

Type systems for ICC analysis of imperative programs

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ICC's last stand

The aim of ICC is to find machine independent characterizations of complexity classes:

- ▶ Function algebra (Bellantoni, Cook, Leivant, Marion, ...)
- ▶ Lights logics (Girard, Lafont, Baillot, Gaboardi, Ronchi Della Rocca, ...)
- ▶ Interpretations of TRS (Bonfante, Marion, Moyen, Péchoux, ...)
- ▶ Non-size increasing principle (Hofmann, ...)
- ▶ Matrices calculus for imperative programs (Jones, Kristiansen, Wunderlich, Moyen, ...)
- ▶ Imperative pointer graph languages for subpolynomial classes (Hofmann, Schoepp, ...)

Mixture

Marion's idea (Lics 2011) is to take advantage of two well-known lines of work:

- ▶ Safe (or tiered) recursion by Bellantoni and Cook [1992]
- ▶ Non-interference by Volpano et al [1996]

in order to obtain a polynomial time characterization on imperative languages.

Safe recursion

The class of functions that can be defined using:

- ▶ constants, projections, successor, predecessor, conditional,
- ▶ safe composition:

$$f(\bar{x}; \bar{a}) = h(r(\bar{x};); t(\bar{x}; \bar{a}))$$

- ▶ and safe recursion (on notation):

$$\begin{aligned} f(0, \bar{x}; \bar{a}) &= g(\bar{x}; \bar{a}) \\ f(i(x), \bar{y}; \bar{a}) &= h_i(x, \bar{y}; f(x, \bar{y}; \bar{a})) \quad i \in \{0, 1\}, \end{aligned}$$

provided h, r, t, g, h_i are already defined in the class,
is exactly the set of functions computable in polynomial time (FPtime).

The tiered viewpoint

The class of functions that can be defined using:

- ▶ constants, projections, successor, predecessor, conditional,
- ▶ safe composition:

$$f(\bar{x}^1; \bar{a}^0) = h(r(\bar{x}^1;); t(\bar{x}^1; \bar{a})^0)$$

- ▶ and safe recursion (on notation):

$$\begin{aligned} f(0, \bar{x}^1; \bar{a}^0) &= g(\bar{x}^1; \bar{a}^0) \\ f(i(x)^1, \bar{y}^1; \bar{a}) &= h_i(x^1, \bar{y}^1; f(x^1, \bar{y}^1; \bar{a})^0) \quad i \in \{0, 1\}, \end{aligned}$$

provided h, r, t, g, h_i are already defined in the class,

is exactly the set of functions computable in polynomial time (FPtime).

Non-interference

Two security levels:

- ▶ H for high
- ▶ L for low

and typing rules of the shape:

$$\frac{\Gamma \vdash E : \tau \quad \Gamma \vdash I : \tau \text{ Cmd}}{\Gamma \vdash \text{while}(E)\{I\} : \tau \text{ Cmd}} \text{ (Wh)}$$

+ command subtyping:

$$\frac{\Gamma \vdash I : \tau \text{ Cmd} \quad \tau < \tau'}{\Gamma \vdash I : \tau' \text{ Cmd}} \text{ (Sub)}$$

Non-interference example

It prevent us from typing the following program:

```
while(x>0 : H) {  
    x = x-- ; : H Cmd  
    y = y++ ; : L Cmd  
}
```

if x is High and y is Low (Indeed there is a flow from x to y) and provided that $H < L$.

Duality of non-interference and tiering

We would like to type following program:

```
while(x>0 : 1) {  
    x = x-- ; : 1 Cmd  
    y = y++ ; : 0 Cmd  
}
```

if x is of tier **1** (High) and y is of tier **0** Low (preventing flows from y to x) and provided that $0 < 1$.

Small imperative language

Every data type is encoded by words over \mathbf{W} .

The size $|w|$ of a word $w \in \mathbf{W}$ is standard.

- ▶ Expressions :

$$E ::= x \mid c \mid \text{true} \mid \text{false} \mid \text{op}(\bar{E})$$

- ▶ Instructions :

$$I ::= ; \mid [\tau] x := E; \mid l_1 \ l_2 \mid \text{while}(E)\{I\} \\ \mid \text{if}(E)\{l_1\}\text{else}\{l_2\}$$

The types τ will be tiers in $\{0, 1\}$ such that $0 < 1$.

Typing rules : expressions

Variable

$$\frac{\Gamma(\mathbf{x}) = \tau}{\Gamma \vdash \mathbf{x} : \tau}$$

Constant

$$\frac{}{\Gamma \vdash n : \tau}$$

Destructor

$$\frac{\Gamma \vdash e : \tau}{\Gamma \vdash op(e) : \tau}$$

Constructor

$$\frac{\Gamma \vdash e : \tau}{\Gamma \vdash op(e) : \mathbf{0}}$$

Typing rules : commands

Assign

$$\frac{\Gamma \vdash x : \tau \quad \Gamma \vdash E : \tau'}{\Gamma \vdash x := E : \tau} \tau \leq \tau'$$

Compose

$$\frac{\Gamma \vdash l_1 : \tau \quad \Gamma \vdash l_2 : \tau'}{\Gamma \vdash l_1 l_2 : \tau \vee \tau'}$$

If

$$\frac{\Gamma \vdash e : \tau \quad \Gamma \vdash l_i : \tau}{\Gamma \vdash \text{if}(E)\{l_1\}\text{else}\{l_2\} : \tau}$$

While

$$\frac{\Gamma \vdash E : \mathbf{1} \quad \Gamma \vdash I : \tau}{\Gamma \vdash \text{while}(E)\{I\} : \mathbf{1}}$$

Improvements

We can extend the type system to more general operators
 $op :: \tau_1 \times \dots \times \tau_n \rightarrow \tau$ such that $\tau \leq \wedge_i \tau_i$.

- ▶ Neutral operators:
 - ▶ either a computable predicate
 - ▶ or a subword operator:

$$\forall \bar{w}, \exists i \in \{1, \dots, n\}, \llbracket op \rrbracket(\bar{w}) \sqsubseteq w_i$$

- ▶ Positive operators:

$$\forall \bar{w}, \llbracket op \rrbracket(\bar{w}) \leq \max_{i \in [1, n]} |w_i| + c, \text{ for } c \geq 0$$

- ▶ In this case $\tau = \mathbf{0}$.

We can also add procedure calls.

Example: addition

```
int add(int x,int y)
{
  while (x>0)
    {
      x--;
      y++;
    }
  return y
}
```

- ▶ y is necessarily of tier **0**
- ▶ x is necessarily of tier **1**
- ▶ and, consequently, $\text{add} :: \mathbf{1} \times \mathbf{0} \rightarrow \mathbf{0}$

Example: multiplication

```
int mult(int x, int y)
{
  int z=0;
  while (x)
  {
    x--;
    z = add(y, z);
  }
  return z;
}
```

- ▶ the output of add is **0**. Consequently, z is of tier **0**.
- ▶ both x and y are of tier **1**
- ▶ and, consequently, $\text{mult} :: \mathbf{1} \times \mathbf{1} \rightarrow \mathbf{0}$

Example: exponential

```
int expo(int x)
{
  int y=1;
  while (x)
  {
    x--;
    y = add(y, y);
  }
  return y;
}
```

- ▶ x is of tier **1**,
- ▶ the output of `add` is of tier **0**,
- ▶ but y has to be of tier **1** in the first argument of `add` !!!

Results

We have a (weak) subject reduction property:

Theorem [Marion and Péchoux (TAMC 2014?)]

If $\sigma \vDash I \rightarrow \sigma' \vDash I'$ and $\Gamma \vdash I : \tau$ then $\Gamma \vdash I' : \tau'$ where $\tau' \leq \tau$.

We obtain a characterization of FPtime:

Theorem [Marion (Lics 2011)]

The set of functions computable by a typable and terminating program with FPtime computable operators is exactly FPtime.

Moreover, type inference is decidable:

Theorem [Hainry, Marion and Péchoux (Fossacs 2013)]

Type inference can be done in polynomial time.

Mechanism

FPtime soundness:

- ▶ No flow from **0** to **1**: tier **1** variables cannot increase
- ▶ Only tier **1** arguments in the guards
- ▶ At most n^k configurations under termination assumption

FPtime completeness:

- ▶ Any polynomial can be computed
- ▶ We simulate polynomial time TMs by an imperative typable (and terminating) program

Type inference:

- ▶ All the constraints are inequalities over 2 tiers
- ▶ That can be reduced to a 2-SAT formula

Multi-threaded

Now we consider multi-threads M to be a fixed collection of commands:

$$M(\alpha) = l, \alpha \in \text{dom}(M)$$

and non-deterministic reduction:

$$\frac{M(\alpha) = l \quad \sigma \Vdash l \rightarrow \sigma_1 \Vdash l_1}{\sigma \Vdash M \rightarrow \sigma_1 \Vdash M[\alpha := l_1]} \text{ (Step)} \quad \frac{M(\alpha) = l \quad \sigma \Vdash l \rightarrow \sigma_1}{\sigma \Vdash M \rightarrow \sigma_1 \Vdash M - \alpha} \text{ (Stop)}$$

and we extend the typing rule by:

$$\frac{\forall \alpha \in \text{dom}(M), \exists \tau, \Gamma \vdash M(\alpha) : \tau}{\Gamma \vdash M : \diamond} \text{ (Multi)}$$

Results

We obtain a polynomial time soundness criterion:

Theorem [Marion and Péchoux (TAMC 2014?)]

A typable and strongly normalizing multi-thread terminates in a polynomially bounded number of transitions.

The strong normalization assumption can be weakened under a fair scheduling policy (depending only on M and tier **1** values):

Theorem [Marion and Péchoux (TAMC 2014?)]

A typable a multi-thread terminating under a fair scheduling policy terminates in a polynomially bounded number of transitions.

Moreover, type inference remains decidable:

Theorem [Hainry, Marion and Péchoux (Fossacs 2013)]

Type inference can be done in polynomial time.

Forks: motivation

- ▶ May the analysis be generalized to more expressive languages ?
- ▶ Can we analyze parallelism ?
- ▶ Is it possible to jump from time (FPtime) to space (Pspace or FPspace) ?

In [Fossacs 2013], we have presented an extension to forks.
The syntax of the language is extended by two commands:

$$X = \text{fork}() \mid X = \text{wait}\{E\}$$

Forks informal semantics

On the execution of $X = \text{fork}(); I$ in a parent process:

- ▶ a new son of (fresh) pid n and instruction I is created (by default, $X := 0$)
- ▶ the father has instruction I and knows the pid of its new son ($X := n$)

On the execution of $X = \text{wait}(E); I$ in a parent process:

- ▶ if E evaluates to n and the process of pid n returns v then $X := v$ in the parent process
- ▶ otherwise the father has to wait.

Forks typing rules

We need to add an extra tier -1 ($-1 < 0 < 1$) in order to prevent accumulation.

$$\frac{\Gamma \vdash x : 0}{\Gamma \vdash x := \text{fork}() : 0} (F) \quad \frac{\Gamma \vdash E : 0 \quad \Gamma \vdash x : -1}{\Gamma \vdash x := \text{wait}(E) : -1} (W)$$

Operators $op :: \tau_1 \times \dots \times \tau_n \rightarrow \tau$ are extended to max operations :

$$\forall \bar{w}, \|\llbracket op \rrbracket(\bar{w})\| \leq \max_{i \in [1, n]} |w_i|$$

provided that $\tau < 1$.

- ▶ It means that forks' pid cannot be used as guards
- ▶ The values returned by sons cannot be accumulated (at most max or neutral operators).

Example "rien que pour les yeux"

```

max_reduce( $n^1$ ,  $A^0$ ) ::=  $r^0 := 0$ : 0;  $f^{-1} := A[r]^0$ : -1;
  flag0 := tt: 0;
  while ( $n^1 \neq 1$ )1 do {
    if flag0 then { // not finished
      pidl0 := fork(): 0
      if (pidl > 0)0 then { // father process
         $r^0 := 2*r+2$ : 0;
        pidr0 := fork(): 0
      } else {  $r^0 := 2*r+1$ : 0 } // left son
      if (pidr == 0)0 or (pidl == 0)0 then {  $f^{-1} := A[r]^0$ :
        else {
          flag0 := ff: 0; // father
           $xl^{-1} := \text{wait}(pidl)$ : 0;
           $xr^{-1} := \text{wait}(pidr)$ : 0;
           $f^{-1} := \max(f^{-1}, \max(xl, xr))$ : 0; } }
       $n^1 := \text{half}(n)^1$ : 1 } // end of while
  return f: -1

```

Results

We obtain a characterization of Pspace computable functions:

Theorem [Hainry, Marion and P  choux (Fossacs 2013)]

The set of functions computed by typable, strongly normalizing and confluent processes is exactly the set of polynomial space computable functions *FPspace*.

Soundness:

- ▶ As for multi-threads, the computation tree has a polynomially bounded depth
- ▶ tier -1 prevents accumulation
- ▶ the considered programs are confluent, consequently, we can perform a "in depth" evaluation

Completeness:

- ▶ Each FPspace function can be bitwise computed
- ▶ We show that QBF can be encoded and typed in our formalism.

OO State of the art

Some techniques and programs to bound resource consumptions

- ▶ Amortised analysis for linear heap (Hofmann & Jost)
- ▶ “Costa” for analyzing Java bytecode (Albert, Arenas, Genaim, Puebla & Zanardini)
- ▶ “Speed” for C++ (Gulwani *et al.*)
- ▶ “ResAna” analyzes Java programs (Shkaravska *et al.*)
- ▶ Non-interference and tiering for a graph based imperative language (Leivant & Marion)

OO: motivation

- ▶ Extend our results to a "daily-life" real programming language
- ▶ Analyze the complexity of the OO paradigm
- ▶ Obtain "practical" upper bound on both the heap and stack space usage
- ▶ Analyze OO features:
 - ▶ mixture of while loops and recursive method calls
 - ▶ objects in loop guards
 - ▶ inheritance
 - ▶ control flow statements such as `break` or `continue`

Core Java

In [FOPARA2013], we have considered the Java-like language:

- ▶ Expressions $E ::= \dots \mid \text{null} \mid \text{this} \mid \text{new } C(\bar{E}) \mid E.m(\bar{E})$
- ▶ Instructions $I ::= \dots \mid E.m(\bar{E});$
- ▶ Methods $M_C ::= \tau m(\tau_1 x_1, \dots, \tau_n x_n) \{ I[\text{return } x;] \}$
- ▶ Cons $K_C ::= C(\tau_1 y_1, \dots, \tau_n y_n) \{ x_1 := y_1; \dots x_n := y_n; \}$
- ▶ Classes $\mathcal{C} ::= C \{ \tau_1 x_1; \dots; \tau_n x_n; K_C M_C^1 \dots M_C^k \}$

Core Java Programs

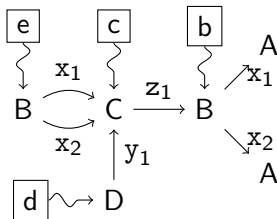
Definition [Core Java Program]

A Core Java Program is a collection of classes and exactly one executable:

$$\text{Exe}\{\text{main()}\underbrace{\{\tau_1 x_1 := E_1; \dots; \tau_n x_n := E_n;\}}_{\text{Initialization}} \underbrace{\{I\}}_{\text{Computation}} \}.$$

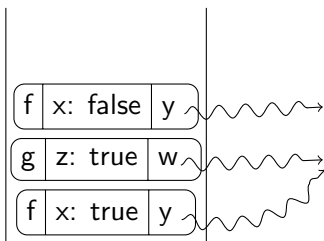
Heap

- ▶ Where objects are created and kept in memory.
- ▶ Maximal heap space is defined at the launch of the JVM.
- ▶ Pointers to the objects, arrows between objects and their attributes.



Stack

- ▶ Where arguments of a method call are put.
- ▶ Primitive types are put by value.
- ▶ Object types are put by reference, *i.e.* a pointer to the heap.
- ▶ May grow indefinitely because of recursive calls.



Tiered types

- ▶ Expressions, Instructions, Constructors and Methods are annotated by tiered types (i.e. a type and a tier (0 or 1)).
- ▶ For instructions, the type will always be `void`.
- ▶ For Constructors and methods the tiered type is functional:

$$\text{boolean}(1) \times \text{BList}(1) \rightarrow \text{BList}(0)$$

- ▶ For methods, the tiered type of the caller object is included:
e.g. for `void setQueue(BList q) {...}`

$$\text{BList}(0) \times \text{BList}(1) \rightarrow \text{void}(0)$$

Typing Simple Expressions

$$\frac{}{\Gamma \vdash \text{true} : \text{boolean}(\mathbf{1})} \textit{(True)} \quad \frac{}{\Gamma \vdash \text{false} : \text{boolean}(\mathbf{1})} \textit{(False)}$$

$$\frac{}{\Gamma \vdash \text{null} : \mathbf{C}(\mathbf{1})} \textit{(Null)}$$

$$\frac{\alpha \preceq \min\{\text{tiers of the attributes}\}}{(m^{\mathbf{C}}, \Delta) \vdash \text{this} : \mathbf{C}(\alpha)} \textit{(Self)}$$

$$\frac{\Delta(m^{\mathbf{C}})(x) = \tau(\alpha)}{(m^{\mathbf{C}}, \Delta) \vdash x : \tau(\alpha)} \textit{(Var)}$$

$$\frac{\forall i \Gamma \vdash E_i : \tau_i(\alpha) \quad \textit{op} :: \tau_1 \times \dots \times \tau_n \rightarrow \text{boolean}}{\Gamma \vdash \textit{op}(E_1, \dots, E_n) : \text{boolean}(\alpha)} \textit{(Op)}$$

Typing Instructions

$$\frac{}{\Gamma \vdash ; : \text{void}(\mathbf{0})} \text{ (Skip)}$$

$$\frac{\Gamma \vdash x : \tau(\alpha) \quad \Gamma \vdash E : \tau(\beta) \quad \alpha \preceq \beta}{\Gamma \vdash [\tau] x := E ; : \text{void}(\alpha)} \text{ (Ass)}$$

$$\frac{\Gamma \vdash I : \text{void}(\alpha) \quad \alpha \preceq \beta}{\Gamma \vdash I : \text{void}(\beta)} \text{ (Sub)}$$

$$\frac{\forall i \Gamma \vdash I_i : \text{void}(\alpha_i)}{\Gamma \vdash I_1 I_2 : \text{void}(\alpha_1 \vee \alpha_2)} \text{ (Seq)}$$

$$\frac{\Gamma \vdash E : \text{boolean}(\alpha) \quad \forall i \Gamma \vdash I_i : \text{void}(\alpha)}{\Gamma \vdash \text{if}(E)\{I_1\}\text{else}\{I_2\} : \text{void}(\alpha)} \text{ (If)}$$

$$\frac{\Gamma \vdash E : \text{boolean}(\mathbf{1}) \quad \Gamma \vdash I : \text{void}(\mathbf{1})}{\Gamma \vdash \text{while}(E)\{I\} : \text{void}(\mathbf{1})} \text{ (Wh)}$$

Typing Constructors

$$\frac{\forall i (m^C, \Delta) \vdash E_i : \tau_i(\beta_i) \quad \alpha_i \preceq \beta_i}{(\epsilon, \Delta) \vdash C(\dots \tau_i y_i \dots) \{ \dots x_i := y_i; \dots \} : \dots \times \tau_i(\alpha_i) \times \dots \rightarrow C(\mathbf{0})} \text{ (New)}$$

$$(m^C, \Delta) \vdash \text{new } C(E_1, \dots, E_n) : C(\mathbf{0})$$

$$\frac{\forall i (\epsilon, \Delta) \vdash y_i : \tau_i(\alpha_i)}{(\epsilon, \Delta) \vdash C(\dots, \tau_i y_i, \dots) \{ \dots x_i := y_i; \dots \} : \dots \times \tau_i(\alpha_i) \times \dots \rightarrow C(\mathbf{0})} \text{ (K}_C\text{)}$$

Constructors make the heap increase, hence output something of tier **0**.

Safety assumption

Definition [Safety]

A well-typed program with respect to a typing environment Δ is safe if for each recursive method $M_C = \tau \ m(\dots)\{l \ [\text{return } x;]\}$:

- ▶ there is exactly one call (even nested) to m ,
- ▶ there is no while loop inside l ,
- ▶ and the following judgment can be derived:

$$(\epsilon, \Delta) \vdash M_C : C(\mathbf{1}) \times \tau_1(\mathbf{1}) \times \dots \times \tau_n(\mathbf{1}) \rightarrow \tau(\mathbf{1}).$$

Results

Theorem [Hainry and P  choux]

In the execution of a safe Core Java program terminating on input \mathcal{C} , the size of the heap and of the stack are in $O(|\mathcal{C}|^{n_1((\nu+1)\lambda)})$.

- ▶ n_1 the number of variables and attributes of tier **1**,
- ▶ λ the maximum number of nested while and
- ▶ ν the maximum number of nested methods.

We are still complete wrt FPtime and type inference is decidable:

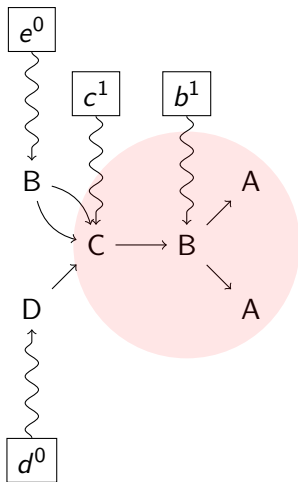
Proposition [Hainry and P  choux]

The set of functions computable by typable, safe and terminating programs is exactly FPtime

Proposition [Type inference]

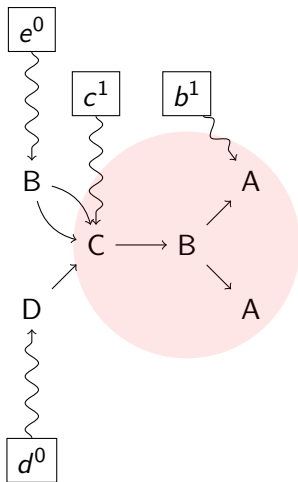
The type inference can be done in time linear in the size of the program.

Idea of the proof



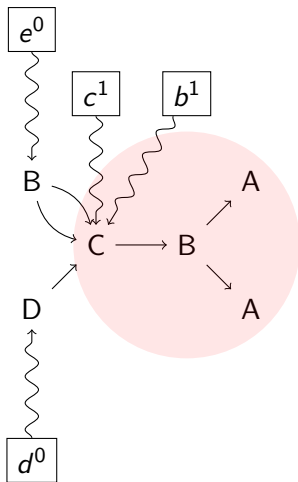
- ▶ The subheap of tier **1** never grows.
- ▶ Only tier **1** variables control `while` and recursive functions.
- ▶ The number of tier **1** configurations is bounded by $|\mathcal{C}|^{2 \times n_1}$.
- ▶ Hence a bound on the stack and heap.

Idea of the proof



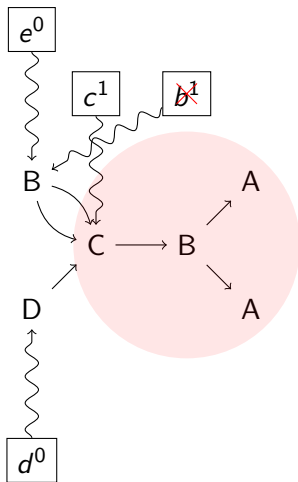
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Conclusion

Result

A static analysis for resource consumption dealing with:

- ▶ several languages (imperative, fork, multi-thread, OO, ...)
- ▶ several classes (FPtime, FPspace,...)
- ▶ both extensional and intensional (heap, stack) properties

Drawbacks and Open questions

- ▶ Not intentionnally complete: improve expressiveness by program transformation
- ▶ Capture Thread creation (work in progress)
- ▶ Do the implementation
- ▶ Extend the characterizations (PP, BPP, ...)