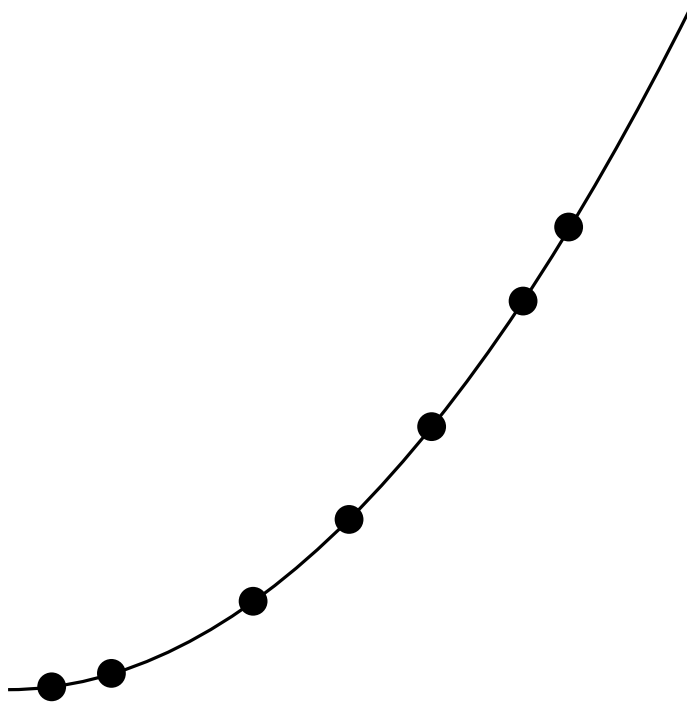


14 - 2

# Convex hull

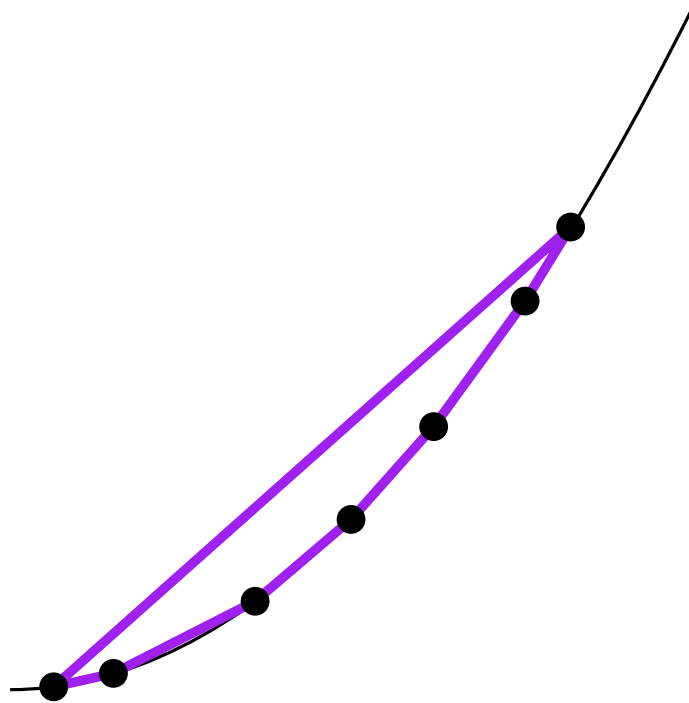
Lower bound

project on parabola



# Convex hull

Lower bound

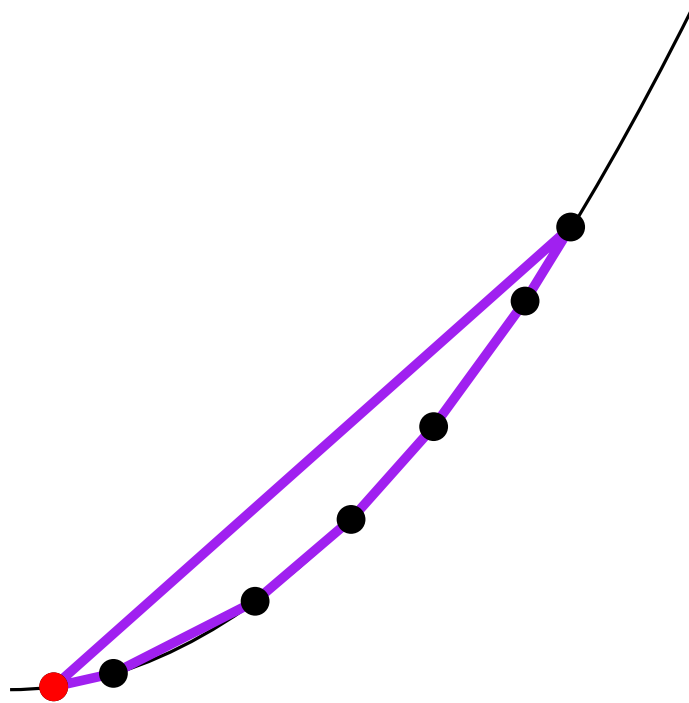


project on parabola

compute convex hull

# Convex hull

Lower bound



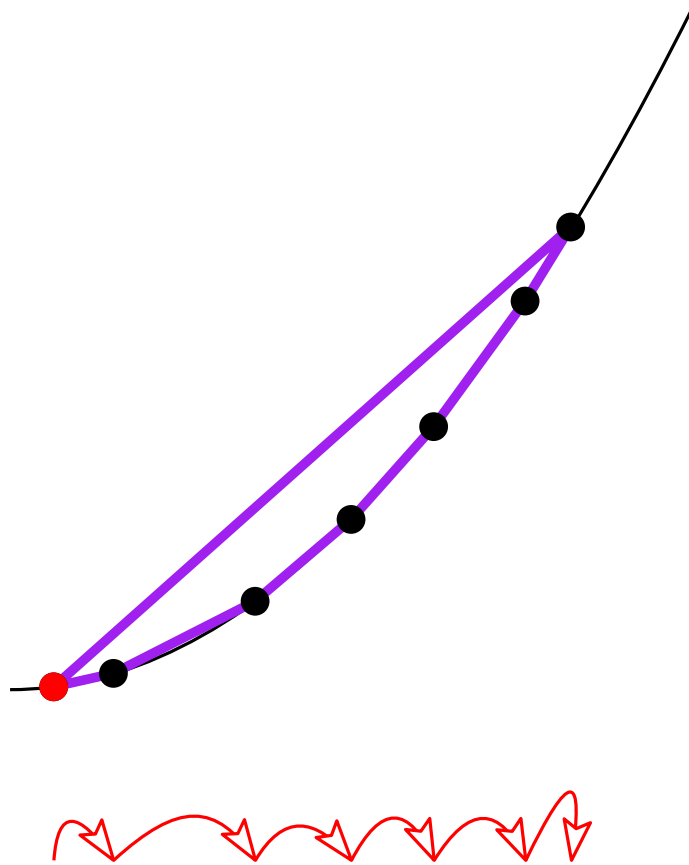
project on parabola

compute convex hull

find lowest point

# Convex hull

Lower bound



project on parabola

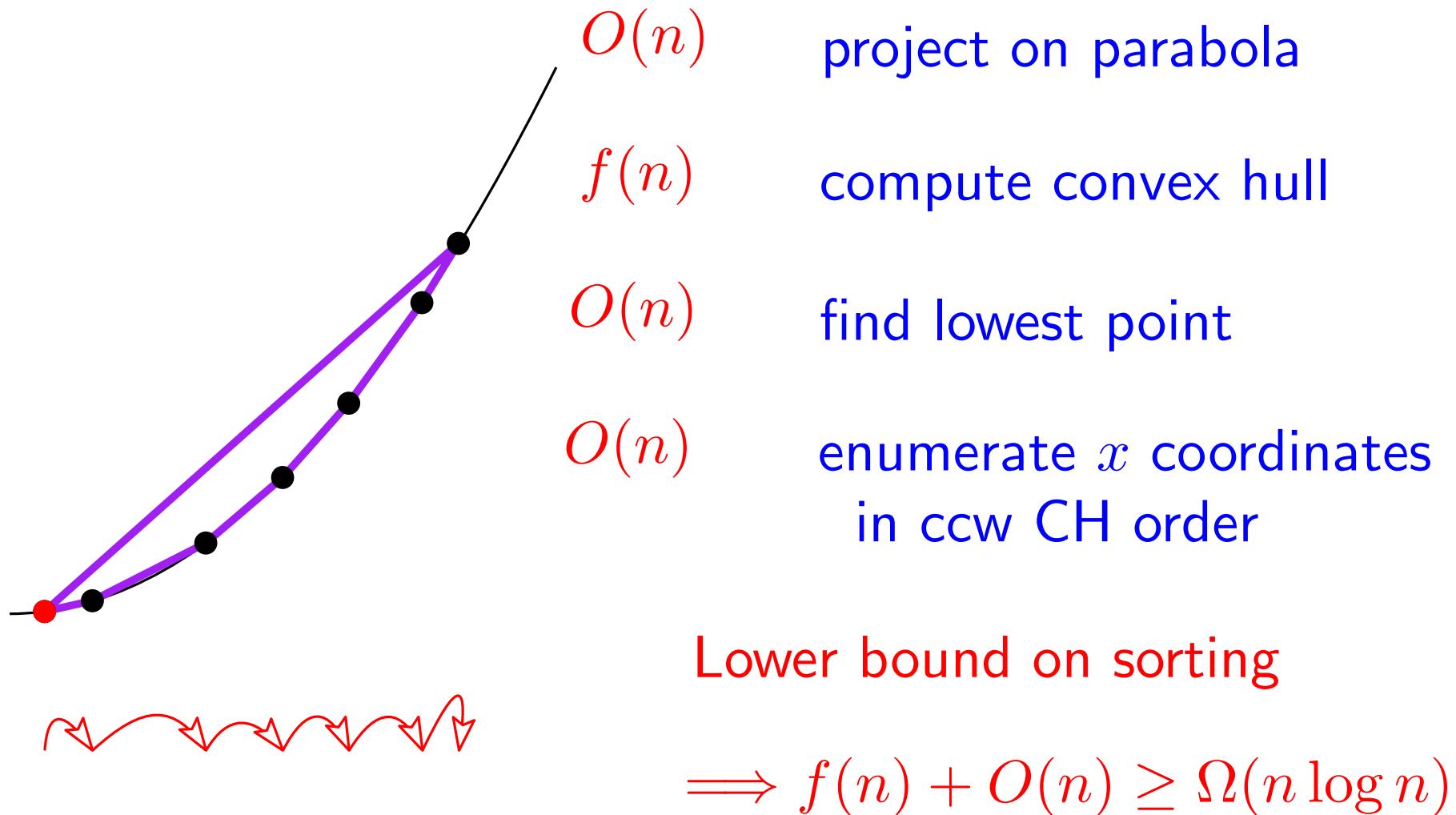
compute convex hull

find lowest point

enumerate  $x$  coordinates  
in ccw CH order

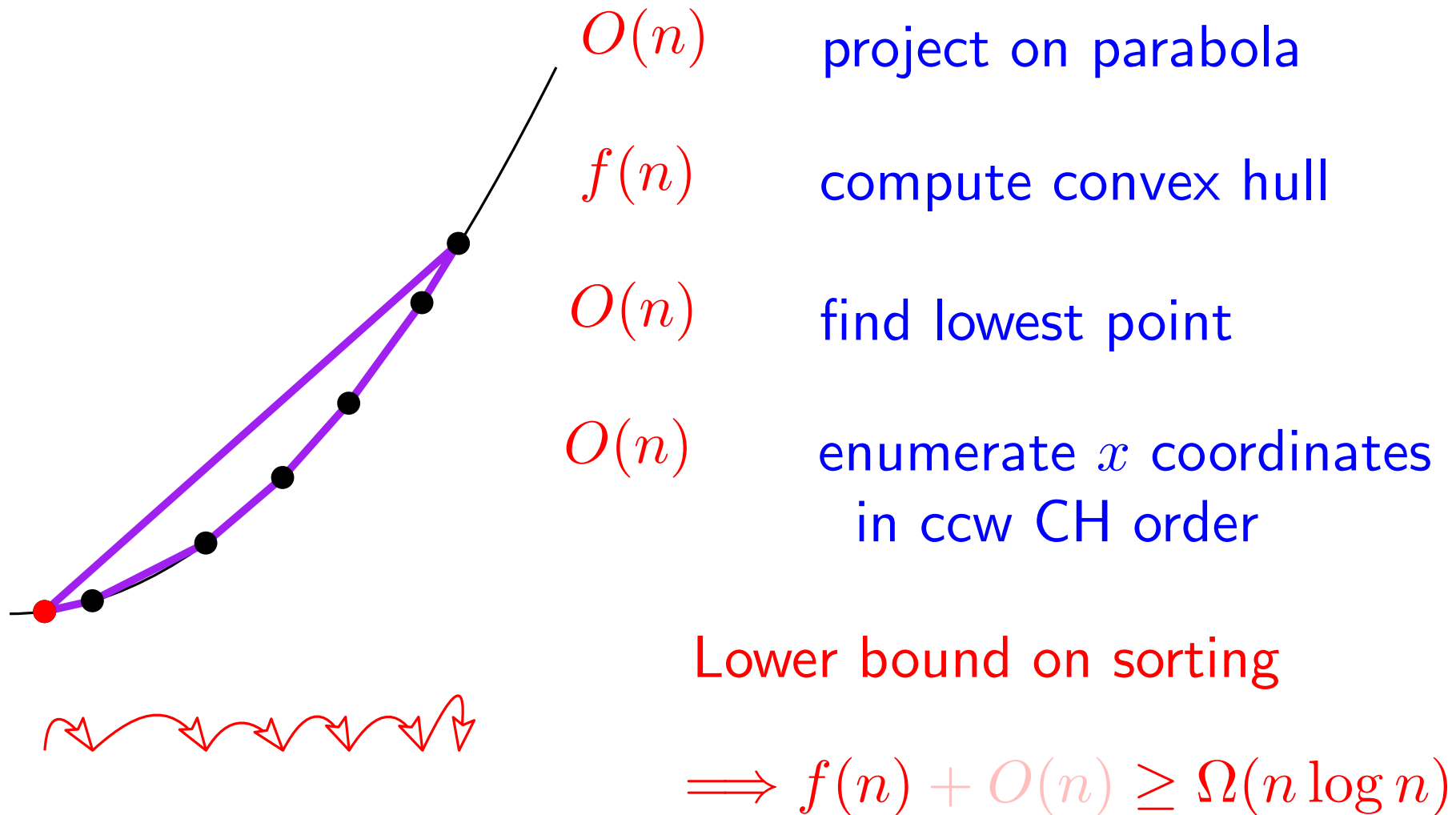
# Convex hull

Lower bound



# Convex hull

Lower bound



# Convex hull

Three dimensions

Euler relation

Polytope boundary

Vertices

Edges

Faces

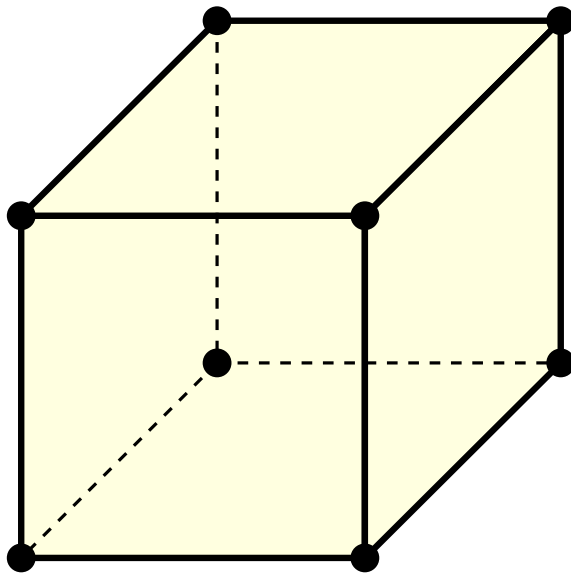


# Convex hull

Three dimensions

Euler relation

Polytope boundary



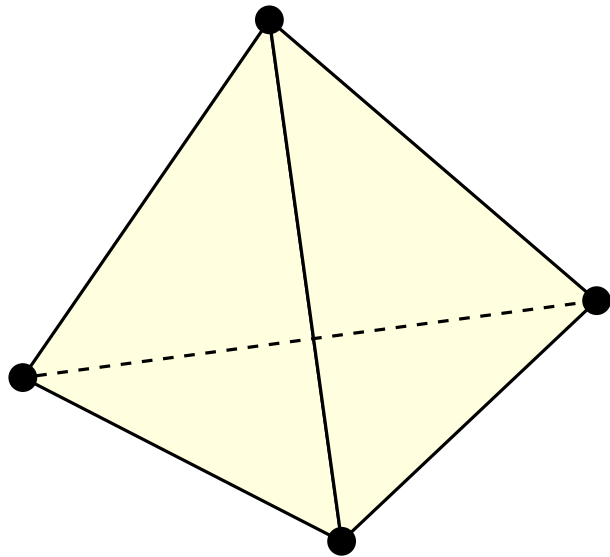
$$\begin{array}{r} \text{Vertices} \\ 8 \end{array} - \begin{array}{r} \text{Edges} \\ 12 \end{array} + \begin{array}{r} \text{Faces} \\ 6 \end{array} = 2$$

# Convex hull

Three dimensions

Euler relation

Polytope boundary



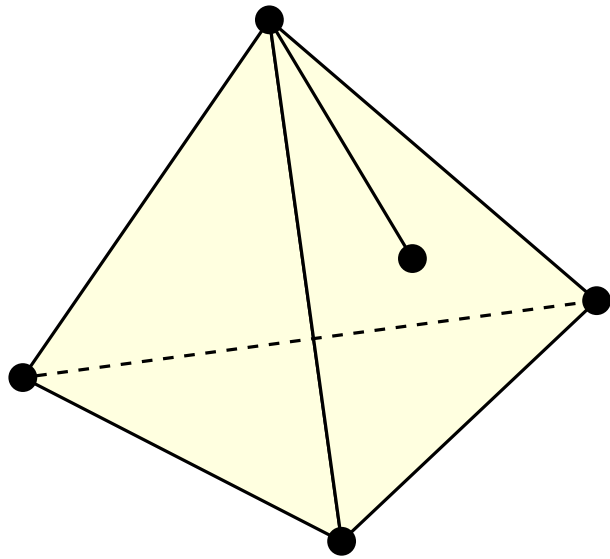
Vertices		Edges		Faces		
8	-	12	+	6	=	2
4	-	6	+	4	=	2

# Convex hull

Three dimensions

Euler relation

Polytope boundary



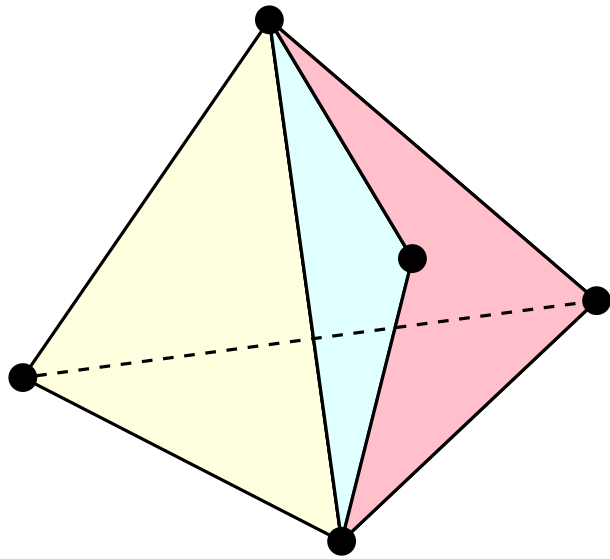
Vertices		Edges		Faces	
8	-	12	+	6	= 2
4	-	6	+	4	= 2
+1	-	+1	+	0	= +0

# Convex hull

Three dimensions

Euler relation

Polytope boundary



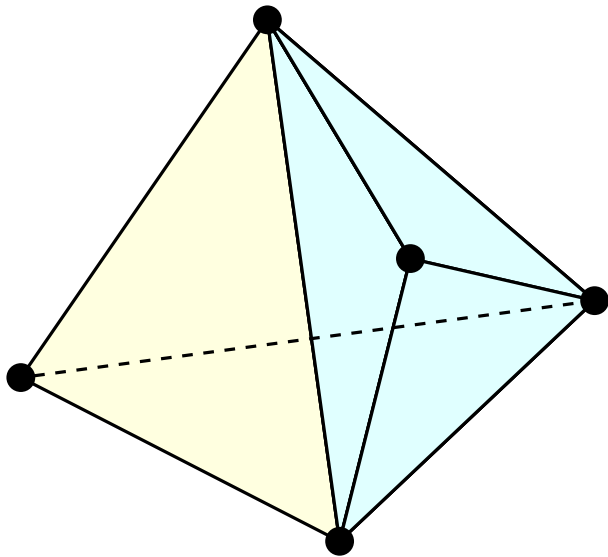
Vertices	Edges	Faces	
8	- 12	+ 6	= 2
4	- 6	+ 4	= 2
+1	-	+1 + 0	= +0
0	-	+1 + +1	= +0

# Convex hull

Three dimensions

Euler relation

Polytope boundary



Vertices	Edges	Faces	
8	- 12	+ 6	= 2
4	- 6	+ 4	= 2
+1	-	+1 + 0	= +0
0	-	+1 + +1	= +0

# Convex hull

Three dimensions

Euler relation

Polytope boundary

Vertices

Edges

Faces

$$n - e + f = 2$$

# Convex hull

Three dimensions

Euler relation

Polytope boundary

Vertices

Edges

Faces

$$n - e + f = 2$$

triangular faces

$$3f = 2e$$

# Convex hull

Three dimensions

Euler relation

Polytope boundary

Vertices      Edges      Faces

$$n - e + f = 2$$

triangular faces

$$3f = 2e$$

$$f = 2n - 4$$

$$e = 3n - 6$$



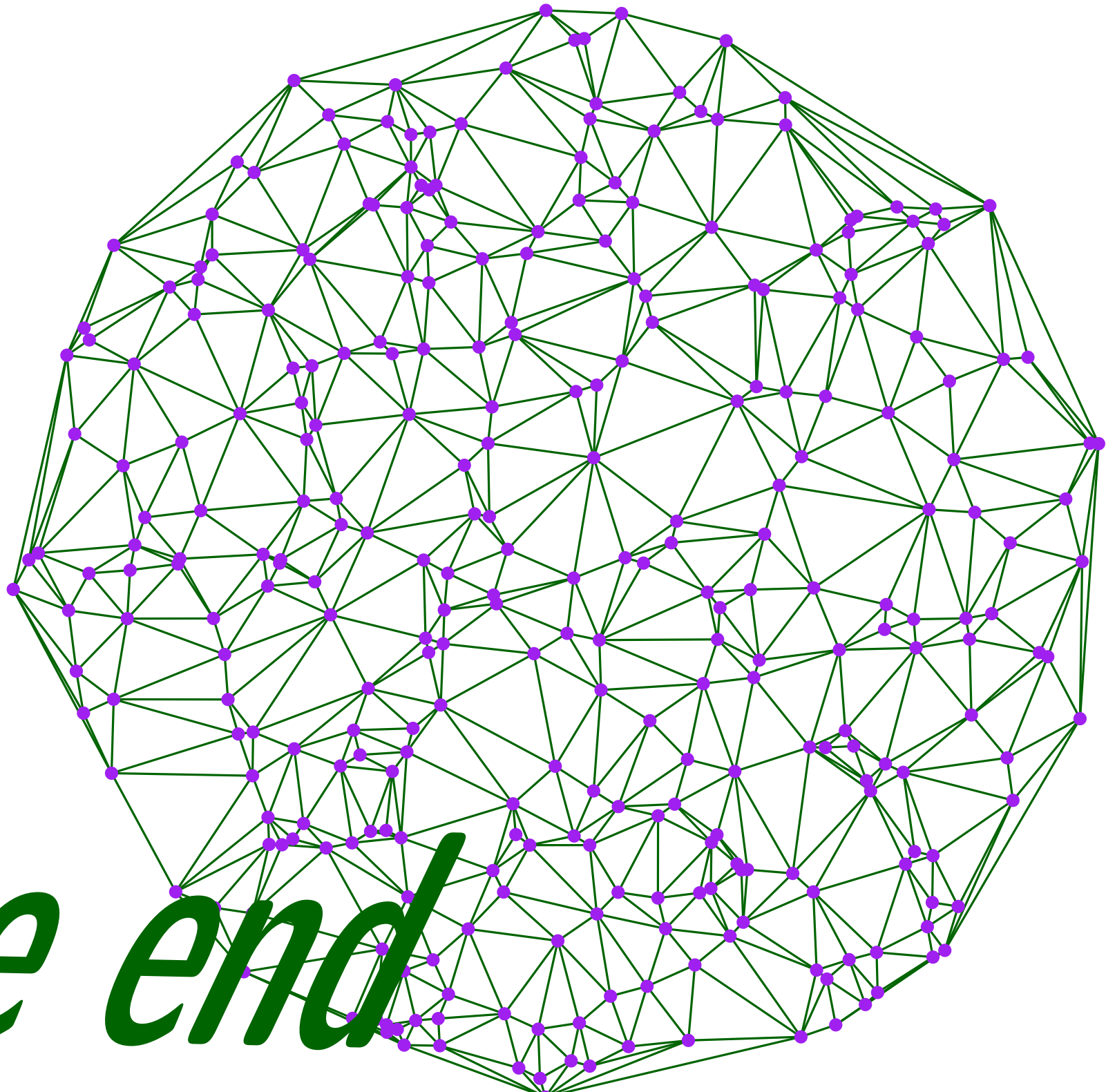
# Convex hull

Three dimensions

Linear size

$O(n \log n)$  divide and conquer algorithm

$O(nh)$  gift wrapping algorithm



*The end*