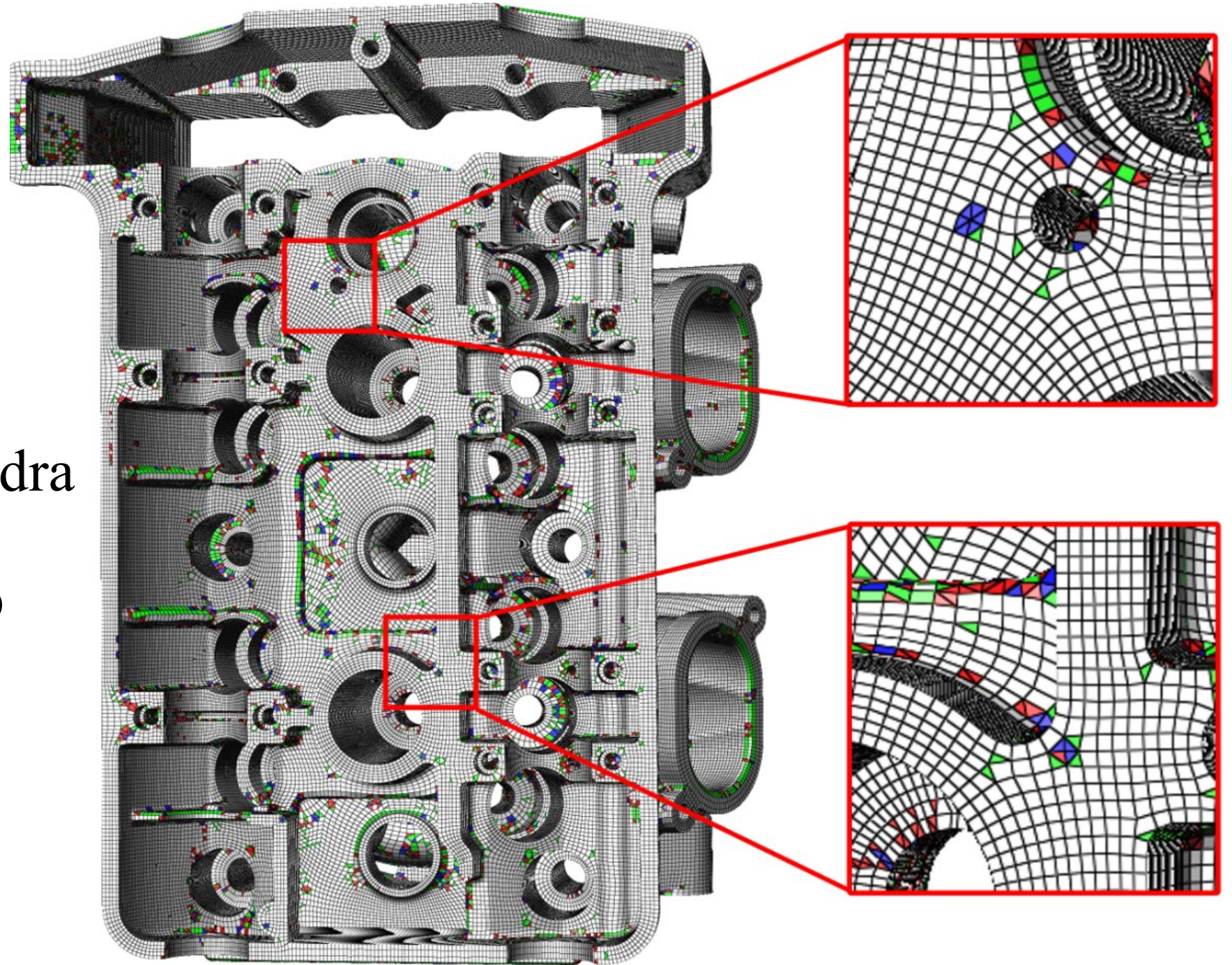


Hexahedral-Dominant Meshing

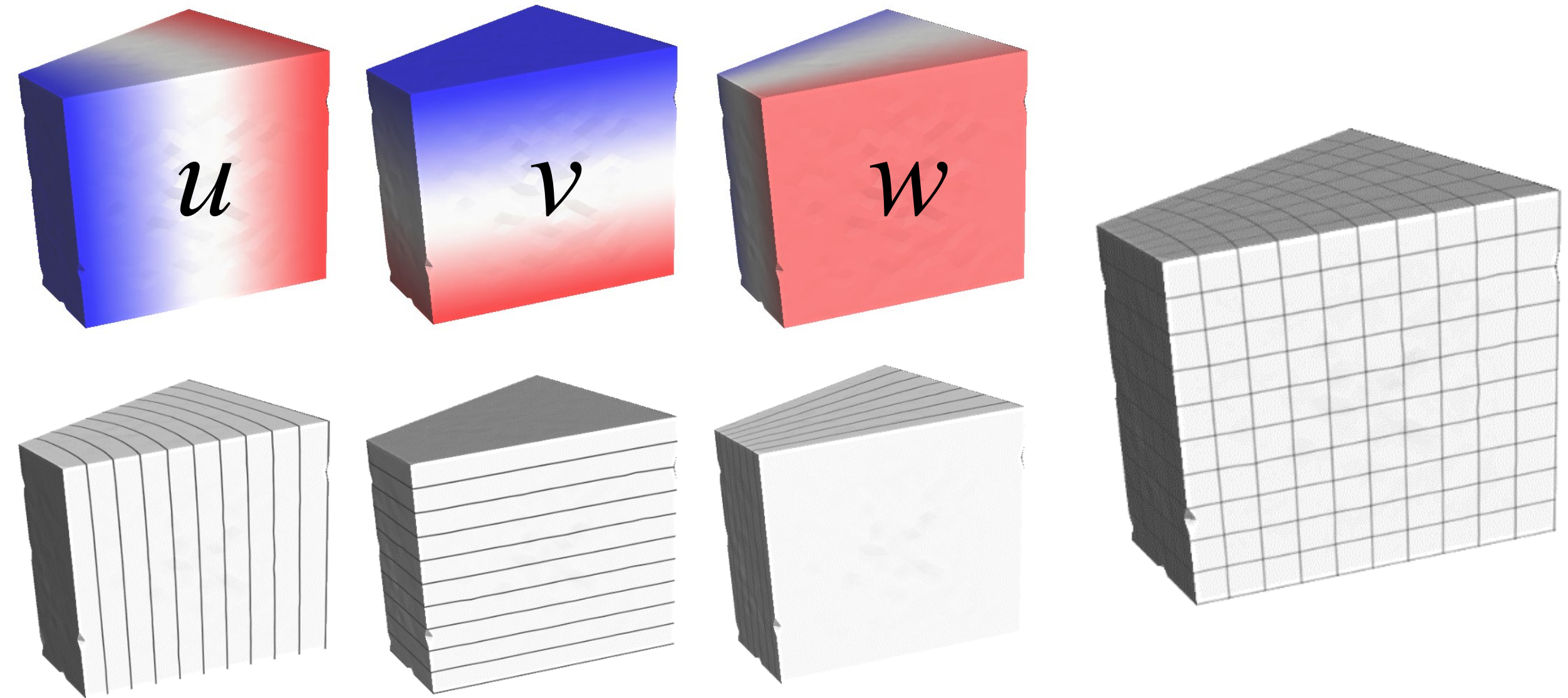
Dmitry Sokolov, Nicolas Ray,
Lionel Untereiner and Bruno Lévy

Teaser!

Remesh 10^7 tetrahedra
models in several
minutes on a laptop

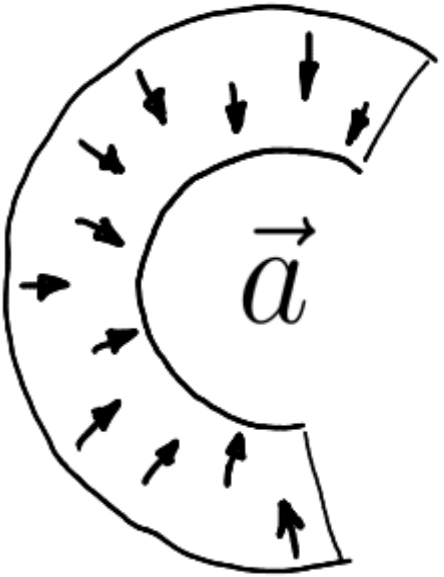


Main idea: compute 3 scalar fields and cut along integer isovalues



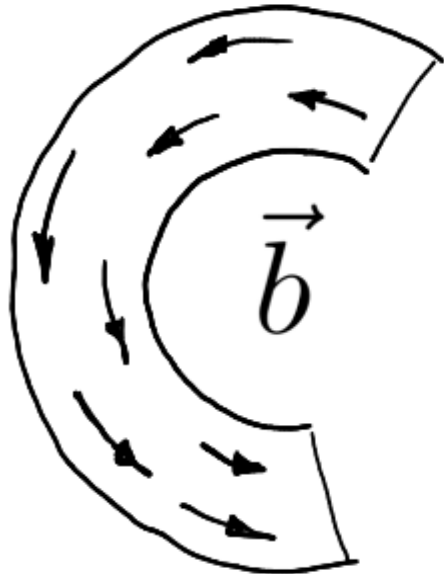
in other words, compute texture coordinates (u, v, w) and apply a grid texture

Introductory example 1 out of 3

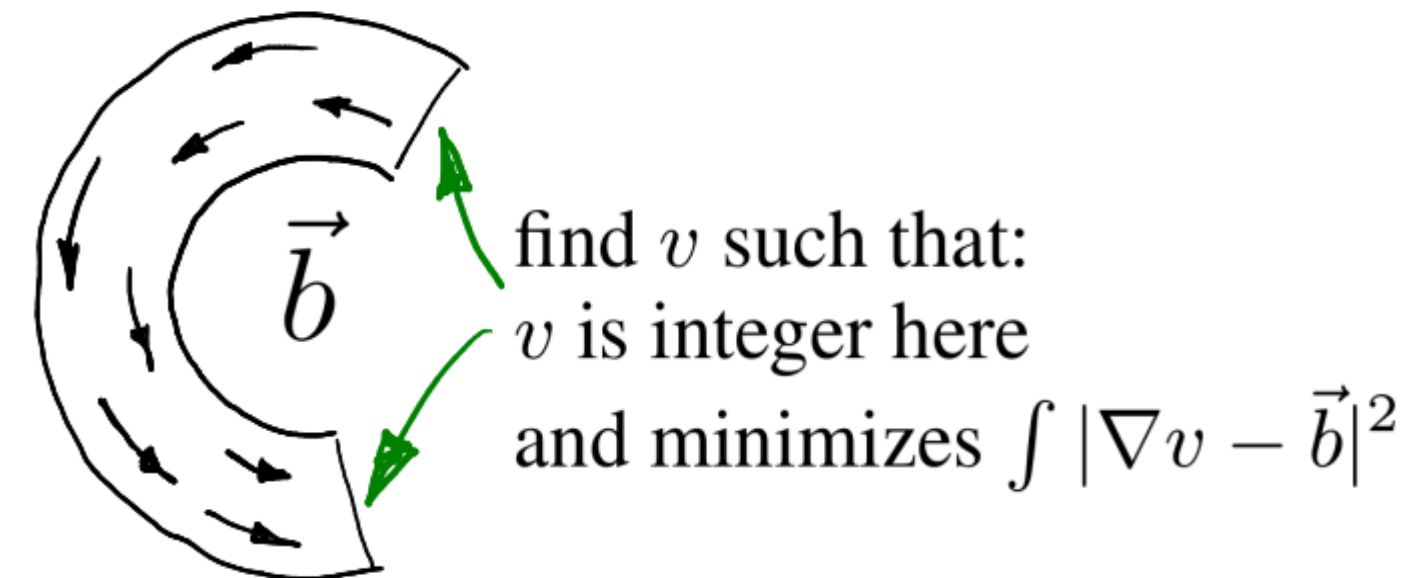
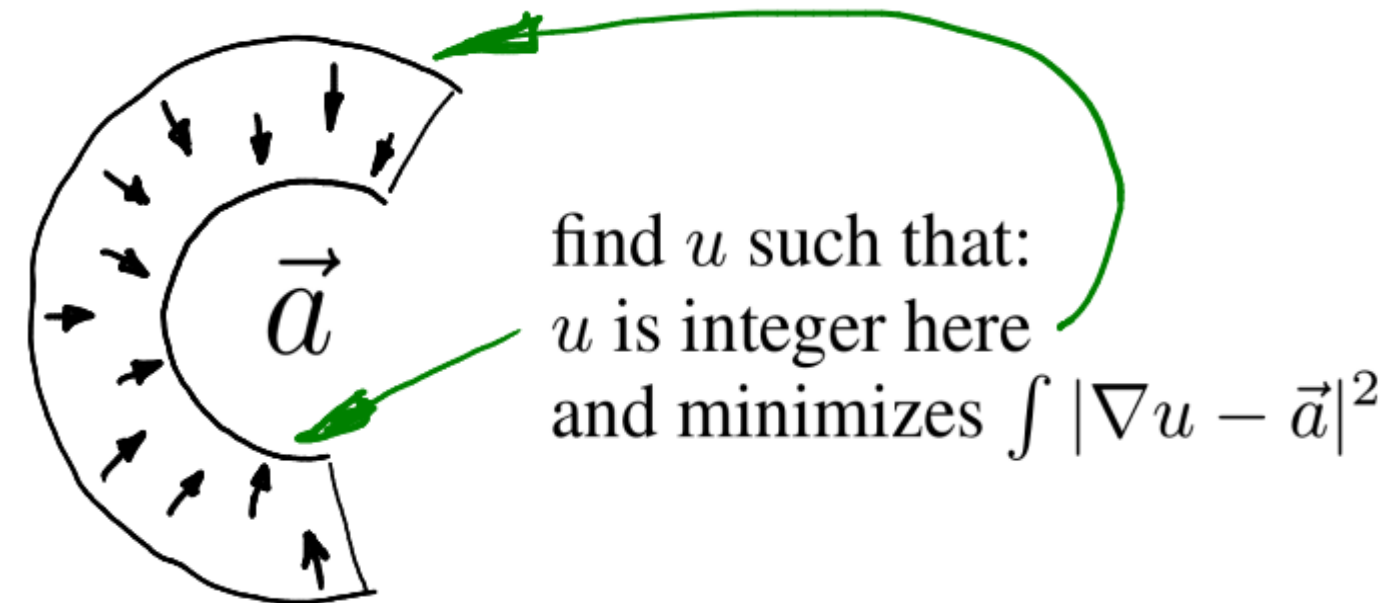


Directional Field Synthesis, Design, and Processing SIGGRAPH 2017 course

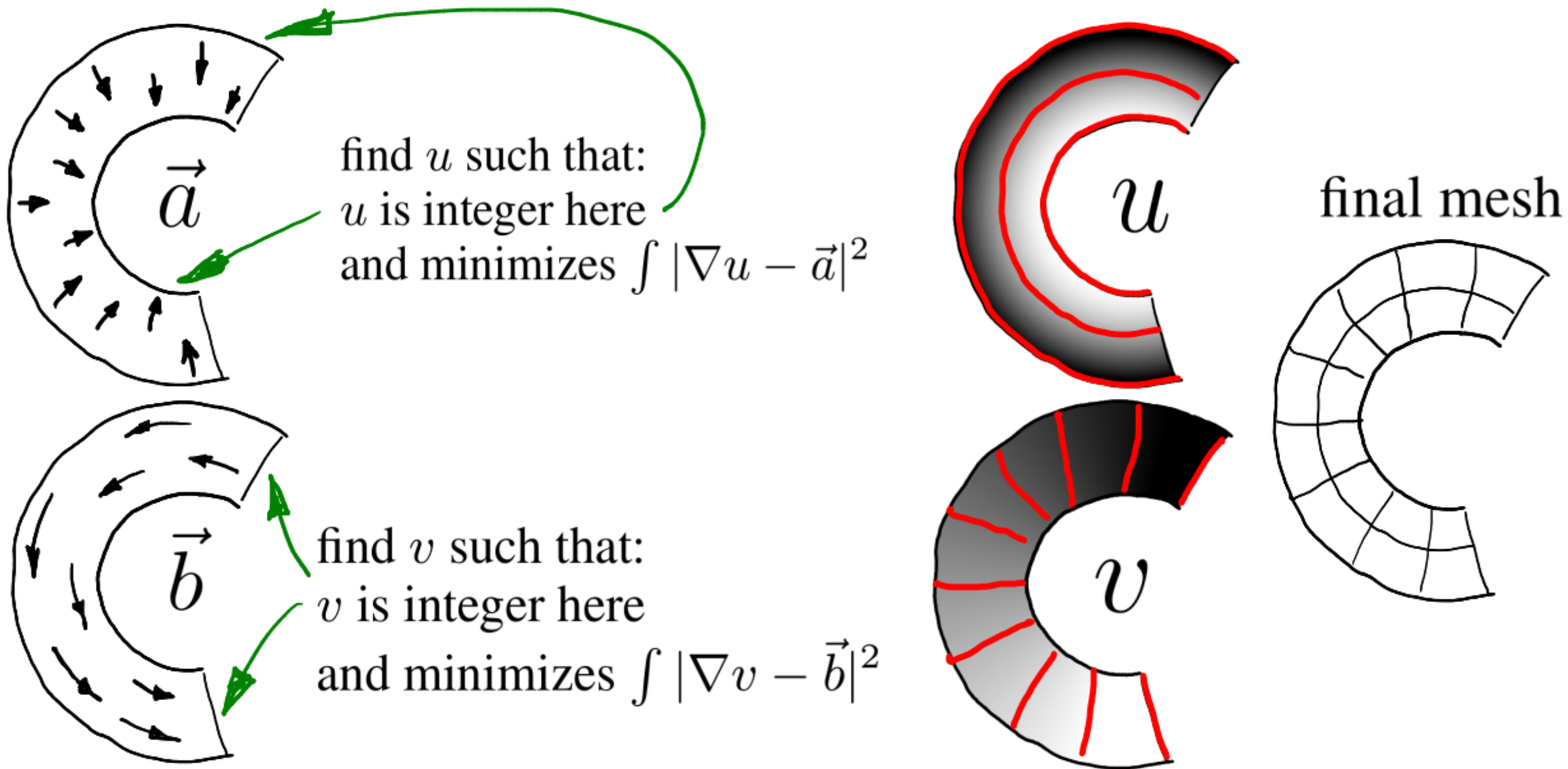
A. Vaxman, M. Campen, O. Diamanti, D. Panozzo,
B. D. Bommers, K. Hildebrandt, M. Ben-Chen



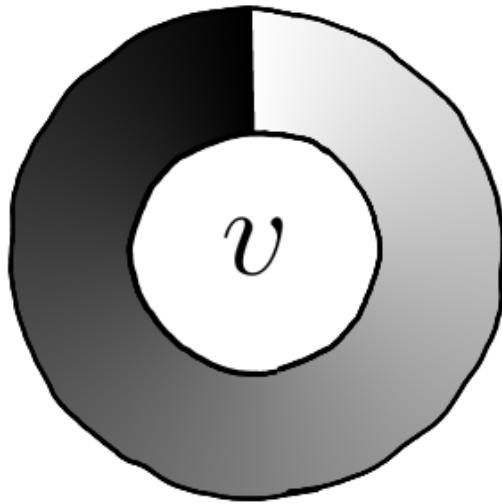
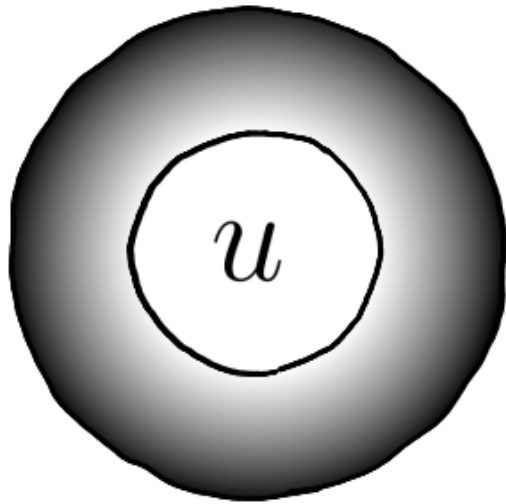
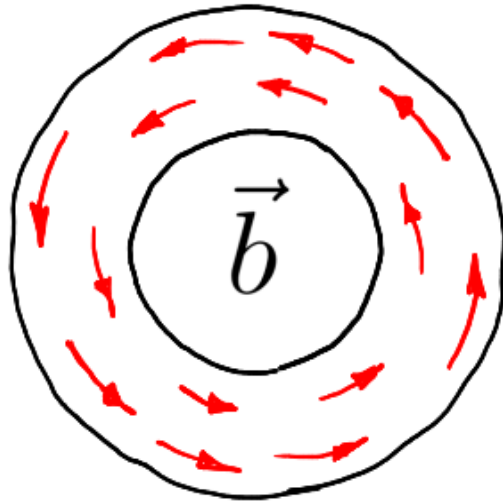
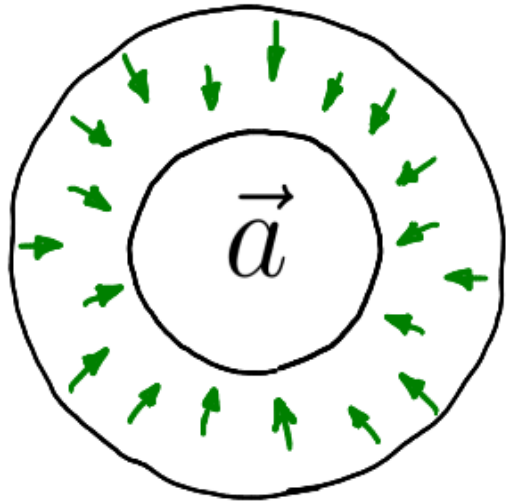
Introductory example 1 out of 3



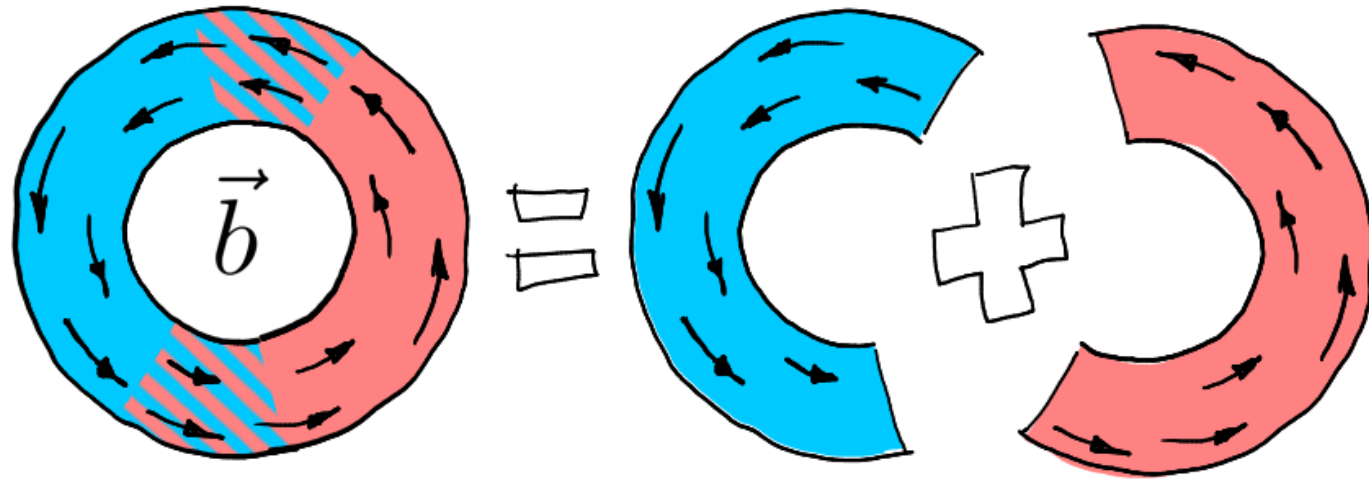
Introductory example 1 out of 3



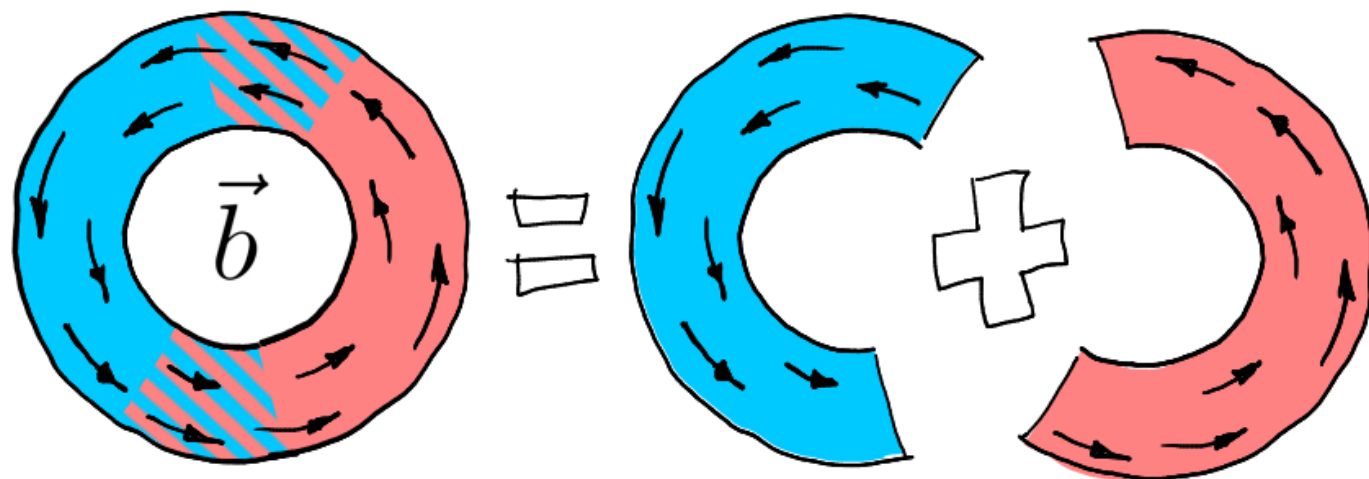
Introductory example 2 out of 3



Introductory example 2 out of 3

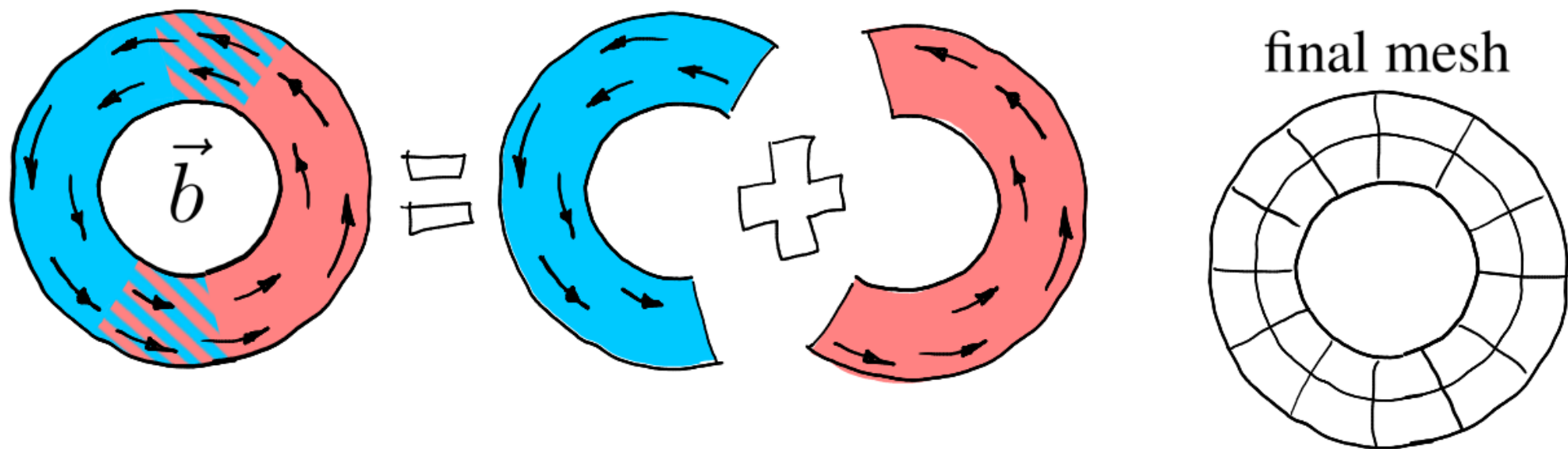


Introductory example 2 out of 3



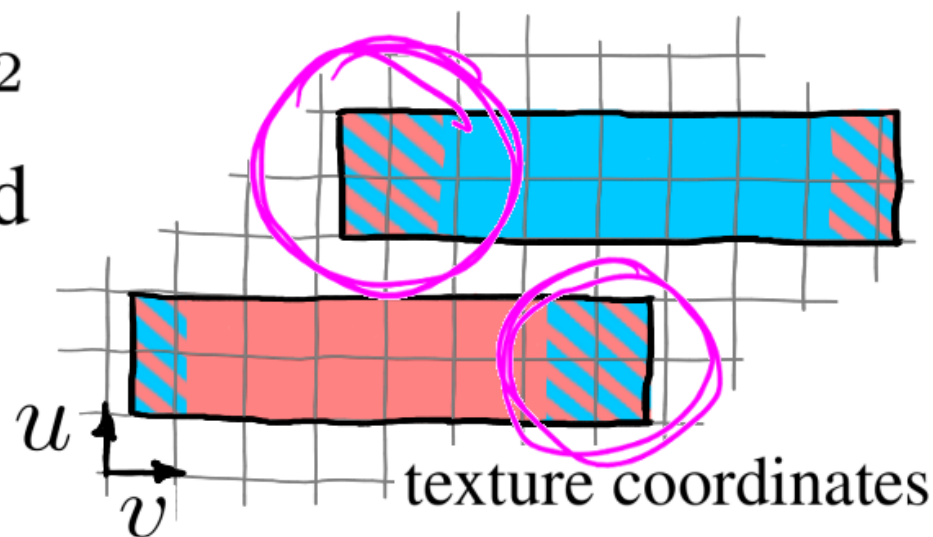
find v_1 and v_2 that minimize
 $\int |\nabla v_1 - \vec{b}|^2 + \int |\nabla v_2 - \vec{b}|^2$
 $v_1 - v_2$ integer where defined

Introductory example 2 out of 3

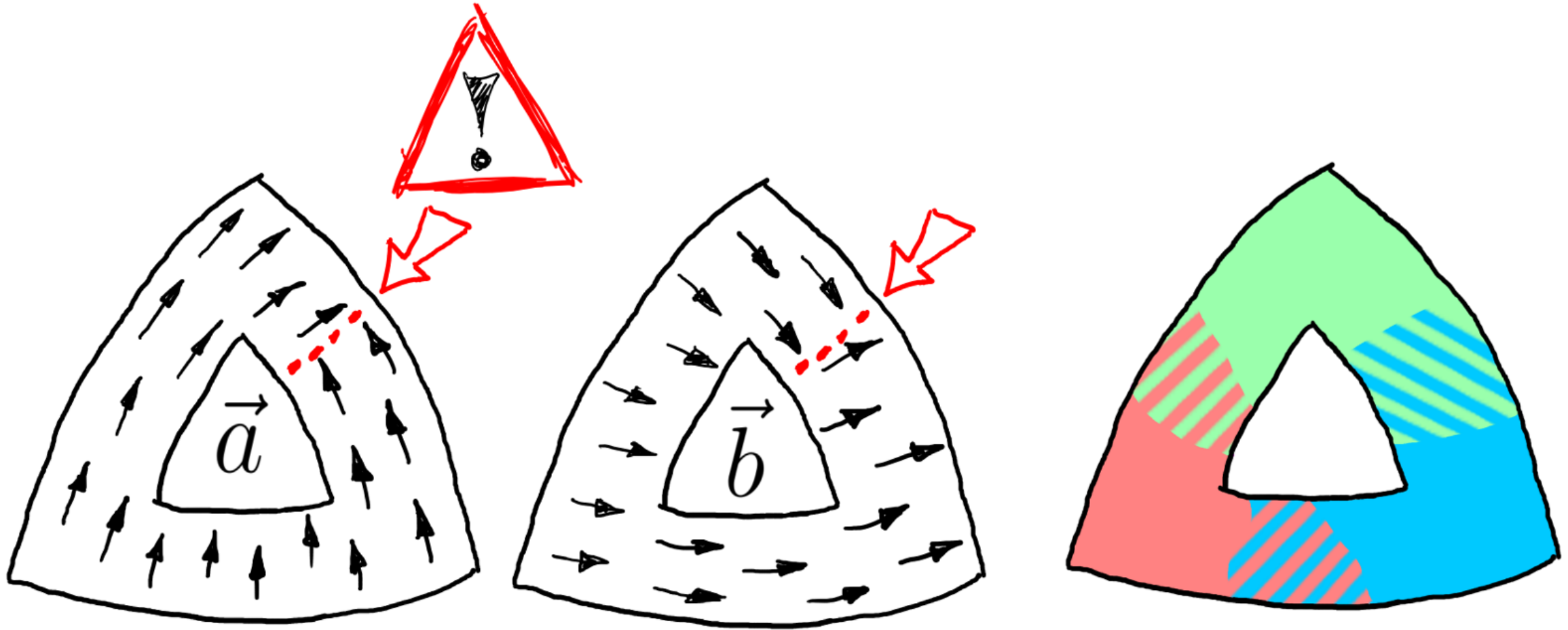


find v_1 and v_2 that minimize
$$\int |\nabla v_1 - \vec{b}|^2 + \int |\nabla v_2 - \vec{b}|^2$$

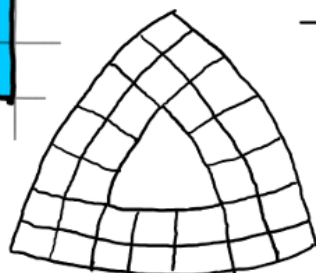
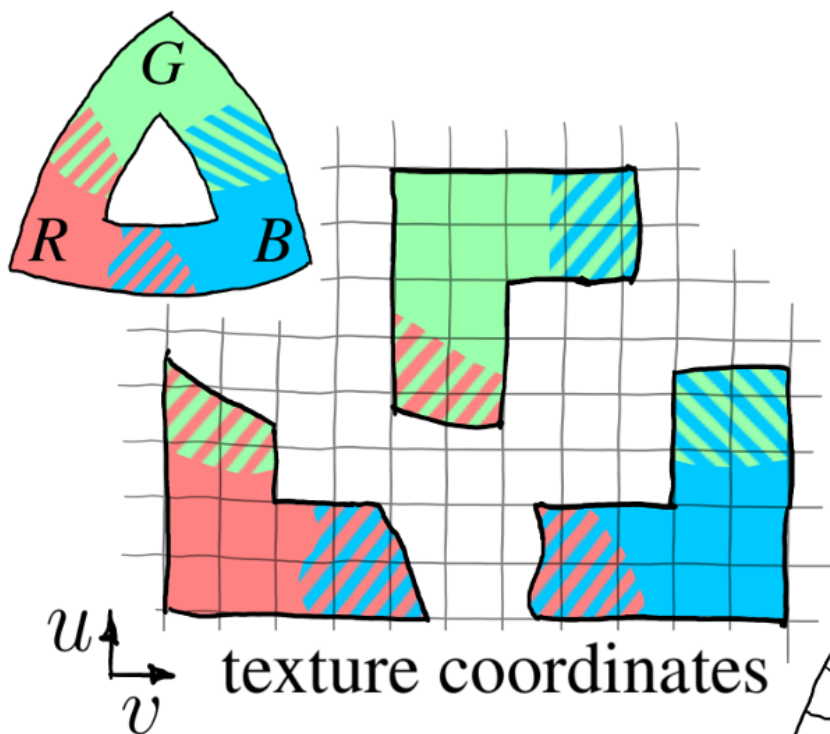
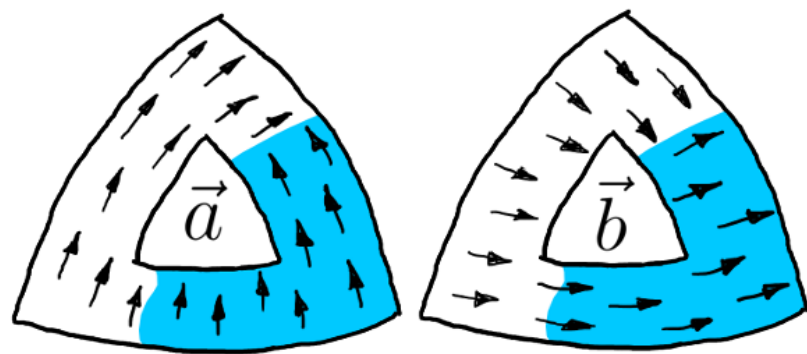
 $v_1 - v_2$ integer where defined



Introductory example 3 out of 3



Introductory example 3 out of 3



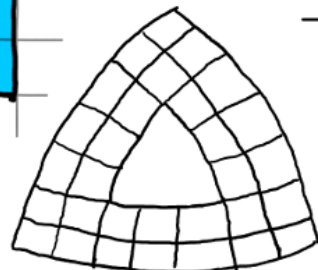
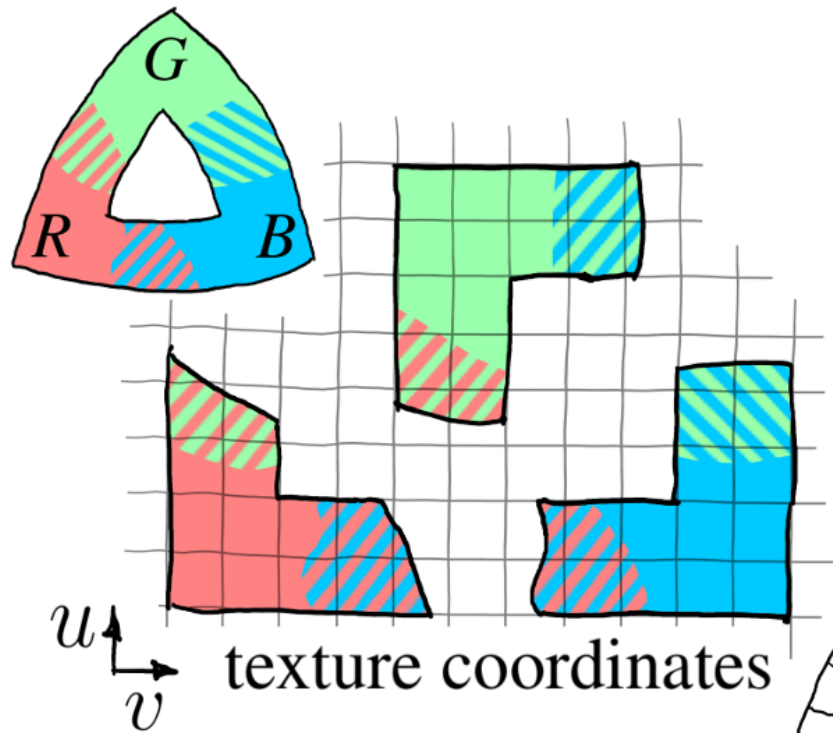
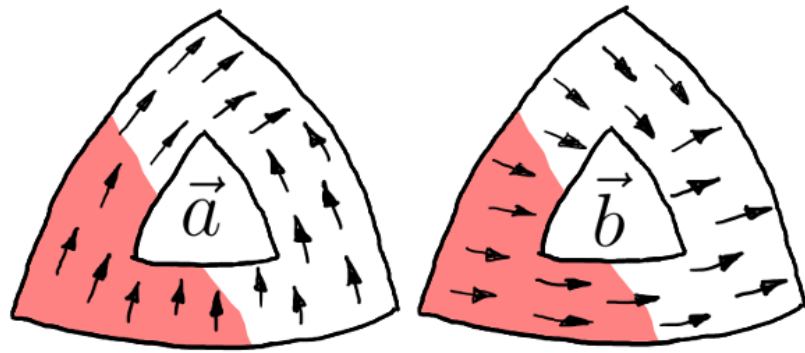
final mesh

find scalar functions $u_B, v_B, u_R, v_R, u_G, v_G$ that minimize

$$\begin{aligned} & \int_B |\nabla u_B - \vec{a}|^2 + \int_B |\nabla v_B - \vec{b}|^2 \\ & + \int_R |\nabla u_R - \vec{a}|^2 + \int_R |\nabla v_R - \vec{b}|^2 \\ & + \int_{G \setminus B} |\nabla u_G - \vec{a}|^2 + \int_{G \setminus B} |\nabla v_G - \vec{b}|^2 \\ & + \int_{G \cap B} |\nabla u_G - \vec{b}|^2 + \int_{G \cap B} |\nabla v_G + \vec{a}|^2 \end{aligned}$$

$u_B - u_R, v_B - v_R, u_G - u_R, v_G - v_R,$
 $u_G - v_B, v_G + u_B$ are integer

Introductory example 3 out of 3



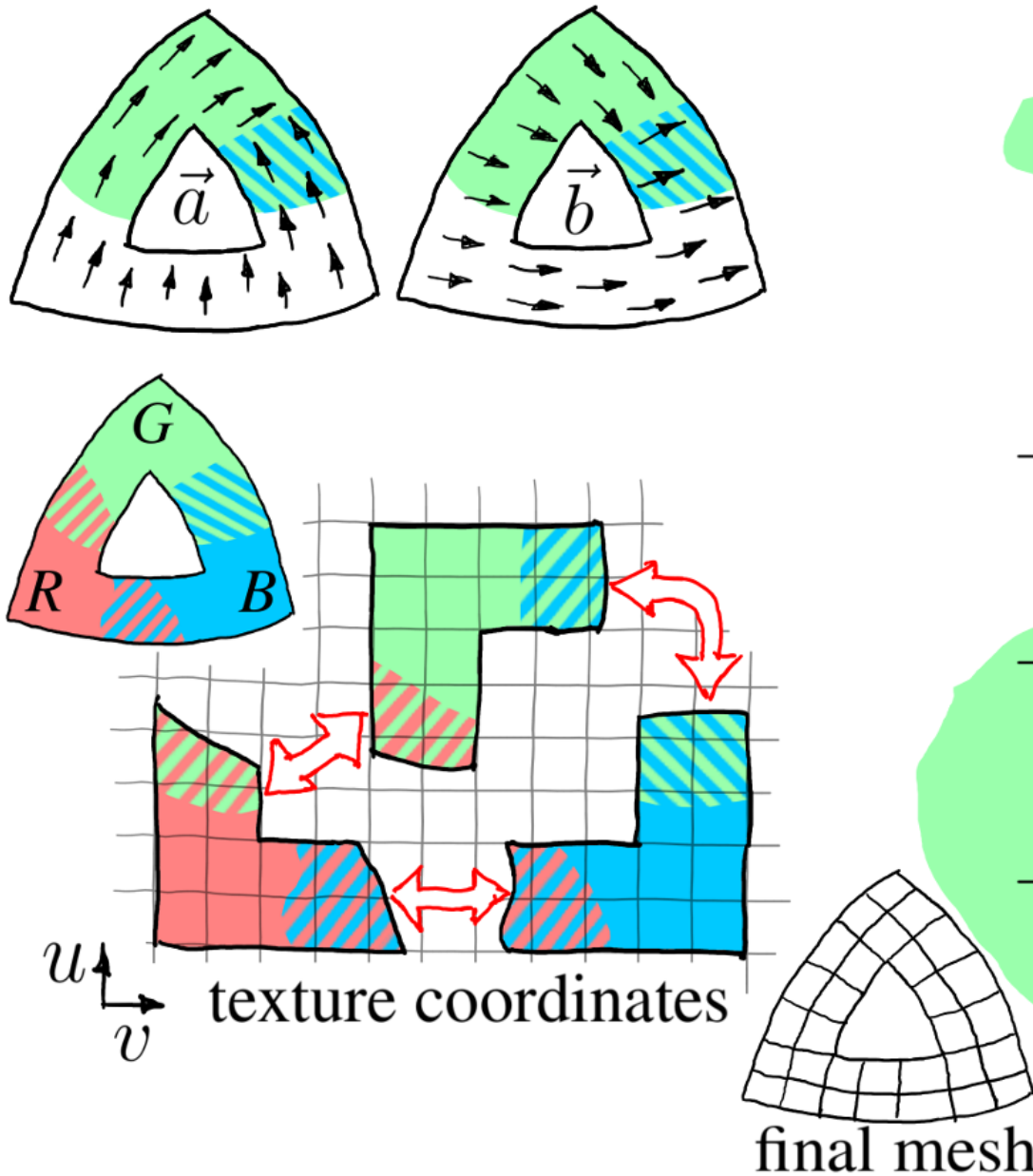
final mesh

find scalar functions $u_B, v_B, u_R, v_R, u_G, v_G$ that minimize

$$\begin{aligned} & \int_B |\nabla u_B - \vec{a}|^2 + \int_B |\nabla v_B - \vec{b}|^2 \\ & + \int_R |\nabla u_R - \vec{a}|^2 + \int_R |\nabla v_R - \vec{b}|^2 \\ & + \int_{G \setminus B} |\nabla u_G - \vec{a}|^2 + \int_{G \setminus B} |\nabla v_G - \vec{b}|^2 \\ & + \int_{G \cap B} |\nabla u_G - \vec{b}|^2 + \int_{G \cap B} |\nabla v_G + \vec{a}|^2 \end{aligned}$$

$u_B - u_R, v_B - v_R, u_G - u_R, v_G - v_R,$
 $u_G - v_B, v_G + u_B$ are integer

Introductory example 3 out of 3



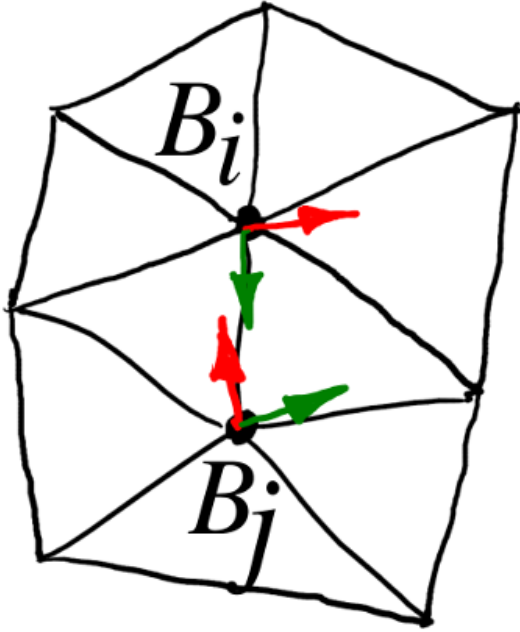
find scalar functions $u_B, v_B, u_R, v_R, u_G, v_G$ that minimize

$$\begin{aligned}
 & \int_B |\nabla u_B - \vec{a}|^2 + \int_B |\nabla v_B - \vec{b}|^2 \\
 & + \int_R |\nabla u_R - \vec{a}|^2 + \int_R |\nabla v_R - \vec{b}|^2 \\
 & + \int_{G \setminus B} |\nabla u_G - \vec{a}|^2 + \int_{G \setminus B} |\nabla v_G - \vec{b}|^2 \\
 & + \int_{G \cap B} |\nabla u_G - \vec{b}|^2 + \int_{G \cap B} |\nabla v_G + \vec{a}|^2
 \end{aligned}$$

$u_B - u_R, v_B - v_R, u_G - u_R, v_G - v_R,$
 $u_G - v_B, v_G + u_B$ are integer

Global parameterization: problem statement

Input: one basis per vertex and
one of 24 (4 in 2d) matrices per edge

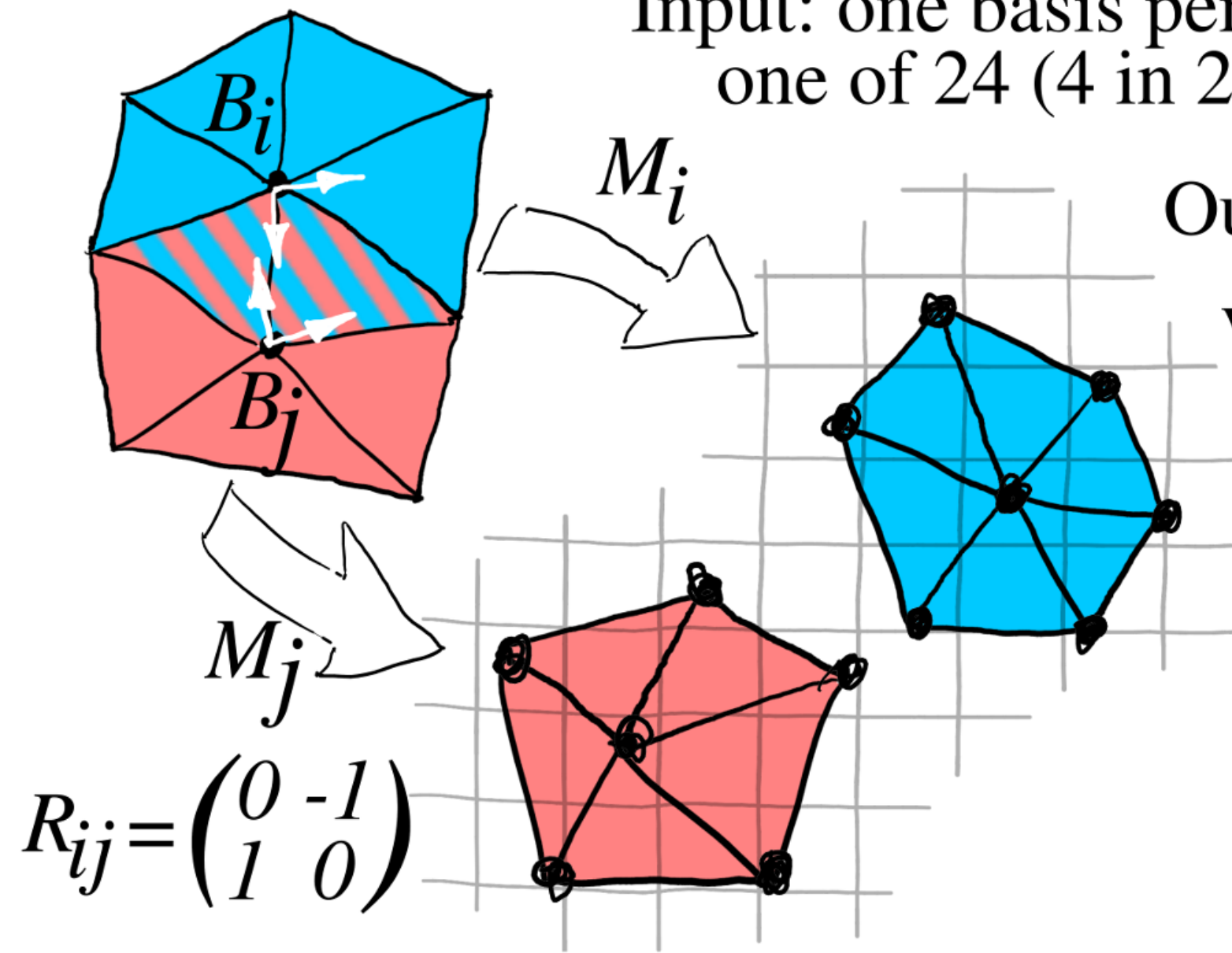


$$R_{ij} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Global parameterization: problem statement

Input: one basis per vertex and
one of 24 (4 in 2d) matrices per edge

Output: one map per
vertex star $J(M_i^{-1}) \approx B_i$



Global parameterization: problem statement

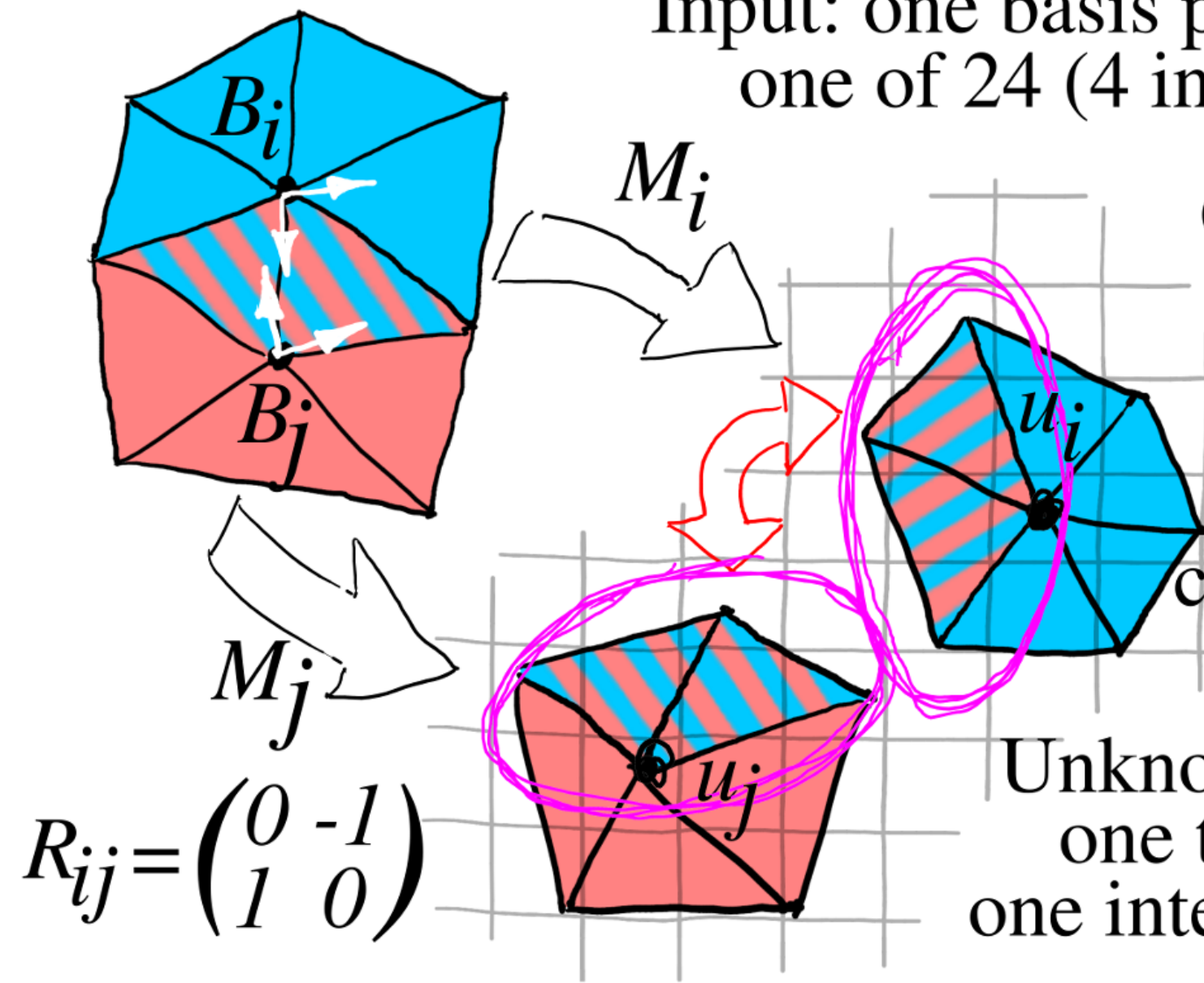
Input: one basis per vertex and
one of 24 (4 in 2d) matrices per edge

Output: one map per
vertex star $J(M_i^{-1}) \approx B_i$

under grid equivalence
constraint $M_j = R_{ij}M_i + t_{ij}$

Unknowns:

one tex coord per vertex (u_i)
one integer vector per edge (t_{ij})

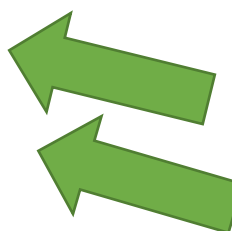


$$R_{ij} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Global parameterization: problem statement

The problem is to find an atlas of grid-equivalent maps;
each map is linear per tet, thus 4 points suffice to enforce the
gr. eq. constraint:

for a tet (i,j,k,l) , maps M_i and M_j must satisfy:

$$\begin{cases} M_i(\mathbf{x}_i) &= R_{ij} M_j(\mathbf{x}_i) + \mathbf{t}_{ij} \\ M_i(\mathbf{x}_j) &= R_{ij} M_j(\mathbf{x}_j) + \mathbf{t}_{ij} \\ M_i(\mathbf{x}_k) &= R_{ij} M_j(\mathbf{x}_k) + \mathbf{t}_{ij} \\ M_i(\mathbf{x}_l) &= R_{ij} M_j(\mathbf{x}_l) + \mathbf{t}_{ij} \end{cases}$$


2 out of 4 constraints are
naturally satisfied with our
choice of the variables

Global parameterization: problem statement

Least-squares problem

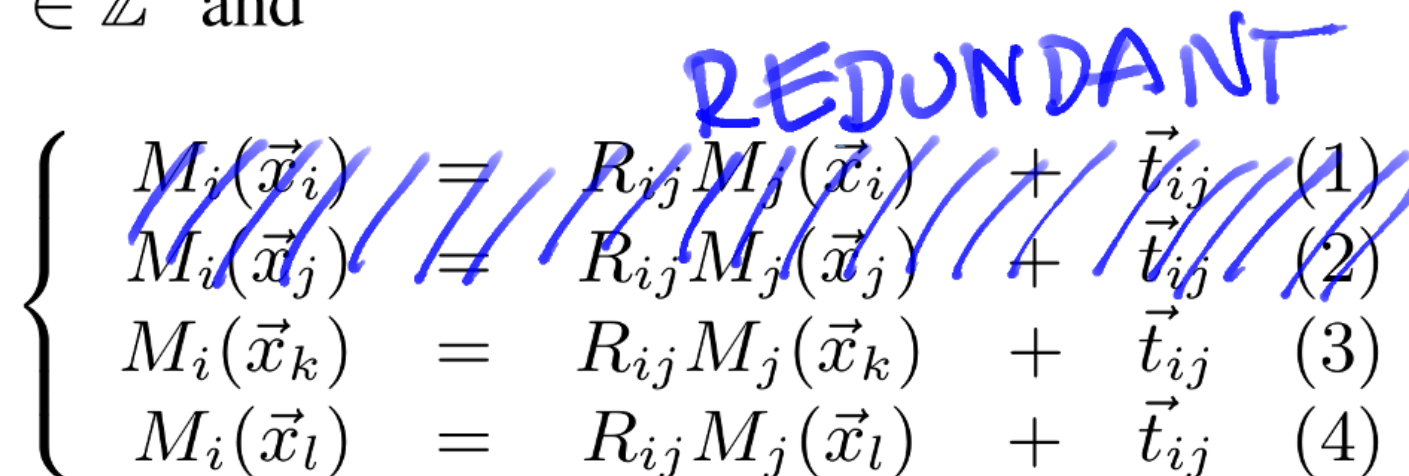
$\forall i < j, \quad \vec{u}_i - R_{ij} \vec{u}_j - \vec{t}_{ij} + \vec{g}_{ij} = \vec{0} \quad \text{with} \quad \vec{g}_{ij} = \frac{(B_i^{-1} + R_{ij} B_j^{-1}) (\vec{x}_j - \vec{x}_i)}{2}$



under constraints:

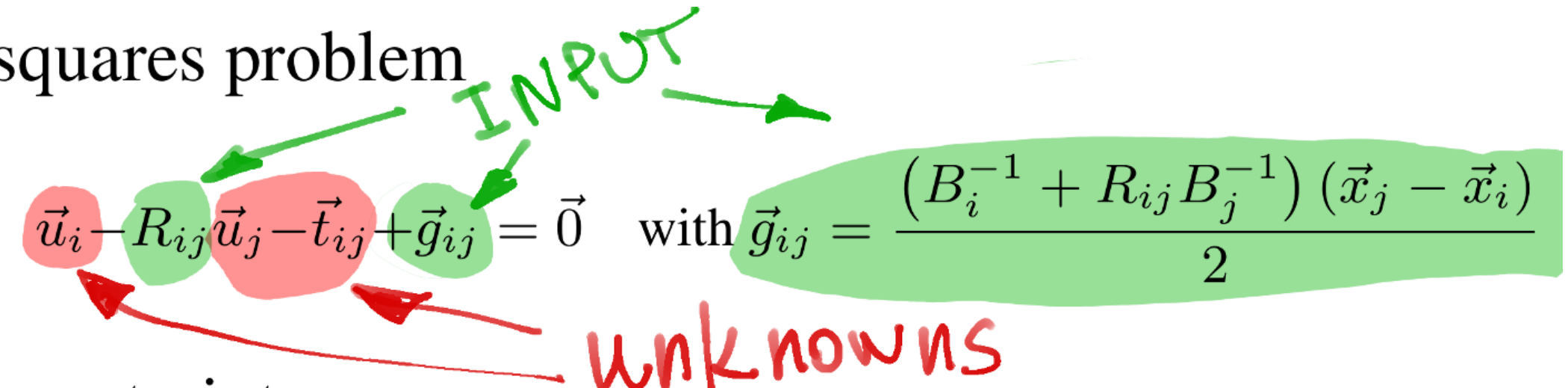
per edge $(i, j) \quad \vec{t}_{ij} \in \mathbb{Z}^3$ and

per tet $(i, j, k, l) \quad \left\{ \begin{array}{l} \cancel{M_i(\vec{x}_i)} = \cancel{R_{ij} M_j(\vec{x}_i)} + \cancel{\vec{t}_{ij}} \quad (1) \\ \cancel{M_i(\vec{x}_j)} = \cancel{R_{ij} M_j(\vec{x}_j)} + \cancel{\vec{t}_{ij}} \quad (2) \\ M_i(\vec{x}_k) = R_{ij} M_j(\vec{x}_k) + \vec{t}_{ij} \quad (3) \\ M_i(\vec{x}_l) = R_{ij} M_j(\vec{x}_l) + \vec{t}_{ij} \quad (4) \end{array} \right.$



Global parameterization: problem statement

Least-squares problem



The diagram shows the equation $\forall i < j, \vec{u}_i - R_{ij}\vec{u}_j - \vec{t}_{ij} + \vec{g}_{ij} = \vec{0}$ with $\vec{g}_{ij} = \frac{(B_i^{-1} + R_{ij}B_j^{-1})(\vec{x}_j - \vec{x}_i)}{2}$. Handwritten green arrows point from the word "INPUT" to the terms R_{ij} and \vec{g}_{ij} . Handwritten red arrows point from the word "unknowns" to the terms \vec{u}_i , \vec{u}_j , and \vec{t}_{ij} . The terms \vec{u}_i and \vec{u}_j are circled in red, while R_{ij} and \vec{g}_{ij} are circled in green. The entire right-hand side of the equation is highlighted in green.

$$\forall i < j, \vec{u}_i - R_{ij}\vec{u}_j - \vec{t}_{ij} + \vec{g}_{ij} = \vec{0} \quad \text{with} \quad \vec{g}_{ij} = \frac{(B_i^{-1} + R_{ij}B_j^{-1})(\vec{x}_j - \vec{x}_i)}{2}$$

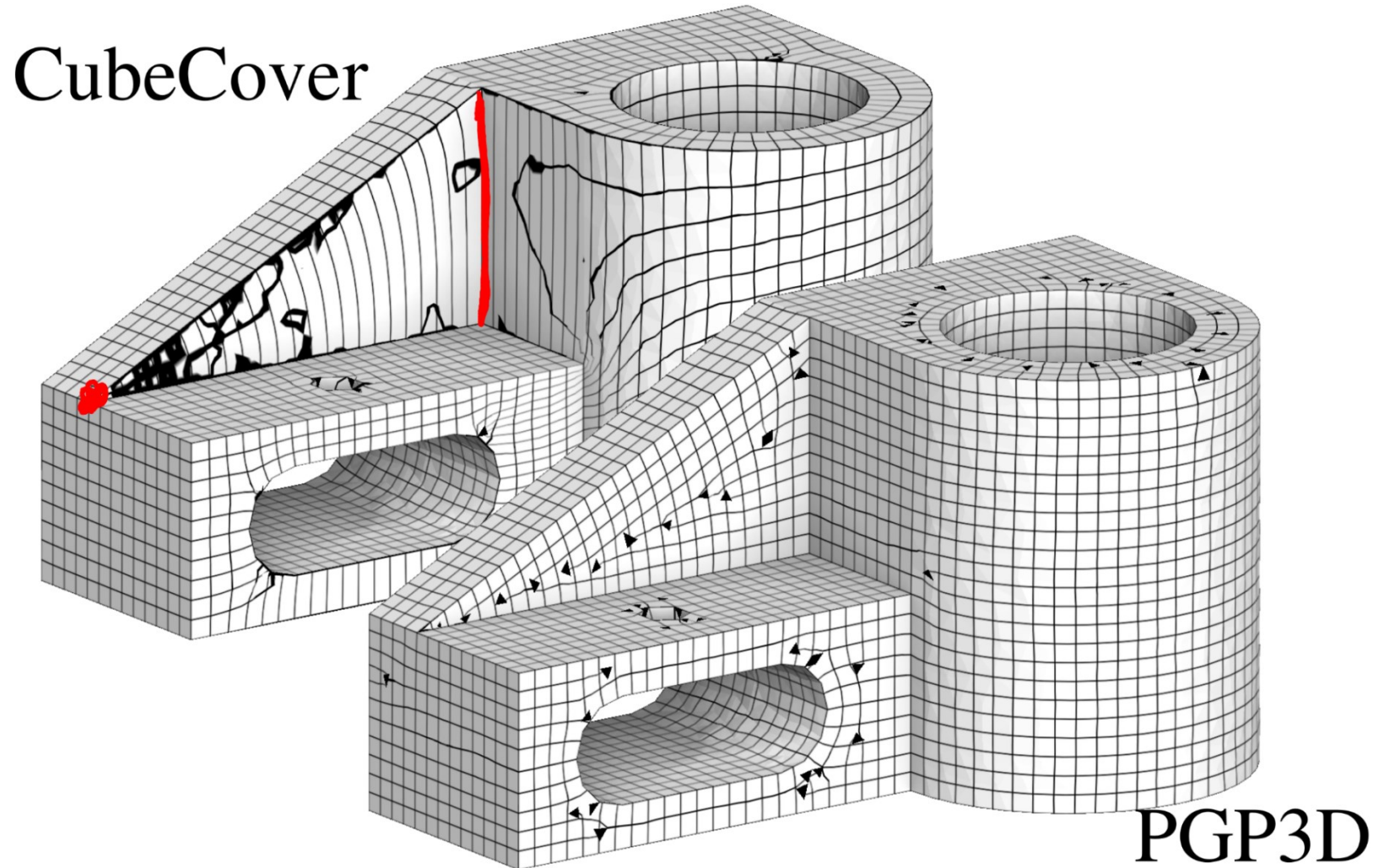
under constraints:

per edge (i, j) $\vec{t}_{ij} \in \mathbb{Z}^3$ and

$$\text{per tet } (i, j, k, l) \quad \begin{cases} R_{ik}(\vec{u}_k - \vec{t}_{ki}) &= R_{ij}R_{jk}(\vec{u}_k - \vec{t}_{kj}) \\ R_{il}(\vec{u}_l - \vec{t}_{li}) &= R_{ij}R_{jl}(\vec{u}_l - \vec{t}_{lj}) \end{cases}$$

Global parameterization: solution mechanism

CubeCover [Nieser et al, 2011] enforces all the constraints, whereas the we ignore half of grid equivalence constraints (it is a feature, not a bug).



Periodic global parameterization

as $\vec{t}_{ij} \in \mathbb{Z}^3$ and appears in exactly one line of the system

$$\forall i < j, \quad \vec{u}_i - R_{ij}\vec{u}_j - \vec{t}_{ij} + \vec{g}_{ij} = \vec{0},$$

we can solve first

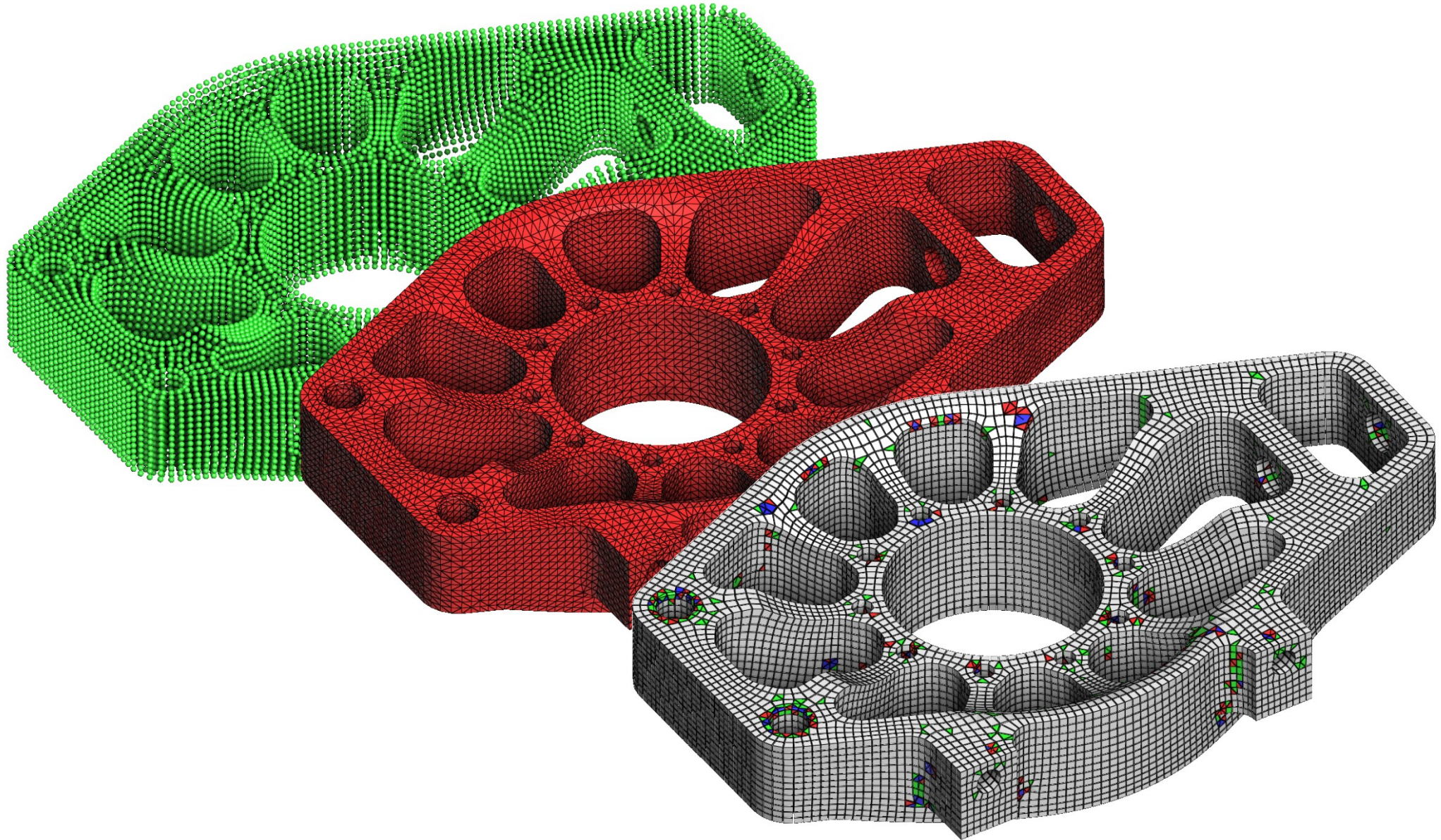
$$\forall i < j, \quad \vec{u}_i + \vec{g}_{ij} = R_{ij}\vec{u}_j \quad \text{mod } 1,$$

then deduce the value of \vec{t}_{ij}

$$\forall i < j, \forall d \in \{0, 1, 2\} \left\{ \begin{array}{l} \cos(2\pi(\vec{u}_i + \vec{g}_{ij})[d]) = \cos(2\pi(R_{ij}\vec{u}_j)[d]) \\ \sin(2\pi(\vec{u}_i + \vec{g}_{ij})[d]) = \sin(2\pi(R_{ij}\vec{u}_j)[d]) \end{array} \right.$$

$$\vec{a}_i[d] = \cos(2\pi\vec{u}_i[d]) \quad \text{and} \quad \vec{b}_i[d] = \sin(2\pi\vec{u}_i[d])$$

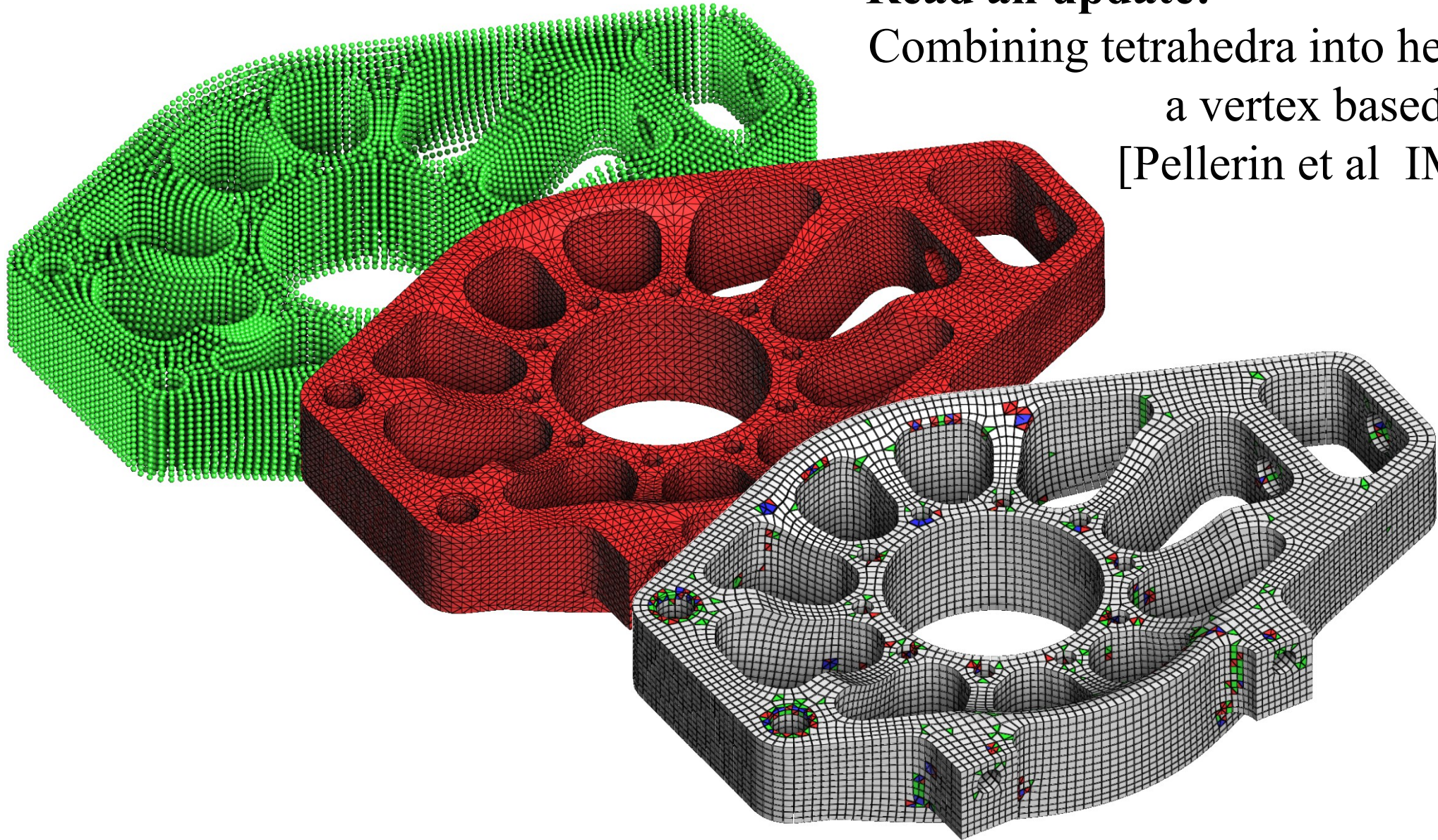
Extract the hex-dominant mesh



Extract the hex-dominant mesh

Read an update:

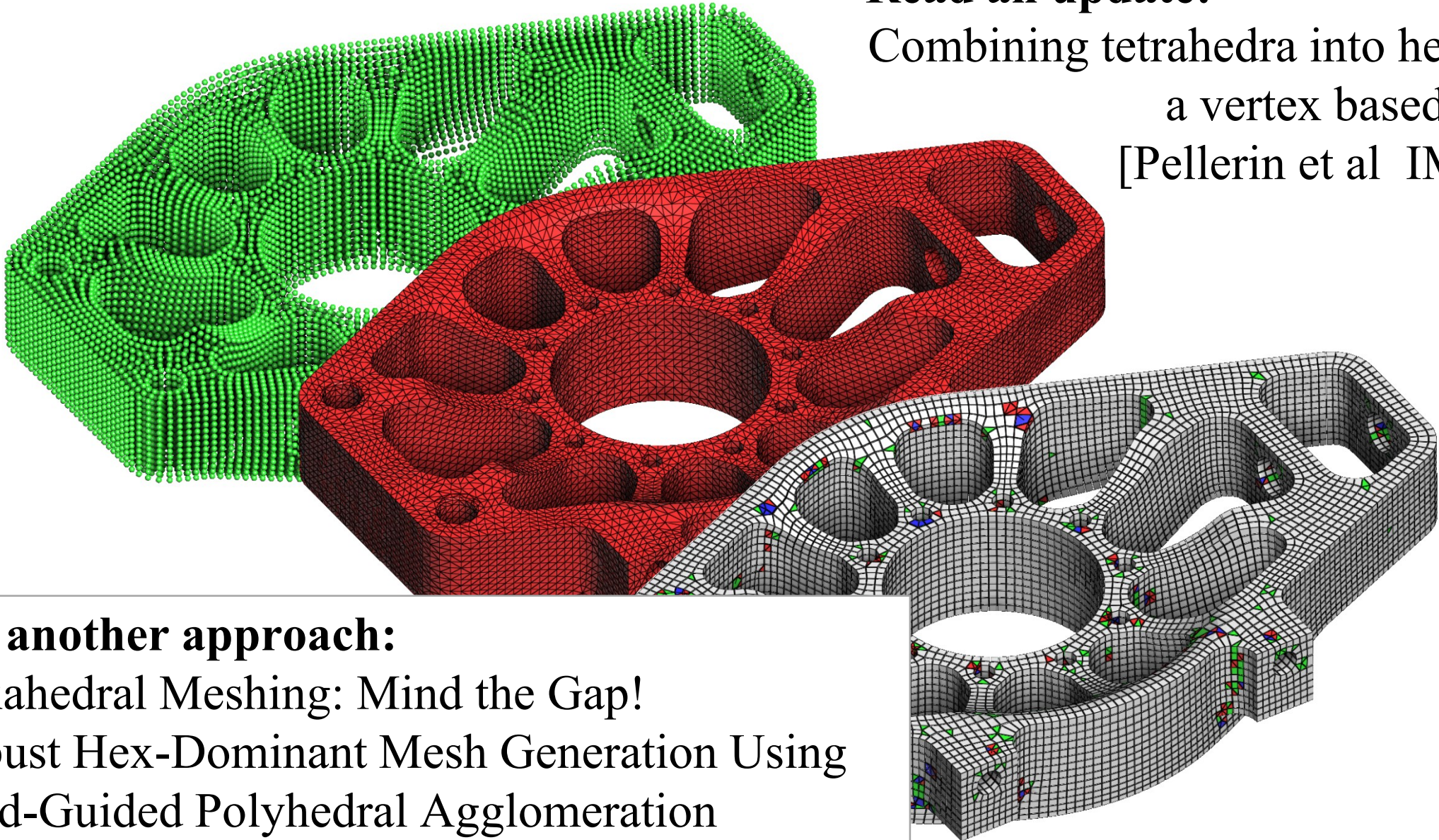
Combining tetrahedra into hexahedra:
a vertex based strategy
[Pellerin et al IMR2017]



Extract the hex-dominant mesh

Read an update:

Combining tetrahedra into hexahedra:
a vertex based strategy
[Pellerin et al IMR2017]



Or use another approach:

- Hexahedral Meshing: Mind the Gap!
- Robust Hex-Dominant Mesh Generation Using Field-Guided Polyhedral Agglomeration

Thank you for your attention!